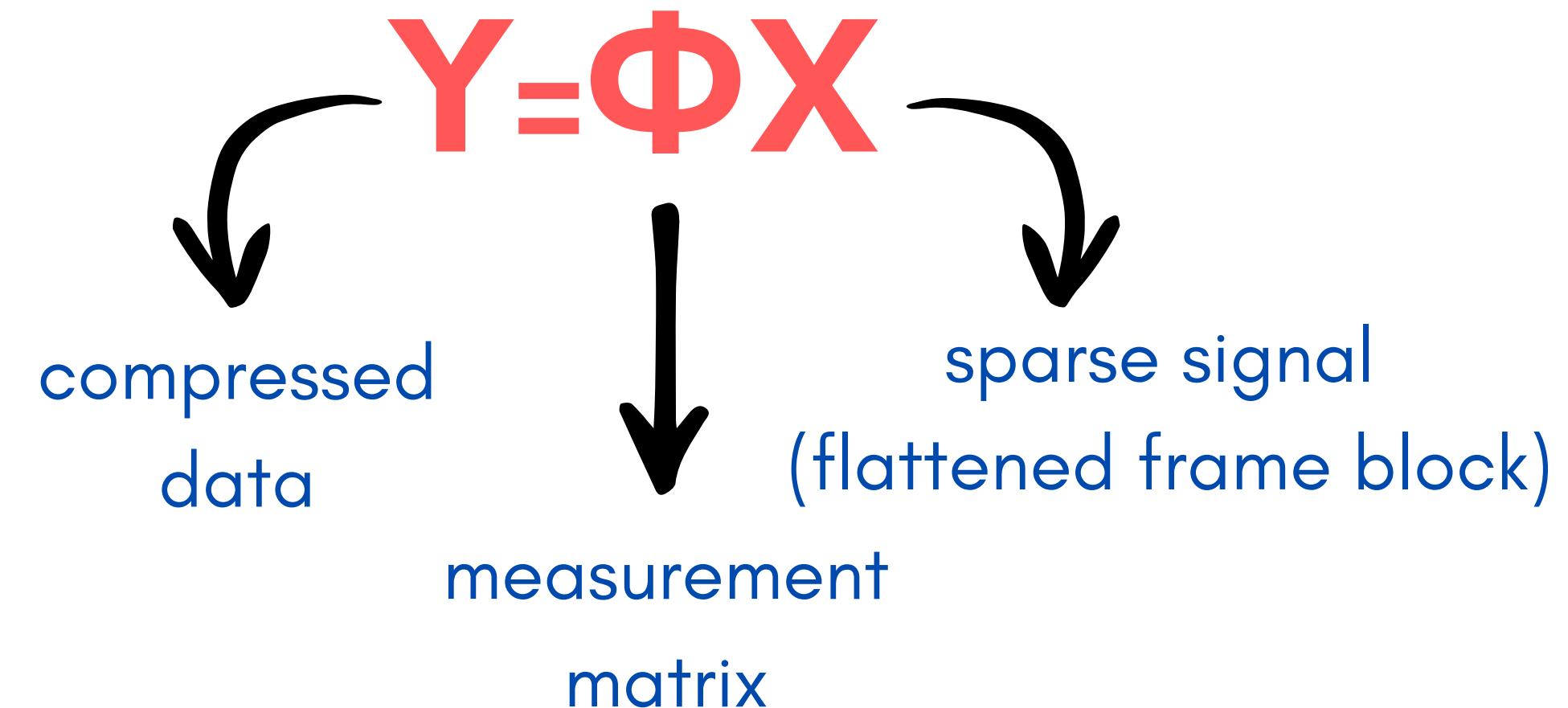


# COMPRESSED SENSING

signal processing method that reconstructs a signal from far fewer samples than required by the Nyquist–Shannon sampling theorem





# APPROACH

## Frame Division –

- Each video frame is split into small square blocks

## Sparsification –

- Each block is transformed to a sparse block using Discrete Cosine Transform (DCT).

## Compression –

- Random Gaussian measurement matrix ( $\Phi$ ) multiplies flattened block.
- Only a fraction (30%) of the data is kept



# WHY SPARSIFY BEFORE CS?

Compressed sensing works best when signal is sparse.

- Natural signals (video frames) are NOT sparse in their raw form: Most pixel values are nonzero – there is no sparsity.
- But many signals become sparse in a transform domain. For videos, DCT is a popular choice because most of the energy is concentrated in just a few DCT coefficients.



# RECONSTRUCTION

## Reconstruction (Sparse Recovery)-

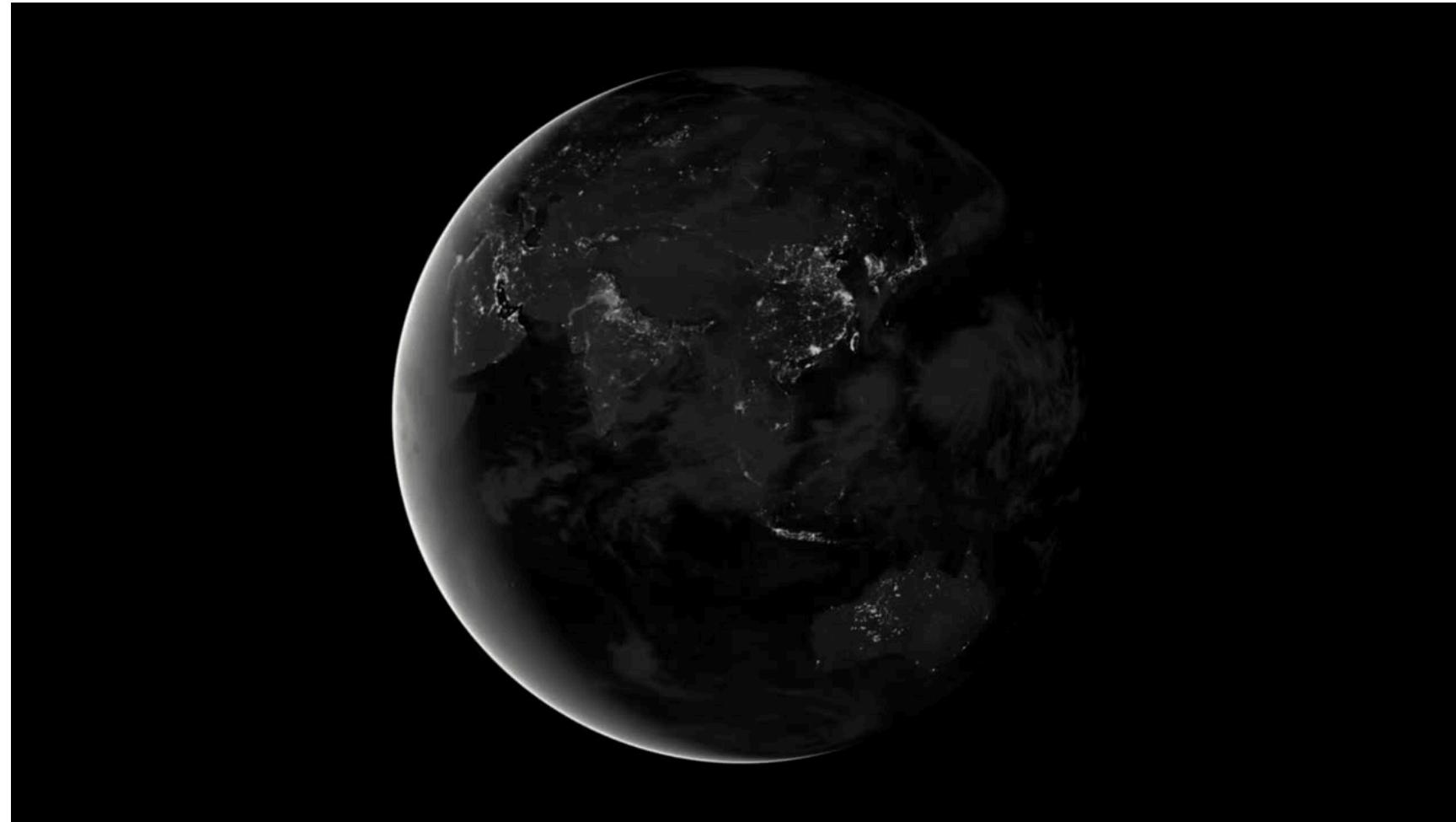
- From the compressed data  $y$ , the system recovers  $x$  using **Orthogonal Matching Pursuit (OMP)** - greedy algorithm used for sparse signal recovery. OMP requires the measurement matrix  $\Phi$  as input.

## Inverse Transform (IDCT)-

- Recovered sparse coefficients are transformed back using **Inverse Discrete Cosine Transform (IDCT)** to get the reconstructed spatial domain block



# RESULTS



ORIGINAL



RECONSTRUCTED



# HOW PRIVACY IS PRESERVED

$$Y = \Phi X$$

- Measurement Matrix as Secret Key:

When we generate  $\Phi$  randomly and keep it private, only those who have access to  $\Phi$  can attempt to invert the process and reconstruct  $x$  from  $y$ .

- Security Through Randomness:

Randomly generated matrices  $\Phi$  make brute-force or analytic reconstruction infeasible



# ISSUES ENCOUNTERED

**Issue** – Measurement matrix is far too large for system memory.

**Reason** – For a 1920x1080 frame, length of flat frame is 2,073,600.

With a compression ratio of 0.3, no of measurements is 622,080.

The measurement matrix size is (622,080, 2,073,600), which is huge.

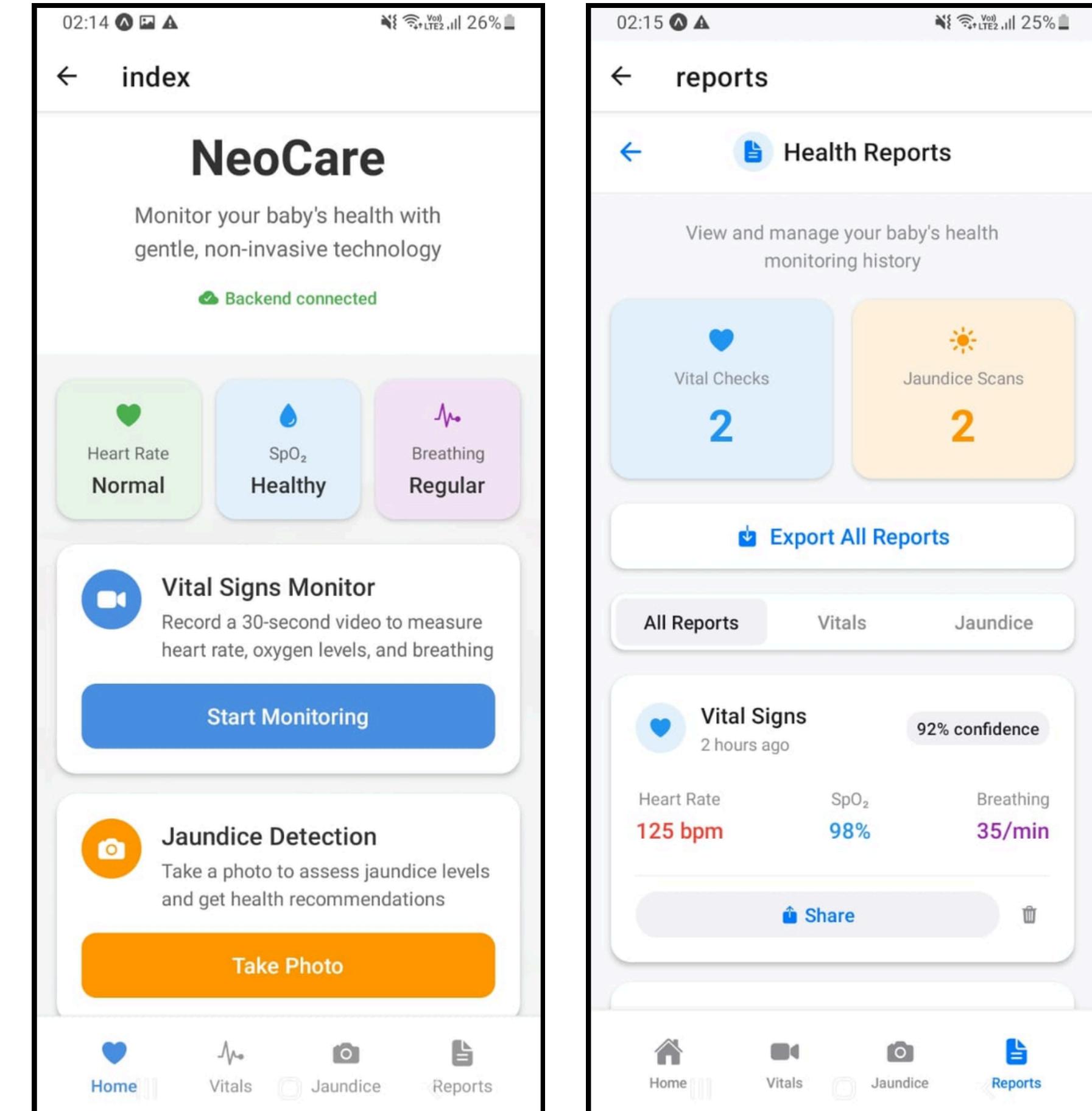
**Solution** – Using block-based compressed sensing (processing smaller blocks of 32x32 pixels at a time) without creating a measurement matrix for the entire frame.



# FEATURES IN MOBILE APPLICATION

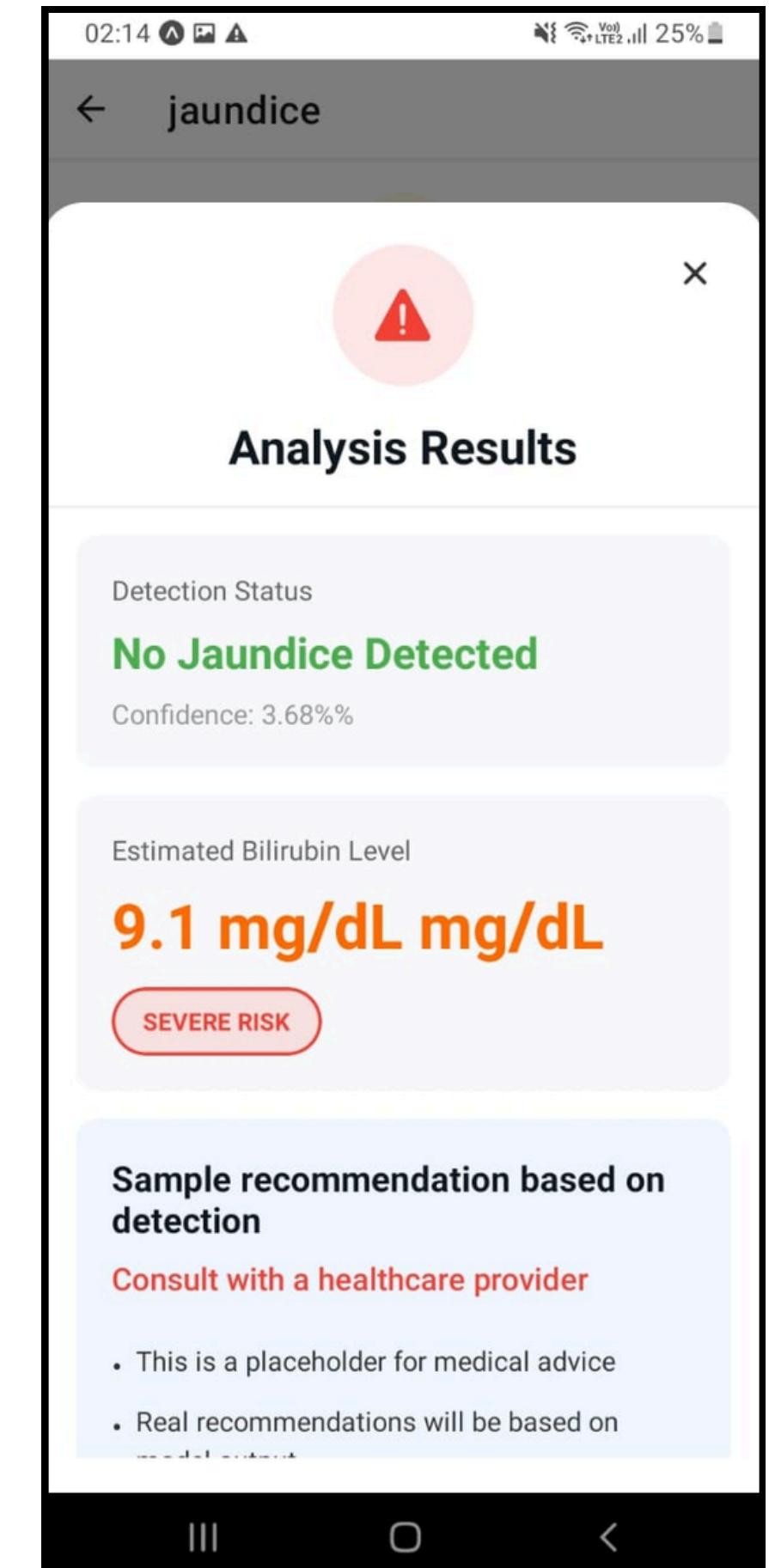
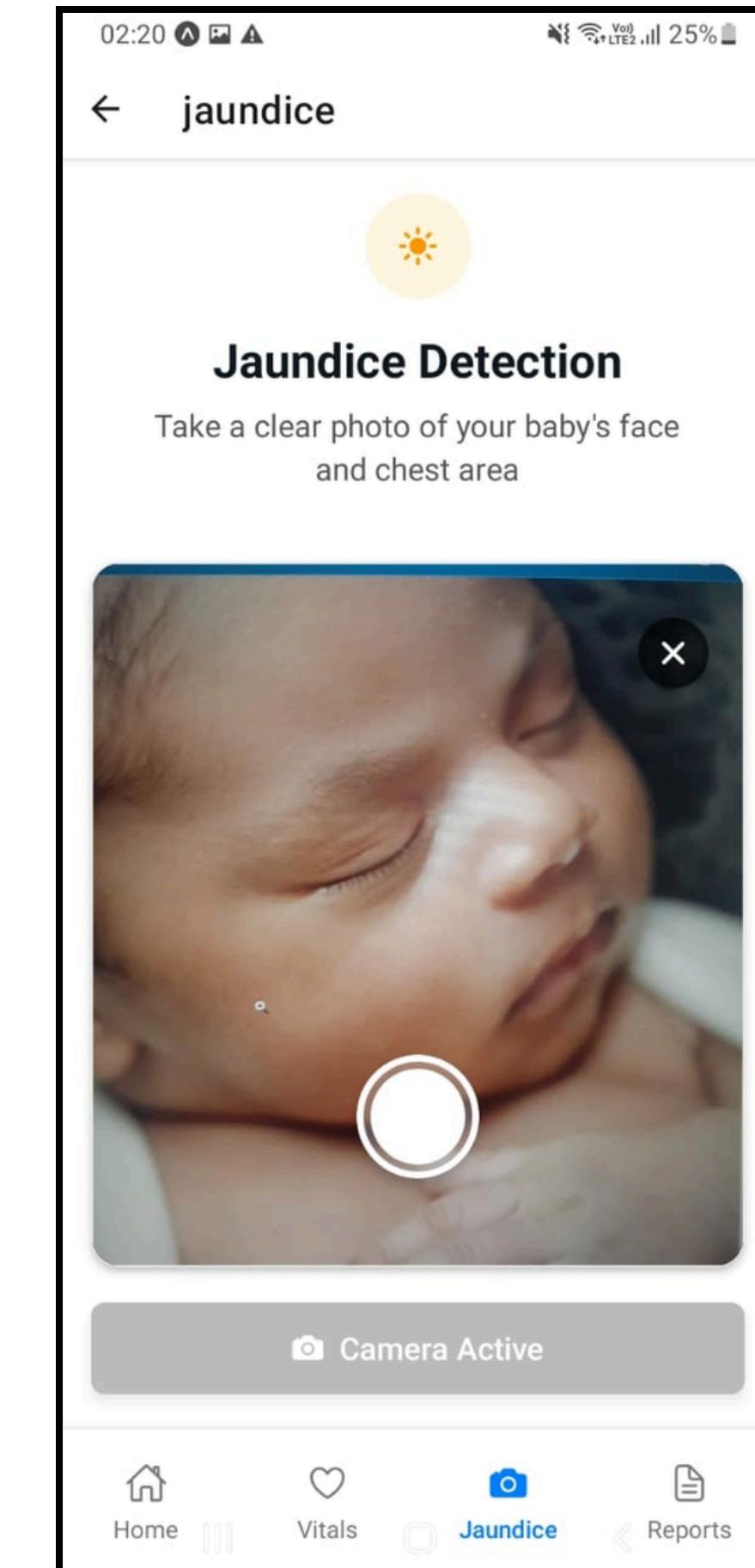


- Created the frontend part using React, using the previously made Figma designs.
- Used Expo - An open-source platform for making universal native apps.
- Test backend using Node.js with Express.js
- It captures video frames using expo-camera

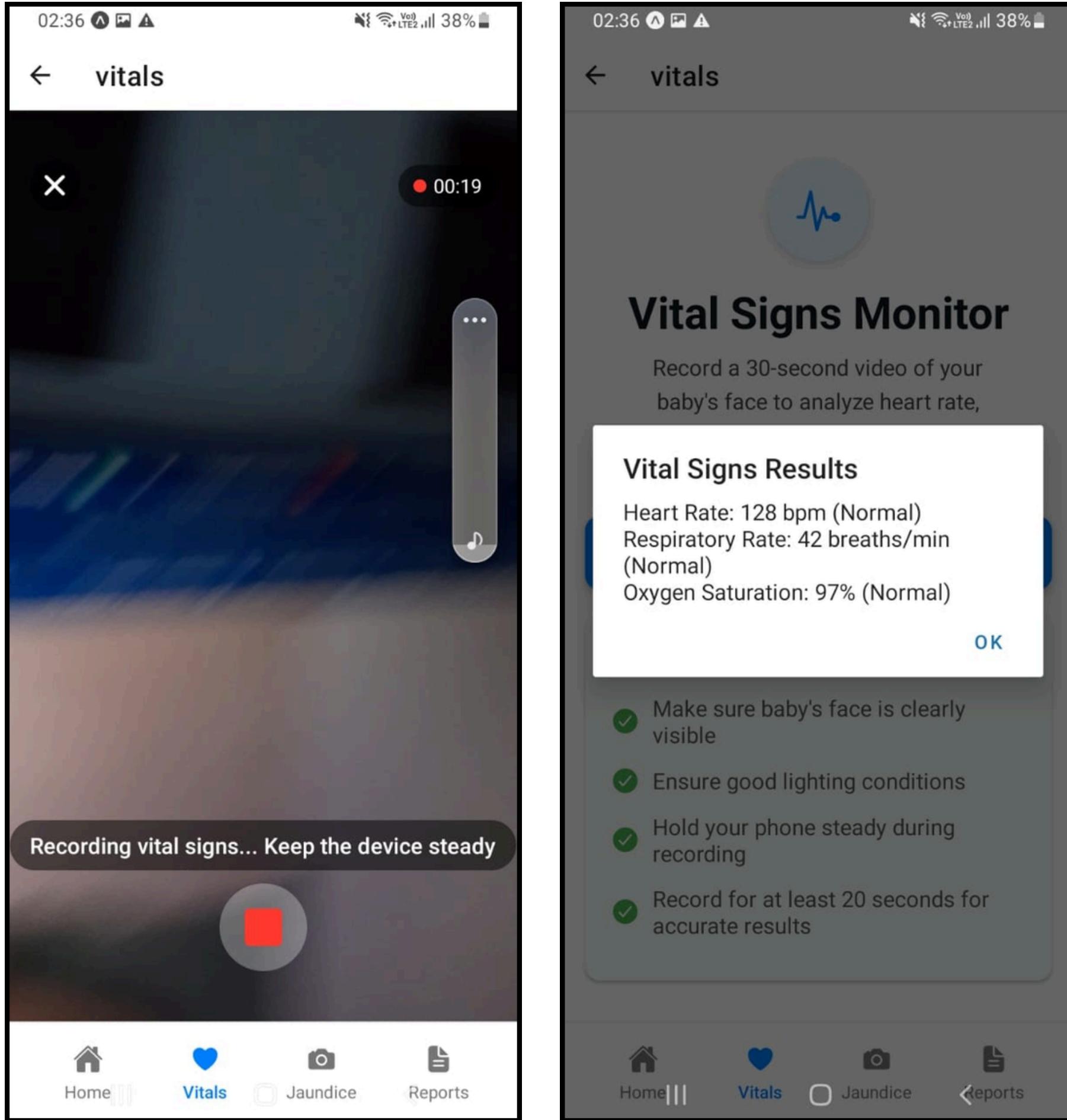




- **Connected the Jaundice detection model with the backend using RESTful API endpoint that receives images captured by the mobile app, processes them through the pre-trained model and returns jaundice assessment results with confidence scores.**



- Connected a test script to detect the other vital signs from the video with a REST API endpoint in local host.
- Implementing multipart video upload with fetch API in React Native, including error and response handling.
- The frontend implementation includes proper video recording cleanup, timer-based recording management.



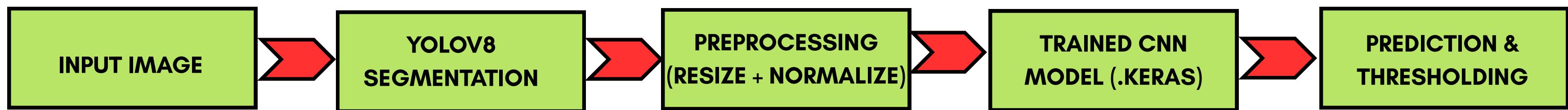
# JAUNDICE DETECTION ACCURACY IMPROVEMENT

CREATED SEGMENTED DATASET USING YOLOV8 SEGMENTATION MODEL

- SEGMENTED BABY REGION FROM ORIGINAL IMAGES
- BUILT TRAIN (600 NORMAL + 600 JAUNDICE), VALIDATION (180), AND TEST (180) SETS



DEVELOPED SEPARATE INFERENCE CODE FOR JAUNDICE DETECTION



USAGE EXAMPLES:

- PYTHON JAUNDICE\_INFERENCE.PY /PATH/TO/IMAGE.JPG (**USE LATEST MODEL + 0.5 DEFAULT CLASSIFICATION THERHOLD**)
- PYTHON JAUNDICE\_INFERENCE.PY /PATH/TO/IMAGE.JPG --THRESHOLD 0.6 (**USE LATEST MODEL**)
- PYTHON JAUNDICE\_INFERENCE.PY /PATH/TO/IMAGE.JPG --MODEL /PATH/TO/MODEL.KERAS

## TESTING

CONDUCTED EXPERIMENTS WITH DIFFERENT BATCH SIZES AND LEARNING RATES  
OBSERVED IMPROVEMENT IN ACCURACY AND CONSISTENCY AFTER SEGMENTATION

### EXAMPLE:

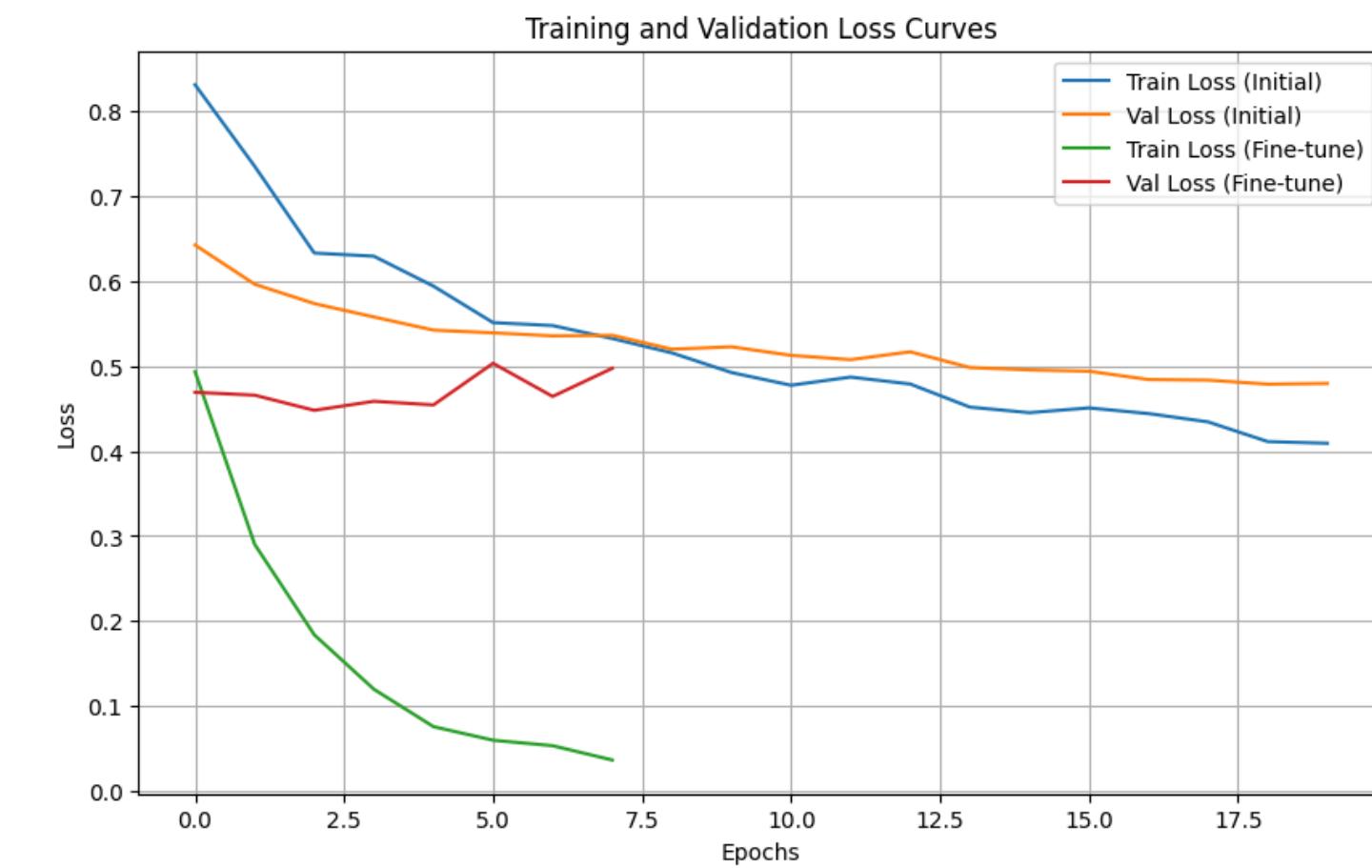
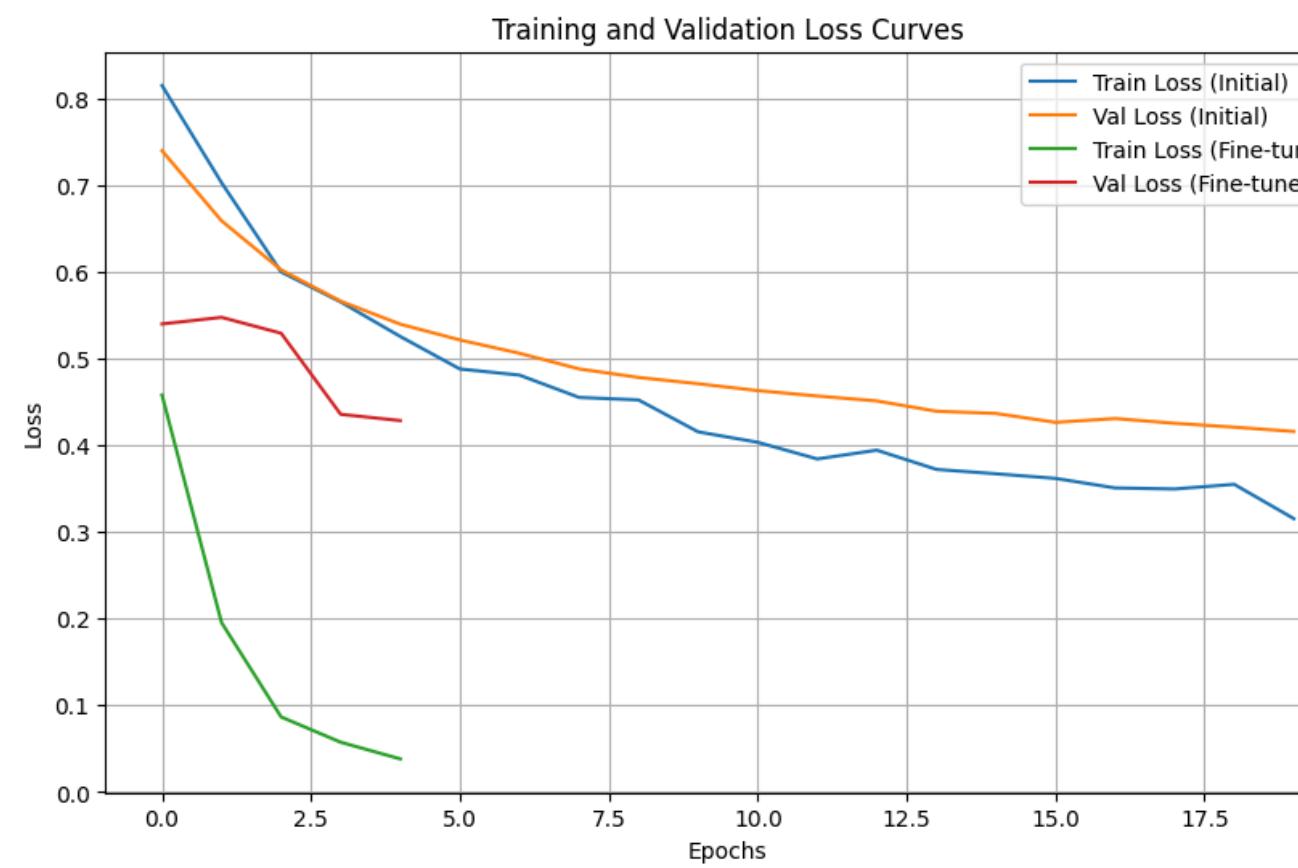
- BATCH SIZE = 64
- LEARNING RATE = 10E-4

#### WITHOUT SEGMENTATION

```
... Train Accuracy: 82.93%
Validation Accuracy: 78.12%
Test Accuracy: 78.91%
```

#### USING SEGMENTED DATASET

- Train Accuracy: 90.50%
- Validation Accuracy: 78.12%
- Test Accuracy: 77.34%



## OBSERVATION

MODEL PERFORMS WELL ON TEST DATA FROM THE NJN DATASET, BUT ACCURACY DROPS FOR UNSEEN IMAGES DUE TO:

- BACKGROUND BIAS (NON-BABY REGIONS INFLUENCING PREDICTIONS)
- LIGHTING VARIATIONS AND COLOR TONE DIFFERENCES



UNSEEN TEST IMAGE

TRAINED WITH ROW DATA	TRAINED WITH THE SEGMENTED DATA
<p>==== JAUNDICE DETECTION RESULTS ===</p> <p>PREDICTION: NORMAL</p> <p>CONFIDENCE: 90.53%</p> <p>JAUNDICE PROBABILITY: 9.47%</p> <p>NORMAL PROBABILITY: 90.53%</p>	<p>==== JAUNDICE DETECTION RESULTS ===</p> <p>PREDICTION: NORMAL</p> <p>CONFIDENCE: 77.66%</p> <p>JAUNDICE PROBABILITY: 22.34%</p> <p>NORMAL PROBABILITY: 77.66%</p>

INFERENCE RESULTS

## RESULTS

- SEGMENTED DATASET → NOTICEABLE ACCURACY IMPROVEMENT
- IMPROVED FEATURE FOCUS ON SKIN REGIONS
- REDUCTION OF NOISE FROM BACKGROUND AREAS
- HOWEVER, GENERALIZATION ON UNSEEN DATA STILL LIMITED

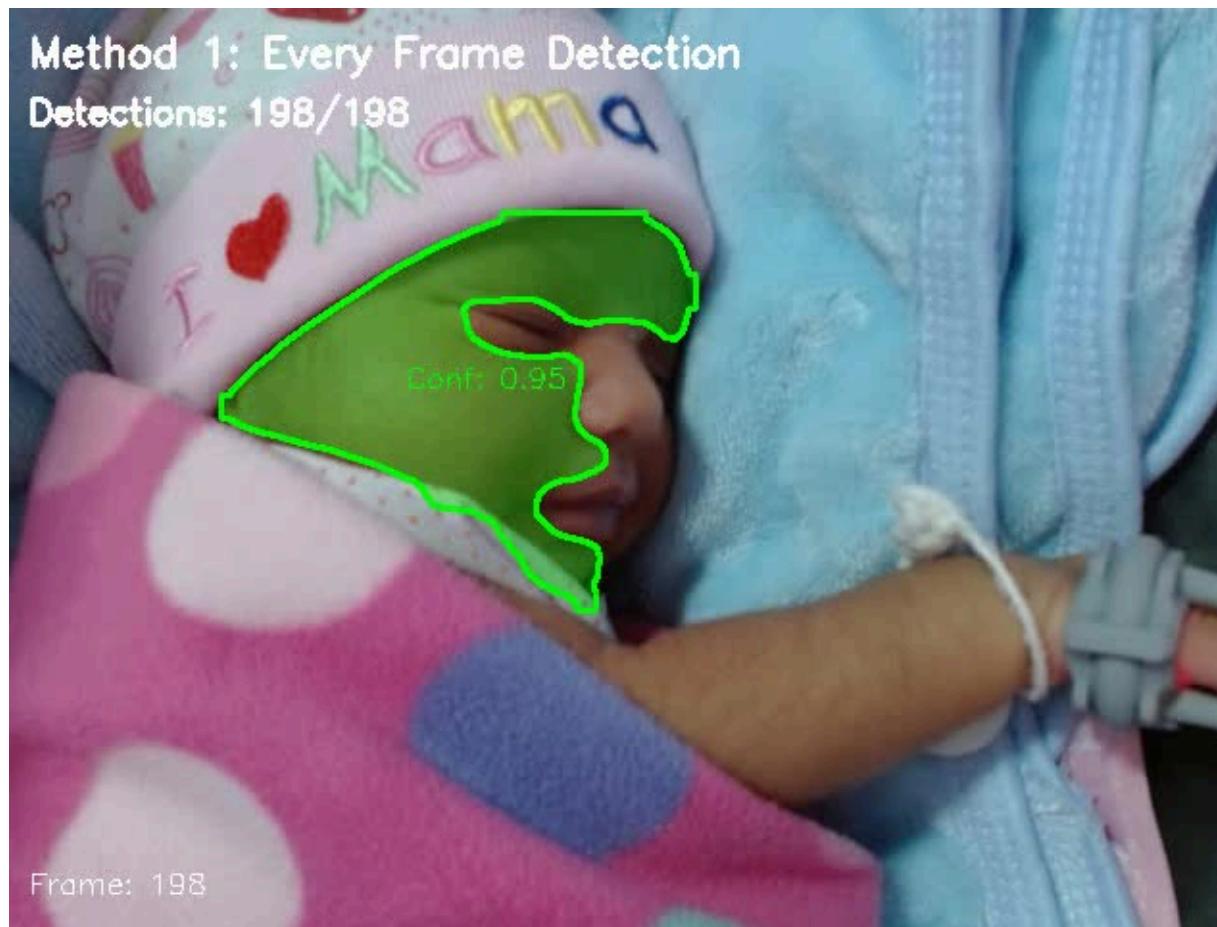
## NEXT STEPS

- APPLY COLOR CORRECTION / NORMALIZATION TO HANDLE LIGHTING BIAS
- EXPERIMENT WITH DATA AUGMENTATION FOR UNSEEN SCENARIO ROBUSTNESS
- FINE-TUNE MODEL THRESHOLDS AND EVALUATE ON LARGER DIVERSE DATASETS
- EXPLORE YOLOV9 OR OTHER LIGHTWEIGHT SEGMENTATION MODELS FOR COMPARISON

# REGION EXTRACTION IN VIDEOS

## METHOD 1 : DETECT EVERY FRAME/ YOLO BASED TRACKING

- Detect region in every frame in the video using the trained model.
- Accuracy is high, but the processing time is large



- Processing speed - 22.9 FPS
- Processing time (for 1 min video) - 89.98 s

- Processing speed - 29.2 FPS
- Speed up - 1.3x

# REGION EXTRACTION IN VIDEOS

## METHOD 2 : STRICT MOTION FREEZE

- Detect regions in a frame only when motion exceeds a specified threshold, performing detection once and keeping it frozen until new motion occurs with no fallbacks.

<b>Motion threshold</b>	<b>Processing speed</b>	<b>Speed compared to Method 1</b>	<b>Accuracy compared to Method 1 (IOU score)</b>
2%	40.4 FPS	1.7x	0.929
5%	47.8 FPS	2.1x	0.893
10%	57.8 FPS	2.5x	0.904
15%	60.7 FPS	2.6x	0.891

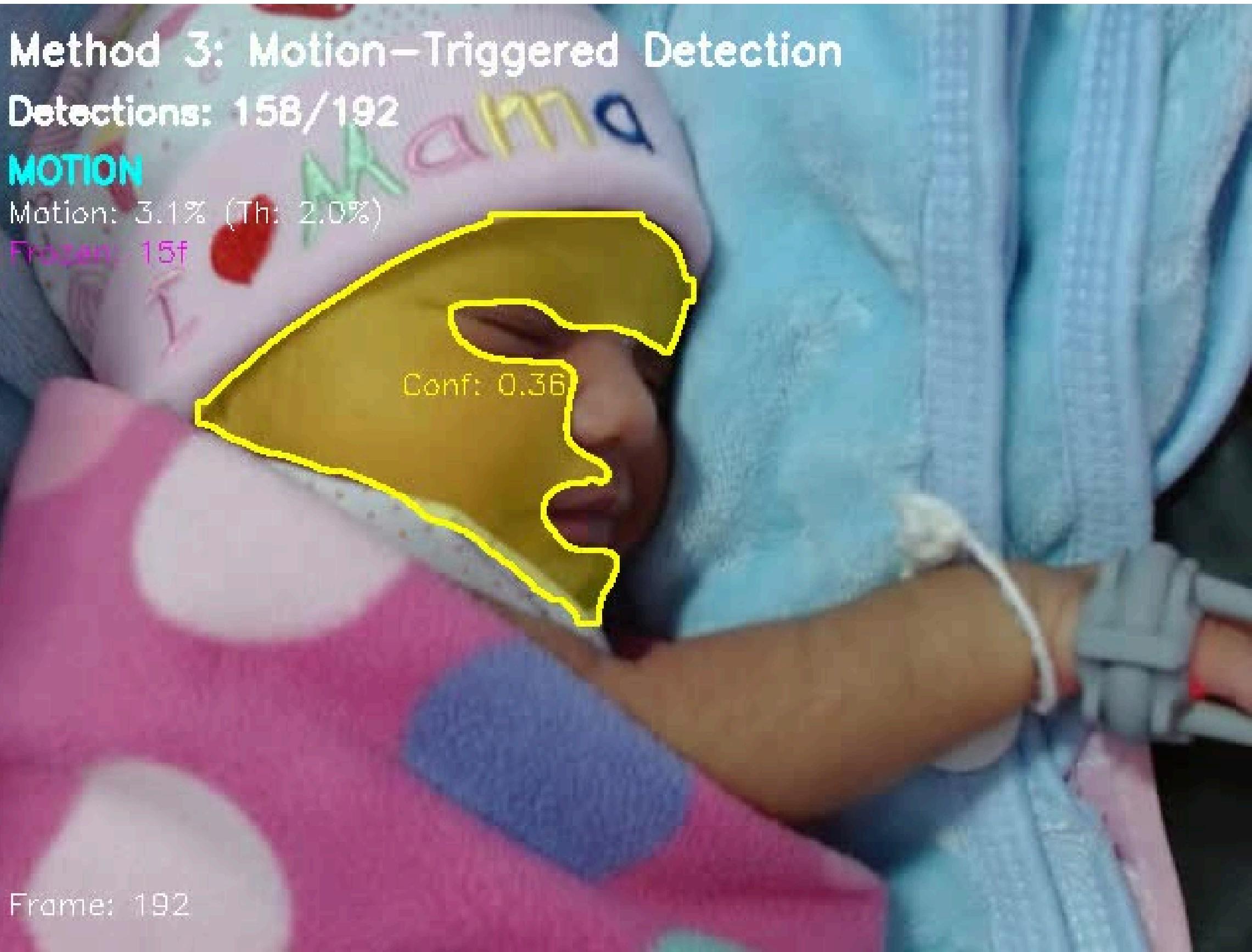


# REGION EXTRACTION IN VIDEOS

## METHOD 3 : STRICT MOTION FREEZE WITH FALLBACKS

- Detect regions in a frame only when motion exceeds a specified threshold or when too many frames have been frozen, performing detection once and keeping it frozen until new motion occurs, with fallbacks.

<b>Motion threshold</b>	<b>Processing speed</b>	<b>Speed compared to Method 1</b>	<b>Accuracy compared to Method 1 (IOU score)</b>
2%	39.4 FPS	1.7x	0.976
5%	45.0 FPS	1.9x	0.973
10%	54.7 FPS	2.5x	0.957
15%	59.4 FPS	2.6x	0.953



# REGION EXTRACTION IN VIDEOS

## METHOD 4 : INTERVAL BASED DETECTION

- Detect regions in the frames at a given interval length

<b>Interval Length</b>	<b>Processing speed</b>	<b>Speed compared to Method 1</b>	<b>Accuracy compared to Method 1 (IOU score)</b>
10 frames	127.5 FPS	5.5x	0.982
20 frames	169.5 FPS	7.4x	0.974
30 frames	193.1 FPS	8.2x	0.967
60 frames	222.9 FPS	9.6x	0.952

**Method 4: Interval 10**

**Detections: 20/192**

**Tracking: 172**

Conf: 0.95

Frame: 192





# PLAN FOR MID EVALUATION

- Train the heart rate and SpO<sub>2</sub> models using the newly segmented data
- Finalize and refine all preprocessing functions.
- Collect a set of the neonatal data from the hospital.