S7L1D-E4 & S7L1W-E4 (Industrial) Wdg.312 - Technical Data Sheet

Standards

STAMFORD industrial alternators meet the requirements of the relevant parts of the IEC 60034 and the relevant sections of other international standards such as BS5000-3, ISO 8528-3, VDE 0530, NEMA MG1-32, CSA C22.2-100 and AS 60034. Other standards and certifications can be considered on request.

Quality Assurance

Alternators are manufactured using production procedures having a quality assurance level to BS EN ISO 9001.



^{*}Image depicts the S7L1D alternator

Excitation and Voltage Regulators

Excitation System				
AVR Type	MX341	MX322	DECS150	
Voltage Regulation	± 1%	± 0.5%	± 0.25%	with 4% Engine Governing
AVR Power	PMG	PMG	PMG	

No Load Excitation Voltage (V)	15.4 - 14.7
No Load Excitation Current (A)	0.68 - 0.64
Full Load Excitation Voltage (V)	58
Full Load Excitation Current (A)	2.6
Exciter Time Constant (seconds)	0.125

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Electrical Data												
Insulation System	ı				1							
Stator Winding	Double Layer Concentric											
Winding Pitch	2/3											
Winding Leads	6											
Winding Number	312											
Number of Poles	4											
IP Rating	IP23 or IP44* (see footnote)											
RFI Suppression	BS EN 61000-6-2 & BS EN 61000-6-4, VDE 0875G, VDE 0875N. Refer to factory for others											
Waveform Distortion	ı	NO LOAD <	1.5% NON-	DISTORTIN	G BALANCE	ED LINEAR I	_OAD < 5.0%	6				
Short Circuit Ratio				1/	Xd							
Steady State X/R Ratio				27	.41							
		50	Hz			60	Hz					
Telephone Interference		THE	<2%			TIF	<50					
Cooling Air Flow		2.52 ו	n³/sec			3.02 r	m³/sec					
Voltage Star (V)	380	400	415	440	416	440	460	480				
Voltage Parallel Star (V)	-	-	-	-	-	-	-	-				
Voltage Delta (V)	-	-	-	-	-	-	-	-				
kVA Base Rating (Class H) for Reactance Values (kVA)	1700	1750	1750	1720	1837	1944	2031	2119				
Saturated Values in Per Unit	at Base R	latings ar	nd Voltag	es								
Xd Dir. Axis Synchronous	2.51	2.33	2.16	1.89	2.71	2.57	2.45	2.35				
X'd Dir. Axis Transient	0.19	0.18	0.17	0.15	0.21	0.20	0.19	0.18				
X"d Dir. Axis Subtransient	0.14	0.13	0.12	0.10	0.15	0.14	0.13	0.13				
Xq Quad. Axis Reactance	1.86	1.73	1.61	1.41	2.01	1.91	1.82	1.75				
X"q Quad. Axis Subtransient	0.22	0.20	0.19	0.16	0.23	0.22	0.21	0.20				
XL Stator Leakage Reactance	0.08	0.07	0.07	0.06	0.09	0.08	0.08	0.07				
X2 Negative Sequence Reactance	0.17	0.16	0.15	0.13	0.19	0.18	0.17	0.16				
X0 Zero Sequence Reactance	0.03	0.03	0.03	0.02	0.03	0.03	0.03	0.03				
Unsaturated Values in Per U	nit at Bas	e Ratings	and Volt	ages								
Xd Dir. Axis Synchronous	3.01	2.80	2.60	2.27	3.26	3.08	2.94	2.82				
X'd Dir. Axis Transient	0.22	0.21	0.19	0.17	0.24	0.23	0.22	0.21				
X"d Dir. Axis Subtransient	0.16	0.15	0.14	0.12	0.17	0.16	0.16	0.15				
Xq Quad. Axis Reactance	1.92	1.78	1.66	1.45	2.08	1.96	1.88	1.80				
X"q Quad. Axis Subtransient	0.26	0.24	0.22	0.19	0.28	0.26	0.25	0.24				
XL Stator Leakage Reactance	0.09	0.08	0.08	0.07	0.10	0.09	0.09	0.08				
XIr Rotor Leakage Reactance	0.20	0.18	0.17	0.15	0.21	0.20	0.19	0.19				
X2 Negative Sequence Reactance	0.21	0.19	0.18	0.16	0.22	0.21	0.20	0.19				
X0 Zero Sequence Reactance	0.04	0.04	0.03	0.03	0.04	0.04	0.04	0.04				

*Notes:

¹⁾ S7L1W: IP44 rating with IC81W cooling (watercooled) and 25°C water inlet temperature.

²⁾ S7L1D: IP23 rating with IC01 cooling (open-circuit cooling) as standard.

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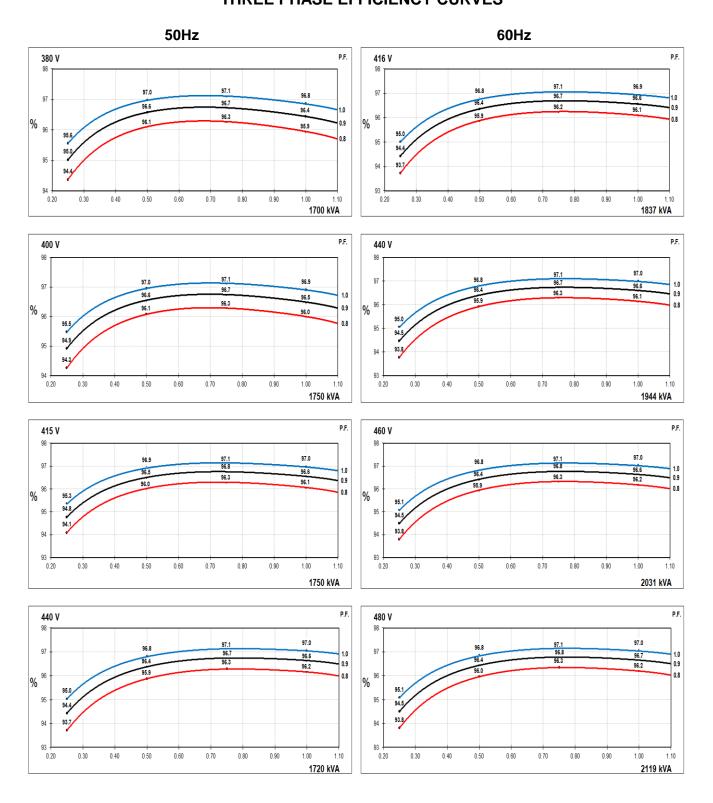
Time Constants (Seconds)										
T'd Transient Time Const.	0.1	150								
T"d Sub-Transient Time Const.		017								
T'do O.C. Field Time Const.		290								
Ta Armature Time Const.										
T''q Sub-Transient Time Const. 0.028 T''q Sub-Transient Time Const. 0.0100										
Resistances in Ohms (Ω) at 2		100								
Stator Winding Resistance (Ra),										
per phase for series connected	0.00	0085								
Rotor Winding Resistance (Rf)	1.	95								
Exciter Stator Winding Resistance	22	2.3								
Exciter Rotor Winding Resistance per	0.0	065								
phase										
PMG Phase Resistance (Rpmg) per phase	1.	91								
Positive Sequence Resistance (R1)	0.0	011								
Negative Sequence Resistance (R2)	0.0	012								
Zero Sequence Resistance (R0)	0.0	011								
Saturation Factors	400V	480V								
SG1.0	0.281	0.304								
SG1.2	1.308	1.184								
Mechanical Data										
Shaft and Keys		ed to better than ISO 21940-11 Grade 2.5 for ng generators are balanced with a half key.								
	1 Bearing	2 Bearing								
SAE Adaptor	SAE0 , 00	SAE0,00								
Moment of Inertia	40.98 kgm²	40.08 kgm²								
Weight Wound Stator	1518kg	1518kg								
Weight Wound Rotor	1353kg	1300kg								
Weight Complete Alternator	3350kg	3264kg								
Shipping weight in a Crate	3399kg	3313kg								
Packing Crate Size	200 X 105 X 155(cm)	200 X 105 X155(cm)								
Maximum Over Speed	2250 RPM fo	r two minutes								
Bearing Drive End	-	BALL. 6228; Sleeve EFWLK 14 (optional)								
Bearing Non-Drive End	BALL. 6319	BALL. 6319; Sleeve EFNLQ 11 (optional)								
Notes:										

Notes:

- 1) Mechanical data are applicable for S7L1D with anti-friction bearing. Refer the GA and rotor drawings for S7L1W and sleeve bearing.
- 2) S7L1W and/ or sleeve bearings are available for 2-bearing alternators only.
- 3) SAE adaptor options are not applicable for sleeve bearing.

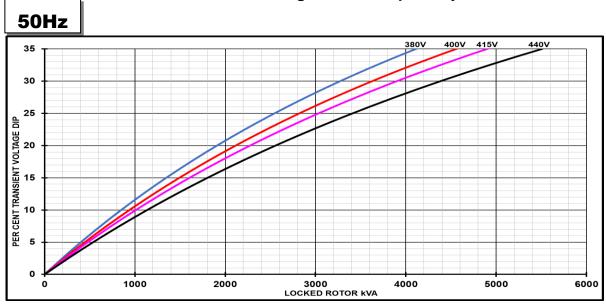


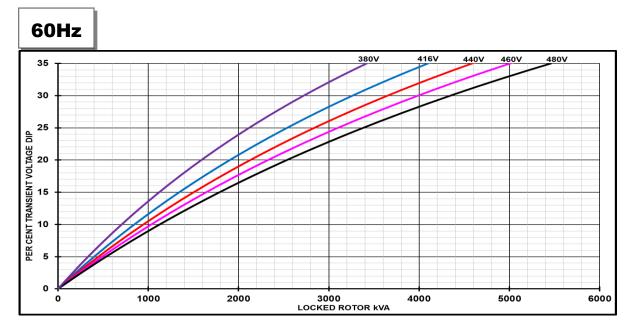
THREE PHASE EFFICIENCY CURVES



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Locked Rotor Motor Starting Curves - Separately Excited





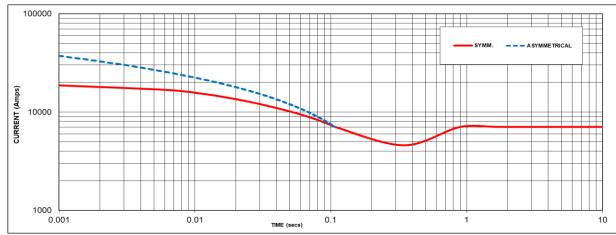
Transient Voltage	Dip Scaling Factor	Transient Voltage Rise Scaling Factor						
Lagging PF	Scaling Factor	Lagging PF	Scaling Factor					
<= 0.4	1.00	<= 0.4	1.25					
0.5	0.95	0.5	1.20					
0.6	0.90	0.6	1.15					
0.7	0.86	0.7	1.10					
0.8	0.83	> 0.7	1.00					
0.9	0.75							
0.95	0.70							
1	0.65							

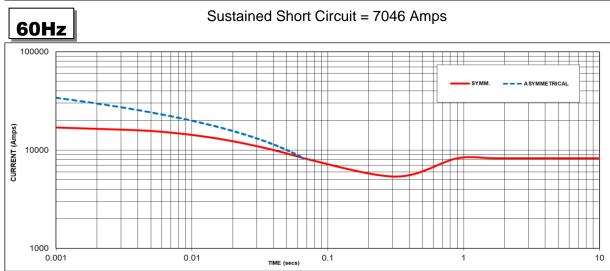
Note: To determine % Transient Voltage Dip or Voltage Rise at various PF, multiply the % Voltage Dip from the curve directly by the Scaling Factor.

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Three-phase Short Circuit Decrement Curve - Separately Excited







Sustained Short Circuit = 8246 Amps

Note 1

The following multiplication factors should be used to adjust the values from curve between time 0.001 seconds and the minimum current point in respect of nominal operating voltage :

50	Hz	60Hz						
Voltage	Factor	Voltage	Factor					
380V	X 1.00	416V	X 1.00					
400V	X 1.05	440V	X 1.06					
415V	X 1.09	460V	X 1.10					
440V	X 1.16	480V	X 1.15					

The sustained current value is constant irrespective of voltage level

If MX322 or digital AVR is used, the sustained short-circuit current value is to be multiplied by a factor of 1.2.

Note 2

The following multiplication factor should be used to convert the values calculated in accordance with NOTE 1 to those applicable to the various types of short circuit:

	3-phase	2-phase L-L	1-phase L-N
Instantaneous	x 1.00	x 0.87	x 1.30
Minimum	x 1.00	x 1.80	x 3.20
Sustained	x 1.00	x 1.50	x 2.50
Max. sustained duration	10 sec.	5 sec.	2 sec.

Note 3 All other times are unchanged

Curves are drawn for Star connections under no-load excitation at rated speeds. For other connection (where applicable) the following multipliers should be applied to current values as shown:

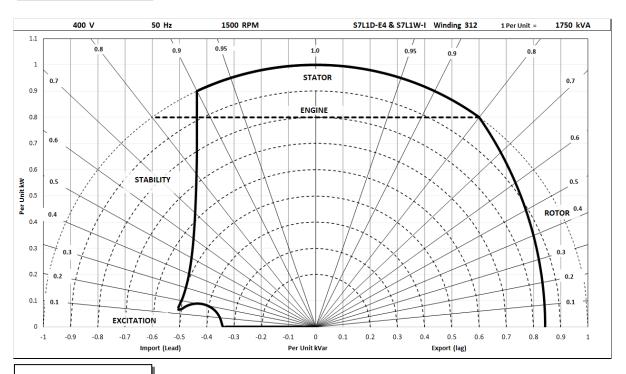
Parallel Star = Curve current value X 2 Series Delta = Curve current value X 1.732



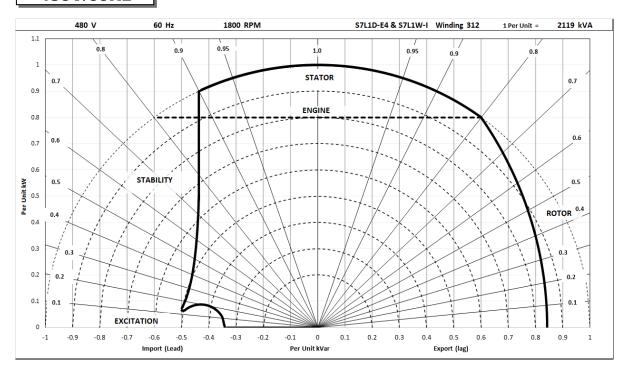
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Typical Alternator Operating Charts

400V/50Hz



480V/60Hz





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RATINGS AT 0.8 POWER FACTOR

	Class - Temp Rise Standby - 163/27°C					St	Standby - 150/40°C			Cont. H - 125/40°C				Cont. F - 105/40°C			
	Star (V)	380	400	415	440	380	400	415	440	380	400	415	440	380	400	415	440
50	Parallel Star (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
H	7 Delta (V)	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
	kVA	1819	1873	1873	1840	1768	1820	1820	1789	1700	1750	1750	1720	1580	1625	1630	1600
	kW	1455	1498	1498	1472	1414	1456	1456	1431	1360	1400	1400	1376	1264	1300	1304	1280
	Efficiency (%)	95.8	95.9	95.9	96.1	95.9	95.9	96.0	96.1	95.9	96.0	96.1	96.2	96.1	96.1	96.2	96.2
	kW Input	1519	1563	1562	1532	1475	1518	1517	1489	1417	1458	1457	1431	1316	1352	1356	1330

	Star (V)	416	440	460	480	416	440	460	480	416	440	460	480	416	440	460	480
60	Parallel Star (V)	N/A															
Hz	Delta (V)	N/A															
	kVA	1969	2081	2175	2263	1912	2025	2112	2200	1837	1944	2031	2119	1712	1812	1888	1969
	kW	1575	1665	1740	1810	1530	1620	1690	1760	1470	1555	1625	1695	1370	1450	1510	1575
	Efficiency (%)	96.0	96.0	96.1	96.1	96.0	96.1	96.1	96.1	96.1	96.1	96.2	96.2	96.2	96.2	96.3	96.3
	kW Input	1641	1733	1811	1884	1593	1686	1758	1831	1529	1618	1689	1762	1424	1507	1569	1636

Note:

For S7L1W industrial application, ratings above are applicable for water inlet temperature up to 25°C. Ratings are subject to the following reduction:

- 3% for every 5°C by which the water inlet temperature exceeds 25°C, up to maximum 38°C Standby (163/27°C) ratings are not applicable for S7L1W.

De-rates

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All values tabulated above are subject to the following reductions:

- 5% when air inlet filters are fitted
- 3% for every 500 meters by which the operating altitude exceeds 1000 meters above mean sea level
- 3% for every 5°C by which the operational ambient temperature exceeds 40°C @ Class H temperature rise (not applicable to S7L1W)
- For marine alternators (IP23), 3% for every 5°C by which the operational ambient temperature exceeds 50°C
- For any other operating conditions impacting the cooling circuit please refer to applications

Note: Requirement for operating in an ambient exceeding 60°C and altitude exceeding 4000 meters (for <690V) or 1500 meters (for >690V) must be referred to applications.

Dimensional and Torsional Drawing

For dimensional and torsional information please refer to the alternator General Arrangement and rotor drawings available on our website (http://stamford-avk.com/)

Note: Continuous development of our products means that the information contained in our data sheets can change without notice, and specifications should always be confirmed with Cummins Generator Technologies prior to purchase.



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