Neeraj Panse

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Education

Carnegie Mellon University, Robotics Institute

August 2022 - December 2023

Master of Science in Computer Vision - GPA: 4.0/4.0

Pittsburgh, USA

Coursework: Visual Learning and Recognition, Learning for 3D Vision, Computer Vision, Machine Learning, Robot Learning, Geomotry Based Vision, Computational Photography **Teaching Assistant**: 11603 - Python for Data Science, 11632 - Data Science Capstone

Experience

Lucid Motors | Perception Software Engineer

January 2024 - Present

- Leading the research and deployment of learning based Lidar object detection in the ADAS-Perception team at Lucid. Improved precision of existing models in adverse weather conditions (rain, fog, snow) from 94% to 96%.
- Working on BEV based multi-camera object detection models for the next generation of Lucid EVs. Increased performance of current object detection from **56 mAP** to **64 mAP** using SOTA BEV techniques such as **PETR and DD3D**.

Airlab, CMU | Research Collaborator advised by Prof. Sebastian Scherer

January 2023 - December 2023

- Worked on Real-Time Multi-layer Semantic 3D Mapping of indoor environments using images and lidar point clouds.
- Built strong baselines using lightweight 2D and 3D instance segmentation architectures such as RangeNet++ and SOLOv2.
- Investigated the use of pillar encoder networks such as **PointPillars** and **PiFeNet** for **3D object detection** in indoor settings.

Zillow Group | Machine Learning Engineering Intern

May 2023 - August 2023

- Worked in the AI Photography at Zillow to create on-device, real-time, 3D floor plans from panoramic images.
- Improved top down room shape representations from individual panoramas through efficient inference pipelines in C++.
- Developed algorithms that eliminated **96% of undesired overlaps** in room shapes by merging upstream panoramic representations, leading to highly interpretable and interactive 3D floor plans for enhanced visual user experience.

Adagrad AI | Research Scientist, Computer Vision

August 2020 - June 2022

- Led the product R&D of <u>GateGuard</u> an edge based Boom Barrier Automation system using Number Plate Recognition.
- Developed data collection, training and deployment pipelines for lightweight object detection models: Yolo-X and Yolo-v5.
- Achieved accuracy of 97% for four-wheelers and 95% for two-wheelers with 50 fps throughput on Nvidia Jetson-TX2
- Built real-time video pipelines in C++ using DeepStream-TensorRT. Deployed at 200+ sites for access control and analytics.
- Designed online analytics, inference and monitoring services using Django, Kafka, Celery, Redis, ONNX, Triton and DALI.

Publications/Projects

S2RF: Semantic Stylizing Neural Radiance Fields | Project Page |

March 2023 - July 2023

- Paper Publication Neeraj P., Moneish K., & Dishani L., S2RF: Semantically Stylized Radiance Fields., ICCV 2023 workshop on AI for 3D Content Creation. Paris, France
- Built techniques to transfer custom styles to custom objects and also maintain 3D consistency in neural 3D reconstructions.
- Designed style transfer methods in Pytorch by combining the NNFM loss and object masks from SOTA models (DETR, Segment Anything). Made use of Plenoxels to optimize radiance fields and get high quality and efficient 3D rendering.

3D Ken Burns Effect using Dual Pixel Sensors | Project Video |

August 2023 - December 2023

- Won the best project award for the Computational Photography course (15-663) at CMU amongst 26 graduate students.
- Designed and implemented a novel algorithm for the 3D Ken Burns effect using traditional techniques and deep learning.
- Built pipelines for creating the 3D Ken Burns effect using depth from dual pixels and SOTA image inpainting techniques.

Computer Vision Based Offside Detection In Soccer | Paper |

January 2020 - August 2020

- Paper Publication Neeraj P. & Ameya M., "A Dataset & Methodology for Computer Vision based Offside Detection in Soccer.", 2020 ACM Multimedia, Multimedia Content Analysis in Sports (MMSports), Seattle, Washington.
- Improved major drawbacks of current, real-world soccer offside decision-making by developing a Computer Vision and Image Processing based pipeline for providing accurate, fast, and explainable offside decisions.