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Computing IV: Project Portfolio  
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## PS0 – Hello World with SFML

The goal of our first assignment was to get us used to using the SFML libraries with our c++ code, as well as giving me some insight on how we would write our expressions and variables for future assignments. We are given most of the code for this assignment already, as it's part of the setup for the SFML libraries. All we needed to do was simply modify the given code so that we could create our own sprite ( i.e any .PNG file ) and have it move around the screen. For extra credit we could implement an additional feature, What I ended up doing for an extra feature is binding the key binds for the sprite's movement with a specific color in the SFML libraries Up is associated with Blue, the down arrow is associated with red, etc.

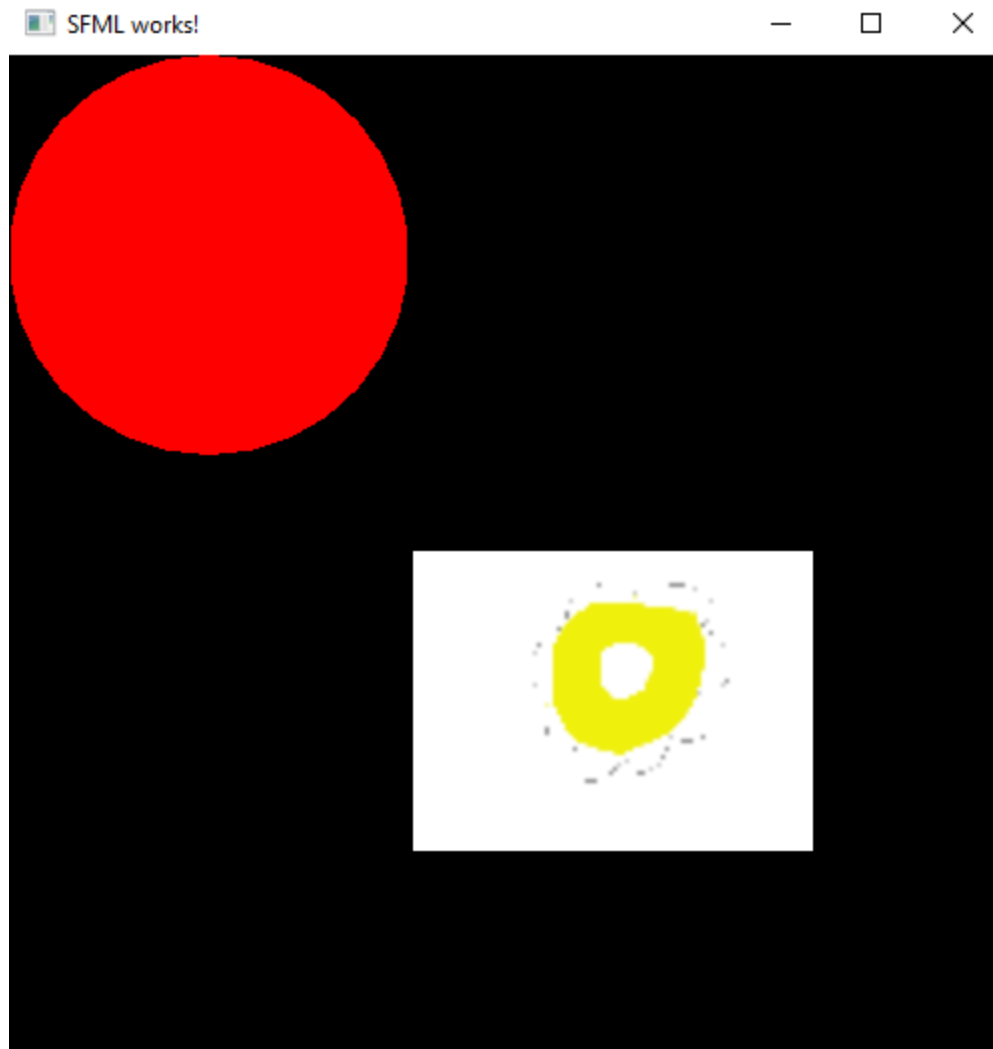
The following code is associated with PS0

```
1 //Thomas Freeman
2 // implementation of main.cpp
3 // 9/13/21
4
5
6 #include <SFML/Graphics.hpp>
7 #include <iostream>
8
9 int main() {
10
11     // Create the window
12     sf::RenderWindow window(sf::VideoMode(500, 500), "SFML works!");
13
14     // Load a sprite
15     sf::Texture texture;
16     if (!texture.loadFromFile("sprite.png"))
17         return EXIT_FAILURE;
18     sf::Sprite sprite(texture);
19
20     // Create a circle
21     sf::CircleShape shape(100.f);
22     shape.setFillColor(sf::Color::Blue);
23
24
25
26     while (window.isOpen()) {
27         sf::Event event;
28         while (window.pollEvent(event)) {
29             if (event.type == sf::Event::Closed)
30                 window.close();
31
32
33         }
34
35         window.clear();
36
37     }
```

```

38
39
40     float offsetX = 0;
41     float offsetY = 0;
42
43     // Get current position of the sprite
44     sf::Vector2f pos = sprite.getPosition();
45
46     // Moves the sprite around
47     if (sf::Keyboard::isKeyPressed(sf::Keyboard::Left) && pos.x != 0)
48         offsetX = -1;
49     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::Right) && pos.x !=
400 - 198)
50         offsetX = 1;
51     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::Up) && pos.y != 0)
52         offsetY = -1;
53     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::Down) &&
pos.y != 400 - 152)
54         offsetY = 1;
55     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::Right))
56         shape.setFillColor(sf::Color::Magenta);
57     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::Left))
58         shape.setFillColor(sf::Color::Yellow);
59     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::Up))
60         shape.setFillColor(sf::Color::Blue);
61     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::Down))
62         shape.setFillColor(sf::Color::Red);
63     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::R)) {
64         sprite.setPosition(0, 0);
65         pos.x = pos.y = 0;
66     }
67     else if (sf::Keyboard::isKeyPressed(sf::Keyboard::Escape))
68         window.close();
69
70     // Assign it to a new position
71     sprite.setPosition(pos.x + offsetX, pos.y + offsetY);
72
73     // Draw the images
74     window.draw(shape);
75     window.draw(sprite);
76
77     window.display();
78 }
79
80 return 0;
81 }

```



### PS1 Linear Feedback Shift Register and Image Encoding

This was our first two-part assignment so I will explain my solution for the first part. To begin PS1, we needed to create our Linear Feedback shift register, operating with 16-bit Fibonacci as our given linear function. There are two methods that are implemented in this first part. Firstly, is the step function, which simulates one step of the LFSR given a seed to use. Generate is the other, simulating the step function k times such that necessary arithmetic of multiple steps is shown at the end. The output of this program is a dynamic array of integers ( 1's and 0's ) that show the steps that came out of the generate function. This assignment was also our introduction to using the boost libraries in order to test certain outputs in our code. I tested for if a given string was 16 bits in length and if the input was properly done (I.e without spaces, unnecessary characters, etc). If either of these tests fail, errors are thrown.

The following is code for ps1a

```

1 CC = g++
2 CFLAGS = -std=c++11 -c -g -Og -Wall -Werror -pedantic
3 LFLAGS = -lboost_unit_test_framework
4 OBJS = test.o FibLFSR.o
5 EXE = ps1a
6 all : $(EXE)
7 ps1a : $(OBJS)
8     $(CC) $(OBJS) -o $(EXE) $(LFLAGS)
9 test.o : test.cpp
10    $(CC) $(CFLAGS) test.cpp
11 FibLFSR.o : FibLFSR.cpp FibLFSR.h
12    $(CC) $(CFLAGS) FibLFSR.cpp
13 clean :
14    \rm *.o $(EXE)

1 // Thomas Freeman
2 // test.cpp for PS1a
3 // Provided test file that I modified with my own Boost tests
4 #include <iostream>
5 #include <string>
6 #include "FibLFSR.h"
7 #define BOOST_TEST_DYN_LINK
8 #define BOOST_TEST_MODULE Main
9 #include <boost/test/unit_test.hpp>
10 BOOST_AUTO_TEST_CASE(sixteenBitsThreeTaps) {
11     FibLFSR l("1011011000110110");
12     BOOST_REQUIRE(l.step() == 0);
13     BOOST_REQUIRE(l.step() == 0);
14     BOOST_REQUIRE(l.step() == 0);
15     BOOST_REQUIRE(l.step() == 1);
16     BOOST_REQUIRE(l.step() == 1);
17     BOOST_REQUIRE(l.step() == 0);
18     BOOST_REQUIRE(l.step() == 0);
19     BOOST_REQUIRE(l.step() == 1);
20     FibLFSR l2("1011011000110110");
21     BOOST_REQUIRE(l2.generate(9) == 51);
22 }
23 // First test case shows simple input and output using the
24 // test value from the initial test case.
25 BOOST_AUTO_TEST_CASE(my_test1) {
26
27     std::cout << "First Test" << std::endl;
28     FibLFSR lfsr("1011011000110110");
29     std::cout << " Original seed: " << lfsr << std::endl;
30
31     int result = lfsr.generate(5);
32     BOOST_REQUIRE(result == 3);

```

```

33
34     std::cout << "After generate(5): " << lfsr << " " << result <<
35     std::endl;
36     std::cout << std::endl;
37 }
38
39 // This test is meant to show when an input seed
40 // is too long or too short.
41 BOOST_AUTO_TEST_CASE(my_test2) {
42
43     std::cout << "\n Test Case #2" << std::endl;
44     std::string testSeed1 = "111000110";
45     std::string testSeed2 = "00000000000000000001";
46
47     std::cout << "Seed is less than 16 bits : "
48         << std::endl;
49     BOOST_REQUIRE_THROW(FibLFSR("0101100101"),
50 std::invalid_argument);
51
52     std::cout << "Seed is more than 16 bits : "
53         << "0111011000110110101100" << std::endl;
54     BOOST_REQUIRE_THROW(FibLFSR("0111011000110110101100"),
55         std::invalid_argument);
56 }

1 // Thomas Freeman
2 // implementation of FibLFSR.h
3 // Simple header file to prevent building
4 // this register from becoming a nightmare.
5
6
7
8 #ifndef FIBLFSR_H
9 #define FIBLFSR_H
10 #include <iostream>
11 #include <exception>
12
13 class FibLFSR {
14 public:
15     FibLFSR(std::string seed);
16     //Constructor creates LFSR with a given seed and set of tap bits
17
18     explicit FibLFSR(FibLFSR& copyLFSR);
19     explicit FibLFSR(FibLFSR&& moveLFSR) noexcept;
20     ~FibLFSR();
21     FibLFSR& operator=(const FibLFSR& rvalue);
22     FibLFSR& operator=(FibLFSR&& rvalue) noexcept;
23
24     int step(); // Shows one step in the algorithm and
25     returns a bit

```

```

26     int generate(int k);    // Shows a given number of steps (k) and
27     returns a value.
28
29     // Displays the register
30     friend std::ostream& operator<<(std::ostream& out, const FibLFSR&
31     flfsr);
32
33 private:
34     int size;                // Register size
35     int* reg;                // Defines register as an array of integers
36 };
37 #endif

```

```

1 // Thomas Freeman
2 // implementation of FibLFSR.cpp
3 // This code is what builds and allows the
4 // sixteen bit linear feedback register to perform operations
5 // along with allowing tests to be used via the boost library's.
6 // I did this by using an array to store the string of bits and
7 // wrote out the step and generate functions.
8
9
10 #include "FibLFSR.h"
11 #define ASCII_OFFSET 48
12
13 // Our FibLFSR constructor, uses a 16 character
14 // string as input
15 FibLFSR::FibLFSR(std::string seed) {
16
17     size = seed.length();
18     if (size == 16) {
19         reg = new int[size];
20
21         int count = 0;
22         for (int i = size - 1; i >= 0; i--) {
23             reg[i] = (int)seed[count] - ASCII_OFFSET;
24             count++;
25         }
26     }
27
28     else {
29
30         reg = nullptr;
31         size = 0;
32         //No try-catch block for BOOST tests
33         throw std::invalid_argument(
34             "Seeds are sixteen bits only!");
35     }
36 }
37
38 FibLFSR::FibLFSR(FibLFSR& copyLFSR) {

```

```

39
40     size = copyLFSR.size;
41     if (size > 0) {
42         reg = new int[size];
43         for (int i = 0; i < size; i++) {
44             reg[i] = copyLFSR.reg[i];
45         }
46     }
47     else reg = nullptr;
48 }
49
50 FibLFSR::FibLFSR(FibLFSR&& moveLFSR) noexcept {
51
52     size = moveLFSR.size;
53     reg = moveLFSR.reg;
54     moveLFSR.reg = nullptr;
55     moveLFSR.size = 0;
56 }
57
58 FibLFSR::~FibLFSR() {
59
60     if (reg != nullptr) delete[] reg;
61     reg = nullptr;
62     size = 0;
63 }
64
65
66 // The Assignment operators for
67 // Assigning new values.
68 FibLFSR& FibLFSR::operator=(const FibLFSR& rvalue) {
69
70     if (this == &rvalue) return *this;
71     if (reg != nullptr) delete[] reg;
72
73     size = rvalue.size;
74     if (size > 0) {
75         reg = new int[size];
76         for (int i = 0; i < size; i++) {
77             reg[i] = rvalue.reg[i];
78         }
79     }
80     return *this;
81 }
82
83 FibLFSR& FibLFSR::operator=(FibLFSR&& rvalue) noexcept {
84
85     if (this == &rvalue) return *this;
86     if (reg != nullptr) delete[] reg;
87
88     size = rvalue.size;
89     reg = rvalue.reg;
90     rvalue.reg = nullptr;
91     rvalue.size = 0;
92

```



```

93     return *this;
94 }
95
96
97 // Step allows us to show one step of the register, specifically the
98 // exclusive or operation on the leftmost bit. Returning the rightmost
99 bit.
100 int FibLFSR::step() {
101
102     int rightmostBit = reg[15] ^ reg[13];
103     rightmostBit ^= reg[12];
104     rightmostBit ^= reg[10];
105
106     // shifts each bit left except for the rightmost bit
107     for (int i = size - 1; i >= 1; i--) {
108         reg[i] = reg[i - 1];
109     }
110     reg[0] = rightmostBit;
111     // As a result, we create a new rightmost bit
112
113     return rightmostBit;
114 }
115
116
117 // Generate takes an int K and generates k number of steps for the
118 LFSR to produce int k
119 int FibLFSR::generate(int k) {
120
121     int result = 0;
122     for (int i = k; i > 0; i--) {
123         result *= 2;
124         result += step();
125     }
126     return result;
127 }
128
129 // Operator displays bits from highest to lowest index by overloading
130 the stream insertion operator
131 std::ostream& operator<<(std::ostream& out, const FibLFSR& flfsr) {
132
133     for (int i = flfsr.size - 1; i >= 0; i--) {
134         out << flfsr.reg[i];
135     }
136     return out;
137 }

```

All tests are ran with the same seed

```

Linux Lite Terminal -
File Edit View Terminal Tabs Help
Welcome to Linux Lite 5.6 osboxes

Thursday 09 December 2021, 15:34:06
Memory Usage: 487/3936MB (12.37%)
Disk Usage: 7/217GB (4%)
Support - https://www.linuxliteos.com/forums/ (Right click, Open Link)

osboxes ~ make
g++ -std=c++11 -c -g -Og -Wall -Werror -pedantic test.cpp
g++ -std=c++11 -c -g -Og -Wall -Werror -pedantic FibLFSR.cpp
g++ test.o FibLFSR.o -o ps1a -lboost_unit_test_framework
osboxes ~ ./ps1a
Running 3 test cases...
First Test
Original seed: 1011011000110110
After generate(5): 1100011011000011 3

Test Case #2
Seed is less than 16 bits :
Seed is more than 16 bits : 0111011000110110101100

*** No errors detected
osboxes ~

```

As for the second part of PS1, we needed to encode any image we wanted by implementing a new class to complement our LFSR. This new class contains a method called transform that takes a 16-bit seed and a given image and encodes said image via the step and generate functions. In order to get our outputs, we'd overload the stream operator to allow input and output to be done with our make files, becoming vital for future assignments. Eventually outputting two windows with the image before and after the encryption is done. This process can also be done in reverse taking an encrypted image and decrypting it to become normal again as well.

Here's the following code for ps1b

```

1 CC = g++
2 CFLAGS = -std=c++11 -c -g -Og
3 LIBS = -lsfml-graphics -lsfml-window -lsfml-system
4 OBJS = PhotoMagic.o FibLFSR.o
5 EXE = PhotoMagic
6 all : $(EXE)
7 PhotoMagic : $(OBJS)
8     $(CC) $(OBJS) -o $(EXE) $(LIBS)
9 FibLFSR.o : FibLFSR.cpp FibLFSR.h
10    $(CC) $(CFLAGS) FibLFSR.cpp
11 PhotoMagic.o : PhotoMagic.cpp

```

```

12 $(CC) $(CFLAGS) PhotoMagic.cpp
13 clean :
14 \rm *.o $(EXE)

1 //Thomas Freeman
2 //implementation of PhotoMagic.cpp
3 //Main method linked to FibLFSR that
4 //transforms the image using two file
5 //and a 16 bit input via the command line.
6 #include "FibLFSR.h"
7 #include <SFML/System.hpp>
8 #include <SFML/Window.hpp>
9 #include <SFML/Graphics.hpp>
10 //The register is responsible for transforming the image
11 void transform(sf::Image& img, FibLFSR* flfsr);
12 int main(int argc, char* argv[]) {
13     if (argc != 4) {
14         std::cerr << "Usage: " << argv[0] <<
15             " <input file> <output file> <16 bit binary seed>" << std::endl;
16         return -1;
17     }
18
19     FibLFSR flfsr;
20     try {
21         flfsr = FibLFSR(argv[3]);
22     }
23     catch (std::invalid_argument invalid) {
24         std::cout << invalid.what() << std::endl;
25         return -1;
26     }
27     //Shows our two windows
28     sf::Image image;
29     if (!image.loadFromFile(argv[1])) { return -1; }
30     sf::Vector2u size = image.getSize();
31     sf::RenderWindow window1(sf::VideoMode(size.x, size.y), "Original");
32     sf::RenderWindow window2(sf::VideoMode(size.x, size.y), "Encrypted/"
33         "Decrypted");
34     //displays the images
35     sf::Texture texture1;
36     texture1.loadFromImage(image);
37     sf::Sprite spritel;
38     spritel.setTexture(texture1);
39     transform(image, &flfsr); //calls transform for the image file
40     sf::Texture texture2;
41     texture2.loadFromImage(image);
42     sf::Sprite sprite2;
43     sprite2.setTexture(texture2);
44     // Allows both windows to be open at the same time
45     while (window1.isOpen() && window2.isOpen()) {
46         sf::Event event;
47         while (window1.pollEvent(event)) {

```

```

48         if (event.type == sf::Event::Closed) { window1.close(); }
49     }
50     while (window2.pollEvent(event)) {
51         if (event.type == sf::Event::Closed) { window2.close(); }
52     }
53     window1.clear();
54     window1.draw(sprite1);
55     window1.display();
56     window2.clear();
57     window2.draw(sprite2);
58     window2.display();
59 }
60 if (!image.saveToFile(argv[2])) { return -1; }
61 return 0;
62 }
63 //Implementation of the transform method to alter the pixels
64 void transform(sf::Image& img, FibLFSR* flfsr) {
65     sf::Vector2u size = img.getSize();
66     sf::Color p;          //p is for pixel
67     for (int x = 0; x < (int)size.x; x++) {
68         for (int y = 0; y < (int)size.y; y++) {
69             p = img.getPixel(x, y);
70             p.r ^= flfsr->generate(8);
71             p.g ^= flfsr->generate(8);
72             p.b ^= flfsr->generate(8);
73             img.setPixel(x, y, p);
74         }
75     }
76 }

```

```

1 //Thomas Freeman
2 //Implementation of FibLFSR.cpp header file
3 //Sets up and displays all methods like ps1a
4 #include <iostream>
5 #include <exception>
6 #include <math.h>
7 #ifndef FIBLFSR_H
8 #define FIBLFSR_H
9 #define ASCII_OFFSET 48
10 class FibLFSR {
11 public:
12     FibLFSR();
13     FibLFSR(std::string seed); // Constructor for the register
14                               // with the seed and tap
15     explicit FibLFSR(const FibLFSR& copyFibLFSR);
16     explicit FibLFSR(FibLFSR&& moveFibLFSR) noexcept;
17     ~FibLFSR();
18     FibLFSR& operator=(const FibLFSR& rvalue);
19     FibLFSR& operator=(FibLFSR&& rvalue) noexcept;
20     int step(); // simulates a step of the register
21 }

```

```

22     int generate(int k);      // simulates k steps of the register
23     //Register is displayed
24     friend std::ostream& operator<<(std::ostream& out, const FibLFSR&
25     flfsr);
26 private:
27     int size;                // register size
28     int* reg;                // integers in an array for the register
29 };
30 #endif

```

```

1 //Thomas Freeman
2 //Implementation of FibLFSR.cpp
3 //Tweaked from the first part to allow for
4 //the intended tap bits to work with the register.
5 //this allows each shift to help in encrypting the
6 //given image.
7 #include "FibLFSR.h"
8 #define TAP_BIT1 13
9 #define TAP_BIT2 12
10 #define TAP_BIT3 10
11 //The Constructors
12 FibLFSR::FibLFSR() : size(0), reg(nullptr) {}
13 FibLFSR::FibLFSR(std::string seed) {
14     size = seed.length();
15     if (size == 16) {
16         reg = new int[size];
17         int bit = 0;
18         int count = 0;
19         for (int i = size - 1; i >= 0; i--) {
20
21             bit = (int)seed[count] - ASCII_OFFSET;
22             if (bit == 0 || bit == 1) {
23                 reg[i] = bit;
24                 count++;
25             }
26             else {
27                 reg = nullptr;
28                 size = 0;
29                 throw std::invalid_argument("Incorrect seed, seed must be"
30                 " in binary form");
31             }
32         }
33     }
34     //Throws exception for strings > 16 bits
35     else {
36         reg = nullptr;
37         size = 0;
38         throw std::invalid_argument("Incorrect seed size, seed must be 16"
39         " bits long");
40     }
41 }

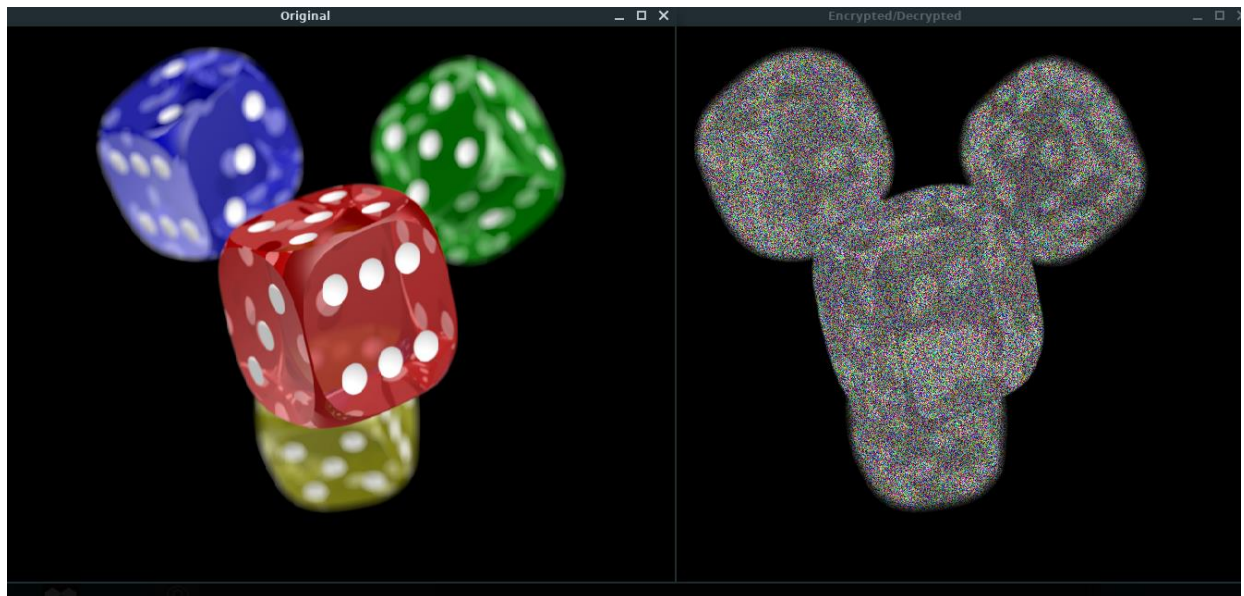
```

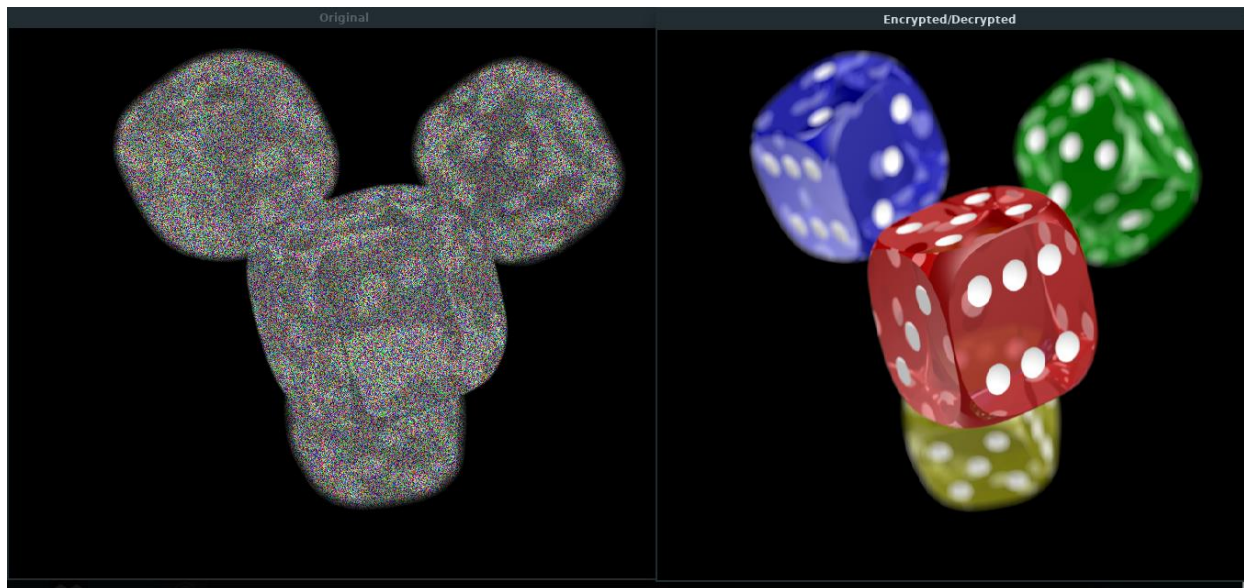
```

42 //Most of the code doesn't change in this method
43 FibLFSR::FibLFSR(const FibLFSR& copyLFSR) {
44     size = copyLFSR.size;
45     if (size > 0) {
46         reg = new int[size];
47         for (int i = 0; i < size; i++) {
48             reg[i] = copyLFSR.reg[i];
49         }
50     }
51     else reg = nullptr;
52 }
53 FibLFSR::FibLFSR(FibLFSR&& moveLFSR) noexcept {
54     size = moveLFSR.size;
55     reg = moveLFSR.reg;
56     moveLFSR.reg = nullptr;
57     moveLFSR.size = 0;
58 }
59 FibLFSR::~FibLFSR() {
60     if (reg != nullptr) delete[] reg;
61     reg = nullptr;
62     size = 0;
63 }
64 //Assignment operators need to be overloaded like lastime
65 FibLFSR& FibLFSR::operator=(const FibLFSR& rvalue) {
66     if (this == &rvalue) return *this;
67     if (reg != nullptr) delete[] reg;
68     size = rvalue.size;
69     if (size > 0) {
70         reg = new int[size];
71         for (int i = 0; i < size; i++) {
72             reg[i] = rvalue.reg[i];
73         }
74     }
75     return *this;
76 }
77 FibLFSR& FibLFSR::operator=(FibLFSR&& rvalue) noexcept {
78     if (this == &rvalue) return *this;
79     if (reg != nullptr) delete[] reg;
80     size = rvalue.size;
81     reg = rvalue.reg;
82     rvalue.reg = nullptr;
83     rvalue.size = 0;
84     return *this;
85 }
86 //Substitute the Tap bits into the step function
87 int FibLFSR::step() {
88     int rightmostBit = reg[size - 1] ^ reg[TAP_BIT1];
89     rightmostBit ^= reg[TAP_BIT2];
90     rightmostBit ^= reg[TAP_BIT3];
91     //Still shifts the bits from left to right
92     for (int i = size - 1; i >= 1; i--) {
93         reg[i] = reg[i - 1];
94     }
95     reg[0] = rightmostBit; //assigns the rightmost bit

```

```
96     return rightmostBit;
97 }
98 //generate method remains the same
99 int FibLFSR::generate(int k) {
100     int result = 0;
101     for (int i = k; i > 0; i--) {
102         result *= 2;
103         result += step();
104     }
105     return result;
106 }
107 // Stream insertion operator doesn't change again
108 std::ostream& operator<<(std::ostream& out, const FibLFSR& flfsr) {
109     for (int i = flfsr.size - 1; i >= 0; i--) {
110         out << flfsr.reg[i];
111     }
112     return out;
113 }
```





### PS2 – N-Body Simulation

This two-part assignment deals with simulating our own universe given some assets to use and text files to create simulation. For the first part, we just implemented a static universe into a single universe with our given assets. In order to output this, we overload the stream operator again to have the terminal determine input and output, since both classes are going to be drawable to the same window, we end up overriding the virtual draw function in our classes Celestial Body and Universe, allowing them to be drawn in the same window, otherwise they'd be in two different windows. I even did the extra credit for this assignment by implementing my own background (.jpg) called cosmos. How are the assets used? Well our input text files contain the number of objects in the universe on the first line and the radius of the universe on the second, with the rest of the file containing information on the planets, such as position based on x and y, and their mass. This positional data is stored as a vector in the universe class to ensure the planets are displayed in the right position. Velocity was included as well but this is only important for ps2b.

The following is the code for ps2a

```

1 CC = g++
2 CFLAGS = -std=c++11 -c -g
3 OBJS = main.o CelestialBody.o Universe.o
4 LIBS = -lsfml-graphics -lsfml-window -lsfml-system
5 EXE = NBody
6 all: $(EXE)
7 NBody: $(OBJS)

```



```

8      $(CC) $(OBJS) -o $(EXE) $(LIBS)
9  %.o: %.cpp
10     $(CC) $(CFLAGS) -o $@ $<
11 clean:
12     \rm $(OBJS) $(EXE)

1 //Thomas Freeman
2 //Implementation of main.cpp
3 //main deals with the command line,
4 //providing our necessary command and the data
5 //from our input
6 #include "Universe.h"
7 int main(int argc, char* argv[]) {
8     if (argc != 1) {
9         std::cerr << "Incorrect usage. Usage: ./NBody < filename.txt" <<
10 std::endl;
11         exit(-1);
12     }
13     Universe universe;
14     try {
15         universe = Universe("nbody/cosmos.jpg");
16     }
17     catch (std::invalid_argument err) {
18         std::cout << err.what() << std::endl;
19         exit(-1);
20     }
21     sf::Vector2u windowSize = universe.getImage().getSize();
22     sf::RenderWindow window(sf::VideoMode(windowSize.x, windowSize.y),
23 "The Solar System!");
24     //call universe for file inputs
25     std::cin >> universe;
26     //SFML window display
27     while (window.isOpen()) {
28         sf::Event event;
29         while (window.pollEvent(event)) {
30             if (event.type == sf::Event::Closed) { window.close(); }
31         }
32         window.clear();
33         window.draw(universe);
34         for (int i = 0; i < universe.getNumOfPlanets(); i++) {
35             window.draw(*universe.planets[i]);
36         }
37         window.display();
38     }
39     return 0;
40 }

```

```

1 #ifndef CELESTIALBODY_H
2 #define CELESTIALBODY_H
3 #include <iostream>
4 #include <exception>
5 #include <SFML/Graphics.hpp>
6 class CelestialBody : public sf::Drawable {
7 public:
8     // Necessary constructors
9     CelestialBody();
10    CelestialBody(float x_position, float y_position, float x_velocity,
11        float y_velocity, float init_mass, std::string image_filename);
12    //accessors and mutators
13    float getXPos() const;
14    float getYPos() const;
15    float getXVel() const;
16    float getYVel() const;
17    float getMass() const;
18    sf::Image getImage() const;
19    void setXPos(float xPos);
20    void setYPos(float yPos);
21    void setXVel(float xVel);
22    void setYVel(float yVel);
23    void setMass(float mass);
24    void setImage(std::string image_filename);
25    // updates the position of a given planet
26    void updatePosition();
27 private:
28    //override virtual draw function
29    void draw(sf::RenderTarget& target, sf::RenderStates states) const
30 override;
31    float xPos, yPos;           //positions of x and y
32    float xVel, yVel;           //Velocity of x and y
33    float mass;                 //given mass
34    sf::Image image;            //image data
35    sf::Texture texture;
36    sf::Sprite sprite;
37 };
38 #endif

1 #include "CelestialBody.h"
2 //constructors
3 CelestialBody::CelestialBody() : xPos(0), yPos(0), xVel(0), yVel(0),
4 mass(0) {}
5 CelestialBody::CelestialBody(float x_position, float y_position, float
6 x_velocity, float y_velocity, float init_mass, std::string
7 image_filename) {
8     if (!image.loadFromFile(image_filename)) {
9         throw std::invalid_argument("Celestial Body image file not found,
10 exiting.");
11     }
12     texture.loadFromImage(image);

```

```

13     sprite.setTexture(texture);
14     xPos = x_position;    yPos = y_position;
15     xVel = x_velocity;    yVel = y_velocity;
16     mass = init_mass;
17 }
18 //accessors and mutators
19 float CelestialBody::getXPos() const { return xPos; }
20 float CelestialBody::getYPos() const { return yPos; }
21 float CelestialBody::getXVel() const { return xVel; }
22 float CelestialBody::getYVel() const { return yVel; }
23 float CelestialBody::getMass() const { return mass; }
24 sf::Image CelestialBody::getImage() const { return image; }
25 void CelestialBody::setXPos(float x_position) { xPos = x_position; }
26 void CelestialBody::setYPos(float y_position) { yPos = y_position; }
27 void CelestialBody::setXVel(float x_velocity) { xVel = x_velocity; }
28 void CelestialBody::setYVel(float y_velocity) { yVel = y_velocity; }
29 void CelestialBody::setMass(float mass) { mass = mass; }
30 void CelestialBody::setImage(std::string image_filename) {
31     if(!image.loadFromFile(image_filename)) {
32         throw std::invalid_argument("Celestial Body image file not
33 found, exiting.");
34     }
35     texture.loadFromImage(image);
36     sprite.setTexture(texture);
37 }
38 //update x and y position of planet
39 void CelestialBody::updatePosition() {
40     sprite.setPosition(xPos, yPos);
41 }
42 //override virtual draw function
43 void CelestialBody::draw(sf::RenderTarget& target, sf::RenderStates
44 states) const {
45     target.draw(sprite, states);
46 }

```

```

1 //Thomas Freeman
2 //Implementation of Universe.h
3 //Header file declaring all methods in
4 //Universe.cpp
5 #ifndef UNIVERSE_H
6 #define UNIVERSE_H
7 #include "CelestialBody.h"
8 #include <vector>
9 class Universe : public sf::Drawable {
10 public:
11     // Our constructors
12     Universe();
13     Universe(std::string image_filename);
14     explicit Universe(const Universe& copyUniverse);
15     explicit Universe(Universe&& moveUniverse) noexcept;
16     ~Universe();

```

```

17     //accessors and mutators
18     int getNumOfPlanets() const;
19     float getRadius() const;
20     sf::Image getImage() const;
21     void setNumOfPlanets(int n);
22     void setRadius(float r);
23     void setImage(std::string image_filename);
24     //overloaded assignment operators
25     Universe& operator=(Universe& rvalue);
26     Universe& operator=(Universe&& rvalue) noexcept;
27     //vector of pointers to celestial bodies
28     std::vector<CelestialBody*> planets;
29     //overloaded insertion operator for file input through terminal
30     friend std::istream& operator>>(std::istream& in, Universe&
31 universe);
32
33 private:
34     //override virtual draw function
35     void draw(sf::RenderTarget& target, sf::RenderStates states) const
36 override;
37     int numOfPlanets;
38     float radius;                //radius of universe
39     sf::Image image;             //image data for universe
40     sf::Texture texture;
41     sf::Sprite sprite;
42 };
43 #endif

```

```

1 //Thomas Freeman
2 //Implementation of Universe.cpp
3 //This program builds the universe from any
4 //of the Nbody files, throwing exceptions for
5 //incorrect inputs and gathering all data values
6 //needed to display the image
7 #include "Universe.h"
8 //Set of constructors to create the universe
9 Universe::Universe() : numOfPlanets(0), radius(0) {}
10 //Basic exception for unavailable image file
11 Universe::Universe(std::string image_filename) {
12     if(!image.loadFromFile(image_filename)) {
13         throw std::invalid_argument("Universe image file not found,
14 exiting.");
15     }
16     texture.loadFromImage(image);
17     sprite.setTexture(texture);
18     numOfPlanets = 0;
19     radius = 0;
20 }
21 Universe::Universe(const Universe& copyUniverse) {
22     numOfPlanets = copyUniverse.numOfPlanets;
23     radius = copyUniverse.radius;

```

```

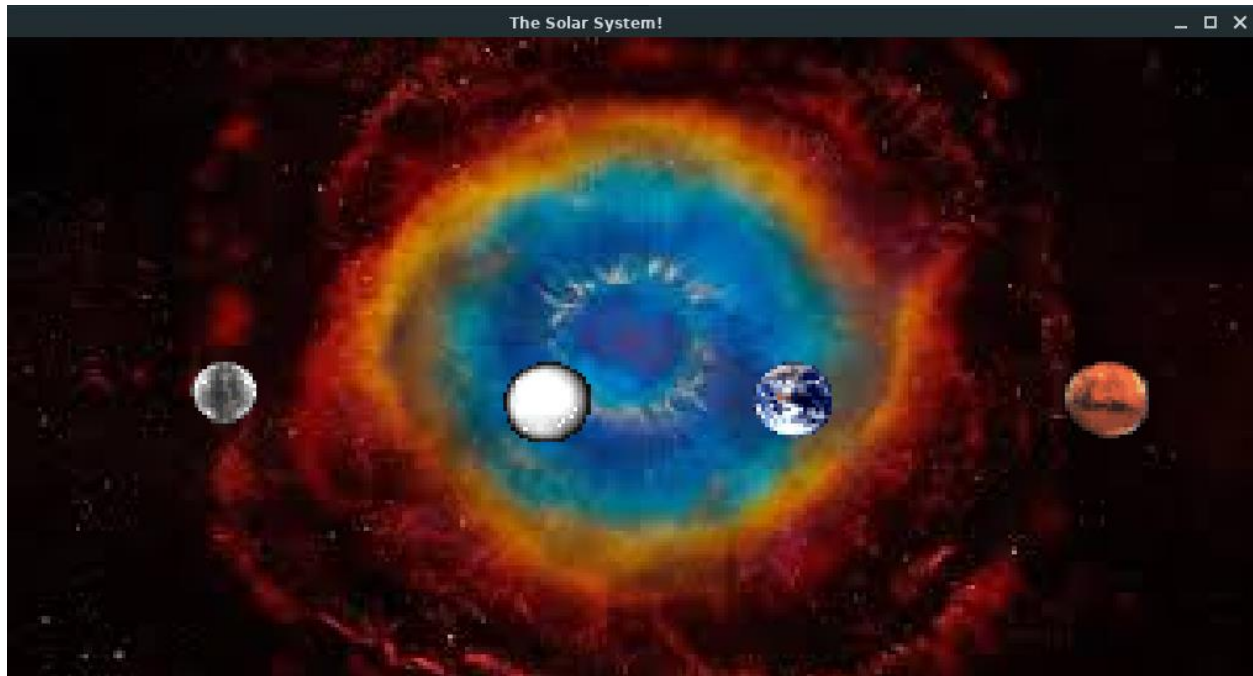
24         image = copyUniverse.image;
25         texture.loadFromImage(image);
26         sprite.setTexture(texture);
27     }
28     Universe::Universe(Universe&& moveUniverse) noexcept {
29         numOfPlanets = moveUniverse.numOfPlanets;
30         radius = moveUniverse.radius;
31         image = moveUniverse.image;
32         texture.loadFromImage(image);
33         sprite.setTexture(texture);
34         moveUniverse.numOfPlanets = 0;
35         moveUniverse.radius = 0;
36     }
37     Universe::~~Universe() {
38         numOfPlanets = 0;
39         radius = 0;
40     }
41     //Allows the mutation and access of values
42     int Universe::getNumOfPlanets() const { return numOfPlanets; }
43     float Universe::getRadius() const { return radius; }
44     sf::Image Universe::getImage() const { return image; }
45     void Universe::setNumOfPlanets(int n) { numOfPlanets = n; }
46     void Universe::setRadius(float r) { radius = r; }
47     void Universe::setImage(std::string image_filename) {
48         if(!image.loadFromFile(image_filename)) {
49             throw std::invalid_argument("Universe image file not found,
50 exiting.");
51         }
52         texture.loadFromImage(image);
53         sprite.setTexture(texture);
54     }
55     //overloaded assingment operators
56     Universe& Universe::operator=(Universe& rvalue) {
57         if (this == &rvalue) { return *this; }
58         numOfPlanets = rvalue.numOfPlanets;
59         radius = rvalue.radius;
60         image = rvalue.image;
61         texture.loadFromImage(image);
62         sprite.setTexture(texture);
63         return *this;
64     }
65     Universe& Universe::operator=(Universe&& rvalue) noexcept {
66         if (this == &rvalue) { return *this; }
67         numOfPlanets = rvalue.numOfPlanets;
68         radius = rvalue.radius;
69         image = rvalue.image;
70         texture.loadFromImage(image);
71         sprite.setTexture(texture);
72         rvalue.numOfPlanets = 0;
73         rvalue.radius = 0;
74         return *this;
75     }
76     // Overload the stream operator to allow terminal input
77     std::istream& operator>>(std::istream& in, Universe& universe) {

```

```

78     float fval;
79     std::string image;
80     sf::Vector2u windowSize = universe.getImage().getSize();
81     in >> universe.numOfPlanets;
82     in >> universe.radius;
83     // get the data for a planet
84     for (int i = 0; i < universe.numOfPlanets; i++) {
85         CelestialBody* planet = new CelestialBody();
86         // Gets planet x
87         in >> fval;
88         fval = (((fval / 2) / universe.radius) * windowSize.x) +
89(windowSize.x / 2);
90         planet->setXPos(fval);
91         //Gets planet y
92         in >> fval;
93         fval = (((fval / 2) / universe.radius) * windowSize.y) +
94(windowSize.y / 2);
95         planet->setYPos(fval);
96         planet->updatePosition();
97         //Gets necessary info
98         in >> fval;
99         planet->setXVel(fval);
100        in >> fval;
101        planet->setYVel(fval);
102        in >> fval;
103        planet->setMass(fval);
104        in >> image;
105        image = "nbody/" + image;
106        try {
107            planet->setImage(image);
108        }
109        catch (std::invalid_argument err) {
110            std::cout << err.what() << std::endl;
111            exit(-1);
112        }
113        universe.planets.push_back(planet);
114    }
115
116    return in;
117 }
118 //override virtual draw function
119 void Universe::draw(sf::RenderTarget& target, sf::RenderStates
120 states) const {
121     target.draw(sprite, states);
122 }

```



Part two had us implement the correct physics and animation for our universe. The planets need their x and y position values updated every second based upon the x and y values of their velocity. In order to preserve the accuracy of the numbers in the text files, all calculations are done in double. These include Velocity, Acceleration, Force, Net force, and a special one, gravity. Gravity is special as it's the only calculation based upon two celestial bodies. A function is made for pairwise force calculating on the pull between two bodies based upon their mass and distance from each other. As for extra credit, I added a loop into the main function that plays our given sound file and even created my own text file to simulate the universe based upon planets.txt. All that was needed was alternate values for xpos, ypos, xvel, etc, in order for the text file to update the positions when the program was ran.

The following is the code for ps2b

```
1 CC = g++
2 CFLAGS = -std=c++14 -c -g -Og -Wall -Werror -pedantic
3 OBJS = main.o CelestialBody.o Universe.o
4 LIBS = -lsfml-graphics -lsfml-audio -lsfml-window -lsfml-system
5 EXE = NBody
6 all: $(EXE)
7 NBody: $(OBJS)
8     $(CC) $(OBJS) -o $(EXE) $(LIBS)
9 %.o: %.cpp
10    $(CC) $(CFLAGS) -o $@ $<
11 clean:
12    \rm $(OBJS) $(EXE)
```

```

1 //Thomas Freeman
2 //Implementation of main.cpp
3 //main deals with the command line,
4 //providing our necessary command and the data
5 //from our input
6 #include "Universe.h"
7 #include <fstream>
8 #include <SFML/Audio.hpp>
9 // This time our command takes
10 int main(int argc, char* argv[]) {
11     if (argc != 3) {
12         std::cerr << "usage: ./Nbody T Î"t < input_file" << std::endl;
13         exit(-1);
14     }
15     double time = strtod(argv[1], nullptr);
16     double deltaT = strtod(argv[2], nullptr);
17     int elapsed_time = 0;
18     Universe universe;
19     try {
20         universe = Universe("nbody/starfield.jpg");
21         // Gets universe data from input file
22         std::cin >> universe;
23     }
24     catch (const std::invalid_argument& err) {
25         std::cout << err.what() << std::endl;
26         exit(-1);
27     }
28     sf::Vector2u windowSize = universe.getImage().getSize();
29     sf::RenderWindow window(sf::VideoMode(windowSize.x, windowSize.y),
30     "The Solar System!");
31     window.setFramerateLimit(60);
32     // Plays sound file from nbody
33     sf::Music music;
34     if (!music.openFromFile("nbody/2001.wav")) {
35         std::cout << "Cannot load music nbody/2001.wav" << std::endl;
36     }
37     music.play();
38     music.setLoop(true);
39     sf::Text timer;
40     sf::Font font;
41     if (!font.loadFromFile("nbody/verdana.ttf")) {
42         std::cout << "Cannot load font nbody/verdana.ttf" << std::endl;
43     }
44     timer.setFont(font);
45     timer.setFillColor(sf::Color::White);
46     timer.setCharacterSize(16);
47     // SFML display loop
48     while (window.isOpen()) {
49         sf::Event event;
50         while (window.pollEvent(event)) {
51             if (event.type == sf::Event::Closed) {
52                 window.close();

```



```

53         }
54     }
55     timer.setString("Elapsed time: " + std::to_string(elapsed_time)+
56     "seconds");
57     window.clear();
58     window.draw(universe);
59     for (int i = 0; i < universe.getNumOfPlanets(); i++) {
60         window.draw(*universe.planets[i]);
61     }
62     window.draw(timer);
63     if (elapsed_time < time) {
64         universe.step(deltaT);        // call to step function
65         elapsed_time += deltaT;
66     }
67     else music.stop();
68     window.display();
69 }
70 // prints final positions of planets to output.txt
71 std::ofstream outfile;
72 outfile.open("output.txt");
73 outfile << universe.getNumOfPlanets() << std::endl;
74 outfile << std::scientific << universe.getRadius() << std::endl;
75 for (int i = 0; i < universe.getNumOfPlanets(); i++) {
76     outfile << std::scientific << universe.planets[i]->getXPos()
77     << " " << std::scientific << universe.planets[i]->getYPos()
78     << " " << std::scientific << universe.planets[i]->getXVel()
79     << " " << std::scientific << universe.planets[i]->getYVel()
80     << " " << std::scientific << universe.planets[i]->getMass()
81     << " " << universe.planets[i]->getImageFilename() << std::endl;
82 }
83 outfile.close();
84 return 0;
85 }

```

```

1 //Thomas Freeman
2 //implementation of CelestialBody.h
3 //header file defining all methods a variables present in
4 //CelestialBody.cpp
5 #ifndef CELESTIALBODY_H
6 #define CELESTIALBODY_H
7 #include <iostream>
8 #include <exception>
9 #include <SFML/Graphics.hpp>
10 class CelestialBody : public sf::Drawable {
11 public:
12     // constructors
13     CelestialBody();
14     CelestialBody(double x_position, double y_position, double
15 x_velocity,
16     double y_velocity, double init_mass, std::string image_filename);
17     // accessors and mutators

```

```

18     double getXPos() const;
19     double getYPos() const;
20     double getXVel() const;
21     double getYVel() const;
22     double getMass() const;
23     sf::Image getImage() const;
24     std::string getImageFilename() const;
25     void setXPos(double x_position);
26     void setYPos(double y_position);
27     void setXVel(double x_velocity);
28     void setYVel(double y_velocity);
29     void setMass(double _mass);
30     void setImage(std::string image_filename);
31     // update x and y position of planet given the scale of the universe
32     void updatePosition(double scale, sf::Vector2u windowSize);
33 private:
34     // override virtual draw function
35     void draw(sf::RenderTarget& target, sf::RenderStates states) const
36     override;
37     double xPos, yPos;      // x and y position
38     double xVel, yVel;      // x and y velocity
39     double mass;
40     std::string imageFilename;
41     sf::Image image;
42     sf::Texture texture;
43     sf::Sprite sprite;
44 };
45 #endif

```

```

1 #include "CelestialBody.h"
2 // constructors
3 CelestialBody::CelestialBody() : xPos(0), yPos(0), xVel(0), yVel(0),
4 mass(0) {}
5 CelestialBody::CelestialBody(double x_position, double y_position,
6 double x_velocity, double y_velocity, double init_mass,
7 std::string image_filename) {
8     if (!image.loadFromFile(image_filename)) {
9         throw std::invalid_argument("Celestial Body image file not found,"
10             " exiting");
11     }
12     imageFilename = image_filename;
13     texture.loadFromImage(image);
14     sprite.setTexture(texture);
15     xPos = x_position;    yPos = y_position;
16     xVel = x_velocity;    yVel = y_velocity;
17     mass = init_mass;
18 }
19 // accessors and mutators
20 double CelestialBody::getXPos() const { return xPos; }
21 double CelestialBody::getYPos() const { return yPos; }
22 double CelestialBody::getXVel() const { return xVel; }

```

```

23 double CelestialBody::getYVel() const { return yVel; }
24 double CelestialBody::getMass() const { return mass; }
25 sf::Image CelestialBody::getImage() const { return image; }
26 std::string CelestialBody::getImageFilename() const {
27     return imageFilename;
28 }
29 void CelestialBody::setXPos(double x_position) { xPos = x_position; }
30 void CelestialBody::setYPos(double y_position) { yPos = y_position; }
31 void CelestialBody::setXVel(double x_velocity) { xVel = x_velocity; }
32 void CelestialBody::setYVel(double y_velocity) { yVel = y_velocity; }
33 void CelestialBody::setMass(double _mass) { mass = _mass; }
34 void CelestialBody::setImage(std::string image_filename) {
35     if(!image.loadFromFile("nbody/" + image_filename)) {
36         throw std::invalid_argument("Celestial Body image file not
37 found");
38     }
39     imageFilename = image_filename;
40     texture.loadFromImage(image);
41     sprite.setTexture(texture);
42 }
43 //update x and y position of planet
44 void CelestialBody::updatePosition(double scale, sf::Vector2u
45 windowSize) {
46     int x, y;
47     x = ((xPos / 2) / scale * windowSize.x) + (windowSize.x / 2);
48     y = ((yPos / 2) / scale * windowSize.y) + (windowSize.y / 2);
49     sprite.setPosition(x, y);
50 }
51 //override virtual draw function
52 void CelestialBody::draw(sf::RenderTarget& target, sf::RenderStates
53 states)
54 const {
55     target.draw(sprite, states);
56 }

```

```

1 //Thomas Freeman
2 //Implementation of Universe.h
3 //Header file declaring all methods in
4 //Universe.cpp
5 #ifndef UNIVERSE_H
6 #define UNIVERSE_H
7 #include "CelestialBody.h"
8 #include <memory>
9 #include <vector>
10 #include <cmath>
11 #define GRAVITY_CONST 6.67e-11
12 class Universe : public sf::Drawable {
13 public:
14     // constructors
15     Universe();
16     Universe(std::string image_filename);

```

```

17     explicit Universe(const Universe& copyUniverse);
18     explicit Universe(Universe&& moveUniverse) noexcept;
19     ~Universe();
20     // accessors and mutators
21     int getNumOfPlanets() const;
22     double getRadius() const;
23     sf::Image getImage() const;
24     void setNumOfPlanets(int n);
25     void setRadius(double r);
26     void setImage(std::string image_filename);
27     /* step moves forward the simulation a single interval of time in
28     seconds */
29     void step(double seconds);
30     // vector of pointers to celestial bodies
31     std::vector<std::unique_ptr<CelestialBody>> planets;
32     // overloaded assignment operators for Universe setup in main
33     Universe& operator=(Universe& rvalue);
34     Universe& operator=(Universe&& rvalue) noexcept;
35     // overloaded insertion operator for file input through terminal
36     friend std::istream& operator>>(std::istream& in, Universe&
37 universe);
38
39 private:
40     // override virtual draw function
41     void draw(sf::RenderTarget& target, sf::RenderStates states) const
42     override;
43     int numOfPlanets;
44     double radius;                // radius of the universe
45     sf::Image image;              // universe background
46     sf::Texture texture;
47     sf::Sprite sprite;
48 };
49 #endif

```

```

1 //Thomas Freeman
2 //Implementation of Universe.cpp
3 //This program builds the universe from any
4 //of the Nbody files, throwing exceptions for
5 //incorrect inputs and gathering all data values
6 //needed to display the image
7 #include "Universe.h"
8 //Set of constructors to create the universe
9 Universe::Universe() : numOfPlanets(0), radius(0) {}
10 //Basic exception for unavailable image file
11 Universe::Universe(std::string image_filename) {
12     if(!image.loadFromFile(image_filename)) {
13         throw std::invalid_argument("Universe image file not found,"
14         " exiting");
15     }
16     texture.loadFromImage(image);
17     sprite.setTexture(texture);

```

```

18     numOfPlanets = 0;
19     radius = 0;
20 }
21 Universe::Universe(const Universe& copyUniverse) {
22     numOfPlanets = copyUniverse.numOfPlanets;
23     radius = copyUniverse.radius;
24     image = copyUniverse.image;
25     texture.loadFromImage(image);
26     sprite.setTexture(texture);
27 }
28 Universe::Universe(Universe&& moveUniverse) noexcept {
29     numOfPlanets = moveUniverse.numOfPlanets;
30     radius = moveUniverse.radius;
31     image = moveUniverse.image;
32     texture.loadFromImage(image);
33     sprite.setTexture(texture);
34     moveUniverse.numOfPlanets = 0;
35     moveUniverse.radius = 0;
36 }
37 Universe::~~Universe() {
38     numOfPlanets = 0;
39     radius = 0;
40 }
41 // accessors and mutators
42 int Universe::getNumOfPlanets() const { return numOfPlanets; }
43 double Universe::getRadius() const { return radius; }
44 sf::Image Universe::getImage() const { return image; }
45 void Universe::setNumOfPlanets(int n) { numOfPlanets = n; }
46 void Universe::setRadius(double r) { radius = r; }
47 void Universe::setImage(std::string image_filename) {
48     if(!image.loadFromFile(image_filename)) {
49         throw std::invalid_argument("Universe image file not found");
50     }
51     texture.loadFromImage(image);
52     sprite.setTexture(texture);
53 }
54 // Moves the simulation forward one second, altering delta x and delta
55 y every second
56 void Universe::step(double seconds) {
57     double d, deltaX, deltaY; // distance d formula
58     double force, forceX, forceY; // force calculation
59     double accelX, accelY; // acceleration calculation
60     for (int i = 0; i < numOfPlanets; i++) {
61         forceX = 0; forceY = 0;
62         // Calculates the Net force on x and y
63         for (int j = 0; j < numOfPlanets; j++) {
64             if (i != j) {
65                 deltaX = planets[j]->getXPos() - planets[i]->getXPos();
66                 deltaY = planets[j]->getYPos() - planets[i]->getYPos();
67                 d = sqrt(deltaX * deltaX + deltaY * deltaY);
68                 //Calculates the pairwise force, a product of
69 gravitational constants
70 //and the mass of two planets divided by the square of
71 the distance between them

```

```

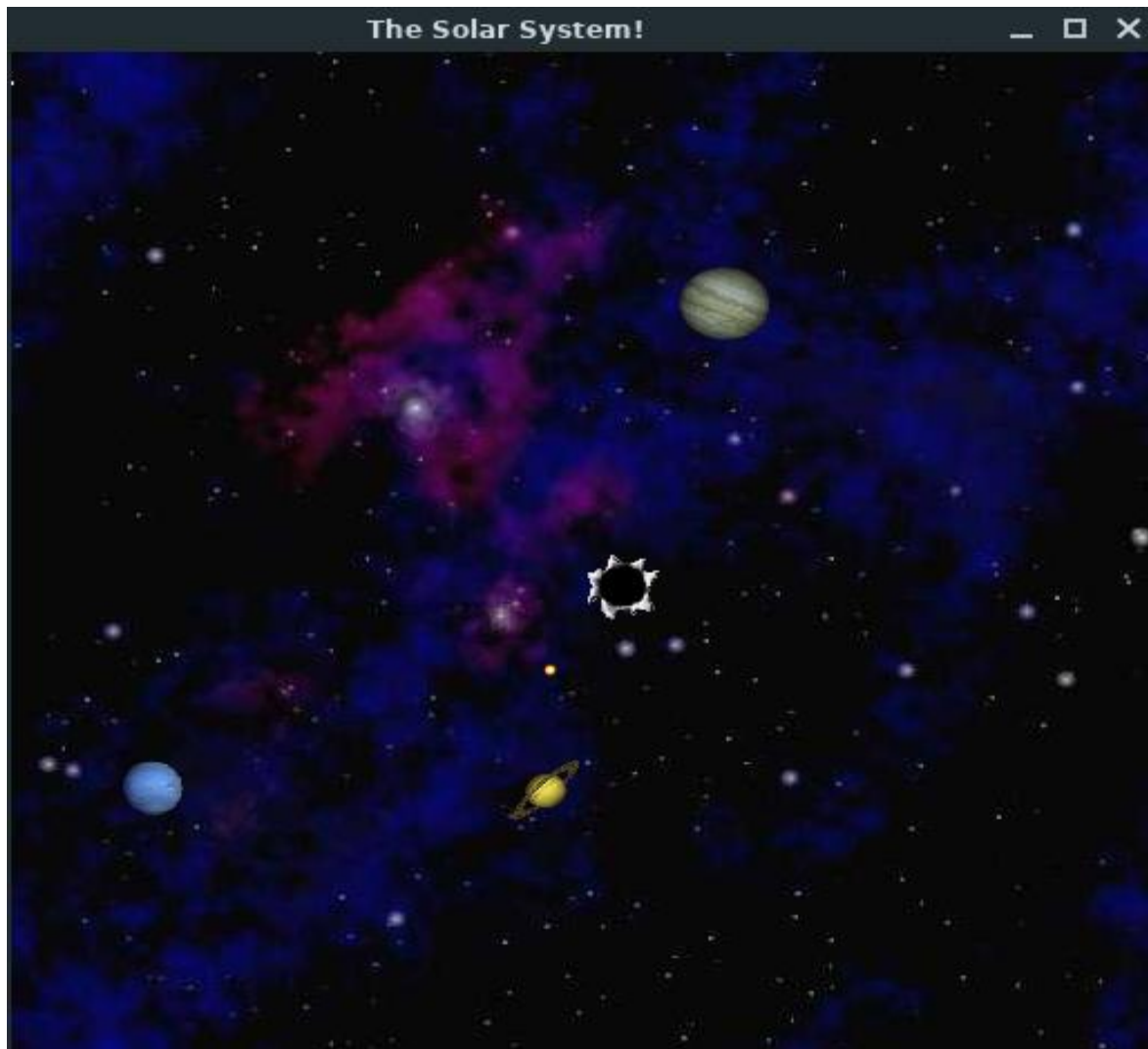
72         force = (GRAVITY_CONST * planets[i]->getMass() *
73         planets[j]->getMass()) / (d * d);
74         forceX += force * (deltaX / d);
75         forceY += force * (deltaY / d);
76     }
77 }
78 // Acceleration calculation
79 accelX = forceX / planets[i]->getMass();
80 accelY = forceY / planets[i]->getMass();
81 // Velocity calculation
82 planets[i]->setXVel(planets[i]->getXVel() + seconds * accelX);
83 planets[i]->setYVel(planets[i]->getYVel() + seconds * accelY);
84 }
85 // Positions are updated
86 for (int i = 0; i < numOfPlanets; i++) {
87     planets[i]->setXPos(planets[i]->getXPos() + seconds *
88     planets[i]->getXVel());
89     planets[i]->setYPos(planets[i]->getYPos() + seconds *
90     planets[i]->getYVel());
91     planets[i]->updatePosition(radius, image.getSize());
92 }
93 }
94 // overloaded assingment operators
95 Universe& Universe::operator=(Universe& rvalue) {
96     if (this == &rvalue) { return *this; }
97     numOfPlanets = rvalue.numOfPlanets;
98     radius = rvalue.radius;
99     image = rvalue.image;
100     texture.loadFromImage(image);
101     sprite.setTexture(texture);
102     return *this;
103 }
104 Universe& Universe::operator=(Universe&& rvalue) noexcept {
105     if (this == &rvalue) { return *this; }
106     numOfPlanets = rvalue.numOfPlanets;
107     radius = rvalue.radius;
108     image = rvalue.image;
109     texture.loadFromImage(image);
110     sprite.setTexture(texture);
111     rvalue.numOfPlanets = 0;
112     rvalue.radius = 0;
113     return *this;
114 }
115 // overload stream operator for command input
116 Std::istream& operator>>(std::istream& in, Universe& universe) {
117     double dval;
118     char buffer[30];    // Files should be less than 30 characters
119     std::string image;
120     in >> universe.numOfPlanets;
121     if (universe.numOfPlanets < 0) { universe.numOfPlanets = 0; }
122     else if (universe.numOfPlanets > 1000) {
123         universe.numOfPlanets = 1000;
124     }
125     in >> universe.radius;

```

```

126     // finds each planets data
127     for (int i = 0; i < universe.numOfPlanets; i++) {
128         std::unique_ptr<CelestialBody> planet(
129             std::make_unique<CelestialBody>(CelestialBody()));
130         //gets all necessary data from the txt file
131         in >> dval;
132         planet->setXPos(dval);
133         in >> dval;
134         planet->setYPos(dval);
135         planet->updatePosition(universe.radius,
136 universe.image.getSize());
137         in >> dval;
138         planet->setXVel(dval);
139         in >> dval;
140         planet->setYVel(dval);
141         in >> dval;
142         planet->setMass(dval);
143         in >> buffer;
144         image = buffer;
145
146         try {
147             planet->setImage(image);
148         }
149         catch (const std::invalid_argument& err) {
150             std::cout << err.what() << std::endl;
151             exit(-1);
152         }
153         universe.planets.push_back(std::move(planet));
154     }
155     return in;
156 }
157 // override virtual draw function
158 void Universe::draw(sf::RenderTarget& target, sf::RenderStates states)
159 const {
160     target.draw(sprite, states);
161 }

```



### PS3 – Recursive Graphics

The goal for assignment 3 was to implement the Sierpinski algorithm. An algorithm that is used to generate triangles in a specific pattern around the base triangle. This assignment was my first experience using CPPLint, a python application that is used to analyze our code we write and give us suggestions on how to rewrite our programs, such that they satisfy googles coding style guidelines. We implemented this in a recursive fashion as creating the algorithm iteratively results in a slow and bugged mess. Every recursive call increases the depth triangles by one, drawing 3 triangles around each one. How are the other triangles drawn? For my implementation I used vectors to ensure that for each side of the triangle, another triangle would be drawn for all depths. The function Convex Shape also proved helpful as it determines the order in which the triangles are drawn for a give depth. The program is effective up until the number of calls becomes too much to process. In my experience I noticed that after 13 recursive calls, there isn't enough memory to process the remaining calls, resulting in a crash of



the virtual machine. The Example below shows the program running with a triangle length of six and algorithmic depth of eight.

The following files are associated with PS3

```

1 CC = g++
2 CFLAGS = -Wall -Werror -ansi -pedantic
3 LFLAGS = -lsfml-graphics -lsfml-window -lsfml-system
4 all: Triangle
5 Triangle: Tfractal.o Triangle.o
6     $(CC) Tfractal.o Triangle.o -o Triangle $(LFLAGS)
7 Tfractal.o: Tfractal.cpp Triangle.hpp
8     $(CC) -c Tfractal.cpp $(CFLAGS)
9 Triangle.o: Triangle.cpp Triangle.hpp
10    $(CC) -c Triangle.cpp $(CFLAGS)
11 clean:
12     rm Triangle
13     rm Tfractal.o
14     rm Triangle.o

```

```

1 // copyright 2021 Thomas Freeman
2 #include "Triangle.hpp"
3 int main(int argc, char* argv[]) {
4     if (argc < 3 || argc > 4) {
5         cout << "./Triangle [L] [N]" << endl;
6         return -1;
7     }
8     int side = atoi(argv[1]);
9     int depth = atoi(argv[2]);
10    if (depth < 0) {
11        cout << "depth should be greater than 0" << endl;
12        return -1;
13    }
14    Triangle obj(side, depth);
15    int window_height = 0.5 * sqrt(3.0) * side;
16    RenderWindow window(VideoMode(side, window_height), "Triangles");
17    window.setFramerateLimit(1);
18    while (window.isOpen()) {
19        Event event;
20        while (window.pollEvent(event))
21            if (event.type == Event::Closed)
22                window.close();
23        window.clear();
24        window.draw(obj);
25        window.display();
26    }
27    return 0;
28 } // end of Tfractal
29

```

```

1 // copyright 2021 Thomas Freeman
2 #ifndef TRIANGLE_HPP //NOLINT
3 #define TRIANGLE_HPP //NOLINT
4 #include <cmath>
5 #include <iostream>
6 #include <vector>
7 #include <SFML/Graphics.hpp>
8 using std::cout;
9 using std::endl;
10 using sf::Color;
11 using sf::Vector2f;
12 using sf::RenderTarget;
13 using sf::RenderWindow;
14 using sf::RenderStates;
15 using sf::VideoMode;
16 using sf::Event;
17 using sf::ConvexShape;
18 using sf::Drawable;
19 class Triangle : public Drawable {
20 public:
21     Triangle(int, int);
22     Triangle(Vector2f, Vector2f, Vector2f, int);
23     void virtual draw(RenderTarget&, RenderStates) const;
24 private:
25     int ftree;
26     Vector2f t, l, r;
27     Vector2f p1, p2, p3;
28     Triangle *t1, *t2, *t3;
29 };
30 #endif //NOLINT

```

```

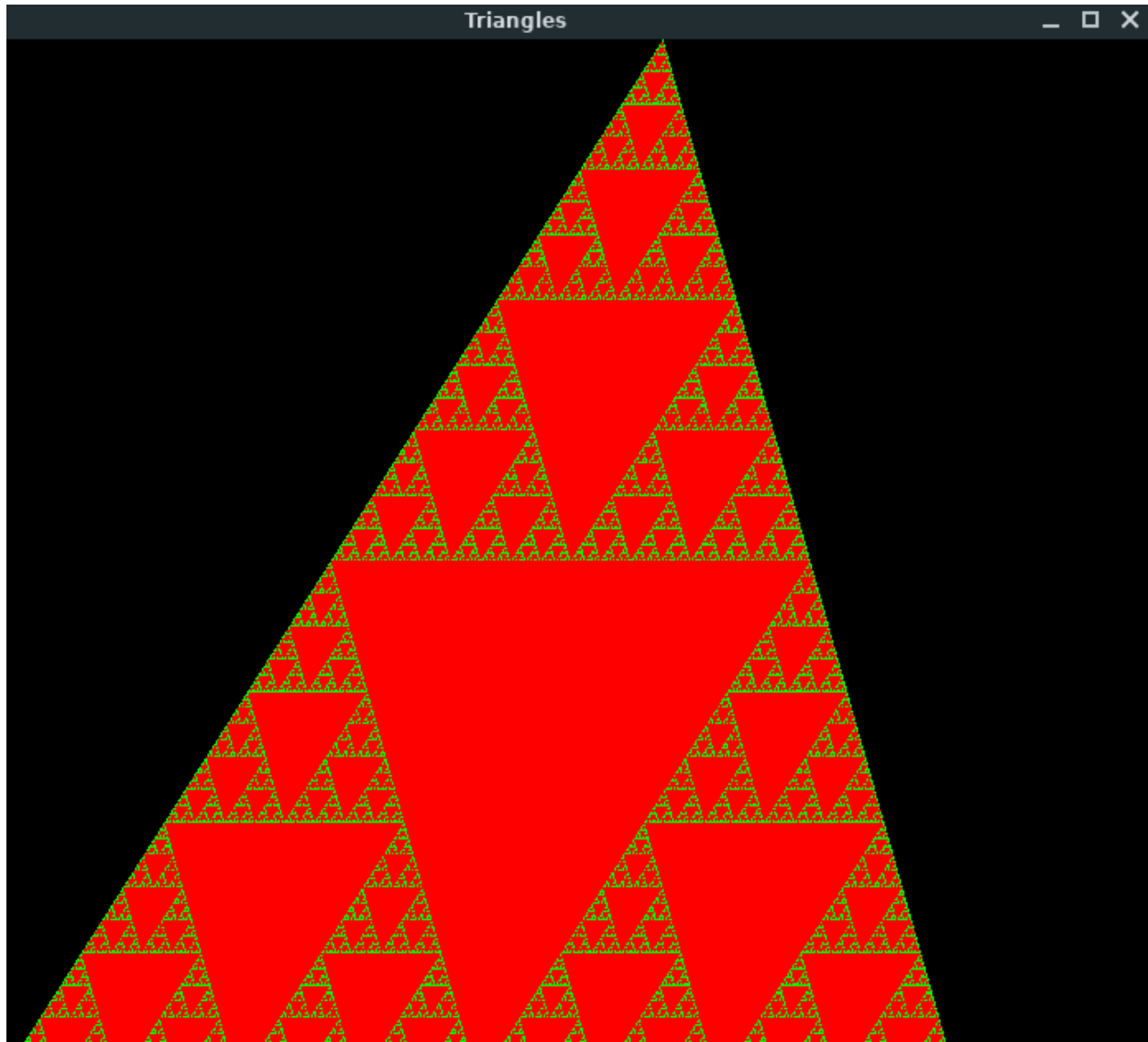
1 // copyright 2021 Thomas Freeman
2 #include "Triangle.hpp"
3 Triangle::Triangle(int side, int depth) : ftree(depth) {
4     t = Vector2f(side / sqrt(3.0), 0);
5     float height = .5 * sqrt(3.0) * side;
6     l = Vector2f(0, height);
7     r = Vector2f(side-1, height);
8     p1 = Vector2f(((t.x + l.x) / 2), ((t.y + l.y) / 2));
9     p2 = Vector2f(((l.x + r.x) / 2), ((l.y + r.y) / 2));
10    p3 = Vector2f(((t.x + r.x) / 2), ((t.y + r.y) / 2));
11    if (ftree - 1 > 0) {
12        t1 = new Triangle(p1, l, p2, depth - 1);
13        t2 = new Triangle(t, p1, p3, depth - 1);
14        t3 = new Triangle(p3, p2, r, depth - 1);
15    } else {

```

```

16     t1 = NULL;
17     t2 = NULL;
18     t3 = NULL;
19 }
20 }
21 Triangle::Triangle(Vector2f top, Vector2f left,
22 Vector2f right, int depth) : ftree(depth) {
23     if (depth <= 0) {
24         t1 = NULL;
25         t2 = NULL;
26         t3 = NULL;
27         return;
28     }
29     t = top;
30     l = left;
31     r = right;
32     p1 = Vector2f(((top.x + left.x) / 2), ((top.y + left.y) / 2));
33     p2 = Vector2f(((left.x + right.x) / 2), ((left.y + right.y) / 2));
34     p3 = Vector2f(((top.x + right.x) / 2), ((top.y + right.y) / 2));
35     t1 = new Triangle(p1, left, p2, depth - 1);
36     t2 = new Triangle(top, p1, p3, depth - 1);
37     t3 = new Triangle(p3, p2, right, depth - 1);
38 }
39 void Triangle::draw(RenderTarget& target, RenderStates states) const {
40     ConvexShape triangle;
41     triangle.setPointCount(3);
42     triangle.setPoint(0, l);
43     triangle.setPoint(1, r);
44     triangle.setPoint(2, t);
45     triangle.setFill(Color::Green);
46     ConvexShape triangle1;
47     triangle1.setPointCount(3);
48     triangle1.setPoint(0, p1);
49     triangle1.setPoint(1, p2);
50     triangle1.setPoint(2, p3);
51     triangle1.setFill(Color::Red);
52     target.draw(triangle);
53     if (ftree > 0)
54         target.draw(triangle1);
55     if (t1 != NULL) {
56         t1->draw(target, states);
57         t2->draw(target, states);
58         t3->draw(target, states);
59     }
60 }

```



#### PS4a – Synthesizing a Plucked String sound

This assignment is more of the setup for PS4b, as the main goal was to create a ring buffer, a data structure that can simulate a string that energy travels through, simulating sound in the final implementation. The idea of a ring buffer comes from the Karplus Strong algorithm which simulates sound based upon different designs of feedback loops. A ring buffer happens to be the one implemented. The Ring Buffer operates like a dynamic Array using the two functions enqueue and dequeue, adding data to the stack's end and popping data from the top.

CircularBuffer also copies and destructs data constantly as enqueue and dequeue run their course through the ring buffer. Since We need at most one loop this is very efficient with a time complexity of  $O(N)$ .

The following is the Code for PS4a

```

1 CC = g++
2 CFLAGS = -std=c++11 -c -g -Og -Wall -Werror -pedantic
3 LIBS = -lboost_unit_test_framework
4 OBJS = test.o CircularBuffer.o
5 EXE = ps4a
6 all : $(EXE)
7 $(EXE) : $(OBJS)
8     $(CC) $(OBJS) -o $(EXE) $(LIBS)
9 %.o : %.cpp
10    $(CC) $(CFLAGS) -o $@ $<
11 clean :
12    \rm $(OBJS) $(EXE)

1 // copyright 2021 Thomas Freeman
2 #ifndef CIRCULARBUFFER_H //NOLINT
3 #define CIRCULARBUFFER_H //NOLINT
4 #include <stdint.h>
5 #include <iostream>
6 #include <exception>
7 class CircularBuffer {
8 public:
9     explicit CircularBuffer(int capacity);
10    // ring buffer is made empty
11    // with its own max capacity
12    CircularBuffer(const CircularBuffer& copyCB);
13    CircularBuffer(CircularBuffer&& moveCB) noexcept;
14    ~CircularBuffer();
15    int size() const;           // return the elements in the buffer
16    bool isEmpty() const;      // checks if size = 0
17    bool isFull() const;       // checks if size = capacity
18    void enqueue(int16_t x);    // add an item
19    int16_t dequeue();          // deletes an item
20    int16_t peek();             // brings an item to the front of the buffer
21    void empty();
22    CircularBuffer& operator=(const CircularBuffer& rightSide);
23    CircularBuffer& operator=(CircularBuffer&& rvalue) noexcept;
24 private:
25    int _size;
26    int _capacity;
27    int _first;
28    int _last;
29    int16_t* _buffer;
30 };
31 #endif //NOLINT

```

```

1 // copyright 2021 Thomas Freeman
2 #include "CircularBuffer.hpp"
3 // List of constructors
4 CircularBuffer::CircularBuffer(int capacity) {
5     if (capacity < 1) {
6         throw std::invalid_argument(" Capacity must be be greater than
7 zero.");
8     }
9     _capacity = capacity;
10    _size = 0;
11    _first = 0;
12    _last = 0;
13    _buffer = new int16_t[capacity];
14 }
15 CircularBuffer::CircularBuffer(const CircularBuffer& copyCB) {
16     _capacity = copyCB._capacity;
17     if (_capacity > 0) {
18         _size = copyCB._size;
19         _first = copyCB._first;
20         _last = copyCB._last;
21         _buffer = new int16_t[_capacity];
22         for (int i = 0; i < _size; i++) {
23             _buffer[i] = copyCB._buffer[i];
24         }
25     } else {
26         _size = 0;
27         _first = 0;
28         _last = 0;
29         _buffer = nullptr;
30     }
31 }
32 CircularBuffer::CircularBuffer(CircularBuffer&& moveCB) noexcept {
33     _capacity = moveCB._capacity;
34     _size = moveCB._size;
35     _first = moveCB._first;
36     _last = moveCB._last;
37     _buffer = moveCB._buffer;
38     moveCB._capacity = 0;
39     moveCB._size = 0;
40     moveCB._first = 0;
41     moveCB._last = 0;
42     moveCB._buffer = nullptr;
43 }
44 CircularBuffer::~CircularBuffer() {
45     if (_buffer != nullptr) { delete[] _buffer; }
46     _capacity = 0;
47     _size = 0;
48     _first = 0;
49     _last = 0;

```

```

50     _buffer = nullptr;
51 }
52 // main functions in circular buffer
53 int CircularBuffer::size() const { return _size; }
54 bool CircularBuffer::isEmpty() const { return _size == 0; }
55 bool CircularBuffer::isFull() const { return _size == _capacity; }
56 void CircularBuffer::enqueue(int16_t x) {
57     if (isFull()) {
58         throw std::runtime_error("enqueue: can't enqueue to a full
59 ring.");
60     }
61     // we add an item to the buffer then increment
62     _buffer[_last] = x;
63     _last++;
64     if (_last == _capacity) { _last = 0; }
65     _size++;
66 }
67 int16_t CircularBuffer::dequeue() {
68     if (isEmpty()) {
69         throw std::runtime_error("dequeue: can't dequeue from an empty
70 ring.");
71     }
72     // return the first item then index the new first item
73     int16_t result = _buffer[_first];
74     _first++;
75     if (_first == _capacity) { _first = 0; }
76     _size--;
77     return result;
78 }
79 // peek exception runs, returns first item after
80 int16_t CircularBuffer::peek() {
81     if (isEmpty()) {
82         throw std::runtime_error("peek: can't peek from an empty
83 ring.");
84     }
85     return _buffer[_first];
86 }
87 void CircularBuffer::empty() {
88     _size = 0;
89     _first = 0;
90     _last = 0;
91 }
92 /** overloaded assignment operators */
93 CircularBuffer& CircularBuffer::operator=(const CircularBuffer&
94 rightSide) {
95     if (this == &rightSide) { return *this; }
96     if (_buffer != nullptr) { delete[] _buffer; }
97     _capacity = rightSide._capacity;
98     if (_capacity > 0) {
99         _size = rightSide._size;
100        _first = rightSide._first;
101        _last = rightSide._last;
102        _buffer = new int16_t[_capacity];
103        for (int i = 0; i < _size; i++) {

```

```

103         _buffer[i] = rightSide._buffer[i];
104     }
105     } else {
106         _size = 0;
107         _first = 0;
108         _last = 0;
109         _buffer = nullptr;
110     }
111     return *this;
112 }
113 CircularBuffer& CircularBuffer::operator=(CircularBuffer&& rvalue)
114 noexcept {
115     if (this == &rvalue) { return *this; }
116     if (_buffer != nullptr) { delete[] _buffer; }
117     _capacity = rvalue._capacity;
118     _size = rvalue._size;
119     _first = rvalue._first;
120     _last = rvalue._last;
121     _buffer = rvalue._buffer;
122     rvalue._capacity = 0;
123     rvalue._size = 0;
124     rvalue._first = 0;
125     rvalue._last = 0;
126     rvalue._buffer = nullptr;
127     return *this;
128 }

1 // Copyright 2021 Thomas Freeman
2 #include "CircularBuffer.hpp"
3 #define BOOST_TEST_DYN_LINK
4 #define BOOST_TEST_MODULE Main
5 #include <boost/test/unit_test.hpp>
6 // Initial test for Circular Buffer
7 BOOST_AUTO_TEST_CASE(functions_test) {
8     std::cout << "\nMember Function Test " << std::endl;
9     std::cout << "Testing construction of CircularBuffer(4)" <<
10 std::endl;
11     BOOST_REQUIRE_NO_THROW(CircularBuffer(4));
12     // Enqueue testing
13     std::cout << "Testing enqueue() for CircularBuffer(4)" << std::endl;
14     CircularBuffer cb(4);
15     BOOST_REQUIRE_NO_THROW(cb.enqueue(1));
16     BOOST_REQUIRE_NO_THROW(cb.enqueue(2));
17     BOOST_REQUIRE_NO_THROW(cb.enqueue(3));
18     BOOST_REQUIRE_NO_THROW(cb.enqueue(4));
19     std::cout << "CircularBuffer(4) is full: " << std::boolalpha <<
20 cb.isFull() << std::endl;
21     // Dequeue testing
22     std::cout << "Testing dequeue() for CircularBuffer(4)" << std::endl;
23     BOOST_REQUIRE_NO_THROW(cb.dequeue());
24     BOOST_REQUIRE_NO_THROW(cb.dequeue());
25     BOOST_REQUIRE_NO_THROW(cb.dequeue());

```



```

26     BOOST_REQUIRE_NO_THROW(cb.dequeue());
27     std::cout << "CircularBuffer(4) is empty: " << std::boolalpha <<
28     cb.isEmpty() << std::endl << std::endl;
29 }
30 // Exception test for capacity
31 BOOST_AUTO_TEST_CASE(excpetion_test1) {
32     std::cout << "Exception Test 1: " <<
33     std::endl << "Testing CircularBuffer(0) throws
34 std::invalid_argument" <<
35     std::endl << std::endl;
36     BOOST_REQUIRE_THROW(CircularBuffer cb1(0), std::invalid_argument);
37 }
38 // Enqueue test exception for adding the full buffer
39 BOOST_AUTO_TEST_CASE(excpetion_test2) {
40     std::cout << "Exception Test 2: " <<
41     std::endl << "Testing if full then enqueue() throws
42 std::runtime_error"
43     << std::endl << std::endl;
44     CircularBuffer cb2(4);
45     cb2.enqueue(1);
46     cb2.enqueue(2);
47     cb2.enqueue(3);
48     cb2.enqueue(4);
49     BOOST_REQUIRE_THROW(cb2.enqueue(5), std::runtime_error);
50 }
51 // Tests the dequeue exception for dequeueing an empty buffer.
52 BOOST_AUTO_TEST_CASE(exception_test3) {
53     std::cout << "Exception Test 3: " <<
54     std::endl << "Testing if empty then peek() and dequeue() throw "
55     "std::runtime_error" << std::endl;
56     CircularBuffer cb3(1);
57     BOOST_REQUIRE_THROW(cb3.peek(), std::runtime_error);
58     BOOST_REQUIRE_THROW(cb3.dequeue(), std::runtime_error);
59 }
60

```

```

g++ -std=c++11 -c -g -Og -Wall -Werror -pedantic -o CircularBuffer.o CircularBuffer.cpp
g++ test.o CircularBuffer.o -o ps4a -lboost_unit_test_framework
osboxes ~ ./ps4a
Running 4 test cases...

Member Function Test
Testing construction of CircularBuffer(4)
Testing enqueue() for CircularBuffer(4)
CircularBuffer(4) is full: true
Testing dequeue() for CircularBuffer(4)
CircularBuffer(4) is empty: true

Exception Test 1:
Testing CircularBuffer(0) throws std::invalid_argument

Exception Test 2:
Testing if full then enqueue() throws std::runtime_error

Exception Test 3:
Testing if empty then peek() and dequeue() throw std::runtime_error

*** No errors detected
osboxes ~

```

#### PS4b – String Sound Implementation and SFML Audio Output

Now we get to play some music by implementing our next class, String Sound. String Sound is a list of constructors that can extract the values generated by our pluck methods Random number generator. These values are then enqueued into `Int_16t` as samples. We then create `KSGuitarSim` which is the main method that gives us the key binds and picture of a keyboard in order to play the Guitar Strings from lowest to highest pitch. The samples are created via the Frequency which comes from the String Sound class. Pluck is assigned a time for each pressed key. There are also exceptions included for Unloadable sounds from the buffer.

The following is the code for PS4b

```

1 CC = g++
2 CFLAGS = -std=c++11 -c -g -Og
3 LIBS = -lsfml-graphics -lsfml-audio -lsfml-window -lsfml-system
4 OBJS = KSGuitarSim.o StringSound.o CircularBuffer.o
5 EXE = KSGuitarSim
6 all : $(EXE)
7 $(EXE) : $(OBJS)
8         $(CC) $(OBJS) -o $(EXE) $(LIBS)
9 %.o : %.cpp
10        $(CC) $(CFLAGS) -o $@ $<
11 clean :
12        \rm $(OBJS) $(EXE)

```

```

1 // Copyright 2021 Thomas Freeman

```

```

2 #include <SFML/Graphics.hpp>
3 #include <SFML/System.hpp>
4 #include <SFML/Audio.hpp>
5 #include <SFML/Window.hpp>
6 #include "StringSound.hpp"
7 // takes input from string sound to make vector of samples
8 std::vector<sf::Int16> makeSamples(StringSound* gs);
9// initializes said vector
10 void setupSoundBuffers(const std::vector<std::vector<sf::Int16>>&
11 samples,
12 std::vector<sf::SoundBuffer>* soundBuffers);
13 // initializes vector from sound buffers
14 void setupSounds(const std::vector<sf::SoundBuffer>& soundBuffers,
15 std::vector<sf::Sound>* sounds);
16 // Display setup
17 int main(int argc, char* argv[]) {
18     sf::Image image;
19     sf::Texture texture;
20     sf::Sprite sprite;
21     if (!image.loadFromFile("Keys.png")) {
22         throw std::runtime_error("sf::Image: could not load Keys.png");
23     }
24     texture.loadFromImage(image);
25     sprite.setTexture(texture);
26     sf::RenderWindow window(sf::VideoMode(image.getSize().x,
27 image.getSize().y), "KS Guitar Sim");
28     // keys used to play guitar
29     std::string keys = "q2we4r5ty7u8i9op-=[zxdcfvgbnjmk,.;/'";
30     std::vector<std::vector<sf::Int16>> samples;
31     std::vector<sf::SoundBuffer> soundBuffers;
32     std::vector<sf::Sound> sounds;
33     StringSound gs;
34     // Frequency determines sound
35     double freq;
36     // sampes are created for each key
37     for (int i = 0; i < static_cast<int>(keys.length()); i++) {
38         freq = 440 * pow(2, (static_cast<double>(i) - 24) / 12);
39         try {
40             gs = StringSound(freq);
41         }
42         catch (std::invalid_argument err) {
43             std::cerr << err.what() << std::endl;
44         }
45         samples.push_back(makeSamples(&gs));
46     }
47     setupSoundBuffers(samples, &soundBuffers);
48     setupSounds(soundBuffers, &sounds);
49     while (window.isOpen()) {
50         sf::Event event;
51         while (window.pollEvent(event)) {
52             if (event.type == sf::Event::Closed) {
53                 window.close();
54             }
55             // Checks for pressed key, if pressed, plays given sound sample

```

```

56         if (event.type == sf::Event::TextEntered) {
57             char key = static_cast<char>(event.text.unicode);
58             for (int i = 0; i < static_cast<int>(keys.length());
59 i++) {
60                 if (key == keys[i]) {
61                     sounds[i].play();
62                 }
63             }
64         }
65     }
66     window.clear();
67     window.draw(sprite);
68     window.display();
69 }
70 return 0;
71 }
72
73 // includes the duration of pluck as int
74 std::vector<sf::Int16> makeSamples(StringSound* gs) {
75     std::vector<sf::Int16> sampleStream;
76     gs->pluck();
77     int duration = 8;
78     for (int i = 0; i < SAMPLE_RATE * duration; i++) {
79         gs->tic();
80         sampleStream.push_back(gs->sample());
81     }
82     return sampleStream;
83 }
84 // Exception for unloadble sound buffer
85 void setupSoundBuffers(const std::vector<std::vector<sf::Int16>>&
86 samples,
87 std::vector<sf::SoundBuffer>* soundBuffers) {
88     sf::SoundBuffer buffer;
89     for (int i = 0; i < static_cast<int>(samples.size()); i++) {
90         if (!buffer.loadFromSamples(&(samples[i])[0], samples[i].size(),
91 2, SAMPLE_RATE)) {
92             throw std::runtime_error("setupSoundBuffers(): could not load"
93 " SoundBuffer");
94         }
95         soundBuffers->push_back(buffer);
96     }
97 }
98 void setupSounds(const std::vector<sf::SoundBuffer>& soundBuffers,
99 std::vector<sf::Sound>* sounds) {
100     sf::Sound sound;
101     for (int i = 0; i < static_cast<int>(soundBuffers.size()); i++) {
102         sound.setBuffer(soundBuffers[i]);
103         sounds->push_back(sound);
104     }
105 }

```

```

3 #define STRINGSOUND_HPP //NOLINT
4 #include <math.h>
5 #include <vector>
6 #include <string>
7 #include <random>
8 #include <SFML/Audio/SoundBuffer.hpp>
9 #include "CircularBuffer.hpp"
10 // sample rate is measured in hertz
11 #define SAMPLE_RATE 44100
12 #define DECAY_FACTOR 0.996
13 class StringSound {
14 public:
15     // default constructor
16     StringSound();
17     // creates stringSound at given frequency
18     explicit StringSound(double frequency);
19     // Vector gives initial string size and values from Int16
20     explicit StringSound(std::vector<sf::Int16> init);
21     StringSound(const StringSound& copySS);
22     StringSound(StringSound&& moveSS) noexcept;
23     ~StringSound();
24     // pluck then replaces random values in the buffer
25     // tic advances by one step, returning the sample
26     // time returns the number of times tic executed
27     void pluck();
28     void tic();
29     sf::Int16 sample();
30     int time();
31     StringSound& operator=(const StringSound& rightSide);
32     StringSound& operator=(StringSound&& rvalue) noexcept;
33 private:
34     CircularBuffer* _rb;
35     int _time;
36 };
37 #endif //NOLINT

1 // Copyright 2021 Thomas Freeman
2 #include "StringSound.hpp"
3 #include <cstdlib>
4 #include <ctime>
5 // All listed constructors with try catch blocks
6 StringSound::StringSound() : _rb(nullptr), _time(0) {}
7 StringSound::StringSound(double frequency) {
8     if (frequency == 0) {
9         throw std::invalid_argument("StringSound constructor: frequency"
10             " cannot be zero");
11     }
12     try {
13         _rb = new CircularBuffer(ceil(SAMPLE_RATE / frequency));
14     }
15     catch (std::invalid_argument err) {
16         std::cerr << err.what() << std::endl;
17     }

```

```

18     _time = 0;
19 }
20 StringSound::StringSound(std::vector<sf::Int16> init) {
21     try {
22         _rb = new CircularBuffer(init.size());
23         for (int i = 0; i < static_cast<int>(init.size()); i++) {
24             _rb->enqueue(init[i]);
25         }
26     }
27     catch (std::invalid_argument err) {
28         std::cerr << err.what() << std::endl;
29     }
30     catch (std::runtime_error err) {
31         std::cerr << err.what() << std::endl;
32     }
33     _time = 0;
34 }
35 StringSound::StringSound(const StringSound& copySS) {
36     _rb = copySS._rb;
37     _time = copySS._time;
38 }
39 StringSound::StringSound(StringSound&& moveSS) noexcept {
40     _rb = moveSS._rb;
41     _time = moveSS._time;
42     moveSS._rb = nullptr;
43     moveSS._time = 0;
44 }
45 StringSound::~StringSound() {
46     if (_rb != nullptr) { delete _rb; }
47     _rb = nullptr;
48     _time = 0;
49 }
50 // Uses ran for int16_t distribution of sound
51 void StringSound::pluck() {
52     std::random_device device;
53     std::mt19937 mt_rand(device());
54     std::uniform_int_distribution<int16_t> distribution(INT16_MIN,
55     INT16_MAX);
56     // buffer is then reset
57     _rb->empty();
58     _time = 0;
59     // and filled with random values
60     try {
61         for (int i = 0; i < _rb->capacity(); i++) {
62             _rb->enqueue(distribution(mt_rand));
63         }
64     }
65     catch (std::runtime_error err) {
66         std::cerr << err.what() << std::endl;
67     }
68 }
69 void StringSound::tic() {
70     try {
71         int16_t next = DECAY_FACTOR * (_rb->dequeue() + _rb->peek()) / 2;

```

```

72     _rb->enqueue(next);
73 }
74 catch (std::runtime_error err) {
75     std::cerr << err.what() << std::endl;
76 }
77 _time++;
78 }
79 sf::Int16 StringSound::sample() {
80     sf::Int16 result = 0;
81     try {
82         result = _rb->peek();
83     }
84     catch (std::runtime_error err) {
85         std::cerr << err.what() << std::endl;
86     }
87     return result;
88 }
89 int StringSound::time() { return _time; }
90 StringSound& StringSound::operator=(const StringSound& rightSide) {
91     if (this != &rightSide) {
92         if (_rb != nullptr) { delete _rb; }
93         _rb = rightSide._rb;
94         _time = rightSide._time;
95     }
96     return *this;
97 }
98 StringSound& StringSound::operator=(StringSound&& rvalue) noexcept {
99     if (this != &rvalue) {
100         if (_rb != nullptr) { delete _rb; }
101         _rb = rvalue._rb;
102         _time = rvalue._time;
103         rvalue._rb = nullptr;
104         rvalue._time = 0;
105     }
106     return *this;
107 }

```

```

// copyright 2021 Thomas Freeman
1 #ifndef CIRCULARBUFFER_HPP //NOLINT
2 #define CIRCULARBUFFER_HPP //NOLINT
3 #include <stdint.h>
4 #include <iostream>
5 #include <exception>
6 class CircularBuffer {
7 public:
8     explicit CircularBuffer(int capacity);
9     // ring buffer is made empty
10    // with its own max capacity
11    CircularBuffer(const CircularBuffer& copyCB);
12    CircularBuffer(CircularBuffer&& moveCB) noexcept;
13    ~CircularBuffer();
14    int size() const;           // return elements in the buffer
15    int capacity() const;      // return capacity of buffer

```

```

16     bool isEmpty() const;           // checks if size = 0
17     bool isFull() const;           // checks if size = capacity
18     void enqueue(int16_t x);        // adds an item
19     int16_t dequeue();              // deletes an item
20     int16_t peek();                 // returns the frontmost item
21     void empty();                   // set size to 0
22     CircularBuffer& operator=(const CircularBuffer& rightSide);
23     CircularBuffer& operator=(CircularBuffer&& rvalue) noexcept;
24 private:
25     int _size;
26     int _capacity;
27     int _first;
28     int _last;
29     int16_t* _buffer;
30 };
31 #endif //NOLINT

1 // copyright 2021 Thomas Freeman
2 #include "CircularBuffer.hpp"
3 // List of constructors
4 CircularBuffer::CircularBuffer(int capacity) {
5     if (capacity < 1) {
6         throw std::invalid_argument("CircularBuffer constructor: capacity"
7             " must be greater than zero.");
8     }
9     _capacity = capacity;
10    _size = 0;
11    _first = 0;
12    _last = 0;
13    _buffer = new int16_t[capacity];
14 }
15 CircularBuffer::CircularBuffer(const CircularBuffer& copyCB) {
16     _capacity = copyCB._capacity;
17     if (_capacity > 0) {
18         _size = copyCB._size;
19         _first = copyCB._first;
20         _last = copyCB._last;
21         _buffer = new int16_t[_capacity];
22         for (int i = 0; i < _size; i++) {
23             _buffer[i] = copyCB._buffer[i];
24         }
25     } else {
26         _size = 0;
27         _first = 0;
28         _last = 0;
29         _buffer = nullptr;
30     }
31 }
32 CircularBuffer::CircularBuffer(CircularBuffer&& moveCB) noexcept {
33     _capacity = moveCB._capacity;
34     _size = moveCB._size;
35     _first = moveCB._first;
36     _last = moveCB._last;

```



```

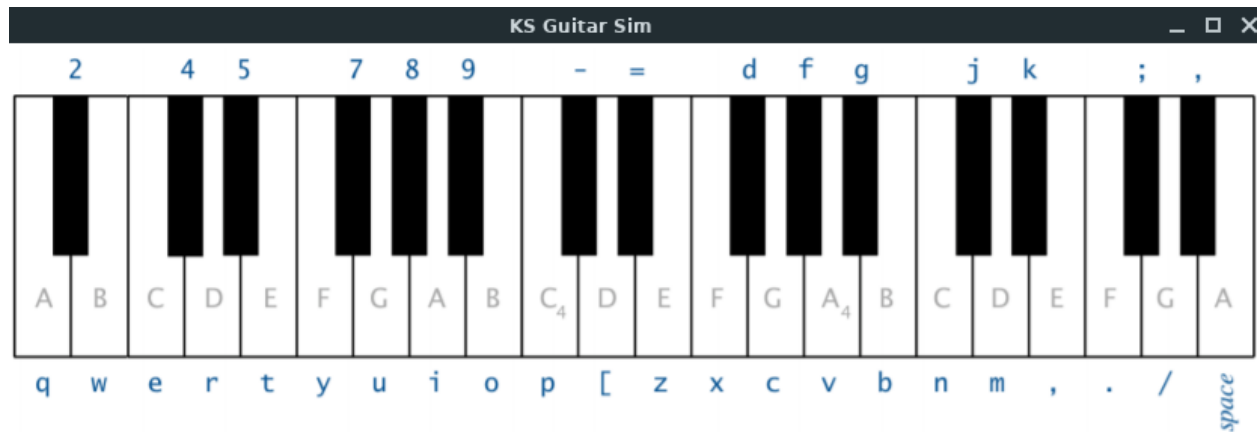
37     _buffer = moveCB._buffer;
38     moveCB._capacity = 0;
39     moveCB._size = 0;
40     moveCB._first = 0;
41     moveCB._last = 0;
42     moveCB._buffer = nullptr;
43 }
44 CircularBuffer::~CircularBuffer() {
45     if (_buffer != nullptr) { delete[] _buffer; }
46     _capacity = 0;
47     _size = 0;
48     _first = 0;
49     _last = 0;
50     _buffer = nullptr;
51 }
52 // main functions in circular buffer
53 int CircularBuffer::size() const { return _size; }
54 int CircularBuffer::capacity() const { return _capacity; }
55 bool CircularBuffer::isEmpty() const { return _size == 0; }
56 bool CircularBuffer::isFull() const { return _size == _capacity; }
57 void CircularBuffer::enqueue(int16_t x) {
58     if (isFull()) {
59         throw std::runtime_error("enqueue: can't enqueue to a full
60 ring.");
61     }
62     // we add an item to the buffer then increment
63     _buffer[_last] = x;
64     _last++;
65     if (_last == _capacity) { _last = 0; }
66     _size++;
67 }
68 int16_t CircularBuffer::dequeue() {
69     if (isEmpty()) {
70         throw std::runtime_error("dequeue: can't dequeue from an empty"
71 " ring.");
72     }
73     // return the first item then index the new first item
74     int16_t result = _buffer[_first];
75     _first++;
76     if (_first == _capacity) { _first = 0; }
77     _size--;
78     return result;
79 }
80 // peek exception runs, returns first item after
81 int16_t CircularBuffer::peek() {
82     if (isEmpty()) {
83         throw std::runtime_error("peek: can't peek from an empty ring.");
84     }
85     return _buffer[_first];
86 }
87 void CircularBuffer::empty() {
88     _size = 0;
89     _first = 0;
90     _last = 0;

```

```

91 }
92 // Overloaded assignment operators
93 CircularBuffer& CircularBuffer::operator=(const CircularBuffer&
94 rightSide) {
95     if (this != &rightSide) {
96         if (_buffer != nullptr) { delete[] _buffer; }
97         _capacity = rightSide._capacity;
98         if (_capacity > 0) {
99             _size = rightSide._size;
100             _first = rightSide._first;
101             _last = rightSide._last;
102             _buffer = new int16_t[_capacity];
103             for (int i = 0; i < _size; i++) {
104                 _buffer[i] = rightSide._buffer[i];
105             }
106         } else {
107             _size = 0;
108             _first = 0;
109             _last = 0;
110             _buffer = nullptr;
111         }
112     }
113     return *this;
114 }
115 CircularBuffer& CircularBuffer::operator=(CircularBuffer&& rvalue)
116 noexcept {
117     if (this != &rvalue) {
118         if (_buffer != nullptr) { delete[] _buffer; }
119         _capacity = rvalue._capacity;
120         _size = rvalue._size;
121         _first = rvalue._first;
122         _last = rvalue._last;
123         _buffer = rvalue._buffer;
124         rvalue._capacity = 0;
125         rvalue._size = 0;
126         rvalue._first = 0;
127         rvalue._last = 0;
128         rvalue._buffer = nullptr;
129     }
130     return *this;
131 }

```



### PS5 – DNA Sequence Alignment

For this assignment Our goal was to choose a way to implement a DNA sequence Analyzer such that we could identify how similar the strings were. We were given multiple ways of doing this and I choose to do the Dynamic Programming approach. This involves the creation of a Matrix that will take the two strings and store sections of each as each section gets analyzed for matches. The Array is filled with the string characters from bottom right to top left and then is traced from top left to bottom right. By Filling and Tracing in this order, the Matrix can store parts of the string that are already analyzed and continue onto the next. Our Main file simply provides the terminal output and syntax for the edit distance and execution time. We also got to see how memory can affect our runtime in this assignment using the valgrind tool to assess our memory usage at runtime. Since My laptop is fairly new it performed above average based upon the availability of memory used for my VM. The example after the code shows the output and execution time of an ecoli strand.

The following Code is for PS5

```
1 CC = g++
2 CFLAGS = -std=c++11 -c -g -O2 -Wall -Werror -pedantic
3 LIBS = -lsfml-system
4 OBJS = main.o EDistance.o
5 EXE = EDistance
6 all : $(EXE)
7 $(EXE) : $(OBJS)
8     $(CC) -o $(EXE) $(OBJS) $(LIBS)
9 %.o : %.cpp
10    $(CC) $(CFLAGS) -o $@ $<
11 clean :
12    \rm $(EXE) $(OBJS)
```

```
1 // copyright 2021 Thomas Freeman
2 #include "EDistance.hpp"
3 #include <SFML/System.hpp>
4 // command line syntax
```

```

5 int main(int argc, char* argv[]) {
6     if (argc != 1) {
7         std::cerr << "usage: ./EDistance < ecoli8000.txt" << std::endl;
8         exit(-1);
9     }
10    EDistance ed;
11    std::cin >> ed;
12    sf::Clock clock;
13    sf::Time t;
14    // Print statements for edit distance and execution time
15    std::cout << "Edit distance = " << ed.optDistance() << std::endl;
16    std::cout << ed.alignment() << std::endl;
17    t = clock.getElapsedTime();
18    std::cout << "Execution time = " << t.asSeconds() << " seconds" <<
19    std::endl;
20    return 0;
21 }
22

```

```

1 // copyright 2021 Thomas Freeman
2 #ifndef EDistance_HPP      //NOLINT
3 #define EDistance_HPP      //NOLINT
4 #include <iostream>
5 #include <string>
6 #include <vector>
7 #include <algorithm>
8 class EDistance {
9 public:
10    EDistance();
11    // edit distance is made from two strings
12    EDistance(std::string x, std::string y);
13    // penalties for char's in strings x and y
14    static int penalty(char a, char b);
15    // returns minimum value of a,b,c
16    static int min(int a, int b, int c);
17    // fills the matrix
18    int optDistance();
19    // traces the matrix, returns alignment
20    std::string alignment();
21    // overload stream operator
22    friend std::istream& operator>>(std::istream& in, EDistance& ed);
23 private:
24    // M is for string x, N for string y
25    int M;
26    int N;
27    std::string _x, _y;
28    // measures the sequence alignment
29    std::vector<std::vector<int> > opt;
30 };
31 #endif //NOLINT

```

```

1 // Copyright 2021 Thomas Freeman
2 #include "EDistance.hpp"

```

```

3 EDistance::EDistance() : M(0), N(0) {}
4 EDistance::EDistance(std::string x, std::string y) {
5     _x = x; _y = y;
6     M = static_cast<int>(_x.length());
7     N = static_cast<int>(_y.length());
8     // initialize vector matrix of ints
9     opt = std::vector<std::vector<int>> (M+2, std::vector<int>(N+2, 0));
10    // base cases for M and N
11    for (int i = M; i >= 0; i--) {
12        opt[i][N+1] = opt[i+1][N+1] + 2;
13    }
14    for (int j = N; j >= 0; j--) {
15        opt[M+1][j] = opt[M+1][j+1] + 2;
16    }
17 }
18 // when both chars are the same return 0, else return 1
19 int EDistance::penalty(char a, char b) {
20     if (a == b)
21         return 0;
22     else
23         return 1;
24 }
25 // returns distance based on the minimum int
26 int EDistance::min(int a, int b, int c) {
27     if (b < a && b < c)
28         return b;
29     if (c < a && c < b)
30         return c;
31     else
32         return a;
33 }
34 int EDistance::optDistance() {
35     // fill matrix with values
36     for (int i = M; i >= 0; i--) {
37         for (int j = N; j >= 0; j--) {
38             opt[i][j] = min(opt[i+1][j+1] + penalty(_x[i], _y[j]),
39                             opt[i+1][j] + 2, opt[i][j+1] + 2);
40         }
41     }
42     return opt[0][0];
43 }
44 std::string EDistance::alignment() {
45     std::string result;
46     if (M != 0 && N != 0) {
47         // checks for empty string in M and N
48         for (int i = 0; i < M; i++) {
49             for (int j = 0; j < N; j++) {
50                 // tracing is done diagonally
51                 if (opt[i][j] == opt[i + 1][j + 1] && _x[i] == _y[j]) {
52                     result.push_back(_x[i]);
53                     result.append(" ");
54                     result.push_back(_y[j]);
55                     result.append(" 0\n");
56                     i++;

```

```

57         } else if (opt[i][j] == opt[i + 1][j + 1] + 1) {
58             result.push_back(_x[i]);
59             result.append(" ");
60             result.push_back(_y[j]);
61             result.append(" 1\n");
62             i++;
63         } else if (opt[i][j] == opt[i + 1][j] + 2) {
64             // move down
65             result.push_back(_x[i]);
66             result.append(" â€" 2\n");
67             i++;
68             j--;
69         } else if (opt[i][j] == opt[i][j + 1] + 2) {
70             // move right
71             result.append("â€" );
72             result.push_back(_y[j]);
73             result.append(" 2\n");
74         }
75     }
76 }
77 } else if (M != 0 && N == 0) {
78     result.append("String y is empty, returning string x: ");
79     result.append(_x);
80     result.append("\n");
81 } else if (M == 0 && N != 0) {
82     result.append("String x is empty, returning string y: ");
83     result.append(_y);
84     result.append("\n");
85 } else {
86     result.append("No two strings provided\n");
87 }
88 return result;
89 }
90 std::istream& operator>>(std::istream& in, EDistance& ed) {
91     std::string x;
92     std::string y;
93     in >> x;
94     in >> y;
95     ed = EDistance(x, y);
96     return in;
97 }

```

```

- G 2
- A 2
- G 2
- T 2
- T 2
- T 2
- A 2
- A 2
- C 2
- G 2
- C 2
- T 2
- G 2
- A 2
- G 2
- G 2
- T 2
- G 2
- A 2
- T 2
- G 2
- T 2
- T 2
- G 2
- C 2

```

Execution time = 0.052978 seconds

osboxes ~

### PS6 – Random Writer

This assignment involves the implementation of what's known as the Markov Model. The algorithm can predict the next given number of characters within a given text based upon our K grams or sets of characters contained within the code. Our text file is taken as a parameter and then we map all our K grams from said text file, in my case I used the Amendments text file. A map can be seen as a table that contains the characters represented by each K gram. This map is created using the Mersenne twister number generator along with the compiler based Krand function to help select proceeding characters. Our new string is then created based upon the generated probabilities for proceeding characters. Our main method Text Writer then analyzes our string and creates a string L that recreates the text up to a certain point. For the Alphabet text file using L = 26 results in printing out the entire alphabet. My example below shows an output of the amendments.txt file.

Here's the following code for PS6

```

1 CC = g++
2 CFLAGS = -std=c++11 -c -g -O1
3 LIBS = -lboost_unit_test_framework
4 OBJS = TextWriter.o RandWriter.o
5 EXE = TextWriter
6 all : $(EXE)
7 $(EXE) : $(OBJS)
8         $(CC) -o $(EXE) $(OBJS) $(LIBS)
9 %.o : %.cpp
10        $(CC) $(CFLAGS) -o $@ $<

```

```

11 clean :
12     \rm $(EXE) $(OBJJS)

1 // copyright 2021 Thomas Freeman
2 #include "RandWriter.h"
3 RandWriter::RandWriter(std::string text, int k) {
4     _text = text;
5     _k = k;
6     if (_text.length() < static_cast<unsigned int>(_k)) {
7         throw std::invalid_argument("RandWriter(string text, int k):
8 order k"
9         " must be less than or equal to text length.");
10    }
11    // Markov table
12    unsigned int pos = 0;
13    for (unsigned int i = 0; i < _text.length(); i++) {
14        std::string k_gram;
15        std::map<char, int> f_table;
16        // maps corresponding char to its frequency
17        // parses the kgrams text and gets characters
18        for (unsigned int j = i; j < i + _k; j++) {
19            if (j >= _text.length()) {
20                pos = j - _text.length();
21            } else {
22                pos = j;
23            }
24            k_gram += _text.at(pos);
25        }
26        // sets up next freq table
27        pos++;
28        if (pos >= _text.length()) { pos -= _text.length(); }
29        f_table.insert(std::make_pair(_text.at(pos), 0));
30        // k_gram and frequency tables are put into the map
31        if (mtable.count(k_gram) == 0) {
32            mtable.insert(std::make_pair(k_gram, f_table));
33        }
34        // update next char in freq table
35        mtable[k_gram][_text.at(pos)]++;
36    }
37 }
38 int RandWriter::kOrder() const { return _k; }
39 std::string RandWriter::getText() const { return _text; }
40 std::map<std::string, std::map<char, int>> RandWriter::getMTable()
41 const {
42     return mtable;
43 }
44 int RandWriter::freq(std::string k_gram) const {
45     if (k_gram.length() < static_cast<unsigned int>(_k)) {
46         throw std::runtime_error("freq(string k_gram): k_gram must be of"
47             " length greater than or equal to order k.");
48     }
49     int count = 0;
50     for (unsigned int i = 0; i < _text.length(); i++) {

```



```

51     unsigned int pos = 0;
52     std::string kg;
53     // parse input text for kgrams
54     for (unsigned int j = i; j < i + _k; j++) {
55         // get characters for kgrams
56         if (j >= _text.length()) {
57             pos = j - _text.length();
58         } else {
59             pos = j;
60         }
61         kg += _text.at(pos);
62     }
63     if (k_gram == kg) { count++; }
64 }
65 return count;
66 }
67 int RandWriter::freq(std::string k_gram, char c) const {
68     if (k_gram.length() < static_cast<unsigned int>(_k)) {
69         throw std::runtime_error("freq(string k_gram, char c): k_gram must be"
70             " of length greater than or equal to order k.");
71     }
72     return mtable.at(k_gram).at(c);
73 }
74 // exceptions for k_gram
75 char RandWriter::kRand(std::string k_gram) const {
76     if (k_gram.length() < static_cast<unsigned int>(_k)) {
77         throw std::runtime_error("kRand(string k_gram): k_gram must be of"
78             " length greater than or equal to order k.");
79     }
80     if (mtable.count(k_gram) == 0) {
81         throw std::runtime_error("kRand(string k_gram): k_gram does not"
82             " exist.");
83     }
84     // next chars stored as a string
85     std::string alphabet;
86     for (auto const &var1 : mtable) {
87         if (var1.first == k_gram) {
88             for (auto const &var2 : var1.second) {
89                 alphabet += var2.first;
90             }
91         }
92     }
93     std::random_device device;
94     std::mt19937 mt_rand(device());
95     std::uniform_int_distribution<int> distribution(0, alphabet.length()
96         - 1);
97     return alphabet[distribution(mt_rand)];
98 }
99 std::string RandWriter::generate(std::string k_gram, int L) const {
100     if (k_gram.length() < static_cast<unsigned int>(_k)) {
101         throw std::runtime_error("generate(string k_gram, int L): k_gram must"
102             " be of length greater than or equal to order k.");
103     }
104     std::string generated = k_gram;

```

```

105     // new characters generated based on k_gram
106     for (int i = _k; i < L; i++) {
107         generated += kRand(generated.substr(i - _k, _k));
108     }
109     return generated;
110 }
111 std::ostream& operator<<(std::ostream& out, const RandWriter&
112 randwriter) {
113     out << "Markov Model\tOrder: " << randwriter._k << std::endl;
114     out << "k_gram:\tfrequency:\tfreqncy of next char:\tprob of next
115 char:" << std::endl;
116
117     for (auto const &var1 : randwriter.mtable) {
118         // var1.first = k_gram
119         out << var1.first << "\t";
120         out << randwriter.freq(var1.first) << "\t\t";
121         for (auto const &var2 : var1.second) {
122             // var2.first = next char
123             // var2.second = data
124             out << var2.first << ":" << var2.second << " ";
125         }
126         out << "\t\t\t";
127         for (auto const &var2 : var1.second) {
128             out << var2.first << ":" << var2.second << "/" <<
129             randwriter.freq(var1.first) << " ";
130         }
131         out << std::endl;
132     }
133     return out;
134 }

```

```

1 // copyright 2021 Thomas Freeman
2 #ifndef RANDWRITER_H //NOLINT
3 #define RANDWRITER_H //NOLINT
4 #include <iostream>
5 #include <string>
6 #include <map>
7 #include <exception>
8 #include <utility>
9 #include <random>
10 class RandWriter {
11 public:
12     // creates markov model of order k based on the text file
13     RandWriter(std::string text, int k);
14     // returns Korder
15     int kOrder() const;
16     // returns input text
17     std::string getText() const;
18     // Returns the table map
19     std::map<std::string, std::map<char, int>> getMTable() const;
20     // returns the number of times K_gram occurs in the text
21     // throws exception if K_gram is not length K
22     int freq(std::string k_gram) const;
23     // returns how many times char c follows k_gram

```

```

24 // throws exception if k_gram is not length K
25 int freq(std::string k_gram, char c) const;
26 // returns random character following k_gram
27 // throws exception if k_gram is not length K
28 // or if there's no k_gram
29 char kRand(std::string k_gram) const;
30 // generates string of length L by simulating the markov chain
31 // first k characters of the new string are K_gram since L is close
32 to K
33 // throws exception otherwise
34 std::string generate(std::string k_gram, int L) const;
35 // overloaded stream insertion operator to show the models state
36 friend std::ostream& operator<<(std::ostream& out, const RandWriter&
37 randwriter);
38 private:
39 int _k; // order of Markov Model
40 std::string _text; // text to analyze
41 // map of k_gram to map of frequency of next char
42 std::map<std::string, std::map<char, int>> mtable;
43 };
44 #endif //NOLINT

```

```

1 // copyright 2021 Thomas Freeman
2 #include "RandWriter.h"
3 #define BOOST_TEST_DYN_LINK
4 #define BOOST_TEST_MODULE Main
5 #include <boost/test/unit_test.hpp>
6 BOOST_AUTO_TEST_CASE(base_test) {
7     std::cout << "Test Case 1 " <<
8     std::endl;
9     int k = 2;
10    std::string str = "gagggagaggcgagaaa";
11    RandWriter randwriter(str, k);
12    std::cout << "Printing out Markov Table for string:\n" <<
13    str << std::endl << std::endl;
14    std::cout << randwriter << std::endl;
15    std::cout << "Testing kOrder and freq functions" << std::endl;
16    BOOST_REQUIRE(randwriter.kOrder() == k);
17    BOOST_REQUIRE(randwriter.freq("gg") == 3);
18    BOOST_REQUIRE(randwriter.freq("ga", 'g') == 4);
19    std::cout << "Testing kRand function" << std::endl;
20    char rand = randwriter.kRand("aa");
21    BOOST_REQUIRE(rand == 'a' || rand == 'g');
22    std::cout << "Testing generate function" << std::endl <<
23    std::endl;
24    BOOST_REQUIRE(randwriter.generate("ga", 10).length() == 10);
25 }
26 BOOST_AUTO_TEST_CASE(exception_test) {
27     std::cout << " Test Case 2 " <<
28     std::endl;
29     std::cout << "Testing construction exception: RandWriter('ADF', 4)"
30 << std::endl;
31     BOOST_REQUIRE_THROW(RandWriter("ADF", 4), std::invalid_argument);

```

```

32     std::cout << "Testing function exceptions" << std::endl;
33     RandWriter testMtable("abc", 3);
34     BOOST_REQUIRE_THROW(testMtable.freq("a"), std::runtime_error);
35     BOOST_REQUIRE_THROW(testMtable.freq("ab", 'b'), std::runtime_error);
36     BOOST_REQUIRE_THROW(testMtable.kRand("g"), std::runtime_error);
37 }

1 // copyright 2021 Thomas Freeman
2 #include "RandWriter.h"
3 #include <fstream>
4 int main(int argc, char *argv[]) {
5     if (argc != 3) {
6         std::cerr << "Usage: ./TextWriter k L < input.txt" << std::endl;
7         exit(-1);
8     }
9     int k = std::atoi(argv[1]);
10    int L = std::atoi(argv[2]);
11    int count = 0;
12    int length = 0;
13    std::string input;
14    std::string output;
15    // reads line by line of the input and generates
16    // characters pseudorandomly
17    while (std::getline(std::cin, input) && count < L) {
18        if (input.length() > static_cast<unsigned int>(k)) {
19            try {
20                RandWriter randwriter(input, k);
21                if (static_cast<int>(input.length()) > L) {
22                    length = L;
23                } else if (static_cast<int>(input.length()) + count > L)
24                {
25                    length = L - count;
26                } else {
27                    length = input.length();
28                }
29                output = randwriter.generate(input.substr(0, k),
30 length);
31                count += output.length();
32                std::cout << output << std::endl;
33            }
34            catch (std::invalid_argument err) {
35                std::cerr << err.what() << std::endl;
36                exit(-1);
37            }
38            catch (std::runtime_error err) {
39                std::cerr << err.what() << std::endl;
40                exit(-1);
41            }
42        }
43    }
44    return 0;
45 }

```

```

Welcome to Linux Lite 5.6 osboxes

Monday 06 December 2021, 16:15:08
Memory Usage: 512/3936MB (13.01%)
Disk Usage: 7/217GB (4%)
Support - https://www.linuxliteos.com/forums/ (Right click, Open Link)

osboxes ~ > ./TextWriter 60 90 < amendments.txt
Congress shall make no law respecting an establishment of religion, or
prohibiting the free exercise thereof; or abridging the free
osboxes ~ >

```

### PS7 – Kronos Time Clock

For Our last assignment we would be using the Kronos Time Clock in order to see how the implementation of regular expressions could help in parsing the Log Files of the Clock. The Log files are mainly used to determine points of failure, determined at the date and time. We would need to implement regular expressions to scan the file to report each time the clock is booted and finished with its boot. Printing this in a separate report file (.rpt). When the Boot Start message in the Log file is scanned the Date and Time is recorded using our regular expression. Upon completion of the boot, the Date and Time is recorded again, being put into our Report files. The Example after the code shows the first report file after scanning the first log file.

The Following Code is for PS7

```

1 CC = g++
2 CFLAGS = -std=c++11 -c -g -O1 -Wall -Werror -pedantic
3 LIBS = -lboost_regex -lboost_date_time
4 OBJS = main.o
5 EXE = ps7
6 all : $(EXE)
7 $(EXE) : $(OBJS)

```

```

8      $(CC) -o $(EXE) $(OBJS) $(LIBS)
9  %.o : %.cpp
10     $(CC) $(CFLAGS) -o $@ $<
11 clean :
12     \rm $(EXE) $(OBJS)

1 // Copyright 2021 Thomas Freeman
2 #include <iostream>
3 #include <fstream>
4 #include <string>
5 #include <exception>
6 #include <boost/regex.hpp>
7 #include <boost/date_time.hpp>
8 // boost libraries for regular expression
9 using boost::regex;
10 using boost::regex_search;
11 using boost::smatch;
12 using boost::posix_time::ptime;
13 using boost::posix_time::time_duration;
14 using boost::posix_time::time_from_string;
15 int main(int argc, char* argv[]) {
16     int lineNum = 1, bootStartCount = 0, bootCompleteCount = 0;
17     bool bootStarted = false;
18     const std::string bootStartMsg = "(log.c.166) server started";
19     const std::string bootCompleteMsg = "oejs.AbstractConnector:Started"
20     "SelectChannelConnector@0.0.0.0:9080";
21     // this regular expressions captures the date and time
22     std::string s;
23     std::string fileName;
24     std::ifstream inputFile;
25     std::ofstream outputFile;
26     regex e("^\\d{4}[-](0[1-9]|1[012])[-](0[1-9]|[12][0-9]"
27     "|3[01])\\s\\d{2}[:]\\d{2}[:]\\d{2}");
28     smatch m;
29     // t1 and t2 determine start and complete times
30     ptime t1, t2;
31     if (argc != 2) {
32         std::cerr << "Usage: ./ps7 device1_intouch.log" << std::endl;
33         return -1;
34     }
35     // setup file I/O
36     inputFile.open(argv[1]);
37     if (!inputFile.is_open()) {
38         std::cerr << "Could not open file: " << argv[1] << std::endl;
39         return -1;
40     }
41     s = fileName = argv[1];
42     outputFile.open(s.append(".rpt.tmp"));
43     fileName = fileName.substr(fileName.find_last_of("\\/") + 1);
44     // scans boot info from log file, transfers info to report file.
45     while (std::getline(inputFile, s)) {
46         if (bootStarted) {
47             if (s.find(bootCompleteMsg) != std::string::npos) {

```

```

48         // device boot completes
49         regex_search(s, m, e);
50         // we then get the date and time
51         t2 = ptime(time_from_string(m[0]));
52         // and total boot time
53         time_duration td = t2 - t1;
54         outputFile << lineNum << "(" << fileName << ")" " << m[0]
55         << " Boot Completed" << std::endl
56         << "\tBoot Time: " << td.total_milliseconds() << "ms"
57         << std::endl << std::endl;
58         bootStarted = false;
59         bootCompleteCount++;
60     } else if (s.find(bootStartMsg) != std::string::npos) {
61         // boot start reports after unsuccessful boot
62         regex_search(s, m, e);
63         t1 = ptime(time_from_string(m[0]));
64         outputFile << " Incomplete boot" << std::endl <<
65         std::endl
66         << " Device boot" << std::endl
67         << lineNum << "(" << fileName << ")" " << m[0]
68         << " Boot Start" << std::endl;
69         bootStartCount++;
70     }
71 } else if (s.find(bootStartMsg) != std::string::npos) {
72     // boot start reports again
73     regex_search(s, m, e);
74     t1 = ptime(time_from_string(m[0]));
75     outputFile << "=== Device boot ===" << std::endl
76     << lineNum << "(" << fileName << ")" " << m[0]
77     << " Boot Start" << std::endl;
78     bootStarted = true;
79     bootStartCount++;
80 }
81 lineNum++;
82 }
83 inputFile.close();
84 outputFile.close();
85 // add .rpt and .tmp to report file
86 s = argv[1];
87 s.append(".rpt");
88 outputFile.open(s);
89 s.append(".tmp");
90 inputFile.open(s);
91 if (!inputFile.is_open()) {
92     std::cerr << "Could not open file: " << s << std::endl;
93     return -1;
94 }
95 outputFile << "Device Boot Report" << std::endl << std::endl
96 << "InTouch log file: " << fileName << std::endl
97 << "Lines Scanned: " << lineNum - 1 << std::endl << std::endl
98 << "Device boot count: initiated: " << bootStartCount << ",
99 completed: "
100 << bootCompleteCount << std::endl << std::endl << std::endl;
101 outputFile << inputFile.rdbuf(); // copies the data

```

```
102     inputFile.close();
103     outputFile.close();
104     // removes the temp file
105     if (std::remove(s.c_str()) != 0) {
106         std::cerr << "Error deleting temp file: " << s << std::endl;
107         return -1;
108     }
109     return 0;
110 }
```

## Device Boot Report

InTouch log file: device1\_intouch.log

Lines Scanned: 443838

Device boot count: initiated: 6, completed: 6

=== Device boot ===

435369(device1\_intouch.log) 2014-03-25 19:11:59 Boot Start

435759(device1\_intouch.log) 2014-03-25 19:15:02 Boot Completed

Boot Time: 183000ms

=== Device boot ===

436500(device1\_intouch.log) 2014-03-25 19:29:59 Boot Start

436859(device1\_intouch.log) 2014-03-25 19:32:44 Boot Completed

Boot Time: 165000ms

=== Device boot ===

440719(device1\_intouch.log) 2014-03-25 22:01:46 Boot Start

440791(device1\_intouch.log) 2014-03-25 22:04:27 Boot Completed

Boot Time: 161000ms

=== Device boot ===

440866(device1\_intouch.log) 2014-03-26 12:47:42 Boot Start

441216(device1\_intouch.log) 2014-03-26 12:50:29 Boot Completed

Boot Time: 167000ms

=== Device boot ===

442094(device1\_intouch.log) 2014-03-26 20:41:34 Boot Start

442432(device1\_intouch.log) 2014-03-26 20:44:13 Boot Completed

Boot Time: 159000ms

=== Device boot ===

443073(device1\_intouch.log) 2014-03-27 14:09:01 Boot Start

443411(device1\_intouch.log) 2014-03-27 14:11:42 Boot Completed

Boot Time: 161000ms