

UNIVERSIDAD NACIONAL SAN AGUSTIN DE AREQUIPA

FACULTAD DE INGENIERÍAS DE PRODUCCION Y SERVICIOS

LABORATORIO

Fisica Computacional

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```
[1]: %matplotlib inline
      #%matplotlib notebook

      import sys
      sys.path.append("../") # go to parent dir
```

1 Importando Modelos

```
[2]: from models.Vector import Vector, Coordinate
      from models.Graphic import Graphic
```

Código de los modelos en los Anexos

2 Importando Librerías

```
[3]: import numpy
      import math
```

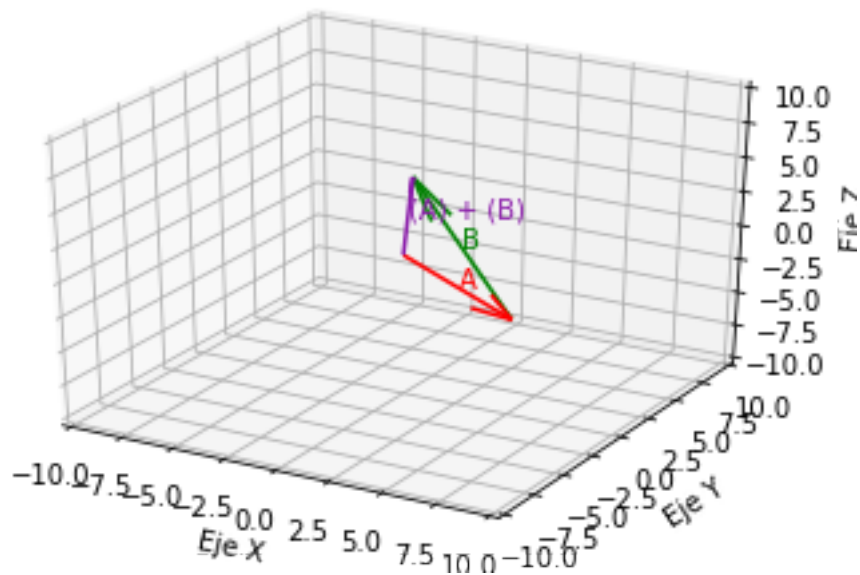
3 Ejercicio 1

Sean los vectores $\vec{A} = 3\vec{i} + 4\vec{j} - 6\vec{k}$ y $\vec{B} = -6\vec{i} + 2\vec{j} + 8\vec{k}$, encuentre gráficamente. Verifique que los resultados están en un plano.

```
[4]: A = Vector( value=Coordinate(3, 4, -6), label="A", color='r')
      B = Vector(origin=A.destiny,value=Coordinate(-6,2,8), label="B", color='g')
```

(a) $\vec{R} = \vec{A} + \vec{B}$, $|\vec{R}|$, sus cosenos directores $\cos \alpha_1 = R_x/R$, $\cos \alpha_2 = R_y/R$, $\cos \alpha_3 = R_z/R$

```
[5]: R = A+B
      G = Graphic()
      G.vector(A)
      G.vector(B)
      G.vector(R)
      G.show()
      print('A:{} + B:{} = R:{}'.format(A,B,R))
      print('Longitud R = {}'.format(R.length))
      print('Cos(a1) = {}'.format(R.value.x/R.length))
      print('Cos(a2)= {}'.format(R.value.y/R.length))
      print('Cos(a3) = {}'.format(R.value.z/R.length))
```



$A:[3.00; 4.00; -6.00] + B:[-6.00; 2.00; 8.00] = R:[-3.00; 6.00; 2.00]$

Longitud R = 7.0

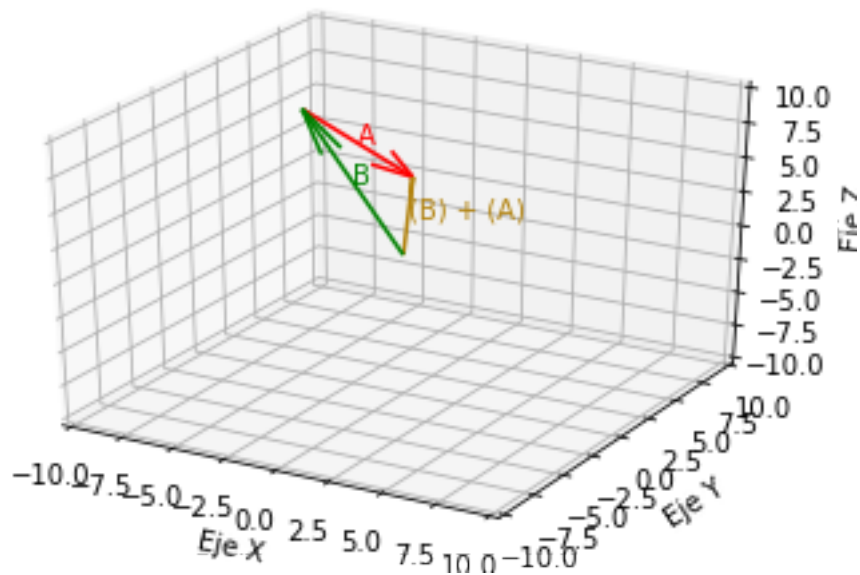
$\cos(a_1) = -0.42857142857142855$

$\cos(a_2) = 0.8571428571428571$

$\cos(a_3) = 0.2857142857142857$

(b) $R = B + A$

```
[6]: B.setOrigin()
A.setOrigin(B.destiny)
R = B+A
G = Graphic()
G.vector(A)
G.vector(B)
G.vector(R)
G.show()
print('A:{} + B:{} = R:{}'.format(A,B,R))
print('Longitud R = {}'.format(R.length))
print('Cos(a1) = {}'.format(R.value.x/R.length))
print('Cos(a2) = {}'.format(R.value.y/R.length))
print('Cos(a3) = {}'.format(R.value.z/R.length))
```



$A: [3.00; 4.00; -6.00] + B: [-6.00; 2.00; 8.00] = R: [-3.00; 6.00; 2.00]$

Longitud R = 7.0

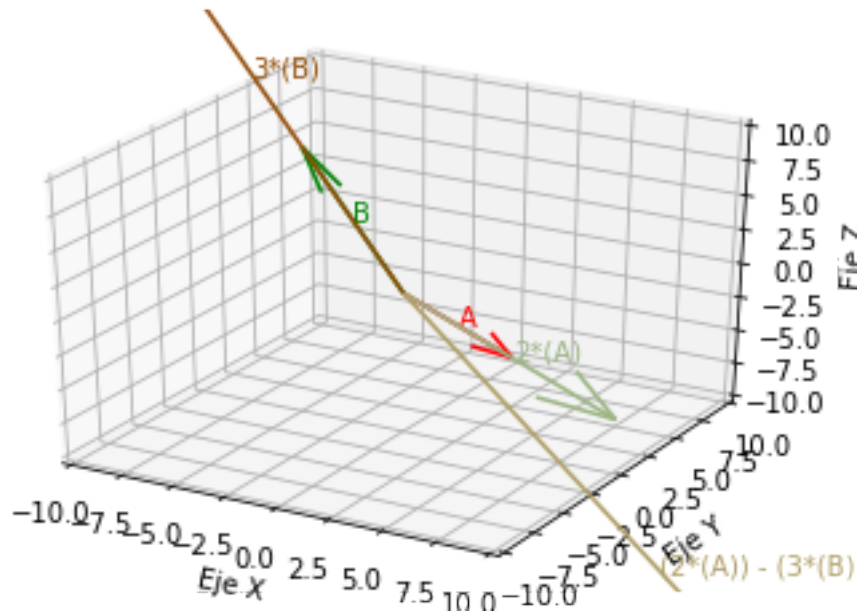
$\cos(a_1) = -0.42857142857142855$

$\cos(a_2) = 0.8571428571428571$

$\cos(a_3) = 0.2857142857142857$

(c) $S = 2A - 3B$

```
[7]: A.setOrigin()
A_2 = A.mulEscalar(2)
B_3 = B.mulEscalar(3)
#B_3.setOrigin(A_2.destiny)
S = A_2-B_3
G = Graphic()
G.vector(A)
G.vector(A_2)
G.vector(B)
G.vector(B_3)
G.vector(S)
G.show()
print('2*A:{} - 3*B:{} = S:{}'.format(A_2,B_3,S))
print('Longitud S = {}'.format(S.length))
print('Cos(a1) = {}'.format(S.value.x/S.length))
print('Cos(a2) = {}'.format(S.value.y/S.length))
print('Cos(a3) = {}'.format(S.value.z/S.length))
```



$2*A:[6.00; 8.00; -12.00] - 3*B:[-18.00; 6.00; 24.00] = S:[24.00; 2.00; -36.00]$

Longitud S = 43.31281565541543

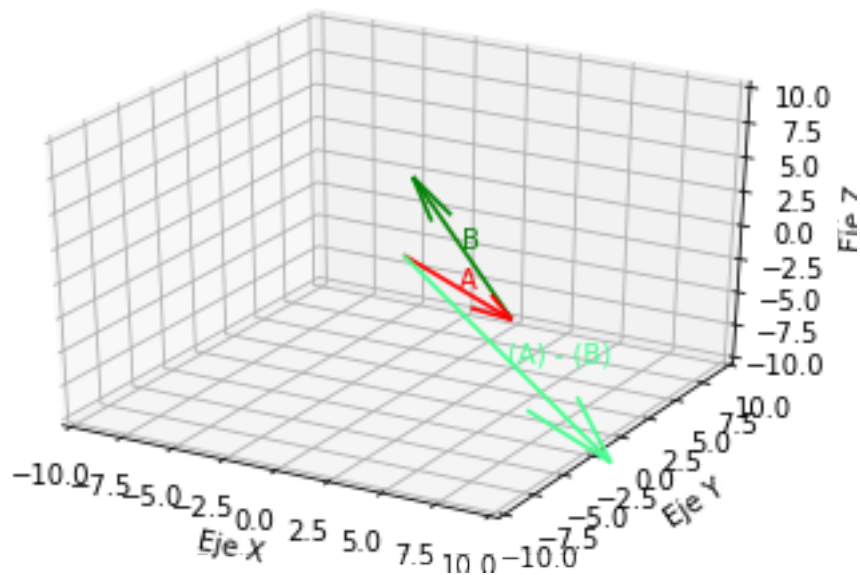
$\text{Cos}(a1) = 0.5541085158475322$

$\text{Cos}(a2) = 0.04617570965396102$

$\text{Cos}(a3) = -0.8311627737712983$

(d) $D = A - B$

```
[8]: A.setOrigin()
B.setOrigin(A.destiny)
D = A-B
G = Graphic()
G.vector(A)
G.vector(B)
G.vector(D)
G.show()
print('A:{} - B:{} = D:{}'.format(A,B,D))
print('Longitud D = {}'.format(D.length))
print('Cos(a1) = {}'.format(D.value.x/D.length))
print('Cos(a2) = {}'.format(D.value.y/D.length))
print('Cos(a3) = {}'.format(D.value.z/D.length))
```



$A:[3.00; 4.00; -6.00] - B:[-6.00; 2.00; 8.00] = D:[9.00; 2.00; -14.00]$

Longitud D = 16.76305461424021

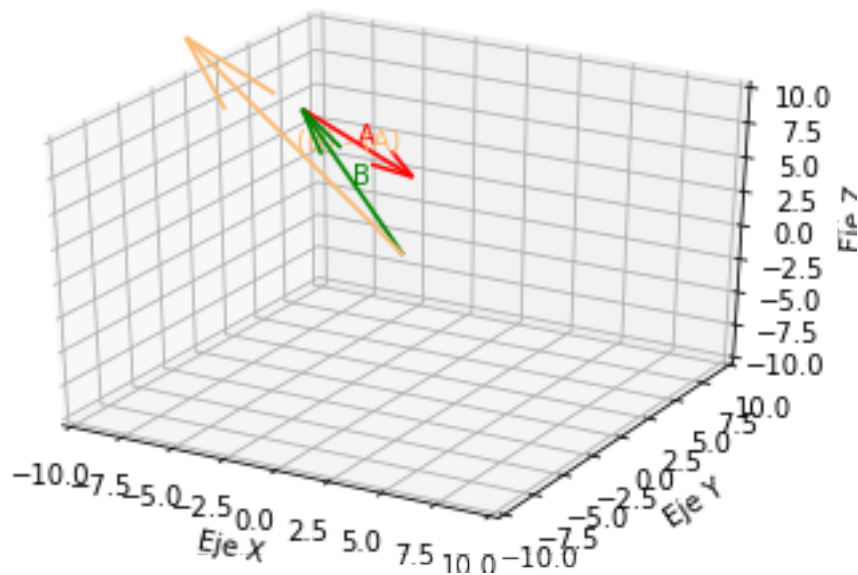
$\cos(a_1) = 0.5368949876447042$

$\cos(a_2) = 0.11930999725437871$

$\cos(a_3) = -0.835169980780651$

(e) $\vec{D} = \vec{B} - \vec{A}$

```
[9]: B.setOrigin()
A.setOrigin(B.destiny)
D = B-A
G = Graphic()
G.vector(A)
G.vector(B)
G.vector(D)
G.show()
print('B:{} - A:{} = D:{}'.format(B,A,D))
print('Longitud D = {}'.format(D.length))
print('Cos(a1) = {}'.format(D.value.x/D.length))
print('Cos(a2) = {}'.format(D.value.y/D.length))
print('Cos(a3) = {}'.format(D.value.z/D.length))
```



```

B: [-6.00; 2.00; 8.00] - A: [3.00; 4.00; -6.00] = D: [-9.00; -2.00; 14.00]
Longitud D = 16.76305461424021
Cos(a1) = -0.5368949876447042
Cos(a2) = -0.11930999725437871
Cos(a3) = 0.835169980780651

```

4 Ejercicio 2

Dibuje un pentágono de lado 5 cm vectorialmente, hacer que cada lado del pentágono sea un vector. Demuestre que la suma de dichos vectores es igual a cero.

```

[10]: labels = ['u', 'v', 'w', 'a', 'b']

length = 5
u = Vector(value=Coordinate(math.cos(0)*length, math.cos(math.pi/2)*length, 0),
    ↪label=labels.pop(), color=numpy.random.rand(3,))
vectors = [u]
prev = 0
ang_inter = 108 # Angulo interno de un pentagono regular
last = u

G = Graphic(xmin=-3.5, xmax=6.5, ymin=-1.25, ymax = 8.75, zmin = -6.5, zmax = 3.
    ↪5)
G.vector(u)

res = "{}: {}".format(last.label, last)
suma = last

```

```

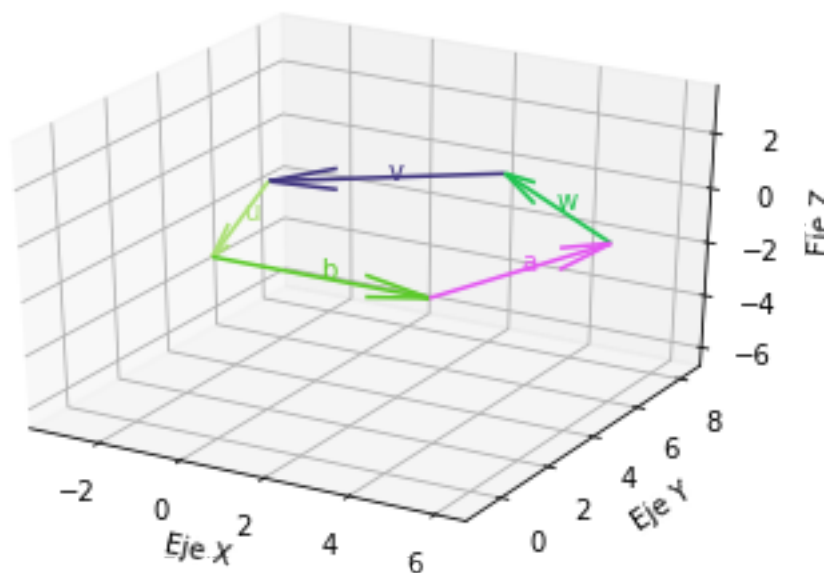
while len(labels)!=0:
    ang_dec = prev + 180- ang_inter
    ang_rad = math.pi/180*ang_dec
    prev = ang_dec
    cos_ang = math.cos(ang_rad)
    cos_comp_ang = math.cos(math.pi/2-ang_rad)
    new_x = cos_ang*length
    new_y = cos_comp_ang*length
    new_z = 0
    last = Vector(origin = last.destiny ,value =Coordinate(new_x, new_y,
↪new_z), label=labels.pop(), color=numpy.random.rand(3,))
    vectors.append(last)

    G.vector(last)
    res = "{} + {}: {}".format(res ,last.label , last)
    suma = suma + last
    print("{} = {}".format(res, suma) )

G.show()

```

b: [5.00; 0.00; 0.00] + a: [1.55; 4.76; 0.00] = [6.55; 4.76; 0.00]
b: [5.00; 0.00; 0.00] + a: [1.55; 4.76; 0.00] + w: [-4.05; 2.94; 0.00] = [2.50;
7.69; 0.00]
b: [5.00; 0.00; 0.00] + a: [1.55; 4.76; 0.00] + w: [-4.05; 2.94; 0.00] + v:
[-4.05; -2.94; 0.00] = [-1.55; 4.76; 0.00]
b: [5.00; 0.00; 0.00] + a: [1.55; 4.76; 0.00] + w: [-4.05; 2.94; 0.00] + v:
[-4.05; -2.94; 0.00] + u: [1.55; -4.76; 0.00] = [-0.00; 0.00; 0.00]



5 Ejercicio 3

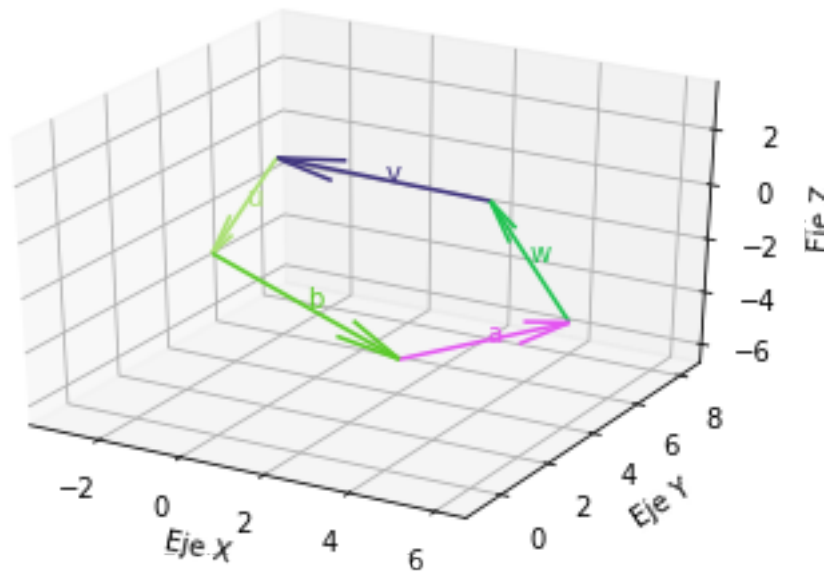
Graficar dicho pentágono de lado 5 cm vectorialmente en 3 dimensiones, sabiendo que dicho pentágono esta perpendicular con el plano xz y forma un ángulo de 30° con el eje x. Demuestre que la suma de dichos vectores es igual a cero

```
[11]: G = Graphic(xmin=-3.5, xmax=6.5, ymin=-1.25, ymax = 8.75, zmin = -6.5, zmax = 3.
      ↪5)

res = "{}: {}".format(last.label , last)
suma = Vector()
origin = Coordinate(0,0,0)

#for vector in vectors:
#    G.vector(vector)
for vector in vectors:
    #G.vector(vector)
    print(vector.value)
    vector.rotateY(30)
    vector.setOrigin(origin)
    origin = vector.destiny
    G.vector(vector)
    res = "{} + {}: {}".format(res ,vector.label , vector)
    suma = suma + vector
    print("{} = {}".format(res, suma) )
G.show()
```

```
(5.0, 3.061616997868383e-16, 0)
u: [1.55; -4.76; 0.00] + b: [4.33; 0.00; -2.50] = [4.33; 0.00; -2.50]
(1.5450849718747373, 4.755282581475767, 0)
u: [1.55; -4.76; 0.00] + b: [4.33; 0.00; -2.50] + a: [1.34; 4.76; -0.77] =
[5.67; 4.76; -3.27]
(-4.045084971874736, 2.938926261462366, 0)
u: [1.55; -4.76; 0.00] + b: [4.33; 0.00; -2.50] + a: [1.34; 4.76; -0.77] + w:
[-3.50; 2.94; 2.02] = [2.17; 7.69; -1.25]
(-4.045084971874738, -2.938926261462365, 0)
u: [1.55; -4.76; 0.00] + b: [4.33; 0.00; -2.50] + a: [1.34; 4.76; -0.77] + w:
[-3.50; 2.94; 2.02] + v: [-3.50; -2.94; 2.02] = [-1.34; 4.76; 0.77]
(1.5450849718747361, -4.755282581475768, 0)
u: [1.55; -4.76; 0.00] + b: [4.33; 0.00; -2.50] + a: [1.34; 4.76; -0.77] + w:
[-3.50; 2.94; 2.02] + v: [-3.50; -2.94; 2.02] + u: [1.34; -4.76; -0.77] =
[-0.00; 0.00; 0.00]
```



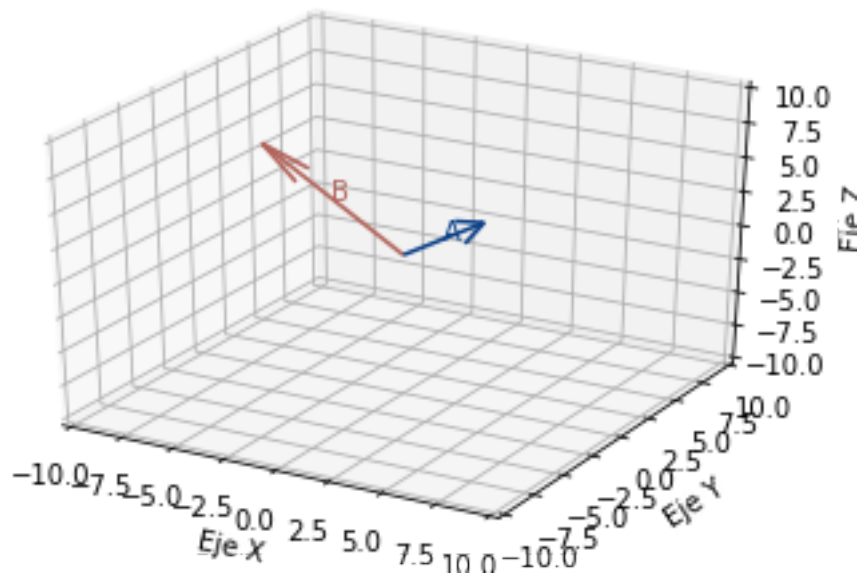
6 Ejercicio 4

Sean los vectores $A = 6i - 4j + 6k$, $B = -8i + 2j + 5k$ y $C = 2i - 7j + 3k$. Determine y grafique según corresponda.

```
[12]: A = Vector(value=Coordinate(6,-4,6), label='A', color=numpy.random.rand(3,))
      B = Vector(value=Coordinate(-8,2,5), label='B', color=numpy.random.rand(3,))
      C = Vector(value=Coordinate(2,-7,3), label='C', color=numpy.random.rand(3,))
```

(a) $e = A \cdot B$ y encuentre el ángulo entre estos vectores

```
[13]: G = Graphic()
      G.vector(A)
      G.vector(B)
      G.show()
      e = A * B
      radiands = A.angle(B)
      grades = radiands*180/math.pi
      print("Producto Punto e = A * B:" , e)
      print("Angulo: {} rad, {}°".format(radiands, grades))
```

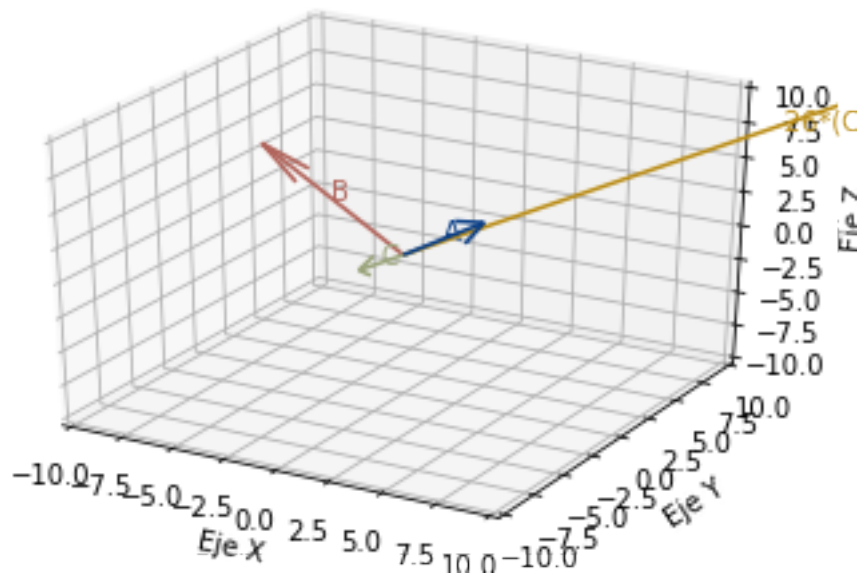


Producto Punto $e = A \cdot B$: -26

Angulo: 1.86231013817353 rad, 106.70251106176846°

(b) $R = (A \cdot B)C$

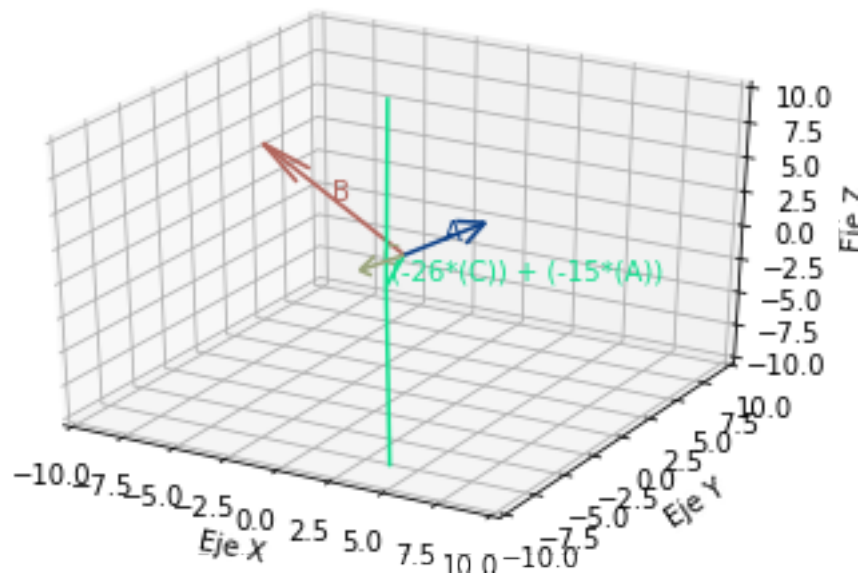
```
[14]: R = C.mulEscalar(A * B)
      G = Graphic()
      G.vector(A)
      G.vector(B)
      G.vector(C)
      G.vector(R)
      G.show()
      print("Producto Punto (A * B) C:" , R)
```



Producto Punto (A * B) C: [-52.00; 182.00; -78.00]

$$(c) R = (A \cdot B)C + (B \cdot C)A$$

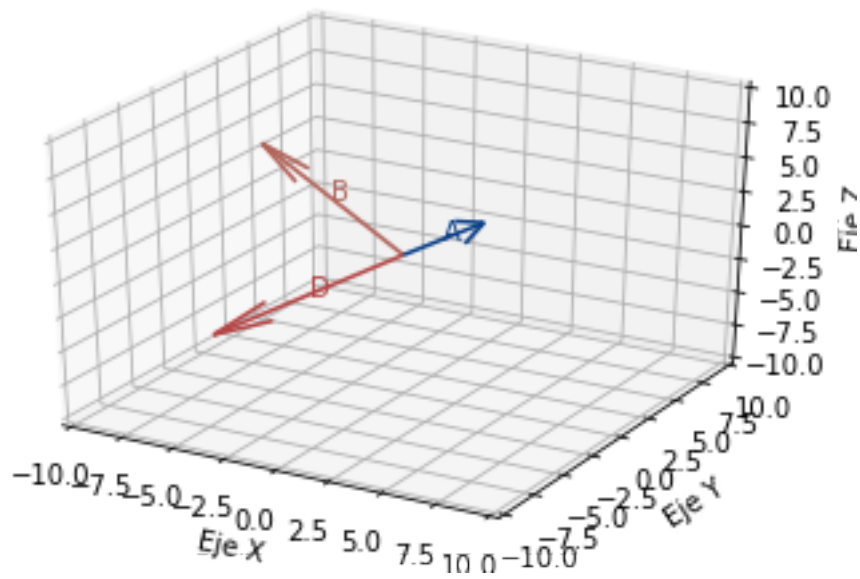
```
[15]: R = C.mulEscalar(A * B)+ A.mulEscalar(B * C)
G = Graphic()
G.vector(A)
G.vector(B)
G.vector(C)
G.vector(R)
G.show()
print("Producto Punto (A * B) C + (B * C) A:" , R)
```



Producto Punto $(A * B) C + (B * C) A$: $[-142.00; 242.00; -168.00]$

(d) $D = A \times B$

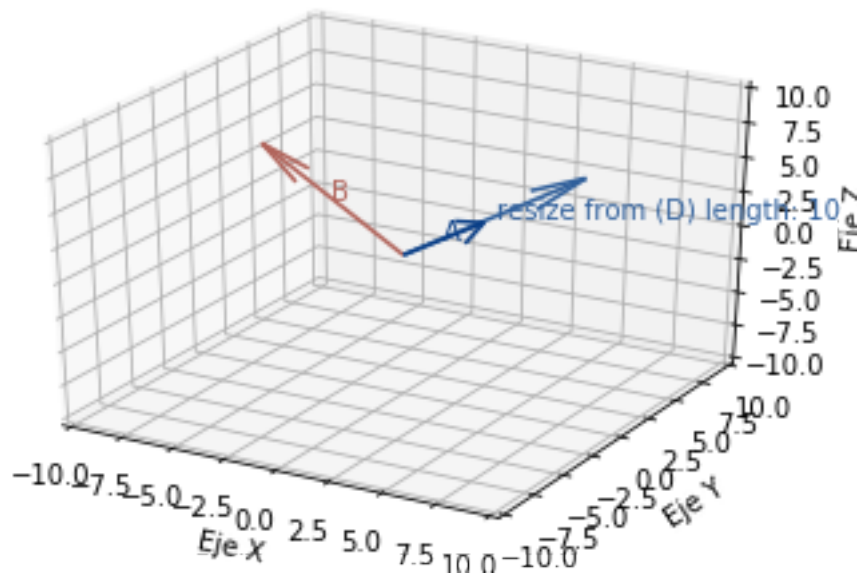
```
[16]: D = A.productCrux(B, length=10)
D.setLabel('D')
G = Graphic()
G.vector(A)
G.vector(B)
G.vector(D)
G.show()
print("A X B = D:{}".format(D))
```



$A \times B = D: [-3.69; -9.00; -2.31]$

(e) $D = B \times A$

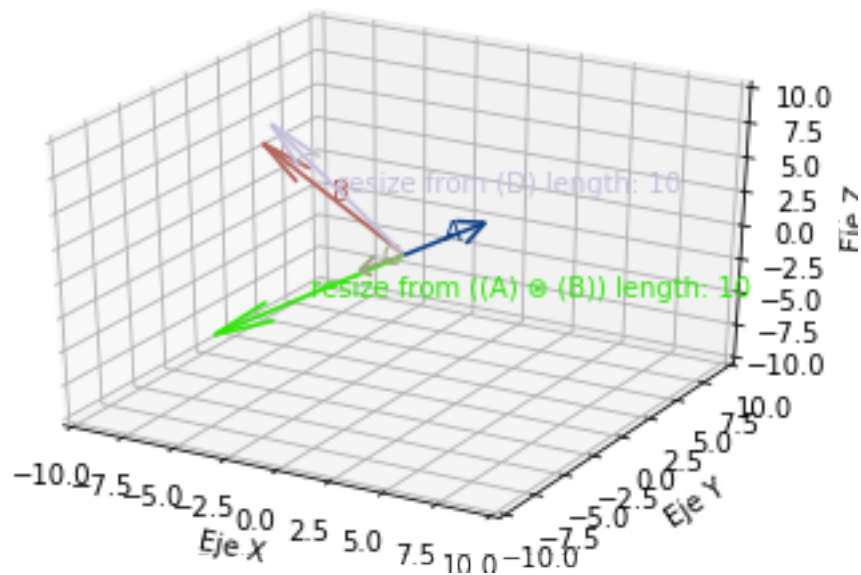
```
[17]: D = B.productCrux(A)
      D.setLabel('D')
      G = Graphic()
      G.vector(A)
      G.vector(B)
      G.vector(D.resize(10))
      G.show()
      print("B X A = D:{}".format(D))
```



$B \times A = D: [32.00; 78.00; 20.00]$

(f) $D = (A \times B) \times C$

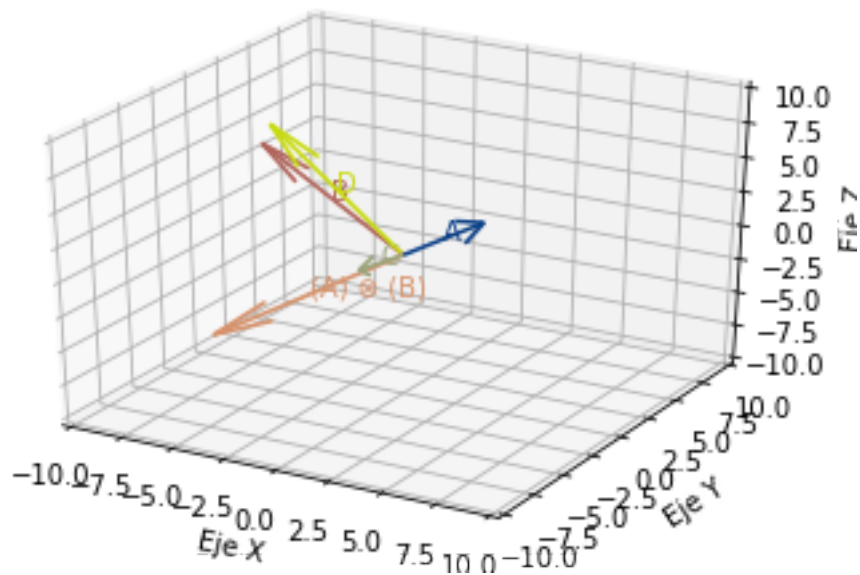
```
[18]: AXB = A.productCrux(B)
      D = AXB.productCrux(C)
      D.setLabel('D')
      G = Graphic()
      G.vector(A)
      G.vector(B)
      G.vector(C)
      G.vector(D.resize(10))
      G.vector(AXB.resize(10))
      G.show()
      print("(A X B) X C:{}".format(D))
```



(A X B) X C: [-374.00; 56.00; 380.00]

(g) $D = A \times (B \times C)$

```
[19]: AXB = A.productCrux(B, length=10)
D = AXB.productCrux(C, length=10)
D.setLabel('D')
G = Graphic()
G.vector(A)
G.vector(B)
G.vector(C)
G.vector(D)
G.vector(AXB)
G.show()
print("(A X B) X C:{}".format(D))
```

$(A \times B) \times C: [-6.98; 1.04; 7.09]$

7 Ejercicio 5

Se ingresan dos vectores. Qué condición óptima aplica para que saber si los vectores son paralelos o perpendiculares?

```
[20]: x1 = float(input("Ingrese coordenada X del Vector u:\t"))
y1 = float(input("Ingrese coordenada Y del Vector u:\t"))
z1 = float(input("Ingrese coordenada Z del Vector u:\t"))
u = Vector(
    value=Coordinate(
        x=x1,
        y=y1,
        z=z1
    ),
    label='u',
    color=numpy.random.rand(3, )
)

x2 = float(input("Ingrese dirección X del Vector v:\t"))
y2 = float(input("Ingrese dirección Y del Vector v:\t"))
z2 = float(input("Ingrese dirección Z del Vector v:\t"))
v = Vector(
    value=Coordinate(
        x=x2,
        y=y2,
```

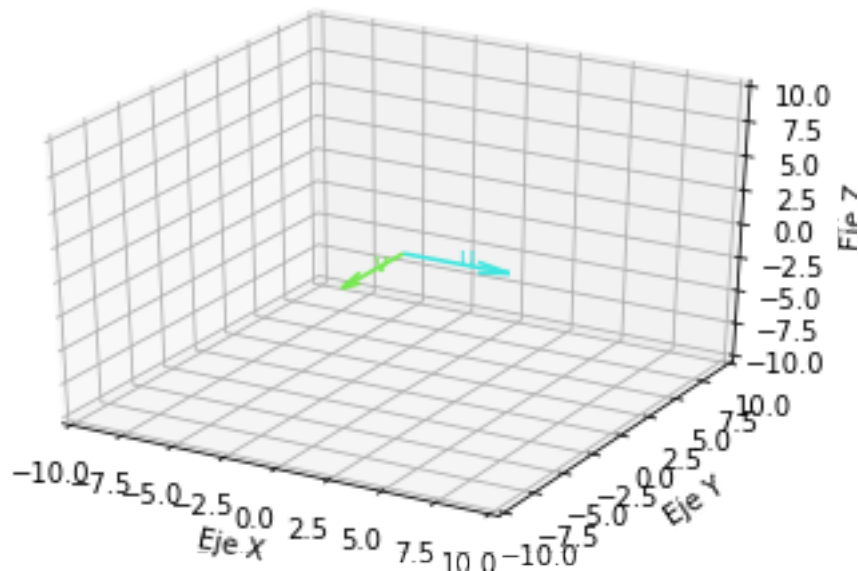
```

        z=z2
    ),
    label='v',
    color=numpy.random.rand(3, )
)

G=Graphic()
G.vector(u)
G.vector(v)
G.show()
print("Son paralelos:\t{}\nSon perpendiculares:\t{}".format(u.areParallels(v),u
    →u.arePerpendicular(v)))

```

Ingrese coordenada X del Vector u: 5
 Ingrese coordenada Y del Vector u: 0
 Ingrese coordenada Z del Vector u: 0
 Ingrese dirección X del Vector v: 0
 Ingrese dirección Y del Vector v: -5
 Ingrese dirección Z del Vector v: 0



Son paralelos: False
 Son perpendiculares: True

8 Anexos

8.1 Clase Grafico

```
[2]: import matplotlib.pyplot as plt
from Vector import Vector
import numpy as np
from mpl_toolkits.mplot3d import axes3d

class Graphic:

    DEFAULT_X_MIN = -10
    DEFAULT_X_MAX = 10
    DEFAULT_Y_MIN = -10
    DEFAULT_Y_MAX = 10
    DEFAULT_Z_MIN = -10
    DEFAULT_Z_MAX = 10

    def __init__(self, xmin=DEFAULT_X_MIN, xmax=DEFAULT_X_MAX,
        ymin=DEFAULT_Y_MIN, ymax = DEFAULT_Y_MAX, zmin = DEFAULT_Z_MIN, zmax =
        DEFAULT_Z_MAX):
        self.__figure__ = plt.figure()
        self.__axis__ = self.__figure__.gca(projection='3d')
        self.__axis__.set(xlim=(xmin, xmax), ylim=(ymin, ymax),
        zlim=(zmin,zmax), xlabel='Eje X', ylabel='Eje Y', zlabel='Eje Z')

    def vector(self, v: Vector):
        self.__axis__.text((v.destiny.x + v.origin.x) / 2, (v.destiny.y + v.
        origin.y) / 2, (v.destiny.z + v.origin.z) / 2, v.label, color=v.color)
        return self.__axis__.quiver(v.origin.x, v.origin.y, v.origin.z, v.
        value.x, v.value.y, v.value.z, color=v.color)

    def show(self):
        plt.show()
```

```
[ ]:
```

8.2 Clase Coordinada

```
[1]: class Coordinate:
    DEFAULT_X = 0
    DEFAULT_Y = 0
    DEFAULT_Z = 0

    def __init__(self, x=DEFAULT_X, y=DEFAULT_Y, z=DEFAULT_X):
        self.__x__ = x
```

```

        self.__y__ = y
        self.__z__ = z

    @property
    def x(self):
        return self.__x__

    @property
    def y(self):
        return self.__y__

    def __add__(self, other):
        return Coordinate(x=self.__x__ + other.__x__, y=self.__y__ + other.
→ __y__, z=self.__z__ + other.__z__)

    def __sub__(self, other):
        return Coordinate(x=self.__x__ - other.__x__, y=self.__y__ - other.
→ __y__, z=self.__z__ - other.__z__)

    @property
    def z(self):
        return self.__z__

    def mulEscalar(self, number):
        return Coordinate(x=self.x * number, z=self.z * number, y=self.y *
→ number)

    def __str__(self):
        return '({}, {}, {})'.format(self.__x__, self.__y__, self.__z__)

```

8.3 Class Vector

```

[2]: class Vector:
    DEFAULT_ORIGIN = Coordinate()
    DEFAULT_VALUE = Coordinate()
    DEFAULT_LABEL = "v"
    DEFAULT_COLOR = "b"

    def __init__(self, origin=DEFAULT_ORIGIN, value=DEFAULT_VALUE,
→ label=DEFAULT_LABEL, color=DEFAULT_COLOR):
        self.__origin__ = origin
        self.__value__ = value
        self.__label__ = label
        self.__color__ = color

    def __add__(self, other):

```

```

        return Vector(origin=self.origin, value=self.value + other.value,
↳color=numpy.random.rand(3, ),
                        label='({}) + ({}).format(self.label, other.label))

    def __sub__(self, other):
        return Vector(origin=self.origin, value=self.value - other.value,
↳color=numpy.random.rand(3, ),
                        label='({}) - ({}).format(self.label, other.label))

    def setOrigin(self, origen=Coordinate()):
        self.__origin__ = origen

    def setLabel(self, label):
        self.__label__ = label

    @property
    def color(self):
        return self.__color__

    @property
    def label(self):
        return self.__label__

    @property
    def origin(self):
        return self.__origin__

    @property
    def destiny(self):
        return self.origin + self.value

    @property
    def value(self):
        return self.__value__

    @property
    def length(self):
        return float(math.sqrt(self.value.x ** 2 + self.value.y ** 2 + self.
↳value.z ** 2))

    def mulEscalar(self, number):
        return Vector(origin=self.origin, value=self.value.mulEscalar(number),
                        label=str(number) + '*( ' + self.label + ' )', color=numpy.
↳random.rand(3, ))

    def __str__(self):

```

```

        return "[{}; {}; {}]".format("{:.2f}".format(self.value.x), "{:.2f}".
↪format(self.value.y),
                                     "{:.2f}".format(self.value.z))

def __matrixRotationZ(self, radians):
    return [
        [math.cos(radians), -1 * math.sin(radians), 0],
        [math.sin(radians), math.cos(radians), 0],
        [0, 0, 1]
    ]

def __matrixRotationY(self, radians):
    return [
        [math.cos(radians), 0, math.sin(radians)],
        [0, 1, 0],
        [-1 * math.sin(radians), 0, math.cos(radians)]]

def __matrixRotationX(self, radians):
    return [
        [1, 0, 0],
        [0, math.cos(radians), -1 * math.sin(radians)],
        [0, math.sin(radians), math.cos(radians)]]

def list(self):
    return [[ self.value.x ],[ self.value.y],[self.value.z ]]

def rotateZ(self, grades):
    radians = grades*math.pi/180
    self.__rotate__(self.__matrixRotationZ(radians))

def rotateY(self, grades):
    radians = grades * math.pi / 180
    self.__rotate__(self.__matrixRotationY(radians))

def rotateX(self, grades):
    radians = grades * math.pi / 180
    self.__rotate__(self.__matrixRotationX(radians))

def __rotate__(self, matrix):
    array = numpy.dot(matrix, self.list())
    x, y, z = numpy.transpose(array).tolist()[0]
    length = self.length
    self.__value__ = Coordinate(x, y, z)

def __mul__(self, vector):
    return self.value.x * vector.value.x + self.value.y * vector.value.y +
↪self.value.z * vector.value.z

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def angle(self, vector):
    return float(math.acos((self * vector)/(self.length * vector.length)))

def productCrux(self, vector, length = None):
    label = "({})  ({}).format(self.label, vector.label)
    crux = Vector(
        value=Coordinate(
            x=self.value.y * vector.value.z - self.value.z * vector.value.y,
            y=self.value.z * vector.value.x - self.value.x * vector.value.z,
            z=self.value.x * vector.value.y - self.value.y * vector.value.
→x),
        label=label,
        color=numpy.random.rand(3, )
    )
    if length is not None:
        crux_resize = crux.resize(length)
        crux_resize.setLabel(label)
        return crux_resize
    else:
        return crux

def unitaryVector(self):
    length = self.length
    return Vector(
        value=Coordinate(
            x=self.value.x/length,
            y=self.value.y/length,
            z=self.value.z/length,
        ),
        label="unitary({}).format(self.label),
        color=numpy.random.rand(3, )
    )

def resize(self, length):
    new_vector = self.unitaryVector()
    new_vector.__value__ = Coordinate(
        x=new_vector.value.x*length,
        y=new_vector.value.y*length,
        z=new_vector.value.z*length
    )
    new_vector.setLabel("resize from ({} length: {}".format(self.label,
→length))
    return new_vector

def areParallels(self, vector):
    try:

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        dx = self.value.x / vector.value.x
        dy = self.value.y / vector.value.y
        dz = self.value.z / vector.value.z
        return dx == dy and dx == dz
    except:
        return False

def arePerpendicular(self, vector):
    return self * vector == 0
```

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[ ]:
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