

Curriculum Vitae



Personal Information

<i>Date of birth:</i>	May 14th 1984
<i>Place of birth:</i>	Nis, Serbia
<i>Marital status:</i>	married
	● sociable
	● didactical and negotiation skills
	● empathic
	● cooperative

Links




<https://www.linkedin.com/in/nenad-balaneskovic-840322223/>
https://www.xing.com/profile/Nenad_Balaneskovic/web_profiles

My Aims

- Participation in diversified data science and AI projects
- Use of software development techniques already acquired at the university and in industry (Python, MATLAB, C#, C++ , JavaScript, RUST, Go)
- Professional software development of Windows applications with Python, R, MATLAB and Visual Studio Code
- Permanent education in the domains AI, Data mining, machine learning and algorithm development

Education (see also: <https://github.com/NenadBalaneskovic>)

- 2016 | **Promotion** at the TU Darmstadt (*magna cum laude*);
Thesis: »Random Unitary Operations and Quantum Darwinism«.
University Library of the TU Darmstadt (link):
 <http://tuprints.ulb.tu-darmstadt.de/5148/>
- 2011 - 2016 | Doctoral studies in Physics (PhD) at the TU Darmstadt.
Research sector: **Quantum Information Theory and Quantum Computers**
- 2008 - 2011 | **Master-Studies** in Physics (MSc.) at the TU Darmstadt;
Thesis: »Nonequilibrium and the Functional Renormalization Group«.
- 2005 - 2008 | **Bachelor-Studies** in Physics (BSc.) at the TU Darmstadt;
Thesis: »Nonequilibrium Initial Conditions for Plasma Instabilities«.
- 2000 - 2005 | Grammar School »Carl-Schurz-Schule« in Frankfurt/M;
Certificate: **Abitur** (university entrance qualification)

Teaching experience

- 2024: Soft2tec GmbH, Rüsselsheim | May-August, supervisor of the **Bachelor-Thesis** of Lennard Schimmer
- 2015 - 2016: TU Darmstadt | **Coordination of tutoring sessions and exams**, Lecture »Classical Mechanics«
- 2015: TU Darmstadt | **Coordination of tutoring sessions**, Lecture »Theoretical Quantum Optics«
- 2014: TU Darmstadt | May-August, supervisor of the **Bachelor-Thesis** of Marc Mendler
- 2013: TU Darmstadt | May-August, supervisor of the **Bachelor-Thesis** of Felix Weber
- 2012 - 2013: TU Darmstadt | **Coordination of tutoring sessions and exams**, Lecture »Classical Mechanics«
- 2012: TU Darmstadt | **Coordination of tutoring sessions and exams**, Lecture »Quantum Mechanics«
- 2011 - 2012: TU Darmstadt | **Coordination of tutoring sessions and exams**, Lecture »Electrodynamics«
- 2011: TU Darmstadt | **Tutoring sessions**, Lecture »Introduction to Theoretical Physics«
- 2010: TU Darmstadt | **Teaching Award** of the Gerhard Herzberg Gesellschaft
- 2010: TU Darmstadt | **Tutoring sessions**, Lecture »Quantum Mechanics«
- 2009 - 2010: TU Darmstadt | **Tutoring sessions**, Lecture »Classical Mechanics«
- 2002 - | Private Tutoring for Grammar school students in physics and mathematics

Job Experience

since 01. 01. 2022

Employed at **nexonar (Atlas Copco Holding GmbH)** in **Rüsselsheim** as **Optical Engineer**

- Data analysis and data engineering as part of various industrial data science projects (automotive, aerospace and medical industries).
- Development and testing of AI- and ML-algorithms for motion tracking, image processing, signal processing, process automation, quality and reliability control of industrial processes and data mining, as well as design, performance and analysis of experiments involving infra-red cameras and sensors

01. 03. 2017 - 31. 12. 2021

Employed at **Soft2tec GmbH** in **Rüsselsheim** as **Technology Consultant**

- Data analysis and data engineering as part of various industrial data science projects (automotive, aerospace and medical industries).
- Managing maintenance, development and tests of hardware calibration procedures and validation algorithms in the laboratory department

01. 10. 2011 - 31. 03. 2016

Research employee of the Federal State of Hesse (**University of Technology Darmstadt**)

- Managing research and deployment of innovative quantum computing technology

Leadership and functional experience

Institution	Time period	# people managed	Description
<i>nexonar (Atlas Copco Holding)</i>	since 01. 01. 2019	4	Managing maintenance, development and tests of hardware calibration procedures and validation algorithms in the laboratory department
<i>Institute for Applied Physics, University of Technology Darmstadt</i>	01. 12. 2011 - 31. 12. 2015	5	Managing research and deployment of innovative technology

Project Experience

- | | |
|-----------------------------|--|
| 01. 08. 2024 - 31. 08. 2024 | nexonar quality control (Desoutter & Atlas Copco Group)
- Design of an interactive panel in PowerBI for displaying latest production details and developments |
| 01. 06. 2024 - 31. 07. 2024 | nexonar AI-management (Desoutter & Atlas Copco Group)
- Write a detailed AI-management report for a fully automated ISO-standardized product certification pipeline (laboratory) |
| 01. 01. 2024 - 31. 05. 2024 | nexonar software development (Desoutter & Atlas Copco Group)
- Design of new Dialog of nexonar Calibration Analyzer (nCA) supporting manual camera validation |
| 01. 01. 2024 - 31. 01. 2025 | nexonar quality control (Desoutter & Atlas Copco Group)
- Design of new Gauge Study-driven procedures and software functionalities for quality control tests of produced hardware batches |
| 01. 01. 2023 - 30. 06. 2024 | nexonar hardware development (Desoutter & Atlas Copco Group)
- Design of a new infra-red tracker form |
| 01. 04. 2022 - 31. 01. 2025 | GUI development (Desoutter & Atlas Copco Group)
- PyQt5-GUI for the automated camera calibration |
| 01. 12. 2021 - 31. 03. 2022 | MQTT-projects (Nissan, BMW, Airbus)
- Automation of lens aperture adjustments |
| 01. 05. 2021 - 30. 06. 2024 | Cloud-based automation of camera validation (Atlas Copco Group)
- Google Apps Script implementation of the camera validation procedure |
| 01. 09. 2019 - 30. 09. 2019 | Faurecia ArtIFIS Project - ML-driven movement control of the robotic agent (ironing and steaming of car seat cushions) |
| 01. 08. 2019 - 31. 12. 2021 | FALCON collaboration - FEM-modeling of external stress on housings of infra-red trackers |
| 01. 05. 2019 - 30. 06. 2024 | LIANDRI collaboration - Error estimation of distance measurements |
| 01. 05. 2019 - 31. 08. 2019 | P&G Manufacturing GmbH (Schwalbach am Taunus)
- ML- and AI-driven mitigation of sensor noise |
| 01. 02. 2018 - 31. 05. 2018 | Honda (London) - Mathematical modeling of factory workers' performance |
| 01. 05. 2017 - 31. 01. 2020 | Sense Vojta Project at DRK-Kinderklinik (Siegen)
- ML-driven frequency analysis of body part movements |
| 01. 03. 2017 - 31. 01. 2025 | nexonar Calibration Automation
- Automation of the camera calibration process |

Certificates

AC-conference (online courses) (contribution: tests & exercises) 08. 09. 2024 - 29. 09. 2024	»1) <i>Arbeitsvertragsrecht in Deutschland</i> « »2) <i>AI Show: Being Responsible with Generative AI</i> « »3) <i>Generative AI vs. Traditional AI</i> «
AC-conference (online courses) (contribution: tests & exercises) 01. 09. 2024 - 03. 09. 2024	»1) <i>OpenCV for Python Developers</i> « »2) <i>Introduction to Deep Learning with OpenCV</i> « »3) <i>Building Computer Vision Applications with Python</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 09. 08. 2024 - 25. 08. 2024	»1) <i>Introduction to IT Automation</i> « »2) <i>Fundamentals of Dynamic Programming</i> « »3) <i>AI Algorithms for Gaming</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 02. 08. 2024	»1) <i>Learning H2O.ai</i> « »2) <i>Learning TinyML: A Hands-On Course</i> «
AC-conference (online course) (contribution: tests & exercises) 23. 07. 2024 - 30. 07. 2024	»1) <i>TensorFlow: Working with NLP</i> « »2) <i>Reading Corporate Financial Statements</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 19. 07. 2024 - 21. 07. 2024	»1) <i>Introduction to Cassandra</i> « »2) <i>Mistakes to Avoid in Machine Learning</i> « »3) <i>Machine Learning with Scikit-Learn</i> « »4) <i>TensorFlow 2: Working with Neural Networks</i> « »5) <i>TensorFlow 2.0: Working with Images</i> «
AC-conference (online course) (contribution: tests & exercises) 06. 07. 2024 - 18. 07. 2024	»1) <i>Introduction to NoSQL</i> « »2) <i>Python Practice: Collections</i> «
AC-conference (online course) (contribution: tests & exercises) 28. 06. 2024 - 29. 06. 2024	»1) <i>Corporate Financial Statement Analysis</i> « »2) <i>Business Collaboration in the Modern Workplace</i> «
AC-conference (online course) (contribution: tests & exercises) 23. 06. 2024 - 26. 06. 2024	»1) <i>Requirements Elicitation and Analysis</i> « »2) <i>Learning Cloud Computing: Serverless Computing</i> « »3) <i>Cloud Computing lernen: Öffentliche (Public) Cloud-Plattformen</i> « »4) <i>Amazon Web Services (AWS): Basiswissen für Administratoren</i> « »5) <i>Microsoft Azure: Basiswissen für Entwickler</i> «
AC-conference (online course) (contribution: tests & exercises) 29. 05. 2024 - 13. 06. 2024	»1) <i>Learning Data Science: Manage Your Team</i> « »2) <i>Learning Data Science: Ask Great Questions</i> « »3) <i>Learning Data Science: Tell Stories With Data</i> « »4) <i>Learning Data Science: Using Agile Methodology</i> « »5) <i>Learning Data Science: Understanding the Basics</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 20. 05. 2024	»1) <i>Why Digital Security at Atlas Copco Group?</i> « »2) <i>How to protect yourself from cyberattacks</i> « »3) <i>Processing personal data</i> « »4) <i>Cyberattack methods and risks</i> «

AC-conference (online course) (contribution: tests & exercises) 01. 05. 2024 - 15. 05. 2024	<ul style="list-style-type: none"> »1) WordPress: Programmierung mit der REST API« »2) SAP Business One Essential Training« »3) Kubernetes: Your First Project«
AC-conference (online course) (contribution: tests & exercises) 22. 04. 2024 - 26. 04. 2024	<ul style="list-style-type: none"> »1) MLOps Essentials: Model Development and Integration« »2) Machine Learning & AI Foundations: Linear Regression« »3) MLOps Essentials: Model Deployment and Monitoring« »4) MLOps Essentials: Monitoring Model Drift and Bias«
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 18. 04. 2024	<ul style="list-style-type: none"> »1) Machine Learning and AI Foundations: Clustering and Association« »2) Introduction to MicroPython and Physical Computing« »3) Learning CircuitPython with Circuit Playground Express« »4) Learning Threat Modeling for Security Professionals«
AC-conference (online course) (contribution: tests & exercises) 14. 04. 2024	<ul style="list-style-type: none"> »1) Machine Learning and AI Foundations: Classification Modeling« »2) Machine Learning and AI Foundations: Value Estimations« »3) Machine Learning and AI Foundations: Recommendations« »4) Grasshopper: Generative Design for Architecture«
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 12. 04. 2024 - 13. 04. 2024	<ul style="list-style-type: none"> »1) Machine Learning and AI Foundations: Decision Trees with KNIME« »2) Predictive Analytics Essential Training: Estimating and Ensuring ROI« »3) Machine Learning with Python: Decision Trees« »4) WordPress 5 für Entwickler: Plugins« »5) Machine Learning and AI Foundations: Advanced Decision Trees with KNIME«
AC-conference (online course) (contribution: tests & exercises) 10. 04. 2024	<ul style="list-style-type: none"> »1) WordPress lernen« »2) WordPress für Entwickler: Auf der Kommandozeile (CLI) arbeiten« »3) Machine Learning and AI Foundations: Causal Inference and Modeling«
AC-conference (online course) (contribution: tests & exercises) 07. 04. 2024 - 09. 04. 2024	<ul style="list-style-type: none"> »1) Machine Learning and AI Foundations: Producing Explainable AI (XAI) and Interpretable Machine Learning Solutions« »2) Machine Learning and AI Foundations: Prediction, Causation, and Statistical Inference« »3) Advanced Predictive Modeling: Mastering Ensembles and Metamodeling«
AC-conference (online course) (contribution: tests & exercises) 03. 04. 2024 - 05. 04. 2024	<ul style="list-style-type: none"> »1) Behavioral Finance Foundations« »2) Finance Essentials for Small Business« »3) Introduction to Machine Learning with KNIME«
AC-conference (online course) (contribution: tests & exercises) 30. 03. 2024	<ul style="list-style-type: none"> »1) Learning Kubernetes« »2) Kubernetes: Cloud Native Ecosystem« »3) Kubernetes: Essential Tools« »4) Predictive Analytics Essential Training for Executives«
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 29. 03. 2024	<ul style="list-style-type: none"> »1) Introduction to Responsible AI Algorithm Design« »2) Debiasing AI Using Amazon SageMaker« »3) Cloud Quantum Computing Essentials« »4) Power BI Data Methods (2019)«
AC-conference (online course) (contribution: tests & exercises) 25. 03. 2024 - 28. 03. 2024	<ul style="list-style-type: none"> »1) Understanding Capital Markets« »2) AutoML: Build Production-Ready Models Quickly!« »3) Executive Guide to AutoML«
AC-conference (online course) (contribution: tests & exercises) 24. 03. 2024	<ul style="list-style-type: none"> »1) AI in Business Essential Training« »2) Artificial Intelligence and Business Strategy: Case Studies« »3) Safeguarding AI«

AC-conference (online course) (contribution: tests & exercises) 22. 03. 2024 - 23. 03. 2024	»1) <i>Artificial Intelligence for Business Leaders</i> « »2) <i>Introducing AI to Your Organization</i> « »3) <i>Learning XAI: Explainable Artificial Intelligence</i> « »4) <i>Artificial Intelligence and Business Strategy</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 20. 03. 2024 - 21. 03. 2024	»1) <i>Learning RhinoCAM</i> « »2) <i>Grasshopper and Rhino: Python Scripting</i> « »3) <i>IoT Foundations: Fundamentals</i> «
AC-conference (online course) (contribution: exercises) 17. 03. 2024 - 18. 03. 2024	»1) <i>Finance Foundations</i> « »2) <i>Learning Algorithmic Design with Grasshopper</i> « »3) <i>Introduction to Digital Twins</i> « »4) <i>Grasshopper Essential Training (2017)</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 15. 03. 2024 - 16. 03. 2024	»1) <i>Introduction to Quantum Computing</i> « »2) <i>Learning Grasshopper</i> « »3) <i>Grasshopper Essential Training</i> «
AC-conference (online course) (contribution: exercises) 07. 03. 2024 - 09. 03. 2024	»1) <i>Quantum Computing Fundamentals</i> « »2) <i>Introduction to Amazon Braket: Quantum Computing on AWS</i> «
AC-conference (online course) (contribution: exercises) 04. 03. 2024 - 05. 03. 2024	»1) <i>Introducing Rhino 6 (2018)</i> « »2) <i>Rhino 6 Essential Training (2018)</i> « »3) <i>Introduction to Quantum Cryptography</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 03. 03. 2024	»1) <i>Learning LabVIEW</i> «
AC-conference (online course) (contribution: exercises) 01. 03. 2024 - 02. 03. 2024	»1) <i>Test Automation with Python: 6 Elements and Selectors</i> « »2) <i>Python GUI Development with Tkinter</i> « »3) <i>Test Automation with Python: 9 Designing Your Test Suite</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 26. 02. 2024	»1) <i>Django Essential Training</i> «
AC-conference (online course) (contribution: exercises) 24. 02. 2024 - 25. 02. 2024	»1) <i>Building RESTful APIs with Flask</i> « »2) <i>Ethereum: Building Blockchain Decentralized Apps (DApps)</i> «
AC-conference, Rüsselsheim am Main (contribution: exercises) 22. 02. 2024	»1) <i>Introduction to F#</i> « »2) <i>Blockchain: Learning Solidity</i> « »3) <i>Corporate Finance Foundations</i> «
AC-conference (online course) (contribution: exercises) 21. 02. 2024	»1) <i>Flask Essential Training</i> «
AC-conference (online course) (contribution: tests & exercises) 20. 02. 2024	»1) <i>Python for Data Science Essential Training Part 1</i> « »2) <i>Python for Data Science Essential Training Part 2</i> «

AC-conference (online course) (contribution: exercises) 19. 02. 2024	»1) <i>Practical Python for Algorithmic Trading</i> « »2) <i>Dart Clean Code: Writing High-Efficiency, Maintainable Dart Programs</i> «
AC-conference, Rüsselsheim am Main (contribution: exercises) 18. 02. 2024	»1) <i>Finance Foundations: Corporate Governance</i> « »2) <i>Managerial Finance Foundations</i> « »3) <i>Introduction to Dart</i> «
AC-conference (online course) (contribution: exercises) 17. 02. 2024	»1) <i>Algorithmic Trading and Stocks Essential Training</i> « »2) <i>Using Tableau to Discover Powerful Business Insights</i> «
AC-conference (online course) (contribution: exercises) 16. 02. 2024	»1) <i>Python: Working with Predictive Analytics</i> « »2) <i>Financial Forecasting with Analytics Essential Training</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 12. 02. 2024- 15. 02. 2024	»1) <i>Data Science Foundations: Data Mining in Python</i> « »2) <i>Foundations of Treasury Management</i> « »3) <i>Getting Started with Python for Finance</i> « »4) <i>Algorithmic Trading and Finance Models with Python, R, and Stata</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 08. 02. 2024	»1) <i>PyTorch Essential Training: Deep Learning</i> « »2) <i>Transfer Learning for Images Using PyTorch: Essential Training</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 06. 02. 2024	»1) <i>Deploying Scalable Machine Learning for Data Science</i> « »2) <i>Hands-On PyTorch Machine Learning</i> « »3) <i>Natural Language Processing with PyTorch</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 05. 02. 2024	»1) <i>Applied Machine Learning: Foundations</i> « »2) <i>Applied Machine Learning: Feature Engineering</i> « »3) <i>DevOps for Data Scientists</i> «
AC-conference (online course) (contribution: exercises) 03. 02. 2024	»1) <i>Applied Machine Learning: Algorithms</i> « »2) <i>Produktiv arbeiten – Schritt für Schritt zur individuellen Lösung</i> « »3) <i>Applied Machine Learning: Algorithms</i> «
AC-conference (online course) (contribution: tests & exercises) 02. 02. 2024	»1) <i>Blockchain and Smart Contracts Security</i> « »2) <i>Introduction to NFTs: Non-fungible Tokens</i> « »3) <i>Cryptocurrency Foundations</i> «
AC-conference, Rüsselsheim am Main (contribution: exercises) 31. 01. 2024	»1) <i>Python for Health Sciences and Healthcare</i> « »2) <i>Blockchain: Beyond the Basics</i> «
AC-conference, Rüsselsheim am Main	30. 01. 2024: »1) <i>Python Statistics Essential Training</i> « (contribution: exercises)
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 29. 01. 2024	»1) <i>Designing RESTful APIs</i> « »2) <i>How Blockchains Will Change Business</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 26. 01. 2024	»1) <i>R und RStudio Grundkurs</i> « »2) <i>Blockchain Basics</i> «

AC-conference (online course) (contribution: tests & exercises) 25. 01. 2024	»1) TensorFlow Grundkurs 2: Machine-Learning-Projekte mit Python«
AC-conference (online course)	23. 01. 2024: »Django: Forms« (contribution: exercise)
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 22. 01. 2024	»1) Building a Personal Portfolio with Django« »2) Test-Driven Development in Django« »3) TensorFlow Grundkurs 1: Neuronale Netzwerke, Komponenten, Tensoren«
AC-conference (online course) (contribution: exercises) 21. 01. 2024	»1) Django Grundkurs« »2) Flask Grundkurs«
AC-conference (online course)	18. 01. 2024: »Kryptografie und Steganografie mit Python« (contribution: exercise)
AC-conference (online course)	16. 01. 2024: »Learning Django« (contribution: exercise)
AC-conference (online course) (contribution: exercises) 14. 01. 2024	»1) Case Study: Visualize Complex Microservice Data Using Python« »2) SQL Queries Made Easy« »3) Introduction to Scala«
AC-conference (online course)	13. 01. 2024: »Learning SQL Programming« (contribution: exercise)
AC-conference (online course) (contribution: tests & exercises) 12. 01. 2024	»1) Finance Foundations: Business Valuation« »2) Python Projects: Create an Interactive Quiz Application«
AC-conference, Rüsselsheim am Main (contribution: exercises) 11. 01. 2024	»1) Finance Foundations: Risk Management« »2) Create an Open-Source Project in Python« »3) Build Three Real-World Python Applications«
AC-conference, Rüsselsheim am Main (contribution: exercises) 10. 01. 2024	»1) Data Ethics: Watching Out for Data Misuse« »2) Machine Learning with Python: Foundations« »3) Machine Learning with Python: k-Means Clustering« »4) Machine Learning with Python: Association Rules« »5) Investment Evaluation«
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 08. 01. 2024	»1) Choose the Right Tool for Your Data: Python, R, or SQL« »2) Advanced Business Development: Communication and Negotiation« »3) Developing Ethical Hacking Tools with Python« »4) Managing Your Personal Investments«
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 07. 01. 2024	»1) Web Scraping with Python« »2) Managing Your Personal Finances« »3) Finance Strategies for Business Leaders« »4) Foundations of Decentralized Finance (DeFi)«
AC-conference (online course) (contribution: tests & exercises) 06. 01. 2024	»1) Corporate Finance: Robust Financial Modeling« »2) Corporate Finance: Profitability in a Financial Downturn« »3) Economics for Everyone: Understanding a Recession«

AC-conference (online course)	06. 01. 2024: »Using Python with Excel« (contribution: exercise)
AC-conference (online course) (contribution: tests & exercises) 29. 12. 2023	»1) Python Parallel and Concurrent Programming Part 2« »2) Python Functions for Data Science« »3) Nail Your Python Interview« »4) Python Data Analysis« »5) Using Python for Automation«
AC-conference (online course) (contribution: exercises) 28. 12. 2023	»1) NLP with Python for Machine Learning: Essential Training« »2) Building Tools with Python«
AC-conference (online course) (contribution: exercises) 27. 12. 2023	»1) NumPy Essential Training 1: Foundations of NumPy« »2) NumPy Essential Training 2: Matplotlib and Linear Algebra Capabilities«
AC-conference (online course)	26. 12. 2023: »Advanced NLP with Python for ML« (contribution: exercise)
AC-conference (online course)	24. 12. 2023: »Python for Data Visualization« (contribution: exercise)
AC-conference (online course) (contribution: tests & exercises) 23. 12. 2023	»1) Python Parallel and Concurrent Programming Part 1« »2) More Python Tips, Tricks, and Techniques for Data Science«
AC-conference, Rüsselsheim am Main (contribution: exercises) 22. 12. 2023	»1) Coding Exercises: pandas« »2) Data Visualization in Python with Dash« »3) Data Visualizations with Plotly« »4) Python Data Science Mistakes to Avoid« »5) Rapid Application Development with Python«
AC-conference, Rüsselsheim am Main	21. 12. 2023: »Text Analytics and Predictions with Python« (contribution: test)
AC-conference, Rüsselsheim am Main	20. 12. 2023: »Faster Python Code« (contribution: test & exercise)
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 19. 12. 2023	»1) pandas Essential Training« »2) Python Data Structures and Algorithms«
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 18. 12. 2023	»1) Secure Coding in Python« »2) Test Automation with Python: Python for Testers« »3) Python for Algorithmic Thinking: Problem-Solving Skills« »4) Algorithmic Thinking with Python: Developing Problem-Solving Skills« »5) Data Ingestion with Python«
AC-conference (online course) (contribution: tests & exercises) 17. 12. 2023	»1) Advanced Python: Working with Databases« »2) Python Data Structures: Sets and Frozen Sets« »3) Python Data Structures: Power of Linked Lists for Technical Interviews« »4) Faster pandas« »5) Advanced Pandas« »6) Python for Data Science Tips, Tricks, & Techniques«
AC-conference (online course) 16. 12. 2023	»Advanced Python: Practical Database Examples« (contribution: exercise)

AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 15. 12. 2023	»1) <i>Effective Serialization with Python</i> « »2) <i>Developing Secure Software</i> « »3) <i>Multithreading mit Python</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 14. 12. 2023	»1) <i>Python: Programming Efficiently</i> « »2) <i>Python: Working with Files</i> «
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 11. 12. 2023	»1) <i>Python Data Structures: Trees</i> « »2) <i>Unit-Testing and Test Driven development in Python</i> « »3) <i>Processing Text with Python: Essential Training</i> «
AC-conference (online course) (contribution: tests & exercises) 10. 12. 2023	»1) <i>Python: Recursion</i> « »2) <i>Functional Programming with Python</i> «
AC-conference (online course) (contribution: tests & exercises) 09. 12. 2023	»1) <i>Programming Concepts for Python</i> « »2) <i>Unit Testing in Python</i> «
AC-conference, Rüsselsheim am Main (contribution: exercises) 07. 12. 2023	»1) <i>Python: Statistische Auswertungen</i> « »2) <i>Python für Systemadministratoren Grundkurs</i> «
AC-conference, Rüsselsheim am Main (contribution: exercises) 06. 12. 2023	»1) <i>8 Things You Must Know in Python</i> « »2) <i>Python: Geometrische Berechnungen</i> «
AC-conference, Rüsselsheim am Main (contribution: tests) 04. 12. 2023	»1) <i>Python Data Structures: Dictionaries</i> « »2) <i>Python: Decorators</i> «
AC-conference (online course) (contribution: tests & exercises) 03. 12. 2023	»1) <i>Learning Selenium</i> « »2) <i>Level Up: Advanced Python</i> « »3) <i>Advanced Python: Working with Data</i> « »4) <i>GitHub Copilot First Look</i> « »5) <i>Learning AI with GitHub Copilot</i> «
AC-conference (online course)	02.12.2023: » <i>Python Object-Oriented Programming</i> « (contribution: test)
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 01. 12. 2023	<i>Essentials of MLOps with Azure:</i> »1) <i>Databricks MLflow and MLflow Tracking</i> « »2) <i>Spark MLflow Projects on Databricks</i> « »3) <i>Spark MLflow Models and Model Registry</i> «
AC-conference, Rüsselsheim am Main	30.11.2023: » <i>Reinforcement Learning Foundations</i> « (contribution: test)
AC-conference, Rüsselsheim am Main	29.11.2023: » <i>Managing Python Projects</i> « (contribution: exercise)
AC-conference, Rüsselsheim am Main (contribution: tests & exercises) 27. 11. 2023	»1) <i>Apache Spark Deep Learning: Essential Training</i> « »2) <i>Test Automation Foundations</i> « »3) <i>Test Automation with Python: 1 Introduction to Automated Testing</i> «

AC-conference (online course) (contribution: tests) 26. 11. 2023	»1) Python: Design Patterns« »2) Python: Advanced Design Patterns« »3) Advanced Design Patterns: Design Principles«
AC-conference (online course) (contribution: exercises) 25. 11. 2023	»1) Python Projects« »2) Python: Unit-Testing« »3) Python: Type Annotations«
AC-conference, Rüsselsheim am Main (contribution: exercises) 24. 11. 2023	»1) Learning Hadoop« »2) Software Design: Modeling with UML« »3) Software Design: Developing Effective Requirements«
AC-conference, Rüsselsheim am Main	21. 11. 2023: »Programming Foundations: Design Patterns« (contribution: exercise)
AC-conference, Rüsselsheim am Main (contribution: tests) 20. 11. 2023	»1) Spark for ML and AI« »2) Fuzzy Logic«
AC-conference, Rüsselsheim am Main	16. 11. 2023: »MongoDB essentials and Python« (contribution: test)
AC-conference, Rüsselsheim am Main	30. 10. - 02. 11. 2023: »SAS Programming Essentials 2« (contribution: test)
AC-conference, Rüsselsheim am Main	09. 09. 2023: »Github for Data Scientists« (contribution: test)
AC-conference, Rüsselsheim am Main	31. 08. 2023: »SAS Programming Essentials« (contribution: test)
AC-conference, Rüsselsheim am Main	01. 06. 2023: »SAP Business One Basics & SAP Production Planning« (contribution: test)
AC-conference, Rüsselsheim am Main	30. 05. 2023: »Develop your leadership philosophy« (contribution: test)
AC-conference, Rüsselsheim am Main	07. 03. 2023: »Power BI: Dashboards for Beginners« (contribution: test)
AC-conference, Rüsselsheim am Main	07. 01. 2023: »Strategic thinking and action for managers« (contribution: test)
AC-conference, Rüsselsheim am Main	24. 11. 2022: »Talent Framework Atlas Copco Course« (contribution: test)
since 01. 08. 2021	14 CCMA ¹ research-conferences conducted (Rüsselsheim am Main)
February 19th 2019, Berlin	VDI-Conference (contribution: presentation »Sensor-based diagnostics according to the Vojta principle«)
November 2016, Atlanta (USA)	Atomic Physics 2016 Conference (invited as a speaker, contributions: presentation & poster)
January 2016, Bad Honnef	605th DPG-seminar (contribution: poster)
October 2015, Bad Honnef	600th DPG-seminar (contribution: poster)
May 2015, Bad Honnef	586th DPG-seminar (contribution: poster)
May 2015, Pecs (Ungarn)	3rd Work Meeting (contribution: presentation, international collaboration)

¹nexonar's research division on "Camera Calibration & Measurement Accuracy"

<i>March 2015, Heidelberg</i>	DPG-conference (contribution: poster)
<i>March 2014, Berlin</i>	DPG-conference (contribution: presentation)
<i>May 2013, TU Darmstadt</i>	Zertifikat Hochschullehre of the HDA (Hochschuldidaktische Arbeitsstelle)
<i>March 2013, Hannover</i>	DPG-conference (contribution: poster)
<i>March 2012, Stuttgart</i>	DPG-conference (contribution: poster)
<i>May 2012, Bad Honnef</i>	500th DPG-seminar (contribution: poster)
01. 10. 2008 - 30. 09. 2010, <i>TU Darmstadt</i>	Business, Corporate and Organization Management (M.Sc. lectures)
01. 10. 2005 - 30. 09. 2010, <i>TU Darmstadt</i>	Internship Measurement technology ²

²Practical physical courses in measurement technology (divisions: Solid state physics, Polymer physics, Nuclear physics, Astronomy, Optics)

Scholarships

2005 - 2007

Scholarship of the **Studienstiftung des deutschen Volkes**
(reimbursement of expenses for books)

2002 - 2005

Scholarship of the **Gemeinnützigen Hertie-Stiftung** for Grammar school students (reimbursement of expenses for books)

Languages

German

fluent

English

fluent

Russian

elementary knowledge

Serbian

native speaker

Computer knowledge

(see also the detailed IT-Skills list below)

Programming languages:

preferred languages: Mathematica, MATLAB, Python, R, C#, GAS, JavaScript
advanced knowledge: Octave, Maple, Maxima, Sage, Scilab, Scala, C++
basic knowledge: Java, HTML, PHP, VBA, Perl, SQL, SPSS, SAS, ASP.NET, MongoDB, RUST, Google Cloud, PowerBI, Django, Hibernate/Spring, F#
Rhino-Grasshopper (with GhPython), Ladybug, Kangaroo

Platforms:

Windows-Vista, -7, -8, -10, -11, Linux

General applications:

MS-Office (Word, PowerPoint, Excel), Open Office, Gnuplot, Origin, Euler, L^AT_EX, E_T_X, LaTeXDraw, Gimp, Inkscape, WinFIG, Visual Studio, ImageJ

Articles

Eur. Phys. J. D **69**, 232 (2015)

Nenad Balanesković
»Random unitary evolution model of quantum Darwinism with pure decoherence«

Eur. Phys. J. D **70**, 177 (2016)

Nenad Balanesković, Marc Mendler
»Dissipation, dephasing and quantum Darwinism in qubit systems with random unitary interactions«

Publications

ISBN 978-3-659-83733-3
Scolar's Press

Nenad Balanesković, »Random Unitary Operations and Quantum Darwinism - Environment as an efficient quantum memory«

Hobbies

Chess, Fitness, Literature

Authors: E. A. Poe, A. C. Doyle, H. G. Wells, U. Eco

Miscellaneous

Advanced knowledge:

Artificial Intelligence, SCRUM, Data Mining, Natural Language Processing, Machine Learning, UML (PlantUML), Design Patterns, MLflow, wxpython, wxGlade, TypeScript, KNIME, H2O.ai, TinyML, GenAI

Overview of IT-Skills

Levels of knowledge and experience

- elementary knowledge
- elementary knowledge and basic project experience
- advanced project experience
- deep knowledge
- expert

Issue	Level	Details	Experience [Years]	Optional : Description of experience
<i>Languages:</i>				
MATLAB / Simulink Wolfram Mathematica	●●●●○	also used: Octave, Sage, Maxima	16	[21]-[18], [16]-[2]
Python, R	●●●●○	Python-Packages: OpenCV, Qt5, SymPy Keras, TensorFlow Control, NumPy Pandas, nltk, PyPI SpaCy, PyTorch, pytest	15	[19], [16]-[1]
(Visual) C++, C#/.NET	●●●○○	regular usage	14	[21]-[19], [17], [13], [11]
VBA, GAS, SPSS, SAS	●●●○○	regular usage	9	[21]-[11], [7]-[6]
Java 8, Shell-Scripting, D	●●○○○	see Description	7	[21]-[19], [11]
Perl, Scala, Dart/Flutter	●●○○○	see Description	6	[11]
Go, PHP, HTML, CSS, Rust	●●○○○	see Description	5	[19], [11]
<i>Data bases:</i>				
MySQL, Postgresql	●●●○○	regular usage	5	[19]-[18], [16]-[11]
MongoDB (PyMongo)	●●●○○	regular usage	5	[18], [16]-[11]
Hadoop, PySpark	●●○○○	see Description	5	[11]
<i>Operating systems:</i>				
Windows (8, 10, 11)	●●●○○	regular usage	18	[18]-[1]
Linux	●●●○○	see Description	14	[21]-[19], [11]
<i>Tools:</i>				
Office: MS, Libre, Open	●●●○○	regular usage	16	[21]-[1]
MS Visual Studio (Code)	●●●○○	regular usage	12	[21]-[1]
Anaconda	●●●○○	regular usage	9	[19], [16]-[1]
Eclipse, NetBeans	●●○○○	see Description	7	[21]-[19]
PowerShell, ImageJ	●●●○○	see Description	4	[18], [15]-[9]
Google Cloud, MS Azure	●●○○○	see Description	4	[8]
<i>Miscellaneous:</i>				
SCRUM, Kanban	●●●○○	regular usage	8	[19]-[18], [12]-[1]
GitHub, GitLab	●●●○○	see Description	8	[13]-[9], [6]-[2]
Gimp, Inkscape, WinFIG	●●●○○	regular usage	14	[19]-[9]
LyX, LaTeX, Atom	●●●●○	regular usage	22	[21]-[18], [16]-[1]
Gnuplot, Origin	●●●●○	regular usage	22	[21]-[9]
UML, Design Patterns	●●●○○	see Description	6	[18], [16], [13]-[11]
LibreCAD, FreeCAD	●●○○○	see Description	4	[11], [9]
Ethereum, Arduino, LabView, F#	●○○○○	see Description	3	[11]

Levels of knowledge and experience

- elementary knowledge
- elementary knowledge and basic project experience
- advanced project experience
- deep knowledge
- expert

Issue	Level	Details	Experience [Years]	Optional : Description of experience
wyPython Tkinter	●●●○○	see Description	6	[11]-[6]
TypeScript JavaScript	●●●○○	see Description	7	[11]-[6]
WordPress	●●○○○	see Description	3	[11]-[6]
PlantUML	●●●○○	regular usage	4	[11]-[2]
Github Copilot	●●○○○	see Description	4	[11]-[2]
AutoCAD	●●○○○	see Description	3	[11], [9]
<i>Frameworks:</i>				
Hibernate Spring Grasshopper Ladybug Rhino <i>Lunchbox</i> Kangaroo <i>Galapagos</i>	●●○○○	see Description, with Python-Packages: GhPython	3	[11]-[2]
Django wxGlade Flask	●●○○○	with Python-Packages: Plotly , Tkinter , Dash alpha_vantage backtesting , yfinance Scrapy , Scipy seaborn , nmap pynput , mlxtend poetry , black flake8 , bs4 bootstrap roboticstoolbox AutoGluon with R-Packages: Shiny , ggplot	3	[11]-[6]
Kubernetes	●●○○○	see Description	3	[11]-[6]
MLflow , TinyML KNIME , H2O.ai	●●○○○	regular usage	4	[11]-[2]
Micro Python CircuitPython	●●○○○	with Python-Packages: machine	3	[11]-[4]
<i>Business Analysis Tools:</i>				
PowerBI Tableau	●●○○○	regular usage	4	[11]-[1]

Levels of knowledge and experience

- elementary knowledge
- elementary knowledge and basic project experience
- advanced project experience
- deep knowledge
- expert

Python / R package	Level	Experience [Years]	Details
<i>OpenCV, cv2</i>	●●●●○	6	Package for machine vision analysis.
<i>Qt5, Tkinter</i>	●●●○○	7	Packages for generating graphical user interfaces (GUIs).
<i>SymPy, ScikitLearn</i>	●●●●○	15	Packages for (symbolic) calculations.
<i>Keras, TensorFlow</i>	●●●○○	4	Frameworks for machine learning analysis of large data sets.
<i>Control</i>	●●○○○	4	Package for system control analysis.
<i>NumPy</i>	●●●●○	15	Package for numeric calculations.
<i>Pandas</i>	●●●●○	15	Package for manipulation of data sets (tables).
<i>nlTK, SpaCy</i>	●●●○○	5	Packages for natural language processing.
<i>roboticstoolbox</i>	●●○○○	3	Python's toolbox for control of robotic agents.
<i>PyTorch</i>	●●●○○	5	Frameworks for machine learning analysis of large data sets.
<i>pytest</i>	●●●○○	6	Package for debugging and testing of python code.
<i>Plotly, Dash</i>	●●○○○	4	Packages for interactive plot generation.
<i>alpha_vantage backtesting yfinance</i>	●●○○○	3	Packages for analysing and testing finance data.
<i>Scrapy bs4</i>	●●●○○	5	Packages for web scraping (BeautifulSoup).
<i>poetry black flake8</i>	●●●○○	5	Packages for code linting.
<i>seaborn matplotlib Shiny ggplot</i>	●●●●○	15	Packages for plotting data sets.
<i>bootstrap, Scipy</i>	●●●○○	6	Packages for statistical data analysis and optimization.
<i>mlxtend</i>	●●●○○	4	ML-library of useful tools for regular data science tasks.
<i>pynput, nmap</i>	●●●○○	3	Libraies for controlling and monitoring input devices and ports.
<i>machine</i>	●●○○○	3	MicroPython package for micro-controllers.
<i>GhPython</i>	●●○○○	3	Package for Python scripting with Rhino's Grasshoper plug-in.
<i>Ladybug</i>	●●○○○	3	Grasshopper's Python plug-in for weather forecast modeling.
<i>Kangaroo</i>	●●○○○	3	Rhino-Grasshopper's live physics plug-in for form finding.
<i>Lunchbox</i>	●●○○○	3	Rhino-Grasshopper's ML solver plug-in.
<i>Galapagos</i>	●●○○○	3	Rhino-Grasshopper's evolutionary solver plug-in.
<i>AutoGluon</i>	●●○○○	3	Library for automated evaluation of ML models.

Professional Experience

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1 Project 21:

08 2024 - 09 2024 Customer: **nexonar GmbH (Rüsselsheim)**
Different research projects for Desoutter & AtlasCopco
»Design of an interactive panel in PowerBI for displaying
latest production details and developments«

Soft2tec's LAB(oratory) division needs an interactive panel in PowerBI for displaying latest camera production details and developments associated with different research topics. It should

1. access appropriate updated Excel-sheets and display latest information regarding s2t storage of needed materials, hardware as well as software components;
2. display changes in the number of produced and / or used calibrated infra-red cameras and track the latest trends regarding upcoming camera orders;
3. present latest software releases, research results and link them to appropriate documentation sources.

The aim of this project is to establish an ISO-conform PowerBI-interface for aiding users in tracking and visually latest production details and developments within the laboratory division of soft2tec GmbH, as well as in performing quality management procedures for testing produced batches of hardware components (backed by appropriate software functionalities) that should reduce the overall dropout of used materials.

Tasks:

- Write an article containing a thorough description of the PowerBI-interface for displaying quality control information regarding camera production tasks and test procedure for nexonar's hardware components.
- Visualization of all results with Excel, Python, PowerBI (or Tableau).
- Bug fixing, process documentation.

Technologies:

- Excel;
 - Python;
 - Google Apps Script, PowerBI, Tableau;
 - Motion Visualizer, 3DAWin, GML, FlyCapture;
 - LaTeX;
 - Scrum, Github/Git.
-

2 Project 20:

06 2024 - 09 2024 Customer: **nexonar GmbH (Rüsselsheim)**

Different research projects for Desoutter & Atlas Copco

» **Write a detailed AI-management report for a fully automated ISO-standardized product certification pipeline (laboratory)** «

Using ML- and AI-methods in combination with novel, as well as standard algorithms of statistical inference, mathematical physics and (non-)linear optimization, has proven itself a crucial component of numerous tasks associated with automating diverse industrial processes. In this report we intend to design a roadmap to the fully automated certification of infra-red cameras, calibrated and validated within the LAB(oratory)-division of s2t GmbH.

The aim of this project is to establish an ISO-conform roadmap to accomplishing a fully automated product certification pipeline within the upcoming 4 years. The roadmap should delve into technological details and potential milestones of this large undertaking.

Tasks:

- Write an article containing a thorough description of Gauge Study-driven quality control test procedure for nexonar's hardware components.
- Perform an ML-driven comparison analysis of different statistical, ML- and AI-algorithms aided by Python and R.
- Visualization of all results with Python, Rhino-Grasshoper, PowerBI (or Tableau) and MATLAB.
- Bug fixing, process documentation.

Technologies:

- MATLAB, R;
 - Python, Rhino-Grasshopper, Ladybug, Kangaroo;
 - Google Apps Script, PowerBI, Tableau;
 - Motion Visualizer, 3DAWin, GML, FlyCapture;
 - LaTeX, LaTeXDraw;
 - Scrum, Github/Git.
-

3 Project 19:

01 2024 - 01 2025 Customer: **nexonar GmbH (Rüsselsheim)**

Different research projects for Desoutter & AtlasCopco

»**Design of new Gauge Study-driven procedures and software functionalities
for quality control tests of produced hardware batches**«

Nexonar's infra-red (IR) trackers and cameras are used in numerous customer applications. In order to guarantee high reliability of these hardware components optimal quality control Gauge Study-driven test procedures need to be designed and implemented as Python-GUI functionalities.

The aim of this project is to establish ISO-conform quality management procedures for testing produced batches of hardware components backed by appropriate software functionalities that should reduce the overall dropout of used materials.

Tasks:

- Write an article containing a thorough description of Gauge Study-driven quality control test procedure for nexonar's hardware components.
- Perform an ML-driven optimization analysis of statistical quality tests of product batches aided by Python and R.
- Visualization of all results with Python, Rhino-Grasshoper, PowerBI (or Tableau) and MATLAB.
- Bug fixing, process documentation.

Technologies:

- MATLAB, R;
 - Python, Rhino-Grasshopper, Ladybug, Kangaroo;
 - Google Apps Script, PowerBI, Tableau;
 - Motion Visualizer, 3DAWin, GML, FlyCapture;
 - LaTeX;
 - Scrum, Github/Git.
-

4 Project 18:

01 2024 - 05 2024 Customer: **nexonar GmbH (Rüsselsheim)**

Different research projects for Desoutter & AtlasCopco

»**Design of new Dialog of nexonar Calibration Analyzer (nCA)**
supporting manual camera validation«

The Pythonic nexonar Calibration Analyzer (nCA) GUI needs a new button which would allow users to generate validation reports (pdfs) from position measurement data recorded with calibrated infra-red FLIR-cameras. This button should provide users with a dialog that

1. allows pre-selection of camera parameters (such as "sensor type" [IR / NIR]) and lens parameters (such as "focal length in mm" [8 / 12.5 / 16 / 25]);
2. enables upload of recorded distance measurement files (csv data) for translation (T) and rotation (R) tests thereby checking whether # of T-files equals # of R-files;
3. performs validation of T- and R-data files (csv) for each camera separately; displays numerical and graphical results in the corresponding display-area of the GUI;
4. stores validation results as pdf report for each camera separately;
5. offers possibilities for correcting displayed values manually by the user (for instance when rounding a result to two digits instead of a four-digit precision or changing the status color of a particular result);
6. aborts the entire procedure, if necessary.

The aim of this project is to establish ISO-conform quality management procedures for manual camera validation within a new dialog of nCA version 3.0.

Tasks:

- Write an article containing a thorough description of manual camera validation test procedures for nexonar's hardware components.
- Perform an ML-driven optimization analysis of statistical quality tests of product batches aided by Python and R.
- Visualization of all results with Python, Rhino-Grasshoper, PowerBI (or Tableau) and MATLAB.
- Bug fixing, process documentation.

Technologies:

- MATLAB, R, MLflow, H2O.ai, TinyML;
- Python, Rhino-Grasshopper, Ladybug, Kangaroo;
- Google Apps Script, PowerBI, Tableau;
- Motion Visualizer, 3DAWin, GML, FlyCapture;
- LaTeX;
- Scrum, Github/Git.

5 Project 17:

01 2023 - 06 2024 Customer: **nexonar GmbH (Rüsselsheim)**

Different research projects for Desoutter & AtlasCopco

»Design of a new infra-red Tracker Form«

Nexonar's infra-red (IR) trackers are used in numerous customer applications. In order to operate these IR-trackers rely on optimal geometrical placement of IR-diodes along their three rigid body axes.

The aim of this project is to design a new form of IR-trackers whose diode placement along its three rigid body axes guarantees robustness of distance measurements with respect to small tracker tilts.

Tasks:

- Write an article containing a thorough mathematical and physical study of desired (optimal) IR-tracker forms.
- Perform an optimization analysis of diode placements along the three rigid body axes of desired IR-tracker design candidates aided by Python, Rhino-Grasshopper and R.
- Visualization of all results with Python and MATLAB.
- Bug fixing, process documentation.

Technologies:

- MATLAB, R;
 - Python, Rhino-Grasshopper, Ladybug, Kangaroo;
 - Google Apps Script, PowerBI, Tableau;
 - Motion Visualizer, 3DAWin, GML, FlyCapture;
 - LaTeX;
 - Scrum, Github/Git.
-

6 Project 16:

04 2022 - 06 2024 Customer: **soft2tec GmbH (Rüsselsheim)**
Different research projects for Desoutter & AtlasCopco
»PyQt5 Camera Pre-Calibration GUI«

Soft2tec's infra-red (IR) cameras are used in numerous customer applications. In order to operate they use license files generated via nexonar's Camera License Tool from an xml-file containing a list of estimated intrinsic camera parameters. These estimates of intrinsic camera parameters (such as its focal length or its principal axis) are generated by OpenCV calibration algorithms running over a set of chessboard images collected by a robotic agent with respect to a specific IR-camera.

The aim of this project is to design a PythonQt5-GUI which should perform a cumulative error-reprojection analysis of an entire set of collected chessboard images associated with a particular IR-camera and extract from them a subset of »appropriate« chessboard images that would lead to optimal estimates of intrinsic camera parameters prior to the final stage of the OpenCV-calibration.

Tasks:

- Write a PythonQt5 script which should provide a GUI-driven characterization of chessboard images based on cumulative OpenCV-error reprojection prior to their final calibration.
- Perform histogram analysis of chessboard images by means of error reprojections with Python, ImageJ and R in order to acquire experimental estimates of a subset of collected chessboard images that may be ignored when performing OpenCV calibrations.
- Visualization of all results with Python and MATLAB.
- Bug fixing, process documentation.

Technologies:

- MATLAB, Wolfram Mathematica, R;
 - Python (Keras, TensorFlow, OpenCV, Qt5, MLflow);
 - Google Apps Script;
 - Motion Visualizer, 3DAWin, GML, FlyCapture;
 - LaTeX, PowerBI;
 - ImageJ, wxpython, Tkinter;
 - Scrum.
-

7 Project 15:

12 2021 - 03 2022 Customer: **soft2tec GmbH (Rüsselsheim)**
Different MQTT-driven projects (Nissan, BMW, Airbus)
»Automation of Lens Aperture Adjustments«

Soft2tec's infra-red (IR) cameras are used in numerous customer applications. Therefore, an automated adjustment of appropriate lens aperture values would accelerate and enhance the procedure of camera calibration and validation considerably. Therefore, it is, as a first step, necessary to obtain reliable theoretical predictions of confidence intervals for aperture adjustments of lenses characterized by different focal lengths (GAS, MATLAB, R).

In addition, as a further research step, it appears important to acquire experimental estimates of reliable confidence intervals for aperture adjustments associated with different types of lenses (Python, ImageJ, R) .

Finally, one should also compare all findings of the afore mentioned two research steps and thus cross-validate them mutually (MATLAB, Wolfram Mathematica).

Tasks:

- Write a GAS script which should provide reliable theoretical confidence intervals for aperture adjustments associated with lenses characterized by different focal lengths.
- Perform histogram analysis of pixel-brightness on GML-generated bmp files with Python, ImageJ and R in order to acquire experimental estimates of reliable confidence intervals for aperture adjustments associated with lenses characterized by different focal lengths.
- Visualization of all results with Python and MATLAB.
- Bug fixing, process documentation.

Technologies:

- MATLAB, Wolfram Mathematica, R;
 - Python (Keras, TensorFlow, OpenCV, MLflow);
 - Google Apps Script;
 - Motion Visualizer, 3DAWin, GML, FlyCapture;
 - LaTeX;
 - ImageJ;
 - Scrum.
-

8 Project 14:

05 2021 - 06 2024 Customer: **soft2tec GmbH (Rüsselsheim)**
»Cloud-based Automation of Camera Validation«

Soft2tec's infra-red (IR) cameras are used in numerous customer applications. Therefore, a stable GAS routine should be designed that would parse csv files of camera-tracker distance measurements captured by Motion Visualizer (MV) and calculate static as well as dynamic projections of error interval width with respect to each individual camera (as specified by its corresponding serial number, SN). This would allow one to classify and validate a camera without being forced to perform manual translation measurements via 3DAWin.

In addition, the functionality of the GAS routine should also be deployed to Google Cloud.

Finally, one should also perform data analysis on xml-files (generated by the GML-software) containing camera parameters and their tolerance intervals and infer whether it is possible to correlate different parameter ranges with specific classification types of the camera validation procedure. If successful, this analysis could even eliminate the necessity of an explicit camera validation by replacing it with an implicit validation approach, in accordance with ISO/IEC 17025.

Tasks:

- Write and deploy a GAS script to Google Cloud that should automatize the camera validation procedure and compute dynamic error tolerances of camera tracker distance measurements based on their static counterparts.
- Perform data mining analysis on GML-generated xml files containing parameters of calibrated cameras and study the possible correlations between calculated tolerance ranges of camera parameters and specific classification types of the camera validation procedure.
- Visualization of all results with Python and MATLAB.
- Bug fixing, process documentation.

Technologies:

- MATLAB, Wolfram Mathematica, R;
- Python (Keras, TensorFlow, OpenCV, MLflow);
- Excel, Google Apps Script, PowerBI;
- Motion Visualizer, 3DAWin, GML;
- LaTeX, GitLab, GitHub;
- Google Cloud, VS Core;
- Scrum, Power-Shell, Kubernetes.

9 Project 13:

08 2019 -12 2021 Customer: **soft2tec GmbH (Rüsselsheim)**
FALCON-project collaboration
»FEM-Modeling of External Stress on Tracker Housings«

Soft2tec's infra-red (IR) trackers are used in numerous customer applications and often have to endure high external forces. Therefore, a thorough FEM-analysis of stress-distribution throughout the entire tracker-housing should lead to valuable insights into robustness of materials currently used in the framework of the tracker manufacturing process.

In addition, the results of an FEM-analysis should be compared with standard predictions of stress distribution within tracker-housings obtained by utilizing a static rigid rod model.

This should also allow to assess whether a full-fledged FEM-modeling should be considered as a necessary analytical approach compared to a simpler (and cheaper) static rigid rod modeling with respect to future robustness tests performed on tracker-housings.

Tasks:

- Perform an FEM-analysis of soft2tec-tracker housings and their robustness when subjected to varying external forces.
- Compare the FEM-results with robustness predictions obtained from a standard static model of tracker-housings composed of rigid rods.
- Visualization of all results with Python and Rhino-Grasshopper.
- Bug fixing, process documentation.

Technologies:

- MATLAB, Wolfram Mathematica, R;
 - Python, Keras, TensorFlow, MLflow;
 - Excel, Google Apps Script;
 - Motion Visualizer, 3DAWin;
 - LaTeX;
 - FreeCAD, LibreCAD;
 - Scrum, Power-Shell.
-

10 Project 12:

05 2019 - 06 2024 Customer: **soft2tec GmbH (Rüsselsheim)**
LIANDRI-project collaboration
»Error Estimation of Distance Measurements«

When providing customer-related service it is of highest importance for soft2tec GmbH to supply each customer with infra-red cameras and trackers suitable for their specific projects. Therefore, an interactive GUI, which should provide reliable estimates of camera-tracker distances and their accuracy with respect to different camera parameters as inquiry inputs, would considerably improve the just-in-time support and interaction between soft2tec and its collaborators. Additionally, a thorough algorithmic design of data acquisition, preparation and pattern extraction methods should lead to new experimental setups and Gauge studies, especially with respect to dynamic measurements of camera-tracker distances.

Tasks:

- Design a MATLAB-module within a MATLAB-GUI that should provide maximum estimates of distance errors along the camera's z-axis measured by IR-cameras (rectangular sensor) and NIR-cameras (square sensor) with respect to lenses of different focal length (8 mm, 12.5 mm and 16 mm) and shutter times (0.5 ms, 1 ms, 1.5 ms and 2 ms) for different z-distances between an infra-red camera and an M-size tracker.
- Analyze the z-dependence of tracker's diode-pixels detected by an infra-red camera with respect different pixel-resolutions of camera sensors and lenses of different focal lengths, as well as by taking into account several increasing values of shutter time.
- Design algorithms for data acquisition with respect to enlarged camera's parameter spaces both within static and dynamic measurements of tracker-camera distances along the camera's z-axis.
- Bug fixing, process documentation.

Technologies:

- MATLAB, Wolfram Mathematica, R;
 - Python, Keras, TensorFlow, MLflow;
 - Motion Visualizer, 3DAWin;
 - LaTeX;
 - Scrum, Power-Shell.
-

11 Project 11:

03 2017 - 01 2025 Customer: **soft2tec GmbH (Rüsselsheim)**
»Automation of the camera calibration process«

In order to standardize the camera and tracker calibration processes their main procedural steps need to be fully automated. This will in turn increase the output of calibrated cameras and trackers and ensure the reliability of their distance measurements and movement tracking capabilities. The main goal remains an automatized, robot-driven system capable of calibrating infra-red (IR) cameras and trackers, as well as validating their performance by means of standardized statistical inference methods. This project relies partially on results and experience obtained within earlier completed projects, such as [18], [14], [13], [12], [10] and [9] introduces new research topics outlined within the task list below.

Tasks:

- Design an appropriate camera calibration procedure and conceptualize its robot-driven implementation;
- Analyze the the ideal placement of electrical components within the robot's control cabinet from the point of view of temperature distribution and ventilation - Python (Qt5, Control, LabView, Simulink);
- Maintain regularly the robot's frontend web page (Go, HTML, PHP, Flutter/Dart);
- Parse robot's log files for specific error message types via Python's Natural Language Processing Toolkit (nltk) in order to improve the error response of the robot's frontend from the standpoint of its clarity.
- Store all images of the calibration chess board into a data lake (PySpark, Hadoop, Java, Scala) and maintain a reference data base of all files (xml, licenses, etc) generated during camera and tracker calibration procedures (MySQL, MongoDB);
- Optimize GML's image processing algorithms - Python (OpenCV, Keras, TensorFlow, MLflow);
- Implement MATLAB-routines for statistical inference and time-series analysis that should aid an automatized validation of calibrated cameras and test them with Wolfram Mathematica and C# (MATLAB, Wolfram Mathematica, R, C#, Excel VBA, SPSS, Google Apps Script, SAS);
- Test the Arduino-code implementing robot's movement trajectories (C++) and time-optimize robot's trajectories by setting up the corresponding movement recipes within the robot's frontend (web page);
- Compare the performance of C++ mathematical libraries with their corresponding Rust implementations (Rust);
- Bug fixing, process documentation (FreeCAD, Rhino, LaTeX).

Technologies:

- MATLAB, Wolfram Mathematica, R;
- Python (Qt5, Control, OpenCV), Keras, TensorFlow ;
- C++, C#, Java, Scala, Rust;
- Excel, Google Apps Script, VBA, SPSS, PowerBI;
- MySQL, MongoDB, SAS, PySpark, Hadoop, Kubernetes;
- LabView, Arduino, Rhino-Grasshopper, Ladybug, Kangaroo;
- Motion Visualizer, 3DAWin;
- Go, HTML, PHP, Flutter/Dart;
- LaTeX, Scrum, Power-Shell, GitHub, GitLab.

12 Project 10:

11 2018 - 03 2019 Customer: **Faurecia Germany (Rüsselsheim)**

»**Quaternion-analysis of movement patterns for a steaming robot with MATLAB**«

In the first instance of this project one aims to characterize relation between the robot's position measurements and the Euler-angle data, which then need to be transformed into the Quaternion picture by means of MATLAB.

Such quaternionic representation of angle-measurement data (robot's orientation) is then fed into robot's software to ensure robot's proper movements during the process of automatized steaming of car seats.

Tasks:

- Design a MATLAB-executable capable of transforming angular movement coordinates into their quaternionic representation a steaming robot-software is capable to understand;
- Bug fixing, process documentation.

Technologies:

- MATLAB, Wolfram Mathematica;
 - Python, Keras, TensorFlow;
 - Excel, Google Apps Script, VBA, SPSS;
 - MySQL, MongoDB;
 - Motion Visualizer, 3DAWin;
 - LaTeX, Scrum, Power-Shell.
-

13 Project 9:

08 2018 - 10 2019 Customer: **soft2tec GmbH (Rüsselsheim)**

»**Gauge R&R Study Optimization of the Robustness of**

Distance Measurements in the Course of a Standard Camera Calibration Procedure«

In the first instance of this project one aims to characterize the robustness of distance-errors obtained in the course of camera calibration-related distance measurements between a specific camera and the standard infra-red (IR) calibration-tracker M13.

This task should be accomplished by means of the Gauge R&R Study. The data evaluation algorithms are intended to be implemented as Google Apps Script and MATLAB's OOP-modules that should, in the long run, be part of the overall automatization-process of the standard camera calibration procedure established in the course of numerous (more than 200) calibration experiments (performed within the time-window between 15. 03. 2017 and 30. 04. 2018). These modules should then be translated (ported) into the C# code.

Finally, by looking at the error-robustness of different cameras (with different serial numbers), one could even obtain a tolerance range within which future error-values of camera-tracker distances could be anticipated, thereby enhancing the decision-making process of the (future) automatized camera-calibration procedure(s). This would allow us in the future to offer customer-adapted camera calibration solutions and thus perform a Gauge R&R Study for each customer separately.

Tasks:

- Design a full-fledged GoogleAppsScript macro capable of performing a Gauge R&R study over gathered measurements recorded with soft2tec's Motion Visualizer software;
- Bug fixing, process documentation.

Technologies:

- MATLAB, Wolfram Mathematica;
 - C#, C++;
 - Python, Keras, TensorFlow, Qt5;
 - Excel, Google Apps Script, VBA;
 - MySQL, MongoDB, SAS, SPSS;
 - Motion Visualizer, 3DAWin;
 - LaTeX, Power-Shell.
-

14 Project 8:

05 2018 - 07 2018 Customer: **soft2tec GmbH (Rüsselsheim)**

**»Linear Regression Optimization of the Robustness
of Distance Measurements in the Course of the Standard Camera Calibration Procedure«**

In the first instance of this project one aims to characterize the robustness of distance-errors obtained in the course of camera calibration-related distance measurements between a specific camera and the standard infra-red (IR) calibration-tracker M13.

This task should be accomplished by means of the machine-learning driven linear (or even non-linear) regression (if necessary). The data evaluation algorithms are intended to be implemented as a MATLAB-module that should, in the long run, be part of the overall automatization-process of the standard camera calibration procedure established in the course of numerous (more than 200) calibration experiments (performed within the time-window between 15. 03. 2017 and 30. 04. 2018).

As a further feature one could also test the distance-error robustness with respect to tracker-codings other than M13, or even with respect to multiple tracker-codings operating simultaneously. This would allow us to extract those coding-combinations (groups) of trackers that operate, from the point of view of the camera calibration, in a mutually compatible manner.

Finally, by looking at the error-robustness of different cameras (with different serial numbers), one could even obtain a tolerance range within which future error-values of camera-tracker distances could be anticipated, thereby enhancing the decision-making process of the (future) automatized camera-calibration procedure(s).

Tasks:

- Analytical and mathematical modeling and description of the robustness of distance measurements generated by the standard soft2tec-calibration procedure by means of standard machine learning techniques;
- Bug fixing, process documentation.

Technologies:

- MATLAB, Wolfram Mathematica;
 - C#, C++, R;
 - Python, Keras, TensorFlow, Qt5;
 - Excel, Octave, MySQL, MongoDB, SAS, SPSS;
 - Motion Visualizer, 3DAWin;
 - LaTeX, Power-Shell.
-

15 Project 7:

03 2018 - 05 2018 Customer: **Honda Engineering Europe Ltd (Swindon)**
»Design of mathematical and physical criteria for the evaluation of
movement and performance processes at a motor block assembly line«

In order to describe temporal performance (efficiency) of workers when bolting together motor blocks at an assembly line in a mathematically and physically correct manner, that would in turn facilitate a design of a proper feedback software system, *Personal Perfomance Index* (**PPI**) has been introduced and thoroughly tested based on real data measurements performed and gathered in a Honda-plant in Swindon.

Tasks:

- Design of mathematically and physically motivated criteria (quantities) for measuring temporal efficiency of workers at a motor block assembly line;
- Bug fixing, process documentation.

Technologies:

- Analytical modeling (especially functional and fractional calculus);
 - MATLAB, Python, Visual C++, Wolfram Mathematica, Rust;
 - Excel, MySQL, MongoDB, SPSS;
 - LaTeX, Power-Shell.
-

16 Project 6:

09 2017 - 03 2020 Customer: **ISI Bau- und Gebäudedienstleistungen GmbH**
(Frankfurt am Main)
»Extension of the Matlab's data analysis GUI with functionalities
for pattern recognition of construction grid movements«

A MATLAB-GUI structure should be designed which would distinguish construction grid undergoing dynamic changes from its state of rest. This could be achieved by exposing a construction grid to diverse controlled external influences (such as shaking, hits, deliberate movements, etc.) and recording its acceleration and angular velocity by means of Internal Measurement Units (IMUs).

Such signals could then be exposed to MATLAB-modules for frequency and time domain analysis already present within the MATLAB-GUI designed in the course of the SenseVojta project in order to enable reliable recognition and prediction of construction grid movements. This type of MATLAB-functionality would then provide essential data analytical services as part of a larger software warning system designed for capturing unexpected (often weather-induced) movements of construction grids.

Tasks:

- Design an appropriate MATLAB-GUI functionality for pattern recognition and prediction of construction grid movements;
- Bug fixing, process documentation.

Technologies:

- MATLAB, Python, Visual C++, Wolfram Mathematica;
 - Excel, MySQL, MongoDB;
 - LaTeX.
-

17 Project 5:

09 2017 - 10 2017 Customer: **Carl-Zeiss SMT GmbH (Roßdorf)**
»Error mitigation in the Auto Global Alignment (AGA) Module«

Extension and repair of the already existing Auto Global Alignment (AGA) module written in C++. The AGA module should correctly recognize edges of all types of masks made from MoSi (molybdenum-silicon) and EUV-materials and yield the correct number of detected mask edges (2, 4 or 6).

Tasks:

- Visual Studio C++ programming of modules responsible for the recognition of edges and structures within mask profiles produced from diverse materials;
- Bug fixing.

Technologies:

- Visual Studio;
 - Visual C++, Excel.
-

18 Project 4:

04 2017 - 02 2020 Customer: **Internationale Vojta Gesellschaft e. V. (Siegen)**
»Matlab Data Analysis Structure for SenseVojta-Measurements«

Through the therapeutic use of reex locomotion, attributed to Dr. Vaclav Vojta, elementary movement patterns of patients with damaged central nervous system and musculoskeletal system can be restored (at least regarding some body areas), i.e. these movement patterns may become accessible to the patient. Reex movements are activated with the help of the SenseVojta (SV) therapy: during a therapy session, the therapist exerts targeted pressure on certain areas of the patient's body.

A patient usually lies on his stomach, back or side. Pressure stimuli of therapists lead to the activation of spontaneous (unconsciously used) movements of muscles, especially within the spine region, however spontaneous movements of patient's arms, legs, hands and feet - regardless of his/her age - may also occur. Through the use of SV reex locomotion, performing elementary components of human locomotion, such as

1. the balance of patient's body during movements (postural control);
2. maintenance of patient's upright body posture (opposed to the direction of the gravitational force) and
3. targeted gripping and walking movements of the limbs (phasic mobility) become feasible again.

The SenseVojta (SV) project aims at aiding therapists with a software infrastructure that could reliably characterize six possible activity levels¹ (0-5) of a particular patient. For details regarding the SV therapy, which we do not intend to address here, please refer to the web site <https://www.vojta.com/en/> (subsection The Vojta principle).

More specically, we will implement a MATLAB-GUI for combining machine learning techniques with standard frequency analysis of measured signals that could offer reliable predictions of patient's activity levels during a regular SV therapy session. This MATLAB-GUI should:

- provide a data analysis structure that would quantitatively aid therapists during therapy sessions in their aim to recognize movement patterns of patients;
- execute different scripts (such as spectrogram or psdWelch) suited for time (series) and frequency analysis of measured signals such that many measurement sessions could be compared with each other;
- allow new MATLAB-scripts to be flexibly added and removed from the execution sequence, if necessary;
- allow machine learning supported comparisons of velocity, acceleration and angular velocity measurements in time and frequency domain extracted from signals recorded by means of infra-red (IR) sensors with respect to different body parts of a patient - breast, arms, legs, abdomen, etc.;
- provide a concise csv report of generated statistical results.

Tasks:

- MATLAB GUI programming for frequency and time analysis of movement signals measured by sensors;
- Design of machine learning algorithms;
- Bugfixing, documentation.

Technologies:

- MATLAB, Octave, Java;
- Excel, MySQL, MongoDB, SAS, SPSS;
- Redmine, Jenkins. Motion Visualizer, 3DAWin;
- Scrum, LaTeX, Power-Shell.

19 Project 3:

10 2011 - 03 2016 Customer: **Institut für Angewandte Physik, TU Darmstadt,**
research group of Prof. Dr. Gernot Alber
»Dynamics of Open Quantum Systems and Quantum Computers« –
research, education and application development

Design of modern concepts of quantum mechanical algorithms and their application in quantum computers. In the course of this research project mathematical and physical criteria for the most efficient data storage of data have been proposed and utilized within the design of an appropriate layered quantum hard disk structure.

Tasks:

- OOP of numerical simulations (quantum networks, stochastic differential equations, graph theory) with C++, C# and MATLAB;
- Code-testing with Wolfram Mathematica, Python, R and MATLAB;
- Process documentation mit LaTeX;
- Development of a GUI for numerical simulations with MATLAB, C# and Visual C++;
- Design, update and maintenance of the Institute's webpage with HTML und PHP.

Technologies:

- Visual Studio;
 - C++, MATLAB, R, Python, Wolfram Mathematica;
 - HTML, PHP, Java, MySQL;
 - Linux/Windows, LaTeX, SPSS, SAS, Shell-Scripting;
 - C#, WPF;
 - Scrum.
-

20 Project 2:

11 2009 - 02 2011 Customer: **Institut für Theoretische Kernphysik, TU Darmstadt,**
research group of Prof. Dr. Jürgen Berges
»Functional Renormalization and Non-Equilibrium
in the Early Evolution of the Universe« –
research, education and application development

Theoretical description of the inflationary phase in the course of the early evolution of the Universe by means of the functional renormalization group (FRG).

Tasks:

- OOP of numerical simulations (functional renormalization group, partial differential equations) with C++ and MATLAB;
- Code-testing with Wolfram Mathematica and MATLAB;
- Process documentation mit LaTeX;
- Development of a GUI for numerical simulations with MATLAB.

Technologies:

- Visual C++;
 - Wolfram Mathematica, MATLAB;
 - Linux/Windows, LaTeX, SPSS, SAS, Shell-Scripting.
-

21 Project 1:

10 2007 - 03 2008 Customer: Institut für Theoretische Kernphysik, TU Darmstadt, research group of Prof. Dr. Jürgen Berges »Non-Equilibrium Initial Conditions for Plasma Instabilities« – research, education and application development

Theoretical description of the universe immediately after its formation („big bang“) along with physical conditions that used to dominate its early evolution by means of modern mathematical and physical concepts of quantum field theory (QFT).

Tasks:

- OOP of numerical simulations (functional renormalization group, partial differential equations) with C++ and C;
- Code-testing with Wolfram Mathematica and MATLAB;
- Process documentation with LaTeX;
- Extension and redesign of an existing C++ console application for numerical simulations.

Technologies:

- Visual C++, Objective C;
 - Wolfram Mathematica, MATLAB;
 - Linux/Windows, LaTeX, SPSS, SAS, Shell-Scripting.
-