

PROJECT

Generate TV Scripts

A part of the Deep Learning Nanodegree Foundation Program

PROJECT REVIEW

CODE REVIEW

NOTES

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Meets Specifications

Woohoo! Nice work. Here's a discussion on LSTMs for natural language generation if you're interested in reading more.



Required Files and Tests

 $The \ project \ submission \ contains \ the \ project \ notebook, \ called \ "dlnd_tv_script_generation.ipynb".$

All the unit tests in project have passed.

Preprocessing

The function create_lookup_tables create two dictionaries:

- Dictionary to go from the words to an id, we'll call vocab_to_int
- Dictionary to go from the id to word, we'll call int_to_vocab

The function create_lookup_tables return these dictionaries in the a tuple (vocab_to_int, int_to_vocab)

Nice job! You don't need to convert the set to a list though.

Build the Neural Network

 $Implemented \ the \ \boxed{\texttt{get_inputs}} \ \ \text{function to create TF Placeholders for the Neural Network with the following placeholders:}$

- Input text placeholder named "input" using the TF Placeholder name parameter.
- Targets placeholder
- Learning Rate placeholder

The get_inputs function return the placeholders in the following the tuple (Input, Targets, LearingRate)

The $[\mathtt{get_init_cell}]$ function does the following:

- Stacks one or more BasicLSTMCells in a MultiRNNCell using the RNN size rnn_size .
- Initializes Cell State using the MultiRNNCell's zero_state function
- The name "initial_state" is applied to the initial state.
- The get_init_cell function return the cell and initial state in the following tuple (Cell, InitialState)

Good work! This is where you could add dropout if you wanted to, with something like this:

```
layers = 2
cells = []
for i in range(layers):
   lstm = tf.contrib.rnn.BasicLSTMCell(rnn_size)
   drop = tf.contrib.rnn.DropoutWrapper(lstm, output_keep_prob=0.7)
   cells.append(drop)
cell = tf.contrib.rnn.MultiRNNCell(cells)
initial_state = tf.identity(cell.zero_state(batch_size, tf.float32), name="initial_state")
return cell, initial state
```

I've also found it necessary in the latest versions of TF to go through the loop and make a list of cells, otherwise they share variables (weights/biases) and it throws an error.

The function get_embed applies embedding to input_data and returns embedded sequence.

Great job! You could also do it like tf.contrib.layers.embed_sequence(input_data, vocab_size, embed_dim) If the embedding_lookup function seems confusing, check out this

Also, here's a video on word embeddings, and here's a nice blog post, if you want to learn more.

The function build rnn does the following:

- Builds the RNN using the tf.nn.dynamic_rnn .
- Applies the name "final state" to the final state.
- Returns the outputs and final_state state in the following tuple (Outputs, FinalState)

The build_nn function does the following in order:

- Apply embedding to input_data using get_embed function.
- Build RNN using cell using build_rnn function.
- Apply a fully connected layer with a linear activation and vocab_size as the number of outputs.
- Return the logits and final state in the following tuple (Logits, FinalState)

The get_batches function create batches of input and targets using int_text. The batches should be a Numpy array of tuples. Each tuple is (batch of input, batch of target).

- The first element in the tuple is a single batch of input with the shape [batch size, sequence length]
- The second element in the tuple is a single batch of targets with the shape [batch size, sequence length]

That works! You could also do it similarly to Mat's example (here's the newest version which is different, and here's the version I used to solve this part):

```
n_batches = int(len(int_text) / (batch_size * seq_length))
# Drop the last few characters to make only full batches
xdata = np.array(int_text[: n_batches * batch_size * seq_length])
ydata = np.array(int_text[1: n_batches * batch_size * seq_length + 1])
vdata[-1] = xdata[0]
x_batches = np.split(xdata.reshape(batch_size, -1), n_batches, 1)
y_batches = np.split(ydata.reshape(batch_size, -1), n_batches, 1)
#print(np.array(list(zip(x batches, y batches))))
return np.array(list(zip(x_batches, y_batches)))
```

Neural Network Training

- Enough epochs to get near a minimum in the training loss, no real upper limit on this. Just need to make sure the training loss is low and not improving much with more
- Batch size is large enough to train efficiently, but small enough to fit the data in memory. No real "best" value here, depends on GPU memory usually.
- Size of the RNN cells (number of units in the hidden layers) is large enough to fit the data well. Again, no real "best" value.
- The sequence length (seq_length) here should be about the size of the length of sentences you want to generate. Should match the structure of the data. The learning rate shouldn't be too large because the training algorithm won't converge. But needs to be large enough that training doesn't take forever. Set show_every_n_batches to the number of batches the neural network should print progress.

You got it! Everything is in a good range. For example, Google's news word vectors, the GloVe vectors, and other word vectors are usually in the range 50 to 300, so I like to use embed_dims in that range for words typically.

Your seq length is good; we base this off the avg sentence length (printed at the top) of 11 words/line. So you've got about 1 line as your seq_length, which is in a good range (0.5-5 lines range).

The project gets a loss less than 1.0

Generate TV Script

"input:0", "initial_state:0", "final_state:0", and "probs:0" are all returned by get_tensor_by_name, in that order, and in a tuple

The $\begin{tabular}{ll} {\it pick_word} \end{tabular}$ function predicts the next word correctly.

The generated script looks similar to the TV script in the dataset.

It doesn't have to be grammatically correct or make sense.

It will look a bit better if you train for some more epochs. You can get the loss down to something like 0.5 or even much less.

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Student FAO