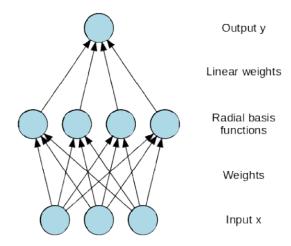
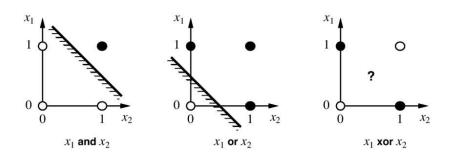
## Radial Basis Functions Neural Networks



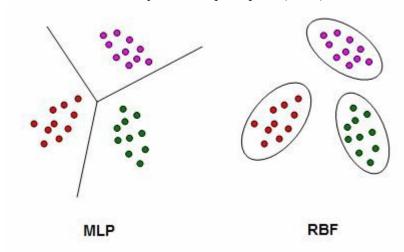
- In **Single Perceptron** / **Multi-layer Perceptron**(**MLP**), we only have linear separability because they are composed of input and output layers(some hidden layers in MLP)
- For example, AND, OR functions are **linearly**-separable & XOR function is **not** linearly separable.

# Linear separability



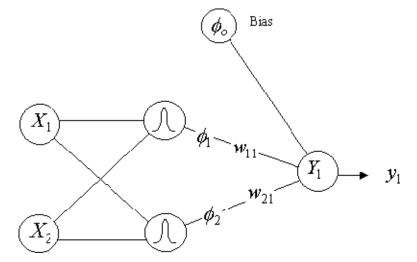
Linear-separability of AND, OR, XOR functions

- We atleast need **one hidden layer** to derive a non-linearity **separation**.
- Our RBNN what it does is, it transforms the input signal into another form, which can be then **feed** into the network to **get linear separability.**
- RBNN is **structurally same** as perceptron(MLP).

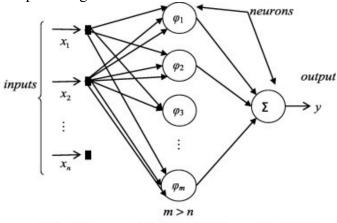


Distinction between MLP and RBF

- RBNN is composed of **input**, **hidden**, and **output** layer. RBNN is **strictly limited** to have exactly **one hidden layer**. We call this hidden layer as **feature vector**.
- RBNN increases dimenion of feature vector.



Simplest diagram shows the architecture of RBNN



Input layer Single hidden layer Output layer

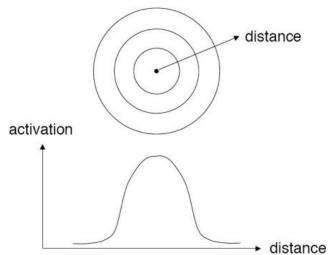
Extended diagram shows the architecture of RBNN with hidden functions.

- We apply **non-linear transfer function** to the feature vector before we go for **classification problem.**
- When we increase the dimension of the feature vector, the linear separability of feature vector increases.

A non-linearity separable problem(pattern classification problem) is highly separable in high dimensional space than it is in low dimensional space.

#### [Cover's Theorem]

- What is a Radial Basis Function?
- we define a receptor = t
- we draw confrontal maps around the receptor.
- Gaussian Functions are generally used for Radian Basis Function(confrontal mapping). So we define the radial distance r = ||x t||.

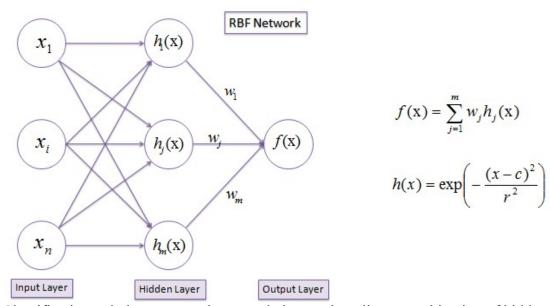


Radial distance and Radial Basis function with confrontal map

Gaussian Radial Function :=

$$\phi(\mathbf{r}) = \exp\left(-\mathbf{r}^2/2\mathbf{\sigma^2}\right)$$

where  $\sigma > 0$ 

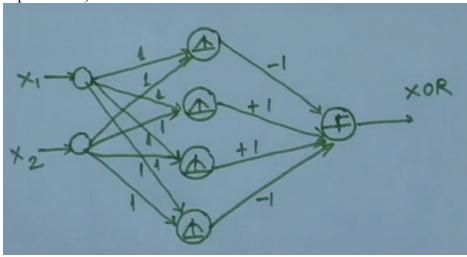


Classification only happens on the second phase, where linear combination of hidden functions are driven to output layer.

#### - Example. XOR function :-

- I have 4 inputs and I will not increase dimension at the feature vector here. So I will select 2 receptors here. For each transformation function  $\phi(x)$ , we will have each receptors t.
- Now consider the RBNN architecture,
- P := # of input features/ values.
- M = # of transformed vector dimensions (hidden layer width). So  $M \ge P$  usually be.
- Each node in the hidden layer, performs a set of non-linear radian basis function.

- Output C will remains the same as for the classification problems(certain number of class labels as predefined).



Architecture of XOR RBNN

Transformation function with receptors and variances.

Imput	φι					output
00	1.0				-0.2	
01	0.6	,			0.2	
10	0.6				0.2	
11	0.4	0.6	0.6	1.0	-0.2	
-	-	+1	+4	-1		-
1	-1	T	71	-		

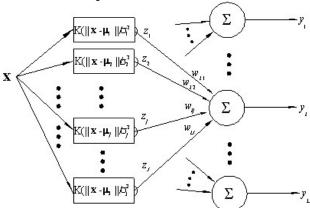
Output  $\rightarrow$  linear combination of transformation function is tabulated.

- Only Nodes in the hidden layer perform the radian basis transformation function.
- Output layer performs the linear combination of the outputs of the hidden layer to give a final probabilistic value at the output layer.
- So the classification is only done only @ (hidden layer  $\rightarrow$  output layer)

#### Training the RBNN:-

- First, we should train the hidden layer using back propagation.
- Neural Network training(back propagation) is a **curve fitting method**. It **fits** a **non-linear curve** during the **training** phase. It runs through stochastic approximation, which we call the back propagation.
- For each of the node in the hidden layer, we have to find  $\mathbf{t}$  (receptors) & the variance  $(\sigma)$  [variance the spread of the radial basis function]

- On the **second** training phase, we have to **update** the **weighting vectors** between **hidden layers** & **output layers**.
- In hidden layers, **each** node represents **each** transformation basis function. **Any** of the function could satisfy the non-linear separability OR even **combination** of set of functions could satisfy the non-linear separability.
- So in our hidden layer transformation, all the non-linearity terms are included. Say like  $X^2 + Y^2 + 5XY$ ; its all included in a hyper-surface equation(X & Y are inputs).
- Therefore, the first stage of training is done by **clustering algorithm.** We define the **number of cluster centers** we need. And by clustering algorithm, we compute the cluster centers, which then is assigned as the **receptors** for each hidden neurons.
- I have to cluster N samples or observations into M clusters (N > M).
- So the output "clusters" are the "receptors".
- for each receptors, I can find the variance as "the squared sum of the distances between the respective receptor & the each cluster nearest samples" :=  $1/N * \|X t\|^2$
- The interpretation of the first training phase is that the "feature vector is projected onto the transformed space".



Complex diagram depicting the RBNN

### Advantages of using RBNN than the MLP:-

- 1. Training in RBNN is **faster** than in Multi-layer Perceptron (MLP)  $\rightarrow$  takes **many** interactions in MLP.
- 2. We can easily interpret what is the meaning / function of the each node in hidden layer of the RBNN. This is difficult in MLP.
- 3. (what should be the # of nodes in hidden layer & the # of hidden layers) this **parameterization** is difficult in MLP. But this is not found in RBNN.
- 4. Classification will take more time in RBNN than MLP.