Terra: A Multi-Stage Language for High-Performance Computing

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- Performance matters!
- Low-level languages(e.g. C) are good: we need to make best use of features of the target architecture(e.g. vector instructions).
- Programming is difficult!
- Solution: use high-level languages to generate low-level languages code(e.g. FFTW: OCaml \rightarrow C).

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- Optimizer: generate plan to guide how to generate code.
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- Runtime: support the generated code and provide feedback to the optimizer.
- Problem1: How can we get the runtime statistics in the compiler and generate high-performance code dynamically?
- Problem2: How can we re-use legacy libraries?

• Lua: high-level, dynamically typed, automatic mm, first class functions.

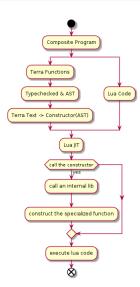
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- Shared lexical scoping, which is hygienic.
- Terra code runs independently, to avoid including high-level features.
- Lua's stack-based C API makes it easy to interface with legacy code.



Some Code Examples

```
terra min(a: int, b: int): int
  if a < b then return a
  else return b end
end
struct GreyScaleImage {
  data: &float
  N: int
}</pre>
```

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- You can dump Terra functions to an object file(i.e. something.o in Linux) if you like.
- Quotation: using brackets([]) for escaping and backtick(expressions)/quote keyword(statements) for creating quotation.

Quotation Example

```
local a = 5
terra sin5()
  return [ math.sin(a) ]
  end
function addtwo(a,b)
  return 'a + b
end
local printtwice = quote
 C. printf ("hello\n")
 C. printf ("hello\n")
end
```

It Just Works!

```
- Lua/Terra
                            terra add(a : int.b : int) : int
int add(int a, int b) {
   return a + b:
                                 return a + h
                             end
                             -- Conditional compilation is done
                             -- with control-flow that
                             -- determines what code is defined
#ifdef VIN32
                            if iswindows() then
void waitatend() {
                                 terra vaitatend()
                                    C. getchar()
    getchar():
                                 end
males
void vaitatend() {}
                                 terra vaitatendO end
#endif
                             end
                             -- Templates become Lua functions
                             -- that take a terra type T and
                             -- use it to generate new types
                             -- and code
template(class T)
                             function Array(T)
struct Array (
                                 struct Array (
    int N:
                                    N : int
   T* data;
                                    data : &T
   T get(int i) {
                                 terra Array:get(i : int)
       return data[i]:
                                    return self.data[i]
                                 and
                                 return Array
1:
                             end
typedef
Array(float) FloatArray; | FloatArray = Array(float)
```

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- e.g. block the loop nests to make the memory access more friendly to the cache.

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- Lua expression: e, evaluation of Lua: \xrightarrow{L}
- Terra expression: \dot{e} , specialization of Terra: $\stackrel{S}{\rightarrow}$
- Specialized Terra expression: $\underline{\dot{e}}$, execution of specailized Terra expression: \xrightarrow{T}

Lua Syntax:

$$e ::= b \mid \dot{T} \mid x \mid let x = e \text{ in } e \mid x := e \mid e(e) \mid fun(x) \{e\} \mid tdecl \mid$$

$$ter e(x : e) : e \{\dot{e}\} \mid \dot{v}$$

$$v ::= b \mid l \mid \dot{T} \mid < \Gamma, x, e > \mid \underline{\dot{e}}$$

$$\dot{T} ::= \dot{B} \mid \dot{T} \rightarrow \dot{T}$$

Terra Syntax:

$$\dot{e} ::= b |x| \dot{e}(\dot{e}) | tlet x : e = \dot{e} in \dot{e} | [e]$$

$$\dot{e} ::= b |\dot{x}| \dot{\underline{e}}(\dot{\underline{e}}) | tlet \dot{\underline{x}} : \dot{T} = \dot{\underline{e}} in \dot{\underline{e}} | I$$

$$v\Sigma \xrightarrow{L} v\Sigma$$
 (LVAL)

$$\frac{\Sigma = \Gamma, S, F}{\times \Sigma \xrightarrow{L} S(\Gamma(x)) \Sigma}$$
 (LVAR)

$$\frac{e_1 \Sigma_1 \xrightarrow{L} v_1 \Sigma_2 \ \Sigma_2 = \Gamma, S, F \ e_2 \Sigma_2 [x \leftarrow v_1] \xrightarrow{L} v_2 \Sigma_3}{let \ x = e_1 \ in \ e_2 \ \Sigma \xrightarrow{L} v_2 (\Sigma_3 \leftarrow \Gamma)}$$
 (LLET)

$$\frac{e\Sigma \xrightarrow{L} v\Gamma, S, F \Gamma(x) = a}{x := e\Sigma \xrightarrow{L} v\Gamma, S[a \leftarrow v], F}$$
(LASN)



$$\frac{\Sigma = \Gamma, S, F}{fun(x)\{e\} \Sigma \xrightarrow{L} < \Gamma, x, e > \Sigma}$$
 (LFUN)

$$e_{1} \Sigma_{1} \xrightarrow{L} < \Gamma_{1}, x, e_{3} > e_{2} \Sigma_{2} \xrightarrow{L} v_{1} \Gamma_{2}, S, F$$

$$\underbrace{a \text{ fresh } e_{3} \Gamma_{1}[x \leftarrow a], S[a \leftarrow v_{1}], F \xrightarrow{L} v_{2} \Sigma_{3}}_{e_{1}(e_{2}) \Sigma_{1} \xrightarrow{L} v_{2} (\Sigma_{3} \leftarrow \Gamma_{2})}$$
(LAPP)

$$\frac{\textit{Ifresh } \Sigma = \Gamma, S, F}{\textit{tdecl} \Sigma \xrightarrow{L} \textit{I} \Gamma, S, F[I \leftarrow \bullet]}$$
 (LTDECL)

$$e_{1} \Sigma_{1} \xrightarrow{L} I \Sigma_{2} \ e_{2} \Sigma_{2} \xrightarrow{L} \dot{T}_{1} \Sigma_{3} \ e_{3} \Sigma_{3} \xrightarrow{L} \dot{T}_{2} \Sigma_{4}$$

$$\Sigma_{4} = \Gamma_{1}, S_{1}, F_{1} \ \underline{\dot{x}} fresh$$

$$\underline{\dot{e} \Sigma_{4} [x \leftarrow \underline{\dot{x}}] \xrightarrow{S} \underline{\dot{e}} \Gamma_{2}, S_{2}, F_{2} \ F_{2}(I) = \bullet}$$

$$ter e_{1}(x : e_{2}) : e_{3} \{\dot{e}\} \Sigma_{1} \xrightarrow{L} I \Gamma_{1}, S_{2}, F_{2}[I \leftarrow \langle \dot{x}, \dot{T}_{1}, \dot{T}_{2}, \dot{e} \rangle]}$$

$$(LTDEFN)$$

$$\frac{\dot{e}\,\Sigma_1 \stackrel{S}{\to} \dot{\underline{e}}\,\Sigma_2}{\dot{e}\,\Sigma_1 \stackrel{L}{\to} \dot{\underline{e}}\,\Sigma_2} \tag{LTQUOTE}$$

$$e_{1} \Sigma_{1} \xrightarrow{L} I \Sigma_{2} \ e_{2} \Sigma_{2} \xrightarrow{L} b_{1} \Sigma_{3}$$

$$\Sigma_{3} = \Gamma, S, F \ F(I) = \langle \underline{\dot{x}}, \dot{T}_{1}, \dot{T}_{2}, \underline{\dot{e}} \rangle \quad b_{1} \in \dot{T}_{1}$$

$$[\underline{\dot{x}} : \dot{T}_{1}], [I : \dot{T}_{1} \to \dot{T}_{2}], F_{2} \vdash \underline{\dot{e}} : \dot{T}_{2} \ \underline{\dot{e}} [\underline{\dot{x}} \leftarrow b], F \xrightarrow{T} b_{2}$$

$$e_{1}(e_{2}) \Sigma_{1} \xrightarrow{L} b_{2} \Sigma_{3}$$
(LTAPP)

$$b\Sigma \xrightarrow{S} b\Sigma$$
 (SBAS)

$$\frac{\dot{e_1} \Sigma_1 \xrightarrow{S} \underline{\dot{e_1}} \Sigma_2 \quad \dot{e_2} \Sigma_2 \xrightarrow{S} \underline{\dot{e_2}} \Sigma_3}{\dot{e_1}(\dot{e_2}) \Sigma_1 \xrightarrow{S} \underline{\dot{e_1}}(\underline{\dot{e_2}}) \Sigma_3}$$
 (SAPP)

$$e \Sigma_{1} \xrightarrow{L} \dot{T} \Sigma_{2} \ \dot{e_{1}} \Sigma_{2} \xrightarrow{S} \underline{\dot{e_{1}}} \Sigma_{3} \ \underline{\dot{x}} \, fresh$$

$$\underline{\Sigma_{3} = \Gamma, S, F \ \dot{e_{2}} \Sigma_{3} [x \leftarrow \underline{\dot{e_{2}}}] \xrightarrow{S} \underline{\dot{e_{2}}} \Sigma_{4}}$$

$$\underbrace{tlet x : e = \dot{e_{1}} \, in \, \dot{e_{2}} \Sigma_{1} \xrightarrow{S} tlet \, \underline{\dot{x}} : \dot{T} = \dot{e_{1}} \, in \, \dot{e_{2}} (\Sigma_{4} \leftarrow \Gamma)}$$
(SLET)



$$\frac{e \Sigma_1 \xrightarrow{L} \underline{\dot{e}} \Sigma_2}{[e] \Sigma_1 \xrightarrow{S} \underline{\dot{e}} \Sigma_2}$$
 (SESC)

$$\frac{[x] \, \Sigma_1 \stackrel{S}{\to} \underline{\dot{e}} \, \Sigma_2}{x \, \Sigma_1 \stackrel{S}{\to} \underline{\dot{e}} \, \Sigma_2} \tag{SVAR}$$

$$b\dot{\Gamma}, F \xrightarrow{T} b \qquad (TBAS)$$

$$I\dot{\Gamma}, F \xrightarrow{T} I \qquad (TFUN)$$

$$\dot{\underline{x}}\dot{\Gamma}, F \xrightarrow{T} \dot{\Gamma}(\dot{\underline{x}}) \qquad (TVAR)$$

$$\frac{\dot{e}_{\underline{1}}\dot{\Gamma}, F \xrightarrow{T} v_{\underline{1}} \ \underline{e}_{\underline{2}}\dot{\Gamma}[\dot{\underline{x}} \leftarrow v_{\underline{1}}], F \xrightarrow{T} v_{\underline{2}}}{tlet \,\dot{\underline{x}} : \, \dot{T} = \, \underline{e}_{\underline{1}} \, in \, \underline{e}_{\underline{2}} \, \dot{\Gamma}, F \xrightarrow{T} v_{\underline{2}}} \qquad (TLET)$$

$$\frac{\dot{e}_{\underline{1}}\dot{\Gamma}, F \xrightarrow{T} I \ \underline{e}_{\underline{2}} \, \dot{\Gamma}, F \xrightarrow{T} v_{\underline{1}}}{F(I) = \langle \, \dot{\underline{x}}, \, \dot{T}_{\underline{1}}, \, \dot{T}_{\underline{2}}, \, \underline{e}_{\underline{3}} \rangle \ \underline{e}_{\underline{3}} \, \dot{\Gamma}[\dot{\underline{x}} \leftarrow v_{\underline{1}}], F \xrightarrow{T} v_{\underline{2}}} \qquad (TAPP)$$

$$\underline{\dot{e}_{\underline{1}}(\dot{e}_{\underline{2}}) \, \dot{\Gamma}, F \xrightarrow{T} v_{\underline{2}}}$$

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- No proof! :)

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- Type Reflection API.

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- Or we need to re-compile y when x_1 changes.
- Requires declaration before using a symbol, which makes recusive function impossible.
- Separate the declaration and definition.



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- Easier to override the default bevavior of a type.

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• Also the metamethods table: override certain compile-time behaviors(e.g. implicit conversion).

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- Shorter code, easier to read/write/maintain.

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Shortages

• Lua is not statically typed.

Reference

- Zachary DeVito, James Hegarty, Alex Aiken, Pat Hanrahan, and Jan Vitek. 2013. Terra: A multi-stage language for highperformance computing. In Proceedings of the 34th ACM SIGPLAN Conference on Programming Language Design and Implementation (PLDI'13). ACM, New York, 105–116.
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