

# ON RIEMANNIAN CURVATURE OF HOMOGENEOUS SPACES

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**1. Introduction.** When developing his theory of symmetric spaces, E. Cartan proved that a compact symmetric Riemannian space has sectional curvature everywhere  $\geq 0$  and that a noncompact irreducible symmetric Riemannian space has sectional curvature everywhere  $\leq 0$ . H. Samelson has recently [5] proved an analogue of Cartan's theorem for the compact case, namely that a homogeneous space  $G/K$  where  $G$  is a connected compact Lie group,  $K$  a closed subgroup, has sectional curvature everywhere  $\geq 0$ . Here the metric on  $G/K$  is the one that is obtained from a two-sided invariant metric on  $G$  by the natural projection. While Samelson's proof is simple and geometric it gives no information in the noncompact case.

In the present paper we give a proof of the theorem of Samelson by a method which furnishes some additional information and which can be used to prove Cartan's theorem for the noncompact case as well as for the compact case.

**2. Preliminaries.** Let  $G$  be a connected Lie group with Lie algebra  $\mathfrak{g}$ . Let  $g \rightarrow \text{Ad}(g)$  denote the adjoint representation of  $G$  on  $\mathfrak{g}$  and let  $X \rightarrow \text{ad}(X)$  denote the adjoint representation of  $\mathfrak{g}$  on  $\mathfrak{g}$  so  $\text{ad}(X)(Y) = [X, Y]$ . Suppose  $K$  is a closed subgroup of  $G$  such that  $\text{Ad}_G(K)$  (the image of  $K$  under  $g \rightarrow \text{Ad}(g)$ ) is compact. If the Lie algebra of  $K$  is  $\mathfrak{k}$  there exists a subspace  $\mathfrak{m} \subset \mathfrak{g}$  such that  $\mathfrak{g} = \mathfrak{m} + \mathfrak{k}$  (direct sum of vector spaces) and such that  $\text{Ad}_G(k)\mathfrak{m} \subset \mathfrak{m}$  for all  $k \in K$ . The manifold  $G/K$  of left cosets  $gK$  can be given the structure of a Riemannian manifold whose metric is invariant under  $G$ , that is for each  $x \in G$  the mapping  $\tau(x): gK \rightarrow xgK$  of  $G/K$  onto  $G/K$  is an isometry. The natural projection  $\pi$  of  $G$  onto  $G/K$  maps  $\mathfrak{m}$  isomorphically onto the tangent space to  $G/K$  at  $\pi(e)$  ( $e$  is the identity element of  $G$ ) in such a way that the action of  $\text{Ad}_G(K)$  on  $\mathfrak{m}$  corresponds to the action of  $\tau(K)$  on the tangent space. Thus a Riemannian metric on  $G/K$  invariant under all  $\tau(x)$ ,  $x \in G$  is uniquely determined by a positive definite quadratic form on  $\mathfrak{m}$ , invariant under  $\text{Ad}_G(K)$ . The space  $G/K$  is called a *symmetric Riemannian homogeneous space* if the subspace  $\mathfrak{m}$  above satisfies  $[\mathfrak{m}, \mathfrak{m}] \subset \mathfrak{k}$ . For such a space we have then the relations

$$(1) \quad \mathfrak{g} = \mathfrak{m} + \mathfrak{k}, [\mathfrak{m}, \mathfrak{m}] \subset \mathfrak{k}, [\mathfrak{m}, \mathfrak{k}] \subset \mathfrak{m}, [\mathfrak{k}, \mathfrak{k}] \subset \mathfrak{k}.$$

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Received by the editors May 23, 1958.

The space  $G/K$  will be called *irreducible* if  $\text{Ad}_G(K)$  acts irreducibly on  $\mathfrak{m}$ .

**3. The exponential mapping of a symmetric space.** Let  $G/K$  be a symmetric Riemannian space. The subspace  $\mathfrak{m}$  of  $\mathfrak{g}$  can be identified with the tangent space to the complete Riemannian manifold  $G/K$  at  $\pi(e)$ . Let  $\text{Exp}$  denote the mapping of  $\mathfrak{m}$  into  $G/K$  which maps straight lines through 0 in  $\mathfrak{m}$  onto geodesics through  $\pi(e)$  in  $G/K$ , preserving lengths of segments of each such line.

An important theorem in the theory of symmetric spaces states that each geodesic through  $\pi(e)$  is an orbit of a one-parameter group of "transvections" (see [1; 4]) which can be expressed

$$(2) \quad \text{Exp } X = \pi \circ \exp X \quad \text{for } X \in \mathfrak{m}.$$

For each  $X \in \mathfrak{m}$ , let  $T_X$  denote the restriction of  $(\text{ad } X)^2$  to  $\mathfrak{m}$ . From the relations (1) we see that  $T_X$  maps  $\mathfrak{m}$  into itself. We consider  $\mathfrak{m}$  as a manifold whose tangent space at each point is identified with  $\mathfrak{m}$  itself under the usual identification of parallel vectors.

**THEOREM 1.** *The differential of the mapping  $\text{Exp}$  satisfies*

$$(3) \quad d \text{Exp}_X = d\tau(\exp X) \circ \sum_{n=0}^{\infty} \frac{T_X^n}{(2n+1)!} \quad \text{for } X \in \mathfrak{m}.$$

This theorem is useful because it describes the  $\text{Exp}$ -mapping by means of an isometry and a linear transformation of  $\mathfrak{m}$  which is given in terms of the Lie algebra.

We first prove a lemma which describes the analogous situation on  $G$ . This lemma is essentially equivalent to Cartan's formula which expresses the Maurer-Cartan forms in canonical coordinates and is proved in [3, p. 157]. We give a different proof here.

For each  $h \in G$ , let  $L(h)$  denote the left translation  $g \rightarrow hg$  on  $G$ .

**LEMMA 2.** *Let  $G$  be a connected Lie group with Lie algebra  $\mathfrak{g}$ . Identifying  $\mathfrak{g}$  with its tangent space at each point we have*

$$(4) \quad d \exp_X = dL(\exp X) \circ \frac{1 - e^{-\text{ad } X}}{\text{ad } X} \quad \text{for } X \in \mathfrak{g}.$$

**PROOF.** If  $D$  is a linear operator on the space  $C^\infty(G)$  of indefinitely differentiable functions on  $G$  and  $F \in C^\infty(G)$ ,  $[DF](g)$  will denote the value of  $DF$  at  $g$ . Each  $Z \in \mathfrak{g}$  gives rise to a left invariant vector field on  $G$  and therefore to an operator  $F \rightarrow ZF$  on  $C^\infty(G)$  which commutes with left translations on  $G$ . The value of the function  $ZF$  at  $g$  is given by

$$[ZF](g) = \lim_{t \rightarrow 0} \frac{F(g \exp tZ) - F(g)}{t}.$$

It follows by a simple induction that  $d^n/du^n F(\exp uZ) = [Z^n F](\exp uZ)$  which by Taylor's formula implies

$$(5) \quad f(g \exp tZ) = \sum_{n=0}^{\infty} \frac{t^n}{n!} [Z^n f](g)$$

if  $f$  is analytic in a neighborhood of  $g$  and  $t$  is sufficiently small. Also the Lie algebra element  $[X, Y]$  induces in the same fashion the operator  $XY - YX$ . Now suppose  $f$  is analytic in a neighborhood  $V$  of  $e$  in  $G$  and that  $U$  is an open neighborhood of  $0$  in  $\mathfrak{g}$  such that  $\exp U \subset V$ . Let  $X \in U$ . Each  $Y \in \mathfrak{g}$  gives by parallel translation a tangent vector to  $\mathfrak{g}$  at  $X$  and

$$\begin{aligned} [d \exp_X(Y)f](\exp X) &= [Y(f \circ \exp)](X) = \left[ \frac{d}{dt} f(\exp(X + tY)) \right]_{t=0} \\ &= \frac{d}{dt} \left\{ \sum_0^{\infty} \frac{1}{n!} [(X + tY)^n f](e) \right\}_{t=0}. \end{aligned} \quad (6)$$

Due to the analyticity of  $f$  the growth of its derivatives is so restricted that the series in the last expression above can be differentiated with respect to  $t$ , term by term. Only the first power of  $t$  gives a contribution so we obtain

$$\begin{aligned} (6) \quad [d \exp_X(Y)f](\exp X) \\ = \sum_{n=0}^{\infty} \frac{1}{(n+1)!} [(YX^n + XYX^{n-1} + \cdots + X^n Y)f](e). \end{aligned}$$

To simplify this last expression we use the formula

$$(7) \quad YX^m = \sum_{p=0}^m (-1)^p C_{m,p} X^{m-p} (\text{ad } X)^p(Y) \quad X, Y \in \mathfrak{g}.$$

For  $m=1$  this amounts to the definition of  $\text{ad } X$  and for a general integer  $m > 0$  it follows easily by induction. Using the relation  $\sum_{p=0}^{n-k} C_{n-p,k} = C_{n+1,k+1}$  we obtain

$$\begin{aligned} YX^n + XYX^{n-1} + \cdots + X^n Y \\ = \sum_{p=0}^n X^p \sum_{k=0}^{n-p} (-1)^k C_{n-p,k} X^{n-p-k} (\text{ad } X)^k(Y) \\ = \sum_{k=0}^n C_{n+1,k+1} (-1)^k X^{n-k} (\text{ad } X)^k(Y) \end{aligned}$$

which combined with (4) and (5) yields

$$\begin{aligned} [d \exp_X (Y)f](\exp X) &= \sum_{r=0}^{\infty} \left[ \frac{X^r}{r!} \sum_{m=0}^{\infty} (-1)^m \frac{1}{(m+1)!} (\operatorname{ad} X)^m (Y)f \right] (e) \\ &= \left[ \frac{1 - e^{-\operatorname{ad} X}}{\operatorname{ad} X} (Y)f \right] (\exp X). \end{aligned}$$

This proves the lemma for all  $X \in U$ . Its validity for all of  $\mathfrak{g}$  is obtained by analytic continuation as follows: Let  $Y_1, \dots, Y_n$  be a basis of  $\mathfrak{g}$  and for each  $X \in \mathfrak{g}$  put  $Y_i^* = dL(\exp X)(Y_i)$ ; then  $Y_i^*$ ,  $i=1, 2, \dots, n$  is a basis for the tangent space to  $G$  at  $\exp X$ . Define the functions  $t_{ij}(X)$  by  $d \exp_X (Y_i) = \sum_j t_{ij}(X) Y_j^*$ . Then each  $t_{ij}(X)$  is an analytic function on  $\mathfrak{g}$ . On the other hand

$$\frac{1 - e^{-\operatorname{ad} X}}{\operatorname{ad} X} (Y_i) = \sum_j s_{ij}(X) Y_j$$

where  $s_{ij}(X)$  are analytic functions on  $\mathfrak{g}$ . We have proved that  $t_{ij}(X) = s_{ij}(X)$  for all  $X \in U$  and all  $i, j$ . But since  $t_{ij}$  and  $s_{ij}$  are analytic functions on  $\mathfrak{g}$  this last equation holds for all  $X$  and the lemma follows.

Theorem 1 now follows easily. From the relation  $\pi \circ L(g) = \tau(g) \circ \pi$  and (2) we obtain for  $Y \in \mathfrak{m}$

$$\begin{aligned} d \operatorname{Exp}_X (Y) &= d\pi \circ d \exp_X (Y) = d\pi \circ dL(\exp X) \circ \frac{1 - e^{-\operatorname{ad} X}}{\operatorname{ad} X} (Y) \\ &= d\tau(\exp X) \circ d\pi \sum_0^{\infty} (-1)^m \frac{(\operatorname{ad} X)^m}{(m+1)!} (Y). \end{aligned}$$

From the relations (1) it follows that

$$d\pi \circ (\operatorname{ad} X)^m (Y) = \begin{cases} (T_X)^n & \text{if } m = 2n, \\ 0 & \text{if } m \text{ is odd} \end{cases}$$

which proves Theorem 1.

**4. The Riemannian curvature of a symmetric space.** Let  $M$  be a Riemannian manifold,  $m$  a point in  $M$ ,  $M_m$  the tangent space to  $M$  at  $m$ . The mapping  $\operatorname{Exp}_m$  maps a neighborhood of 0 in  $M_m$  onto a neighborhood of  $m$  in  $M$  in a one-to-one fashion such that line segments through 0 go into geodesics through  $m$  in  $M$ . Let  $S$  be a two-dimensional subspace of  $M_m$  and  $K(S)$  the corresponding sectional curvature. In order to apply Theorem 1 it is convenient to derive a new expression for  $K(S)$ .

LEMMA 3. Let  $\Delta$  denote the Laplacian of the metric vector space  $S$  above and let  $f$  be the Radon-Nikodym derivative of the restriction of  $\text{Exp}_m$  to  $S$  (the ratio of the volume elements in  $\text{Exp}_m(S)$  and  $S$ ) normalized by  $f(0) = 1$ . Then

$$K(S) = -\frac{3}{2} \Delta f(0).$$

PROOF. Let  $A_0$  denote a small disk in  $S$  with center at 0 and radius  $r$  and we put  $A = \text{Exp}_m(A_0)$ . Let  $A_0(r)$  and  $A(r)$  denote the corresponding areas. Then

$$A(r) = \int_{A_0} f(X) dX = A_0(r) \left\{ f(0) + \frac{1}{8} r^2 [\Delta f](0) + \cdots \right\}.$$

Applying Vermeil's formula

$$K(S) = \lim_{r \rightarrow 0} 12 \frac{A_0(r) - A(r)}{r^2 A_0(r)},$$

[2, p. 253], we get Lemma 3 immediately.

THEOREM 2. Let  $G/K$  be a symmetric Riemannian space,  $Q$  the quadratic form on  $\mathfrak{m}$  that gives the invariant metric on  $G/K$ . Let  $S$  be a two-dimensional subspace of  $\mathfrak{m}$  spanned by the orthonormal vectors  $Y$  and  $Z$ . Then

$$K(S) = -Q(T_Y(Z), Z).$$

PROOF. Let  $X_1, \cdots, X_n$  be a basis of  $\mathfrak{m}$  such that  $Q(X_i, X_j) = \delta_i^j$  and such that  $X_1 = Y$ ,  $X_2 = Z$ . Each  $X \in S$  can be represented  $X = x_1 X_1 + x_2 X_2$  and the Laplacian  $\Delta$  on  $S$  has the form

$$\Delta = \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}.$$

If  $a$  and  $b$  are two vectors in a metric vector space we denote by  $a \vee b$  the parallelogram spanned by  $a$  and  $b$  and by  $|a \vee b|$  the area. We write  $A_X = \sum_0^\infty [(2n+1)!]^{-1} T_X^n$  and  $A_X(X_i) = v_i$ ,  $i = 1, 2$ . Since the mapping  $\tau(\exp X)$  is an isometry we see from Theorem 1

$$f(X) = \frac{|v_1 \vee v_2|}{|X_1 \vee X_2|} = |v_1 \vee v_2|.$$

If  $A_X$  has the matrix  $(A_{ij})$  with respect to the basis  $X_1, \cdots, X_n$ ,

$$\begin{aligned} f(X) &= |(A_{11}X_1 + \cdots + A_{n1}X_n) \vee (A_{12}X_1 + \cdots + A_{n2}X_n)| \\ &= [(A_{11}A_{22} - A_{12}A_{21})^2 + \cdots + (A_{i1}A_{j2} - A_{j1}A_{i2})^2 + \cdots]^{1/2} \end{aligned}$$

since  $| (A_{i1}A_{j2} - A_{j1}A_{i2}) |$  is the area of the projection of  $v_1 \vee v_2$  on the  $(X_i, X_j)$ -plane. In computing  $\Delta f(0)$  from the expression for  $f(X)$  we only have to consider terms of second order in  $x_1$  and  $x_2$ . Since the matrix elements  $T_{ij}$  of  $T_X$  are either 0 or are of second order in  $x_1$  and  $x_2$  we find easily

$$\begin{aligned} [\Delta f](0) &= [\Delta A_{11}A_{22}](0) = \left[ \Delta \left( 1 + \frac{1}{3!} T_{11} \right) \left( 1 + \frac{1}{3!} T_{22} \right) \right](0) \\ &= \frac{1}{3!} [\Delta(T_{11} + T_{22})](0) \end{aligned}$$

and since  $T_X = (\text{ad}(x_1X_1 + x_2X_2))^2$  restricted to  $\mathfrak{m}$ ,

$$[\Delta f](0) = \frac{1}{3} [Q(T_Y(Z), Z) + Q(T_Z(Y), Y) + Q(T_Y(Y), Y) + Q(T_Z(Z), Z)].$$

Here the last two terms vanish, the two first are equal and the theorem follows from Lemma 3.

**THEOREM 3.** *Let  $G/K$  be an irreducible symmetric Riemannian space.*

- (i) *If  $G/K$  is compact the sectional curvature is everywhere  $\geq 0$ .*
- (ii) *If  $G/K$  is noncompact the sectional curvature is everywhere  $\leq 0$ .*

**PROOF.** We can assume that  $G$  acts effectively on  $G/K$ ; it is well known [4, p. 56] that either  $\mathfrak{g}$  is semi-simple or  $[\mathfrak{m}, \mathfrak{m}] = 0$ . In the latter case Theorem 3 is obvious so we assume  $\mathfrak{g}$  is semi-simple. Let  $B$  denote the Killing form on  $\mathfrak{g}$ . By the irreducibility

$$(7) \quad B(X, X) = \lambda Q(X, X) \quad \text{for all } X \in \mathfrak{m}$$

where  $\lambda$  is a constant. Let  $D$  be a positive definite quadratic form on  $\mathfrak{f}$  invariant under  $\text{Ad}_G(K)$ . The form  $\Phi(Z, Z) = Q(X, X) + D(Y, Y)$  ( $Z = X + Y$ ,  $X \in \mathfrak{m}$ ,  $Y \in \mathfrak{f}$ ) is positive definite and invariant under  $\text{Ad}_G(K)$ ; hence if  $Y \in \mathfrak{f}$ , the linear transformation  $\text{ad } Y$  has a skew symmetric matrix with respect to  $\Phi$  and

$$(8) \quad B(Y, Y) = \text{Tr}(\text{ad } Y \text{ ad } Y) \leq 0.$$

Now let  $Z$  denote the center of  $G$ . Then the compact group  $\text{Ad}_G(K)$  is isomorphic to  $K/(Z \cap K)$ . But  $Z \cap K = e$  since  $G$  acts effectively so  $K$  is compact. The constant  $\lambda$  is negative in the case (i) and positive in case (ii). Using the notation of Theorem 2 we obtain from (8)  $B(T_Y(Z), Z) = -B([Y, Z], [Y, Z]) \geq 0$ . Theorem 3 now follows from (7).

**REMARK.** The conclusion of (i) in Theorem 3 holds whether or not

$G/K$  is irreducible. This can be seen by decomposing  $\mathfrak{m}$  into irreducible subspaces invariant under  $\text{Ad}_G(K)$  and orthogonal with respect to  $Q$ . On each of those subspaces  $B$  is a nonpositive multiple of  $Q$  and we can proceed as before.

**5. Compact homogeneous spaces.** The theorem of H. Samelson mentioned in the introduction can be stated as follows.

**THEOREM 4.** *Let  $G$  be a compact connected Lie group,  $K$  a closed subgroup. Let  $Q$  be a positive definite quadratic form on the Lie algebra  $\mathfrak{g}$  invariant under  $\text{Ad}(G)$  and let  $\mathfrak{m}$  be the orthogonal complement to the subalgebra  $\mathfrak{k}$ . The restriction of  $Q$  to  $\mathfrak{m}$  defines a Riemannian metric on  $G/K$  invariant under  $G$ , and with respect to this metric the sectional curvature is everywhere  $\geq 0$ .*

**PROOF.** In the two-sided invariant metric on  $G$  given by  $Q$  the geodesics are the cosets of one-parameter subgroups. This is a special case of (2) applied to the symmetric space  $G = (G \times G)/D$  where  $D$  is the diagonal of  $G \times G$ , the symmetry automorphism of  $G \times G$  being  $(x, y) \rightarrow (y, x)$  and each  $(g, g_1) \in G \times G$  giving the isometry  $x \rightarrow gxg_1^{-1}$  of  $G$ . The geodesics in  $G/K$  through  $\pi(e)$  are again projections of certain one-parameter subgroups in  $G$ , that is

$$(9) \quad \text{Exp } X = \pi \circ \exp X \quad \text{for } X \in \mathfrak{m}.$$

(See [4, Theorem 13.2]. In [5] a simple geometric proof was based on comparison between lengths of curves in  $G$  and their projections in  $G/K$ .) Now let  $S$  be a two-dimensional subspace of  $\mathfrak{m}$ . We can then find an orthonormal base  $(X_i)$  of  $\mathfrak{m}$  and an orthonormal base  $(X_a)$  of  $\mathfrak{k}$  such that  $X_1$  and  $X_2$  span  $S$ . Each  $X \in S$  can be written  $X = x_1 X_1 + x_2 X_2$  and the Laplacian on  $S$  is

$$\Delta = \frac{\partial^2}{\partial x_1^2} + \frac{\partial^2}{\partial x_2^2}.$$

We also put  $[X_i, X_j] = \sum_k c_{ijk} X_k + \sum_\rho c_{ij\rho} X_\rho$  and  $A_X = (\text{ad } X)^{-1} \cdot (1 - e^{-\text{ad } X})$ . Let  $f$  and  $F$  denote the Radon-Nikodym derivative of the restrictions of  $\exp$  and  $\text{Exp}$  to  $S$ . Then

$$f(X) = \frac{|A_X(X_1) \vee A_X(X_2)|}{|X_1 \vee X_2|}$$

and

$$F(X) = \frac{|d\pi \cdot A_X(X_1) \vee d\pi \cdot A_X(X_2)|}{|X_1 \vee X_2|}.$$

Now it is easily seen, that on cancelling terms of order  $\geq 2$  in  $x_1$  and  $x_2$

$$A_X(X_1) = (1 + p_1)X_1 + p_2X_2 + \cdots + p_nX_n + \cdots + p_\rho X_\rho + \cdots, \\ A_X(X_2) = q_1X_1 + (1 + q_2)X_2 + \cdots + q_nX_n + \cdots + q_\sigma X_\sigma + \cdots$$

where the coefficients  $p$  and  $q$  are polynomials in  $x_1$  and  $x_2$  of degree  $\geq 1$  without constant terms. Moreover  $p_\rho = -c_{21\rho}x_2/2$ ,  $q_\sigma = -c_{12\sigma}x_\sigma/2$ . The expressions for  $d\pi \cdot A_X(X_1)$  and  $d\pi A_X(X_2)$  are obtained by cancelling the  $X_\alpha$  from the expressions above. By a computation similar to the one used in the proof of Theorem 2 we find

$$(10) \quad \Delta f(0) = \Delta F(0) + \frac{1}{2} \sum_{\rho} c_{12\rho}^2.$$

By the remark following Theorem 3  $(G \times G)/D$  has curvature everywhere  $\geq 0$ ; by Lemma 3  $\Delta f \leq 0$  and by (10)  $\Delta F \leq 0$ . This proves Theorem 4.

REMARK. From relation (10) it is easily seen that in the situation described in Theorem 4, the curvatures of  $G$  and  $G/K$  are the same for all sections of  $\mathfrak{m}$  if and only if  $c_{ij\rho} \equiv 0$ , that is  $\mathfrak{m}$  is a subalgebra, hence an ideal in  $\mathfrak{g}$ .

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