

Date
20/07/21

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Practical-03

* Aim - Implement A^* search algorithm for romanian map problem

* A^* search Algorithm Description -

→ A^* search algorithm is an informed search algorithm or a best first search, meaning that it is formulated weighted graphs; starting from a specific starting node of a graph; it aims to find a path of the graph from goal node having the smallest cost

* Strategies evaluated along the following dimensions

1) Completeness - does it always find a solution if one exists?

→ The A^* algorithm is the optimal algorithm provided heuristic function is underestimated, complete and admissible

2) Optimality - does it always find a least cost solution

→ A search algorithm is optimal if no other search algorithm uses less time or space or expands fewer nodes, both will guarantee of solution quality. The optimal search algorithm would be one that picks the correct node at choice

3) Time complexity - number of nodes generated

→ The time complexity of A^* depends on heuristic. In worst case of an unbounded search space, the number of nodes expanded is exponential in the depth of solution

- 4) Space complexity - maximum number of nodes in memory $O(VD) = O(b^d)$, Stores all generated nodes in memory
- 5) Time and space complexity are measured in terms of
 - a) b - maximum branching factor of search tree is $O(b^d)$
 - b) d - depth of least cost solution is Shortest path
 - c) m - maximum depth of State Space (may ∞)
 - d) Search cost (time), total cost (time + space)

* Algorithm

- 1) Start
- 2) Import heapq
- 3) Add Class priorityQueue with Functions - init - push, pop, is Empty, check
- 3) Take class Node to write parent, cost parameters self, city and distance in --init-- function
- 4) Write function makeDict to open romania.txt to read
- 5) Write function makeHeuristicDict to open romaniast.txt to read
- 6) Take heuristic function to return nodes and values
- 7) Take astar function to call class priorityQueue and makeHeuristicDict function
- 8) Write parameters necessary to print output in printOutput class
- 9) Give source and destination in main function
- 10) Stop

* Flowchart

Initial start sector 'n'
and put it on open list

Calculate cost function
 $f(n) = g(n) + h(n)$

remove from open list and
put on closed and store the
index of the sector 'j', which
has the smallest 'f'

IF 'n' is the
target sector

Yes

Terminate the
algorithm and get
the points of index
to get optimal path

No

Identify all the successor
sectors of 'n' which not on
closed list

Calculate cost function 'f' for
each sector

try 3.py - E:/fffiiles/college pracs and projects/AI/try 3.py (3.8.3)
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```
import heapq
print("Neeraj Appari")

class priorityQueue:
    def __init__(self):
        self.cities = []

    def push(self, city, cost):
        heapq.heappush(self.cities, (cost, city))

    def pop(self):
        return heapq.heappop(self.cities)[1]

    def isEmpty(self):
        if (self.cities == []):
            return True
        else:
            return False

    def check(self):
        print(self.cities)

class ctNode:
    def __init__(self, city, distance):
        self.city = str(city)
        self.distance = str(distance)

romania = {}
```

Python 3.8.3 Shell

File Edit Shell Debug Options Window Help

Python 3.8.3 (tags/v3.8.3:6f8c832, May 13 2020, 22:20:19) [MSC v.1925 32 bit (Intel)] on win32
Type "help", "copyright", "credits" or "license()" for more information.

>>>

===== RESTART: E:/fffiiles/college pracs and projects/AI/try 3.py =====

Neeraj Appari

Program algoritma Astar untuk masalah Romania

Arad => Bucharest

Kota yg mungkin dijelajah : ['Arad', 'Sibiu', 'Rimnicu Vilcea', 'Fagaras', 'Pitesti', 'Bucharest']

Jumlah kemungkinan kota : 6

Kota yg dilewati dg jarak terpendek : ['Arad', 'Sibiu', 'Rimnicu Vilcea', 'Pitesti', 'Bucharest']

Jumlah kota yang dilewati : 5

Total jarak

: 418

>>> |

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ENG

try 3.py - E:\fffiles\college pracs and projects\AI\try 3.py (3.8.3)

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```
distance = {}
q = priorityQueue()
h = makeheuristicdict()

q.push(start, 0)
distance[start] = 0
path[start] = None
expandedList = []

while (q.isEmpty() == False):
    current = q.pop()
    expandedList.append(current)

    if (current == end):
        break

    for new in romania[current]:
        g_cost = distance[current] + int(new.distance)

        # print(new.city, new.distance, "now : " + str(distance[current]), g_cost)

        if (new.city not in distance or g_cost < distance[new.city]):
            distance[new.city] = g_cost
            f_cost = g_cost + heuristic(new.city, h)
            q.push(new.city, f_cost)
            path[new.city] = current

printoutput(start, end, path, distance, expandedList)

def printoutput(start, end, path, distance, expandedlist):
    finalpath = []
```

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```
romania = {}

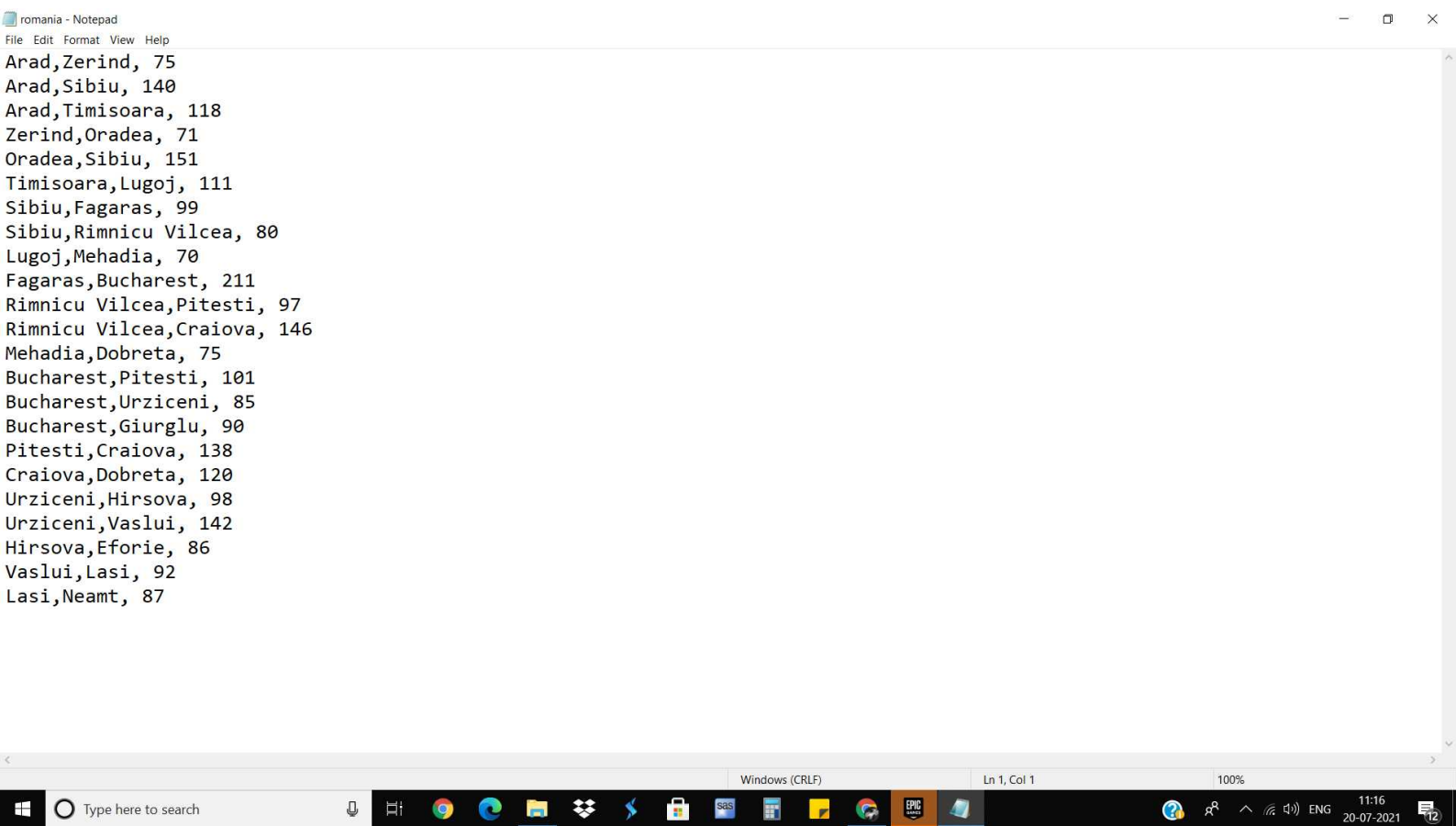
def makedict():
    file = open("romania.txt", 'r')
    for string in file:
        line = string.split(',')
        ct1 = line[0]
        ct2 = line[1]
        dist = int(line[2])
        romania.setdefault(ct1, []).append(ctNode(ct2, dist))
        romania.setdefault(ct2, []).append(ctNode(ct1, dist))

def makehuristikdict():
    h = {}
    with open("romania_sld.txt", 'r') as file:
        for line in file:
            line = line.strip().split(",")
            node = line[0].strip()
            sld = int(line[1].strip())
            h[node] = sld
    return h

def heuristic(node, values):
    return values[node]

def astar(start, end):
    path = {}
```

```
def printoutput(start, end, path, distance, expandedlist):  
    finalpath = []  
    i = end  
  
    while (path.get(i) != None):  
        finalpath.append(i)  
        i = path[i]  
    finalpath.append(start)  
    finalpath.reverse()  
    print("Program algoritma Astar untuk masalah Romania")  
    print("\tArad => Bucharest")  
    print("=====")  
    print("Kota yg mungkin dijelajah \t\t: " + str(expandedlist))  
    print("Jumlah kemungkinan kota \t\t: " + str(len(expandedlist)))  
    print("=====")  
    print("Kota yg dilewati dg jarak terpendek\t: " + str(finalpath))  
    print("Jumlah kota yang dilewati \t\t\t: " + str(len(finalpath)))  
    print("Total jarak \t\t\t\t\t: " + str(distance[end]))  
  
def main():  
    src = "Arad"  
    dst = "Bucharest"  
    makedict()  
    astar(src, dst)  
  
if __name__ == "__main__":  
    main()
```



Arad, 366
Bucharest, 0
Craiova, 160
Dobreta, 242
Eforie, 161
Fagaras, 176
Giurgiu, 77
Hirsowa, 151
Lasi, 226
Lugoj, 244
Mehadia, 241
Neamt, 234
Oradea, 380
Pitesti, 100
Rimnicu Vilcea, 193
Sibiu, 253
Timisoara, 329
Urziceni, 80
Vaslui, 199
Zerind, 374

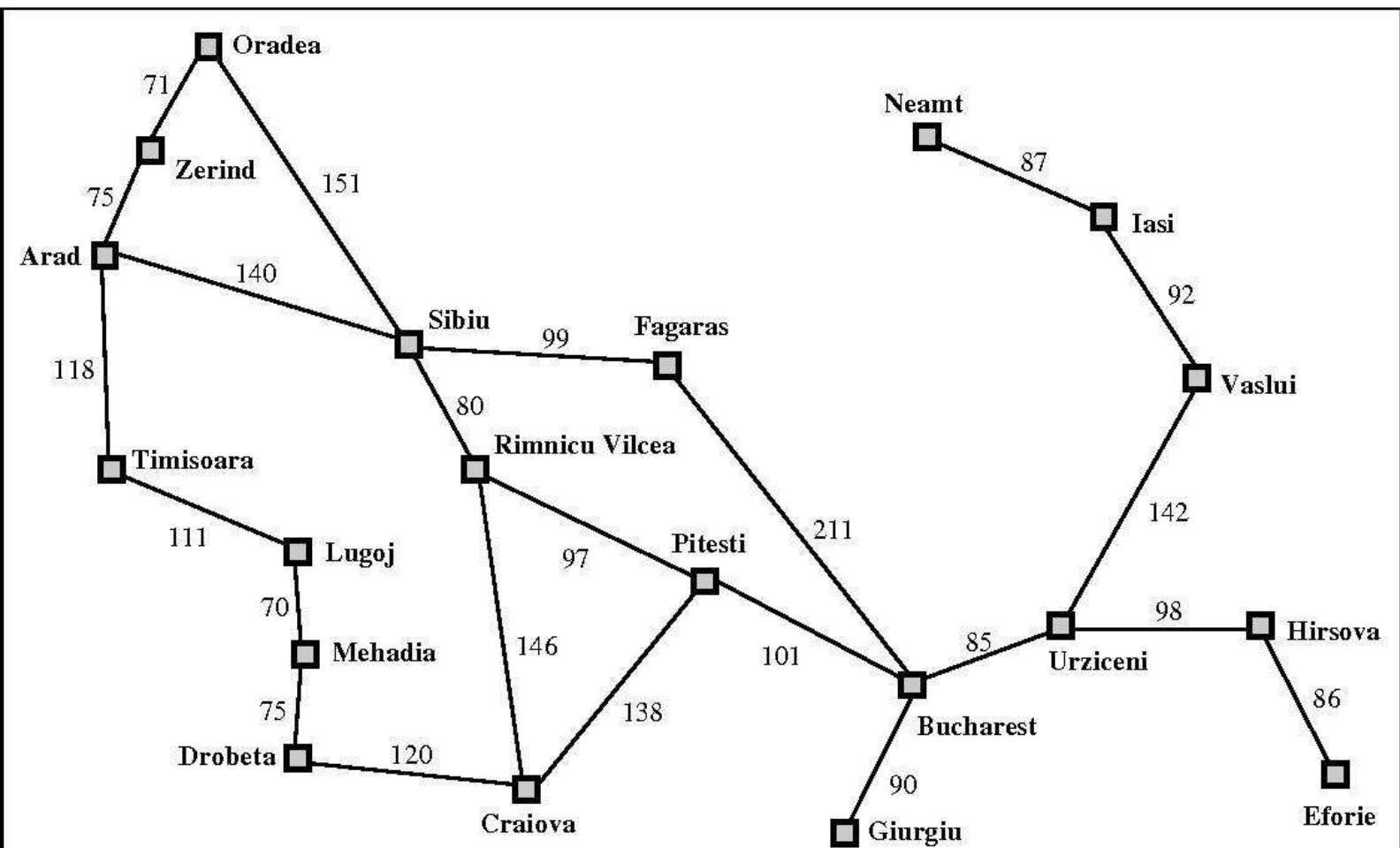


Figure 3.2 A simplified road map of part of Romania.