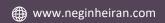
# Fatemeh (Negin) Heiran



### **Summary**

Fatemeh (Negin) Heiran received her MSc (2021) and BSc (2018) in Mechanical Engineering from Shiraz University in Iran. Her research interests include the development of novel mechanical mechanisms and robotic systems, controller design, and data analysis. She served as the senior of the Robotics team at Medis Studio in Iran, primarily working on the Painverse tele-robotic system and Estella humanoid robot.

### **Educations**

2018 -Master of Science in System Dynamics, Control and 2021 Vibration, Shiraz University, Shiraz, Iran, "Thesis: The effect of geometric and environmental parameters on scanning earth horizon sensor modeling and error analysis in satellite attitude determination" (Thesis Grade: Excellent)

2014 -Bachelor of Science in Mechanical Engineering, Shiraz 2018 University, Shiraz, Iran, "Final Project: Kinematics and workspace analysis of a novel parallel mechanism with kinematic redundancy".

#### **Experiences**

#### 01/2019-Senior Robotics Engineer and Project Manager - Medis 12/2024 Studio (Iran):

- Project manager of more than 10 products such as Painverse telerobotics system, Pandora compute
- Developing mechanical design by considering the feasibility of production
- Designing and analyzing of mechanical systems
- Trajectory and path planning algorithms by considering obstacle avoidance
- Design, prototyping and manufacturing products

#### Robotics Teacher - Saran Academy (Iran): 07/2019-

07/2021 Teaching robotics to kids and teenagers in 3 levels of Saran Academy

#### 08/2018-Research & Development Member - Medis Studio (Iran):

## 12/2024

- R&D process for more than 30 projects
- Business model, feasibility study and business plan
- Financial analysis of projects
- Designing company administration systems

#### **Contact**

heiran.fatemeh@gmail.com info@neginheiran.com



https://www.linkedin.com/in/fatemehheiran-337bb416a/

#### Research Interests

- Robotic mechanical design
- Motion planning
- Controller design
- Mathematical modeling of biological events
- Data analysis

#### Languages

English: B2 Persian: Native

#### **Technical Skills**

Software: MATLAB, Simulink, C, SolidWorks

Hardware: Modular Electronics Circuiting, 3D Printing (FDM, SLS), Sheet Metal, Laser Cutting, Lathe & Drilling Machines

Robotics: Mechanical Design, Humanoid Robot Design, Kinematics, Dynamics, Motion Control, Prototyping, Robot Manipulation Systems

Other: Product Prototyping, Arduino Programming, Satellite Toolkit (STK), NASA PSG, Office Suite, Excel VBA

#### **Soft Skills**

- Collaborative in interdisciplinary teams
- Strategic problem-solving & innovative thinking
- Project management experience
- Adaptability to emerging technologies

#### 06/2017-01/2019

06/2017- Junior Robotics Engineer - Medis Studio (Iran):

- Mechanical design with Solidworks
- Involve with the manufacturing process
- Prototyping robotics parts especially 3d printing

#### 10/2015-06/2017

#### **Robotics Intern - Medis Studio (Iran):**

- Learning mechanical design and prototyping
- Learning electronics, programming and robotics
- Part-time internship

#### **Patent**

B. Rahnama and F. Heiran, Multi-purpose expandable computing case with detachable enclosure, National Patent (ipm.ssaa.ir), Application No. 140150140003005180, Apr. 5, 2023.

#### **Publications**

- [1] B. Rahnama, F. Heiran, "Estella: a humanoid robot for enhanced human-robot interaction.", 6th Shiraz International Congress on Mobile Health, 2025. (Abstract Paper)
- [2] B. Rahnama, F. Heiran, A. Karimi, M. Radmehr, H. Zakeri, "Revolutionizing telemedicine with Painverse: the role of telerobotics in addressing the physician shortage", 6th Shiraz International Congress on Mobile Health, 2025. (Abstract Paper)
- [3] A. Khakpour Komarsofla, F. Heiran, J. Kodaei-Mehr, R. Vatankhah, "Hybrid control of immune response and HCMV infection of renal transplant recipient.", IEEE Transactions on Systems, Man, and Cybernetics: Systems, 53 (4), 2399 2409, 2022.
- [4] A. Mirahmadizadeh, A. Heiran, K.B. Lankarani, M. Serati, M. Habibi, O. Eilami, F. Heiran, M. Moghadami, "Effectiveness of covid-19 vaccines in preventing infectiousness, hospitalization and mortality: a historical cohort study using Iranian registration data during vaccination program", Open Forum Infectious Diseases, 9(6), 2022.
- [5] F. Heiran, B. Raeisy, R. Vatankhah, S. Taghvaei, "Investigating the effects of geometric and environmental parameters on the governing equations of scanning earth horizon sensor and attitude determination error analysis", Journal of Solid and Fluid Mechanics of Shahroud University, 12(5), 73-91, 2022. Doi: 10.22044/jsfm.2022.11309.3487. (In Persian)
- [6] F. Heiran, B. Raeisy, R. Vatankhah, S. Taghvaei, "Earth oblateness effect on satellite attitude determination with dual cone scanning earth horizon sensor modeling", 6th National Conference on Mechanical and Aerospace Engineering", 2022, Iran.
- [7] F. Heiran, J. Khodaei-Mehr, R. Vatankhah and M. Sharifi, "Nonlinear adaptive control of immune response of renal transplant recipients in the presence of uncertainties", Biomedical Signal Processing and Control Journal, Volume 63, January 2021.
- [8] B. Rahnama, F. Heiran, L. Rahnama, "Estella humanoid robot: an anatomical replicant", 2<sup>nd</sup> World Congress on Rheumatology and Orthopedics, Paris, France, pp 48, September 2019.
- [9] F. Heiran, B. Nouri Rahmat Abadi, S. Taghvaei, R. Vatankhah, "Kinematics and workspace analysis of a novel parallel mechanism with kinematic redundancy", 5th International Conference on Control, Instrumentation, and Automation (ICCIA), Shiraz, Iran, November 2017.

#### **Main Projects**

### 2023- Painverse Tele-robotics System

Present w

www.painverse.org

Painverse is revolutionizing telemedicine system by combining AI, robotics, and XR to enable real-time remote medical examinations across the globe.

#### 2018-Present

**Estella Humanoid Robot** 

www.estellahumanoids.com

Estella is a highly realistic humanoid robot that have flexible spine and can simulate human facial expressions.

#### Certificates

- [1] The non-degree program DBA (Business Administration) (2022 2023), University of Tehran, Iran.
- [2] Artificial Intelligence Fundamentals, 2025, IBM.
- [3] CS50: Introduction to Computer Sciences, 2025, Harvard university Edx.
- [4] An Intuitive Introduction to Probability, 2025, University of Zurich, Coursera.