Week 6 Assignment

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(a) (i) Implementing mini-batch Stochastic Gradient Descent Our global loss function is

$$f_T(x) = \sum_{w \in T} \frac{loss(x, w)}{\#W}$$

which is just the average of loss(w, x) ranging over the entire dataset, T. We can also calculate an approximation of the loss using a subset (minibatch) of T.

$$f_N(x) = \sum_{w \in N} \frac{loss(x, w)}{\#N}$$

This is implemented on line 17 of Algorithm 1. We can also approximate the gradient w.r.t. to the minibatch rather than the full training dataset. In these experiments we use the finite difference methods to estimate the mini-batch gradient according to

$$\frac{df_N}{dx_i} \approx \frac{f_N([x_1, \dots, x_i + \epsilon, \dots, x_d]) - f_N(x)}{\epsilon}$$

where we set $\epsilon=10^{-15}$ for the remainder of this discussion. We also look at only at an example with d=2 so the finite difference gradient is:

$$\nabla f_N = \left[\frac{f_N([x_1 + \epsilon, x_2]) - f_N(x)}{\epsilon}, \frac{f_N([x_1, x_2 + \epsilon]) - f_N(x)}{\epsilon}\right]$$

The code implementation of this is on line 4 in Algorithm 1.

To generate mini-batches we first shuffle the rows data set and then take successive slices with n rows, where n is the mini-batch size. The first mini-batch consists of the 1st to the nth data items, the second consists of the (n+1)th to the (n+n)th, etc. If we reach the end of the dataset before filling the minibatch we shuffle the dataset and start again from index 1. This is implemented on line 10 of Algorithm 1.

The implementation of mini-batch SGD here relies on generating successive f_{N_t} and ∇f_{N_t} , where N_t is the mini-batch for iteration t. This is implemented on line 40 of Algorithm 1.

At each iteration the step size can be calculated with respect to f_{N_t} and ∇f_{N_t} using of the Polyak, RMSProp, Heavy Ball, and Adam methods. Each of the step types are implemented in src/sgd.py which is included in the appendix.

Algorithm 1 Generating mini-batches, N, and associated f_N and ∇f_N .

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src/ai.py

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1: import numpy as np
2: import sympy as sp
3:
4: def gradient_function_fd(minibatch, epsilon=10**(-15)):
5: def gradient_fa(x):
6: dydxl = (f(x + np.array([epsilon, 0]), minibatch) - f(x, minibatch)) / epsilon
7: dydx2 = (f(x + np.array([dp, epsilon]), minibatch) - f(x, minibatch)) / epsilon
8: return up.array([dydxl, dydx2])
9: return gradient_fd
10:
11: def loss(x, w):
12: z = x - w - 1
13: left = 10 * (z[0]**2*z[1]**2)
14: right = (z[0]*2***2*(z[1]*4)**2
15: return min(left, right)
16:
17: def f_clear(x, minibatch):
18: return sum(loss(x, w) for w in minibatch) / len(minibatch)
19:
20: def generate_minibatches(T, n=5, seed=42, shuffle=True):
21: if shuffle:
22: T = T.copy()
23: np.random.seed(seed)
10: np.random.seed(seed)
24: np.random.seed(seed)
25: num_rows = T.shape[0]
26: i = 0
27:
28: minibatch = np.zeros((n, T.shape[1]), T.dtype)
29: while True:
29: while True:
29: minibatch = np.zeros((n, T.shape[1]), T.dtype)
29: while True:
29: minibatch = np.zeros(n, T.shape[1])
20: def generate_optimisation_functions(batch, minibatch_size=5, finite_difference=True, **kwargs):
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20: def optim_func(x):
21: return f_clear(x, minibatch)
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23: return f_clear(x, minibatch)
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26: def optim_func(x):
27: return f_clear(x, minibatch)
28: return f_clear(x, minibatch)
29: def gradient_function_fd(minibatch)
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20: def function_finentience
20: def optim_func, gradf)
21: return f_clear(x, minibatch)
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29: return f_clear(x, minibatch)
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20: def
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