

◆ **1 Pass-I of Two Pass Assembler**

Question

Answer

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|---|---|
| 1. What is an assembler? | It converts assembly language code into machine code. |
| 2. What are the two passes of an assembler? | Pass-I and Pass-II. |
| 3. What is the main function of Pass-I? | To generate symbol table, literal table, and intermediate code. |
| 4. What is symbol table? | It stores symbols (labels, variables) with their addresses. |
| 5. What is literal table? | It stores constants (like =5) with assigned addresses. |
| 6. What is intermediate code? | It is an intermediate representation generated after Pass-I. |
| 7. What is a pseudo instruction? | An instruction that doesn't produce machine code (e.g., START, END, LTORG). |
| 8. What is opcode table? | It stores mnemonic operation codes and their binary equivalent. |
| 9. What happens during LTORG? | Literals are assigned memory locations. |
| 10. Why assembler uses two passes? | To resolve forward references and generate final addresses. |
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◆ **2 Pass-II of Two Pass Assembler**

Question

Answer

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|---|---|
| 1. What is the purpose of Pass-II? | To generate actual machine code using tables from Pass-I. |
| 2. What inputs are used in Pass-II? | Intermediate code, symbol table, and literal table. |
| 3. What is forward reference? | A symbol used before it is defined. |
| 4. What is machine code? | Binary or hexadecimal code that can be executed by CPU. |
| 5. Why is Pass-II required? | To convert assembly instructions into object code. |
| 6. What is the output of Pass-II? | Object code (final executable). |
| 7. What does (IS,04)(1)(S,1) mean? | It means Instruction Statement, opcode 04, operand 1, symbol 1. |
| 8. What are assembler directives? | Instructions to assembler (e.g., START, END, EQU, ORIGIN). |
| 9. What is difference between Pass-I and Pass-II? | Pass-I creates tables; Pass-II generates machine code. |
| 10. What data structures are used in assembler? | Symbol table, literal table, opcode table, pool table. |
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◆ **3 Pass-I of Macro Processor**

Question

Answer

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|---|--|
| 1. What is a macro? | A single name representing a group of instructions. |
| 2. What is a macro processor? | It expands macros before assembly. |
| 3. What is the function of Pass-I in macro processor? | To create MNT, MDT, and Intermediate code without macro definitions. |
| 4. What is MNT? | Macro Name Table — stores macro name and pointer to MDT. |
| 5. What is MDT? | Macro Definition Table — stores body of macro. |

Question

6. What is ALA?
7. What is macro definition?
8. What is macro call?
9. Why macros are used?
10. What is the output of Pass-I?

Answer

Argument List Array — stores macro arguments.

The code written between MACRO and MEND.

Using macro name with parameters in the program.

To reduce code repetition and errors.

MNT, MDT, ALA, and intermediate code without macro body.

◆ 4 Pass-II of Macro Processor

Question

1. What is main function of Pass-II?
2. What is macro expansion?
3. What inputs are used in Pass-II?
4. What is #0, #1 used in MDT?
5. What happens to macro body in Pass-II?
6. What is difference between assembler and macro processor?
7. What is the output of Pass-II macro processor?
8. What is advantage of macro processor?
9. What is the use of MEND?
10. How many passes are used?

Answer

To expand macros in source code using MDT and ALA.

Replacing macro call with its actual statements.

MNT, MDT, ALA, and intermediate code.

It indicates argument positions.

It is replaced with actual code.

Assembler converts to machine code, macro processor expands macros.

Expanded source code ready for assembly.

Reduces coding time and increases reusability.

It marks the end of macro definition.

Two passes — one for table creation, one for expansion.

◆ 5 CPU Scheduling Algorithms (FCFS, SJF, Priority, Round Robin)

Question

1. What is CPU scheduling?
2. What is FCFS?
3. What is SJF?
4. What is Priority Scheduling?
5. What is Round Robin?
6. What is preemptive scheduling?
7. What is non-preemptive scheduling?
8. What is turnaround time?
9. What is waiting time?
10. Which is best for time-sharing?
11. Which algorithm may cause starvation?
12. What is time quantum?

Answer

It decides which process runs next on CPU.

First Come First Serve — process arriving first gets CPU first.

Shortest Job First — process with smallest burst time runs first.

Process with highest priority runs first.

Each process runs for a fixed time (quantum) in a cycle.

CPU can be taken from a running process.

Once CPU is given, it can't be taken until process completes.

Time from process submission to completion.

Time a process spends in ready queue.

Round Robin scheduling.

SJF and Priority scheduling.

The fixed time slice given to each process in RR.

◆ 6 Page Replacement Algorithms (LRU)

Question	Answer
1. What is paging?	Memory management technique that divides memory into pages.
2. What is page fault?	When required page is not found in main memory.
3. What is page replacement?	Replacing one page with another when memory is full.
4. What is LRU?	Least Recently Used — replaces page that hasn't been used for longest time.
5. What is FIFO?	First In First Out — replaces oldest page first.
6. What is Optimal algorithm?	Replaces page that won't be used for longest future time.
7. What is frame?	Fixed-size block of physical memory.
8. What causes thrashing?	Too many page faults due to less memory.
9. What is hit ratio?	Percentage of page requests found in memory.
10. What is fault ratio?	Percentage of page requests not found in memory.

⚙ IOT PRACTICALS VIVA QUESTIONS & ANSWERS

◆ 7 Interfacing LED Bar

Question	Answer
1. What is LED bar?	Module with 10 LEDs used for display patterns.
2. What function is used to turn ON/OFF LED?	<code>digitalWrite()</code>
3. What does <code>pinMode()</code> do?	Sets pin as input or output.
4. What is used for delay between LEDs?	<code>delay()</code> function.
5. What voltage do LEDs need?	5V DC.
6. Why use resistor with LED?	To limit current.
7. Which Arduino pins are used?	Digital pins.
8. What is advantage of LED bar?	Visual indication of level or pattern.
9. How many LEDs are in bar?	Usually 10.
10. What is current limiting resistor value?	Commonly 220Ω.

◆ 8 Piezo Buzzer Interfacing

Question	Answer
1. What is piezo buzzer?	A device that produces sound using vibrations.
2. What function generates sound in Arduino?	<code>tone(pin, frequency)</code>
3. What stops the sound?	<code>noTone(pin)</code>
4. What type of output is produced?	Sound frequency.
5. What voltage is used?	3.3V–5V.

Question

Answer

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|----------------------------------|---|
| 6. What is active buzzer? | Has built-in oscillator. |
| 7. What is passive buzzer? | Needs external signal. |
| 8. What are applications? | Alarm, alert, notification systems. |
| 9. What function creates melody? | Multiple tone() with different frequencies. |
| 10. Why buzzer used in IoT? | For alert or warning signals. |
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◆ 9 Ultrasonic Sensor

Question

Answer

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|-------------------------------------|--|
| 1. What is Ultrasonic sensor? | It measures distance using sound waves. |
| 2. What are its pins? | VCC, GND, TRIG, ECHO. |
| 3. What is TRIG pin used for? | Sends ultrasonic signal. |
| 4. What is ECHO pin used for? | Receives reflected signal. |
| 5. What is formula for distance? | $\text{Distance} = (\text{Time} \times 343) / 2$. |
| 6. What is range? | 2cm to 400cm. |
| 7. What type of signal used? | Ultrasonic sound. |
| 8. What voltage needed? | 5V. |
| 9. What is used in parking systems? | Ultrasonic sensor. |
| 10. Why divide by 2 in formula? | Because wave travels twice (forward and back). |
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◆ 10 Light Sensor (LDR)

Question

Answer

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|-------------------------------|---|
| 1. What is LDR? | Light Dependent Resistor. |
| 2. How does it work? | Resistance decreases with light increase. |
| 3. What type of output? | Analog. |
| 4. Which pin reads data? | Analog pin A0. |
| 5. What happens in dark? | LED turns ON. |
| 6. What happens in light? | LED turns OFF. |
| 7. What voltage needed? | 5V. |
| 8. What is threshold value? | Value for light-dark decision. |
| 9. What are applications? | Automatic lights, security. |
| 10. What is full form of LDR? | Light Dependent Resistor. |
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◆ 11 Water Level Sensor

Question

Answer

Question

1. What does water level sensor detect?
2. What is output type?
3. Which pin is used?
4. What happens if tank full?
5. What happens if empty?
6. What voltage used?
7. What are uses?
8. What are electrodes made of?
9. Can it control motor?
10. What is the range?

Answer

Amount of water present.

Analog voltage.

A0 (Analog input).

LED or buzzer turns ON.

LED OFF.

5V.

Water tanks, irrigation.

Copper.

Yes, automatically.

0 to 100% water level.

◆ 1 2 Soil Moisture Sensor

Question

1. What does it measure?
2. What type of output?
3. Which pin used?
4. What happens when soil is dry?
5. What happens when soil is wet?
6. What voltage used?
7. What are uses?
8. What are electrodes made of?
9. What is threshold value?
10. What is application?

Answer

Water content in soil.

Analog.

A0.

LED/Buzzer turns ON.

LED OFF.

5V.

Smart irrigation, gardening.

Metal.

Minimum moisture for alert.

Automatic watering system.

◆ 1 3 DHT11/DHT22 Temperature Sensor

Question

1. What does DHT11 measure?
2. How many pins?
3. Which pin reads data?
4. What is data type?
5. What is temperature range?

Answer

Temperature and humidity.

3 or 4.

Digital pin D2.

Digital output.

0°C–50°C.

Question

Answer

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|---------------------------------------|---|
| 6. What is humidity range? | 20%–90%. |
| 7. What library used? | DHT.h |
| 8. What is difference DHT11 vs DHT22? | DHT22 is more accurate and wider range. |
| 9. What voltage needed? | 3.3V–5V. |
| 10. What is used for alert? | LED or buzzer. |
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◆ 1 📌 Obstacle Detector (IR Sensor)

Question

Answer

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|---------------------------------------|--|
| 1. What is IR sensor? | Infrared sensor detects obstacle using reflection. |
| 2. What are its pins? | VCC, GND, OUT. |
| 3. What type of output? | Digital. |
| 4. What happens when obstacle near? | Output LOW or HIGH (depends on module). |
| 5. What happens when obstacle far? | No output change. |
| 6. What voltage used? | 5V. |
| 7. What are applications? | Robots, counters, security. |
| 8. What is detection range? | 2cm–30cm. |
| 9. Why IR used instead of ultrasonic? | Short range, less power. |
| 10. What component emits IR? | IR LED. |
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