

## CSE 250A Lecture 3.

Notation :

\* Joint distribution  $P(X_1=x_1, X_2=x_2, \dots, X_n=x_n)$   
involves  $O(2^n)$  numbers for binary random variables

\* More Compact representations  
More efficient Algorithms

Example :

\* Binary Variable :

Burglary ?	$\rightarrow B$
Earthquake ?	$\rightarrow E$
Alarm ?	$\rightarrow A$
John Calls ?	$\rightarrow J$
Mary Calls ?	$\rightarrow M$

\* Joint Distribution :

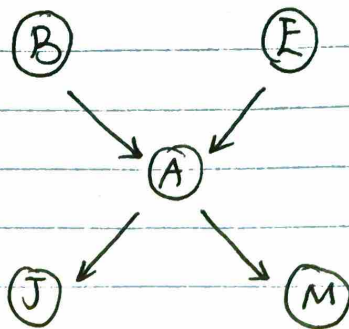
$$P(E, B, A, J, M) = P(B) P(E|B) P(A|B, E) \\ P(J|B, E, A) P(M|J, B, E, A)$$

\* Domain-Specific Assumption of (Marginal, Conditional) Independence.

$$P(B, E, A, J, M) = P(B) P(E) P(A|B, E) \\ P(J|A) P(M|A)$$

$\Uparrow$   $\Uparrow$   
J independence from  $B, E$ .      M independent from  $J, B, E$ .

\* Direct Acyclic Graph (DAG)



$$P(B=1) = 0.001 \quad P(E=1) = 0.002$$

B	E	$P(A=1 B,E)$
0	0	0.001
1	0	0.94
0	1	0.29
1	1	0.95

A	$P(J=1 A)$
0	0.05
1	0.9

A	$P(M=1 A)$
0	0.01
1	0.7

These are called conditional probability table (CPT)

Joint probability are easy to compute :

$$P(B=1, E=0, A=1, J=1, M=0)$$

$$= P(B=1) P(E=0) P(A=1|B=1, E=0) P(J=1|A=1) P(M=0|A=1)$$

$$= 0.001 \times 0.998 \times 0.94 \times 0.9 \times 0.3$$

\* Any "query" can be answered from joint distribution

$$\text{e.g. } P(B=1, E=0 | M=1) = \frac{P(B=1, E=0, M=1)}{P(M=1)}$$

$$= \sum_{A, J} P(B=1, E=0, M=1, A=a, J=j)$$

$$\sum_{b, j, e, a} P(M=1, B=b, E=e, A=a, J=j)$$



\* More efficient Algorithm?

Exploit structure of DAG (ordering of nodes, missing edges  $\leftrightarrow$  conditional independence)

### Belief Network (BNs)

A Belief Network is a DAG which

- ① Nodes  $\rightarrow$  random variables
- ② Edges  $\rightarrow$  conditional dependence.
- ③ Tables (CPTs)  $\rightarrow$  how each node depends on parents.

\* Conditional Independence

Generally True that  $P(X_1, \dots, X_n) = P(X_1)P(X_2|X_1) \dots P(X_n|X_1, X_2, \dots, X_{n-1})$

$$= \prod_{i=1}^n P(X_i | X_{i-1}, \dots, X_1)$$

In a particular domain, suppose that =

$$P(X_1, \dots, X_n) = \prod_{i=1}^n P(X_i | \text{parent}(X_i))$$

where  $\text{parent}(X_i) \subseteq \{X_1, X_2, \dots, X_{i-1}\}$ . (\*)

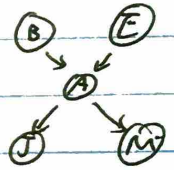
\* Big Idea: represent conditional independence by DAG

## Constructing BN

- (1) choose random variables
- (2) choose ordering
- (3) while there're variables left :
  - (a) Add  $X_i$  to BN
  - (b) Set parents of  $X_i$  to be minimal subset satisfying
  - (c) Define CPT  $P(X_i | \text{parent}(X_i))$

\* ~~Write~~ Node ordering :

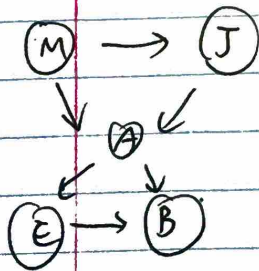
- Best ordering is to add "root causes", then variable they influence, so on.
- Ex :  $\{B, E, J, A, M\}$ .



- Ex : wrong ordering  $\{M, J, A, E, B\}$ .

$$P(M, J, A, E, B) = P(M) P(J|M) P(A|M, J) P(E|M, A, J) P(B|M, J, A, E)$$

$$= P(M) P(J|M) P(A|J, M) \cancel{P(B|J, A, M, E)} P(E|A) \cdot P(B|A, E)$$



Note : - 2 extra edges in BN

- Some independence not obvious in DAG
- more numbers to estimate for CPTs
- more difficult CPTs ~~to~~ to access.



\* Advantage of BNs :

- complete, self-consistent, compact, non-redundant, representation of joint distribution.

Ex: for  $n$  binary variables, if  $k$  is max # of parents of nodes in DAG (also called in-degree)

then  $O(nz^k)$  to represent joint distribution.  
versus  $O(z^n)$

- clean separation of qualitative & quantitative knowledge.
- DAG encodes conditional independence
- CPTs encodes numerical influences.