Terra: A Multi-Stage Language for High-Performance Computing

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- Low-level languages(e.g. C) are good: we need to make best use of features of the target architecture(e.g. vector instructions).
- Programming is difficult!
- Solution: use high-level languages to generate low-level languages code(e.g. FFTW: OCaml \rightarrow C).

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- Optimizer: generate plan to guide how to generate code.
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- Problem1: Separating compiler and optimizer from the runtime makes it difficult to feed runtime statistics back to the compiler to perform problem-specific optimizations.
- Problem2: How can we re-use legacy libraries?

• Lua: high-level, dynamically typed, automatic mm, first class functions.

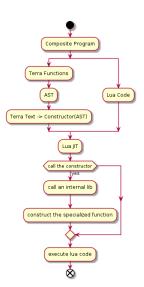
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- Shared lexical scoping, which is hygienic.
- Terra code runs independently, to avoid including high-level features.
- Lua's stack-based C API makes it easy to interface with legacy code.



Some Code Examples

```
terra min(a: int, b: int): int
  if a < b then return a
  else return b end
end
struct GreyScaleImage {
  data: &float
  N: int
}</pre>
```

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- Quotation: using brackets([]) for escaping and backtick(expressions)/quote keyword(statements) for creating quotation.

Quotation Example

```
local a = 5
terra sin5()
  return [ math.sin(a) ]
  end
function addtwo(a,b)
  return 'a + b
end
local printtwice = quote
  C. printf("hello\n")
  C. printf("hello\n")
end
```

It Just Works!

```
-- Lua/Terra
int add(int a, int b) [
                             terra add(a : int,b : int) : int
    return a + b:
                                 return a + b
                             end
                             -- Conditional compilation is done
                             -- with control-flow that
                             -- determines what code is defined
#ifdef WIN32
                             if iswindows() then
void vaitatend() {
                                 terra waitatend()
    getchar():
                                     C. getchar ()
                                 end
moleo
                             else
void vaitatend() {}
                                 terra waitatend() end
#endif
                             end
                             -- Templates become Lua functions
                             -- that take a terra type T and
                             -- use it to generate new types
                             -- and code
template(class T)
                             function Array(T)
struct Array (
                                 struct Array {
    int N:
                                     N : int
   T* data;
                                     data : &T
   T get(int i) {
                                 terra Array:get(i : int)
       return data[i]:
                                     return self. data[i]
                                 end
                                 return Array
                             end
typedef
Array(float) FloatArray; | FloatArray = Array(float)
```

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- e.g. block the loop nests to make the memory access more friendly to the cache.

A Simple Filter Example

```
GreyscaleImage = Image(float)
terra laplace(img: &GreyscaleImage,
out: &GreyscaleImage) : {}
 -shrink result, do not calculate boundaries
  var newN = img.N - 2
  out:init(newN)
  for i = 0.newN do
    for j = 0, newN do
      var v = -img: get(i+0,j+1) - img: get(i+2,j+1)
      -img:get(i+1,i+2) - img:get(i+1,i+0)
      + 4 * img: get(i+1, i+1)
      out:set(i,j,v)
    end
  end
end
```

A Simple Filter Example

```
terra runlaplace(input: rawstring,
output: rawstring) : {}
  var i = GreyscaleImage {}
  var o = GreyscaleImage {}
  i:load(input)
  laplace(&i,&o)
  o:save(output)
  i:free(); o:free()
end
```

Optimize The Filter

```
function blockedloop (N, blocksizes, bodyfn)
  local function generatelevel (n, ii, jj, bb)
    if n > \#blocksizes then
      return bodyfn(ii,jj)
    end
    local blocksize = blocksizes[n]
    return auote
      for i = ii, min(ii+bb, N), blocksize do
        for j = jj, min(jj+bb,N), blocksize do
             generatelevel(n+1,i,j,blocksize)
        end
      end
    end
  end
  return generatelevel (1,0,0,N)
end
```

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  [blockedloop(newN,\{128,64,1\}, function(i,j)
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      -img:get(i+1,i+2) - img:get(i+1,i+0)
      + 4 * img: get(i+1, i+1)
      out:set(i,j,v)
    end
  end)]
end
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- Lua expression: e, evaluation of Lua: \xrightarrow{L}
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- Specialized Terra expression: $\underline{\dot{e}}$, execution of specailized Terra expression: \xrightarrow{T}

Terra Core

Lua Syntax:

$$e ::= b \mid \dot{T} \mid x \mid let x = e \text{ in } e \mid x := e \mid e(e) \mid fun(x)\{e\} \mid tdecl \mid$$

$$ter e(x : e) : e\{\dot{e}\} \mid \dot{v}\dot{e}$$

$$v ::= b \mid I \mid \dot{T} \mid < \Gamma, x, e > \mid \dot{\underline{e}}$$

$$\dot{T} ::= \dot{B} \mid \dot{T} \rightarrow \dot{T}$$

Terra Syntax:

$$\dot{e} ::= b \mid x \mid \dot{e}(\dot{e}) \mid tlet \ x : \ e = \dot{e} \ in \ \dot{e} \mid [e]$$

$$\dot{\underline{e}} ::= b \mid \dot{\underline{x}} \mid \underline{\dot{e}}(\dot{\underline{e}}) \mid tlet \ \dot{\underline{x}} : \ \dot{T} = \dot{\underline{e}} \ in \ \dot{\underline{e}} \mid I$$

$$v \Sigma \xrightarrow{L} v \Sigma$$
 (LVAL)

$$\frac{\Sigma = \Gamma, S, F}{\times \Sigma \xrightarrow{L} S(\Gamma(x)) \Sigma}$$
 (LVAR)

$$\frac{e_1 \; \Sigma_1 \xrightarrow{L} v_1 \; \Sigma_2 \quad \Sigma_2 = \Gamma, S, F \quad e_2 \Sigma_2 [x \leftarrow v_1] \xrightarrow{L} v_2 \Sigma_3}{\text{let } x = e_1 \; \text{in } e_2 \; \Sigma \xrightarrow{L} v_2 (\Sigma_3 \leftarrow \Gamma)} \tag{LLET}$$

$$\frac{e \Sigma \xrightarrow{L} v \Gamma, S, F \quad \Gamma(x) = a}{x := e \Sigma \xrightarrow{L} v \Gamma, S[a \leftarrow v], F}$$
 (LASN)



$$\frac{\Sigma = \Gamma, S, F}{fun(x)\{e\} \Sigma \xrightarrow{L} < \Gamma, x, e > \Sigma}$$
 (LFUN)

$$e_{1} \Sigma_{1} \xrightarrow{L} < \Gamma_{1}, x, e_{3} > e_{2} \Sigma_{2} \xrightarrow{L} v_{1} \Gamma_{2}, S, F$$

$$\frac{a \text{ fresh} \quad e_{3} \Gamma_{1}[x \leftarrow a], S[a \leftarrow v_{1}], F \xrightarrow{L} v_{2} \Sigma_{3}}{e_{1}(e_{2}) \Sigma_{1} \xrightarrow{L} v_{2} (\Sigma_{3} \leftarrow \Gamma_{2})}$$
(LAPP)

$$\frac{l \ fresh \quad \Sigma = \Gamma, S, F}{t decl \Sigma \xrightarrow{L} l \Gamma, S, F[l \leftarrow \bullet]}$$
 (LTDECL)



$$\begin{array}{cccc} e_1 \; \Sigma_1 \stackrel{L}{\rightarrow} I \; \Sigma_2 & e_2 \; \Sigma_2 \stackrel{L}{\rightarrow} \; \dot{T}_1 \; \Sigma_3 & e_3 \; \Sigma_3 \stackrel{L}{\rightarrow} \; \dot{T}_2 \; \Sigma_4 \\ & \; \Sigma_4 = \Gamma_1, S_1, F_1 \quad \dot{\underline{x}} \; \textit{fresh} \\ \\ \frac{\dot{e} \; \Sigma_4 [x \leftarrow \dot{\underline{x}}] \stackrel{S}{\rightarrow} \dot{\underline{e}} \; \Gamma_2, S_2, F_2 \quad F_2(I) = \bullet}{\textit{ter} \; e_1(x : e_2) : e_3 \{\dot{e}\} \; \Sigma_1 \stackrel{L}{\rightarrow} I \; \Gamma_1, S_2, F_2[I \leftarrow < \dot{\underline{x}}, \dot{T}_1, \dot{T}_2, \dot{\underline{e}} >]} \end{array} \; \text{(LTDEFN)} \end{array}$$

$$\frac{\dot{e} \; \Sigma_1 \stackrel{\mathcal{S}}{\to} \; \underline{\dot{e}} \; \Sigma_2}{\stackrel{\mathsf{L}}{\circ} \; \Sigma_1 \stackrel{\mathsf{L}}{\to} \; \dot{e} \; \Sigma_2} \tag{LTQUOTE}$$

$$e_{1} \Sigma_{1} \xrightarrow{L} I \Sigma_{2} \quad e_{2} \Sigma_{2} \xrightarrow{L} b_{1} \Sigma_{3}$$

$$\Sigma_{3} = \Gamma, S, F \quad F(I) = \langle \underline{\dot{x}}, \dot{T}_{1}, \dot{T}_{2}, \underline{\dot{e}} \rangle \quad b_{1} \in \dot{T}_{1}$$

$$\underline{[\dot{x}: \dot{T}_{1}], [I: \dot{T}_{1} \to \dot{T}_{2}], F_{2} \vdash \underline{\dot{e}}: \dot{T}_{2} \quad \underline{\dot{e}}[\underline{\dot{x}} \leftarrow b], F \xrightarrow{T} b_{2}}$$

$$e_{1}(e_{2}) \Sigma_{1} \xrightarrow{L} b_{2} \Sigma_{3}$$
(LTAPP)

$$b \Sigma \xrightarrow{S} b \Sigma$$
 (SBAS)

$$\frac{\dot{e_1} \ \Sigma_1 \overset{S}{\to} \underline{\dot{e_1}} \ \Sigma_2 \quad \dot{e_2} \Sigma_2 \overset{S}{\to} \underline{\dot{e_2}} \Sigma_3}{\dot{e_1}(\dot{e_2}) \ \Sigma_1 \overset{S}{\to} \underline{\dot{e_1}}(\underline{\dot{e_2}}) \ \Sigma_3} \tag{SAPP}$$

$$e \; \Sigma_{1} \stackrel{L}{\rightarrow} \; \dot{T} \; \Sigma_{2} \quad \dot{e_{1}} \; \Sigma_{2} \stackrel{S}{\rightarrow} \; \underline{\dot{e_{1}}} \; \Sigma_{3} \quad \underline{\dot{x}} \; \textit{fresh}$$

$$\frac{\Sigma_{3} = \Gamma, S, F \quad \dot{e_{2}} \; \Sigma_{3} [x \leftarrow \underline{\dot{e_{2}}}] \stackrel{S}{\rightarrow} \; \underline{\dot{e_{2}}} \; \Sigma_{4}}{\underline{tlet} \; x \colon e = \dot{e_{1}} \; \textit{in} \; \dot{e_{2}} \; \Sigma_{1} \stackrel{S}{\rightarrow} \; \textit{tlet} \; \underline{\dot{x}} \colon \dot{T} = \underline{\dot{e_{1}}} \; \textit{in} \; \underline{\dot{e_{2}}} \; (\Sigma_{4} \leftarrow \Gamma)}$$
(SLET)

$$\frac{e \; \Sigma_1 \overset{L}{\rightarrow} \; \underline{\dot{e}} \Sigma_2}{[e] \; \Sigma_1 \overset{S}{\rightarrow} \; \underline{\dot{e}} \; \Sigma_2} \tag{SESC}$$

$$\frac{[x] \ \Sigma_1 \xrightarrow{S} \underline{\dot{e}} \ \Sigma_2}{x \ \Sigma_1 \xrightarrow{S} \underline{\dot{e}} \ \Sigma_2}$$
 (SVAR)

$$b \dot{\Gamma}, F \xrightarrow{T} b$$
 (TBAS)

$$I\dot{\Gamma}, F \xrightarrow{T} I$$
 (TFUN)

$$\underline{\dot{x}}\dot{\Gamma}, F \xrightarrow{T} \dot{\Gamma}(\underline{\dot{x}})$$
 (TVAR)

$$\frac{\underline{\dot{e_1}}\ \dot{\Gamma}, F \xrightarrow{T} v_1 \quad \underline{\dot{e_2}}\dot{\Gamma}[\underline{\dot{x}} \leftarrow v_1], F \xrightarrow{T} v_2}{tlet\ \underline{\dot{x}}: \ \dot{T} = \underline{\dot{e_1}}\ in\ \underline{\dot{e_2}}\ \dot{\Gamma}, F \xrightarrow{T} v_2}$$
 (TLET)

$$\frac{\underline{\dot{e}_{1}}\,\dot{\Gamma},F\stackrel{T}{\rightarrow}I\quad\underline{\dot{e}_{2}}\,\dot{\Gamma},F\stackrel{T}{\rightarrow}v_{1}}{\underline{F(I)}=<\underline{\dot{x}},\,\dot{T}_{1},\,\dot{T}_{2},\,\underline{\dot{e}_{3}}>\quad\underline{\dot{e}_{3}}\,\dot{\Gamma}[\underline{\dot{x}}\leftarrow v_{1}],F\stackrel{T}{\rightarrow}v_{2}}{\dot{e}_{1}(\dot{e}_{2})\,\dot{\Gamma},F\stackrel{T}{\rightarrow}v_{2}}$$
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- No proof! :)

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- Type Reflection API.

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- Requires declaration before using a symbol, which makes recusive function impossible.
- Separate the declaration and definition.



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- Easier to override the default bevavior of a type.

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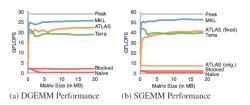
• Also the metamethods table: override certain compile-time behaviors(e.g. implicit conversion).

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Shortages

• Lua is not statically typed.

Reference

- Zachary DeVito, James Hegarty, Alex Aiken, Pat Hanrahan, and Jan Vitek. 2013. Terra: A multi-stage language for highperformance computing. In Proceedings of the 34th ACM SIGPLAN Conference on Programming Language Design and Implementation (PLDI'13). ACM, New York, 105–116.
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