

```
1  private class Node {
2      volatile boolean flag;    // signal when done
3      boolean active;         // active or passive?
4      Node parent;            // parent node
5      Node partner;           // partner node
6      // create passive node
7      Node() {
8          flag = false;
9          active = false;
10         partner = null;
11         parent = null;
12     }
13     // create active node
14     Node(Node myParent) {
15         this();
16         parent = myParent;
17         active = true;
18     }
19     void await(boolean sense) {
20         if (active) { // I'm active
21             if (parent != null) {
22                 while (flag != sense) {}; // wait for partner
23                 parent.await(sense);   // wait for parent
24                 partner.flag = sense; // tell partner
25             }
26         } else {                  // I'm passive
27             partner.flag = sense; // tell partner
28             while (flag != sense) {}; // wait for partner
29         }
30     }
31 }
```

FIGURE 18.15 The TourBarrier class.