# Terra: A Multi-Stage Language for High-Performance Computing

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- Performance matters!
- Low-level languages(e.g. C) are good: we need to make best use of features of the target architecture(e.g. vector instructions).
- Programming is difficult!
- Solution: use high-level languages to generate low-level languages code(e.g. FFTW: OCaml  $\to$  C).

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- Optimizer: generate plan to guide how to generate code.
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- Runtime: support the generated code and provide feedback to the optimizer.
- Problem1: How can we get the runtime statistics in the compiler and generate high-performance code dynamically?
- Problem2: How can we re-use legacy libraries?

• Lua: high-level, dynamically typed, automatic mm, first class functions.

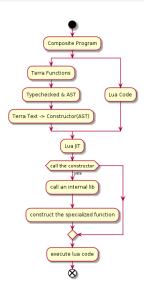
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- Shared lexical scoping, which is hygienic.
- Terra code runs independently, to avoid including high-level features.
- Lua's stack-based C API makes it easy to interface with legacy code.



# Some Code Examples

```
terra min(a: int, b: int): int
  if a < b then return a
  else return b end
end
struct GreyScaleImage {
  data: &float
  N: int
}</pre>
```

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- You can dump Terra functions to an object file(i.e. something.o in Linux) if you like.
- Quotation: using brackets([]) for escaping and backtick(expressions)/quote keyword(statements) for creating quotation.

# Quotation Example

```
local a = 5
terra sin5()
  return [ math.sin(a) ]
  end
function addtwo(a,b)
  return 'a + b
end
local printtwice = quote
 C. printf ("hello\n")
 C. printf ("hello\n")
end
```

## It Just Works!

```
- Lua/Terra
                            terra add(a : int.b : int) : int
int add(int a, int b) {
   return a + b:
                                 return a + b
                             end
                             -- Conditional compilation is done
                             -- with control-flow that
                             -- determines what code is defined
#ifdef VIN32
                             if iswindows() then
void waitatend() {
                                 terra vaitatend()
                                     C. getchar()
    getchar():
                                 end
males
void vaitatend() {}
                                 terra vaitatendO end
#endi f
                             end
                             -- Templates become Lua functions
                             -- that take a terra type T and
                             -- use it to generate new types
                             -- and code
template(class T)
                             function Array(T)
struct Array (
                                 struct Array (
    int N:
                                     N : int
   T* data;
                                     data : &T
   T get(int i) {
                                 terra Array:get(i : int)
       return data[i]:
                                     return self.data[i]
                                 and
                                 return Array
1:
                             end
typedef
Array(float) FloatArray; | FloatArray = Array(float)
```

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- e.g. block the loop nests to make the memory access more friendly to the cache.

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- Terra expression:  $\dot{e}$ , specialization of Terra:  $\stackrel{S}{\rightarrow}$
- Specialized Terra expression:  $\underline{\dot{e}}$ , execution of specailized Terra expression:  $\xrightarrow{T}$

#### Lua Syntax:

$$e ::= b \mid \dot{T} \mid x \mid let x = e \text{ in } e \mid x := e \mid e(e) \mid fun(x) \{e\} \mid tdecl \mid$$

$$ter e(x : e) : e \{\dot{e}\} \mid \dot{v}$$

$$v ::= b \mid l \mid \dot{T} \mid < \Gamma, x, e > \mid \underline{\dot{e}}$$

$$\dot{T} ::= \dot{B} \mid \dot{T} \rightarrow \dot{T}$$

#### Terra Syntax:

$$\dot{e} ::= b | x | \dot{e}(\dot{e}) | tlet x : e = \dot{e} in \dot{e} | [e] 
\underline{\dot{e}} ::= b | \underline{\dot{x}} | \underline{\dot{e}}(\underline{\dot{e}}) | tlet \underline{\dot{x}} : \dot{T} = \underline{\dot{e}} in \underline{\dot{e}} | I$$

$$v\Sigma \xrightarrow{L} v\Sigma$$
 (LVAL)

$$\frac{\Sigma = \Gamma, S, F}{\times \Sigma \xrightarrow{L} S(\Gamma(x)) \Sigma}$$
 (LVAR)

$$\frac{e_1 \Sigma_1 \xrightarrow{L} v_1 \Sigma_2 \ \Sigma_2 = \Gamma, S, F \ e_2 \Sigma_2 [x \leftarrow v_1] \xrightarrow{L} v_2 \Sigma_3}{let \ x = e_1 \ in \ e_2 \Sigma \xrightarrow{L} v_2 (\Sigma_3 \leftarrow \Gamma)}$$
(LLET)

$$\frac{e\Sigma \xrightarrow{L} v\Gamma, S, F \Gamma(x) = a}{x := e\Sigma \xrightarrow{L} v\Gamma, S[a \leftarrow v], F}$$
 (LASN)

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$$\frac{\Sigma = \Gamma, S, F}{fun(x)\{e\} \Sigma \xrightarrow{L} < \Gamma, x, e > \Sigma}$$
 (LFUN)

$$e_{1} \Sigma_{1} \xrightarrow{L} < \Gamma_{1}, x, e_{3} > e_{2} \Sigma_{2} \xrightarrow{L} v_{1} \Gamma_{2}, S, F$$

$$\underbrace{a \text{ fresh } e_{3} \Gamma_{1}[x \leftarrow a], S[a \leftarrow v_{1}], F \xrightarrow{L} v_{2} \Sigma_{3}}_{e_{1}(e_{2}) \Sigma_{1} \xrightarrow{L} v_{2} (\Sigma_{3} \leftarrow \Gamma_{2})}$$
(LAPP)

$$\frac{|\mathit{fresh}\ \Sigma = \Gamma, S, F|}{\mathit{tdecl}\Sigma \xrightarrow{L} |\Gamma, S, F| |I \leftarrow \bullet|}$$
 (LTDECL)

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$$\frac{\dot{e}\,\Sigma_1 \stackrel{S}{\to} \dot{\underline{e}}\,\Sigma_2}{\dot{e}\,\Sigma_1 \stackrel{L}{\to} \dot{\underline{e}}\,\Sigma_2} \tag{LTQUOTE}$$



$$e_{1} \Sigma_{1} \xrightarrow{L} I \Sigma_{2} \ e_{2} \Sigma_{2} \xrightarrow{L} b_{1} \Sigma_{3}$$

$$\Sigma_{3} = \Gamma, S, F \ F(I) = \langle \underline{\dot{x}}, \dot{T}_{1}, \dot{T}_{2}, \underline{\dot{e}} \rangle \quad b_{1} \in \dot{T}_{1}$$

$$[\underline{\dot{x}} : \dot{T}_{1}], [I : \dot{T}_{1} \to \dot{T}_{2}], F_{2} \vdash \underline{\dot{e}} : \dot{T}_{2} \ \underline{\dot{e}}[\underline{\dot{x}} \leftarrow b], F \xrightarrow{T} b_{2}$$

$$e_{1}(e_{2}) \Sigma_{1} \xrightarrow{L} b_{2} \Sigma_{3}$$
(LTAPP)

$$b\Sigma \xrightarrow{S} b\Sigma$$
 (SBAS)

$$\frac{\dot{e_1} \Sigma_1 \xrightarrow{S} \underline{\dot{e_1}} \Sigma_2 \quad \dot{e_2} \Sigma_2 \xrightarrow{S} \underline{\dot{e_2}} \Sigma_3}{\dot{e_1}(\dot{e_2}) \Sigma_1 \xrightarrow{S} \underline{\dot{e_1}}(\underline{\dot{e_2}}) \Sigma_3}$$
 (SAPP)

$$e \Sigma_{1} \xrightarrow{L} \dot{T} \Sigma_{2} \ \dot{e_{1}} \Sigma_{2} \xrightarrow{\dot{S}} \underline{\dot{e_{1}}} \Sigma_{3} \ \underline{\dot{x}} \textit{fresh}$$

$$\underline{\Sigma_{3} = \Gamma, S, F \ \dot{e_{2}} \Sigma_{3} [x \leftarrow \underline{\dot{e_{2}}}] \xrightarrow{S} \underline{\dot{e_{2}}} \Sigma_{4}} \qquad (SLET)$$

$$tlet x : e = \dot{e_{1}} \textit{in } \dot{e_{2}} \Sigma_{1} \xrightarrow{S} tlet \underline{\dot{x}} : \dot{T} = \dot{e_{1}} \textit{in } \dot{e_{2}} (\Sigma_{4} \leftarrow \Gamma)$$

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$$\frac{e \Sigma_1 \xrightarrow{L} \underline{\dot{e}} \Sigma_2}{[e] \Sigma_1 \xrightarrow{S} \underline{\dot{e}} \Sigma_2}$$
 (SESC)

$$\frac{[x] \Sigma_1 \xrightarrow{S} \underline{\dot{e}} \Sigma_2}{x \Sigma_1 \xrightarrow{S} \underline{\dot{e}} \Sigma_2}$$
 (SVAR)

$$b\dot{\Gamma}, F \xrightarrow{T} b \qquad (TBAS)$$

$$I\dot{\Gamma}, F \xrightarrow{T} I \qquad (TFUN)$$

$$\dot{\underline{x}}\dot{\Gamma}, F \xrightarrow{T} \dot{\Gamma}(\dot{\underline{x}}) \qquad (TVAR)$$

$$\frac{\dot{\underline{e_1}}\dot{\Gamma}, F \xrightarrow{T} v_1 \ \underline{\dot{e_2}}\dot{\Gamma}[\dot{\underline{x}} \leftarrow v_1], F \xrightarrow{T} v_2}{tlet \dot{\underline{x}} : \dot{T} = \underline{\dot{e_1}} in \underline{\dot{e_2}} \dot{\Gamma}, F \xrightarrow{T} v_2} \qquad (TLET)$$

$$\frac{\dot{\underline{e_1}}\dot{\Gamma}, F \xrightarrow{T} I \ \underline{\dot{e_2}}\dot{\Gamma}, F \xrightarrow{T} v_1}{\underline{\dot{e_2}}\dot{\Gamma}, F \xrightarrow{T} v_2} \qquad (TAPP)$$

$$\frac{\dot{\underline{e_1}}(\dot{\underline{e_2}})\dot{\Gamma}, F \xrightarrow{T} v_2}{\dot{\underline{e_1}}(\underline{\dot{e_2}})\dot{\Gamma}, F \xrightarrow{T} v_2} \qquad (TAPP)$$

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- No proof! :)

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- Type Reflection API.

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- Separate the declaration and definition.



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- Easier to override the default bevavior of a type.

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• Also the metamethods table: override certain compile-time behaviors(e.g. implicit conversion).

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# **Shortages**

• Lua is not statically typed.

### Reference

- Zachary DeVito, James Hegarty, Alex Aiken, Pat Hanrahan, and Jan Vitek. 2013. Terra: A multi-stage language for highperformance computing. In Proceedings of the 34th ACM SIGPLAN Conference on Programming Language Design and Implementation (PLDI'13). ACM, New York, 105–116.
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