

IOT Practical 08

Aim - Trigger a set of led GPIOs on the pi in a Node-Red

Steps:

- 1) Open Node-Red from application
- 2) Open browser and type localhost:1880
- 3) Drag and drop nodes - inject, vpi-gpio:raspberrypi on the right and debug
- 4) Double-click on the node and a box will appear to let you configure the node
- 5) Change the GPIO pin to be GPIO22
- 6) Gives the node a name - we called it RED LED
- 7) Click Done
- 8) Click on the Deploy button once it is deployed successfully
- 9) Click on the inject button

Date
21/10/21

Neeraj Appan 10/15
T01 Practical -09

SDS	Page No.
Date	

Aim: Setup a Mosquitto MQTT server and client and write a Python script to communicate data between Pi's

Steps

- 1) Install MQTT
- 2) Open terminal
- 3) Sudo apt-get install -y mosquitto mosquitto-clients
- 4) Mosquitto sub -h localhost -u -t test-channel
- 5) Open second terminal
- 6) Mosquitto pub -h localhost -t test-channel -m "Hello Raspberry Pi"
- 7) Sudo pip install paho-mqtt
- 8) Sudo nano -mqtt subscriber.py pub.py

```
import paho.mqtt.publish as publish
```

```
MQTT_SERVER = "192.168.0.112"
```

```
MQTT_PATH = "test-channel"
```

```
Publish.single(MQTT_PATH, "Welcome to TRES Practical", hostname = MQTT_SERVER)
```

```
Sub.py
```

```
import paho.mqtt.client as mqtt
```

```
MQTT_SERVER = "192.168.0.112" MQTT_PATH = "test-channel"
```

```
def on_connect(client, userdata, flags, rc):
```

```
print("Connected with result code" + str(rc)) client.subscribe(MQTT_PATH)
```

```
def on_message(client, userdata, msg):
```

```
print(msg.topic + " " + str(msg.payload))
```


Client = mqtt-client
 Client on _connect = on _connect client on _message -
 = on _message = on _message client.connect (mqtt server,
 1883, 60) client.loop-forever()

Date
21/10/21

Neeraj Appam T073
I07 Practical - 10

SDS	Page No.
Date	

Aim. Setup a physical button switch and trigger an led in node red and python w debounce

Steps

- 1) Open an idle
- 2) Type the code

Code

```
import RPi.GPIO as GPIO
import time
GPIO.setmode(GPIO.BCM)
GPIO.setup(19, GPIO.IN)
GPIO.setup(16, GPIO.IN)
GPIO.setup(20, GPIO.OUT)
GPIO.setup(21, GPIO.OUT)
while True:
    reading = GPIO.input(19)
    if reading == 0:
        print "FIRST Button Pressed"
        GPIO.output(20, 1)
        time.sleep(0.2)
        GPIO.output(20, 0)
        time.sleep(0.2)
        reading1 = GPIO.input(16)
        if reading1 == 0:
            print "Second Button Pressed"
            GPIO.output(21, 1)
            time.sleep(0.2)
            GPIO.output(21, 0)
            time.sleep(0.2)
            GPIO.output(20, 1)
            time.sleep(0.2)
            GPIO.output(20, 0)
            time.sleep(0.2)
            GPIO.output(21, 1)
            time.sleep(0.2)
            GPIO.output(21, 0)
            time.sleep(0.2)
```

- 3) Open the terminal
- 4) Type : sudo python pythonfile.py

Node-RED

Deploy

Q filter nodes

Flow 1 Flow 2

csv, html, json, xml, yaml

storage

file, file in, watch

Raspberry Pi

rpi - gpio in, rpi - gpio out, rpi - mouse, rpi - keyboard

timestamp

msg.payload

PIN: tri

PIN:

PI Mouse Left

Edit rpi-gpio out node

Delete Cancel Done

Properties

3.3V Power - 17	18 - GPIO24
MOSI - GPIO10 - 19	20 - Ground
MISO - GPIO09 - 21	22 - GPIO25
SCLK - GPIO11 - 23	24 - GPIO8 - CE0
Ground - 25	26 - GPIO7 - CE1
SD - 27	28 - SC
GPIO05 - 29	30 - Ground
GPIO06 - 31	32 - GPIO12
GPIO13 - 33	34 - Ground
GPIO19 - 35	36 - GPIO16
GPIO26 - 37	38 - GPIO20
Ground - 39	40 - GPIO21

15

Type: Digital output

☐ Initialise pin state?

Name: RED LED

Pins in Use:

Tip: For digital output - input must be 0 or 1.

☐ Enabled

info

Search flows

- Flows
- Subflows
- Global Configuration Nodes

PIN:

Node: "3cabe3a85a79e8ef"

Type: rpi-gpio out

show more

click and drag on a node port to move all of the attached wires or just the selected one

WhatsApp Practical 8,9&10 Node-RED

127.0.0.1:1880/#flow/f4ba65a9c1b61bd6

Apps Ubuntu Gnome 16 BScCS Web Service... Reading list

Node-RED

Deploy

filter nodes

Flow 2 Flow 3

storage

- file
- file in
- watch

redPic modules

- gpio

Raspberry PI

- rpi - gpio in
- rpi - gpio out
- rpi - mouse
- rpi - keyboard

timestamp

timestamp

Edit rpi-gpio out node

Delete Cancel Done

Properties

GPIO05 - 29	30 - Ground
GPIO06 - 31	32 - GPIO12
GPIO13 - 33	34 - Ground
GPIO19 - 35	36 - GPIO16
GPIO26 - 37	38 - GPIO20
Ground - 39	40 - GPIO21

15

Type Digital output

☐ Initialise pin state?

Name Red LED

Pins in Use:

Tip: For digital output - input must be 0 or 1.

☐ Enabled

info

Search flows

Flows

- Flow 1
- Flow 2
- Flow 3
- Flow 4
- Flow 5
 - timestamp
 - PIN: tri
 - msg payload
- Flow 6

PIN:

Node "34a232fb114140d3"

Type rpi-gpio out

show more

Type here to search

10:26 21-10-2021

FrontPage - Rasp...rasberry pi instal...Raspberry Pi Doc...Raspberry Pi Doc...How to Use the L...Practical 8,9&10...rasberry pi os or...Node-RED

localhost:1880/#flow/f10c03d6aa202947

Node-RED

Successfully injected: OFF

Deploy

Flow 1Flow 2

filter nodes

common

inject

debug

complete

catch

status

link in

link out

comment

function

function

switch

change

range

template

timestamp

msg.payload

ON

OFF

RED LED

N/A : 1634896374891

debug

all nodes

10/22/2021, 2:09:29 PM node: b4d29a37e0cc3daa
msg.payload : number
1634891969923

10/22/2021, 3:22:51 PM node: b4d29a37e0cc3daa
msg.payload : number
1634896371153

Type here to search

15:22

22-10-2021

ENG

Node-RED

Deploy

filter nodes

Flow 1 Flow 2

timestamp

msg.payload

RED LED

not available

debug

all nodes

10/22/2021, 2:09:29 PM node: b4d29a37e0cc3daa
msg.payload : number
1634891969923

csv

html

json

xml

yaml

storage

file

file in

watch

Raspberry Pi

rpi - gpio in

rpi - gpio out

rpi - mouse

rpi - keyboard





