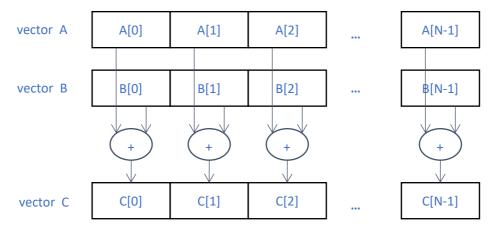
Programming Practice 1: Vector Addition

Objective: To understand basic programming model of GPU-accelerated heterogenous computing.

Vector addition:

- Given two arrays on *n* integers A, B.
- An empty array C of size n.
- Add elements of A and B in corresponding positions (i.e., compute C[i] = A[i] + B[i]).



(NVIDIA and UIUC, 2017)

Simple flow in GPU-accelerated heterogenous computing:

- Part 1: Copy input data from CPU memory to GPU memory.
- Part 2: Load GPU program and execute, caching data on GPU chip for full performance.
- Part 3: Copy results from GPU memory to CPU memory.

Host code template:

```
#include<cuda.h>
                                                                                           Part 1
int main()
                                                                                                         Part 2
 // allocate and initialize host memory
                                                                                                  Device Memory
                                                                       Host Memory
 int n = 512; int *h_a = ..., *h_b = ...; *h_c = ...(empty);
                                                                               CPU
                                                                                                        GPU
 // Part 1
 // allocate device memory for a, b, and c
                                                                                            Part 3
 // copy a and b to device memory
                                                                                (NVIDIA and UIUC, 2017)
 // Part 2
 // kernel launch code which let the device performs the actual vector addition
 // Part 3
 // copy c to host memory
 // free device memory
```

Basic CUDA Device Memory Management API functions:

- *cudaMalloc*(): allocates an object in the device global memory with the following two parameters in order:
 - o Address of a pointer to the allocated object.
 - Size of allocated object in terms of bytes.

```
Example: int size = n * sizeof(float); float *d_A;
cudaMalloc((void **) &d_A, size);
```

- cudaFree(): frees object from device global memory with the following parameter.
 - o pointer to freed object.

```
Example: cudaFree(d_A);
```

- cudaMemcpy(): memory data transfer with the following four parameters in order:
 - o pointer to destination
 - o pointer to source
 - o number of bytes copied
 - Type/direction of transfer

Example: cudaMemcpy(h_C, d_C, size, cudaMemcpyDeviceToHost);

Practice1.1: Implement host code for parallel addition of 512-element vectors.

Practice 1.2: Implement device code for parallel addition of 512-element vectors.

<u>Practice 1.3:</u> Combine your codes in 1.1 and 1.2 to compute parallel addition of 512-element vectors.

Practice 1.4: Adjust your codes in 1.3 to compute parallel addition of *n*-element vectors.