#### Steady Magnetic Fields RC 7:

By Mo Yang

### Magnetic Field Intensity, Relative Permeability and Magnetic circuit

Considering the effect of both the internal dipole moment and the induced magnetic moment in a magnetic material, the magnetic field intensity H is defined as:

$$0 = 2 + 0$$

$$H = \frac{B}{\mu_0} - M$$
(1)

$$\mathcal{B} = \mu, \mathcal{A} + M \qquad \nabla \times H = J \qquad (2)$$

directly relates the magnetic field intensity with the density of free charge. The integral

form of which is then, 
$$\iint_{S} \int d\zeta = \iint_{S} \nabla \times H dS = \iint_{S} H dU$$

$$\oint_{C} H \cdot dl = I$$
(3)

It is another form of Ampere's circuital law: the circulation of the magnetic field intensity around any closed path is equal to the free current flowing through the surface bounded by the path.

If the closed path C is chosen to enclose N turns of a winding carrying a current I that excites a magnetic circuit, we have

$$\oint_{C} H \cdot dl = NI = V_m \tag{4}$$

 ${\it V_m}$  is analogous to electromotive force (emf) and is called magnetomotive force (mmf).

If we define:

$$D = \mathcal{E}_r \mathcal{G}_o E \Rightarrow P = (\mathcal{E}_{r-1}) \mathcal{E}_o E \qquad \frac{\mathcal{E}_o E}{\rho} = \mathcal{E}_{r-1}$$

Core: 
$$P \propto E$$
  $\underline{M = \chi_m H}$  Now we have  $M \propto H$  (5)

where  $\chi_m$  is magnetic susceptibility, Then

$$B = \mu_0(1 + \chi_m)H = \mu_0 \mu_r H = \mu H$$
 (6)

$$H = \frac{1}{\mu}B\tag{7}$$

$$\mu_r = 1 + \chi_m = \frac{\mu}{\mu_0} \tag{8}$$

where  $\mu_r$  is the relative permeability of the medium.  $\mu = \mu_r \mu_0$  is the absolute

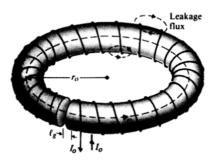
permeability/permeability.

Greate Megnetic field M.

#### Exercise

Assume that N turns of wire are wound around a toroidal core of a ferromagnetic material with permeability  $\mu$ . The core has a mean radius  $r_o$ , a circular cross section of radius a ( $a \ll r_o$ ), and a narrow air gap of length  $l_g$ , as shown in the following figure. A steady current  $I_o$  flows in the wire. Determine:

- (a) the magnetic flux density,  $B_f$ , in the ferromagnetic core;
- (b) the magnetic field intensity,  $H_f$ , in the core;
- (c) the magnetic field intensity,  $H_g$ , in the air gap.



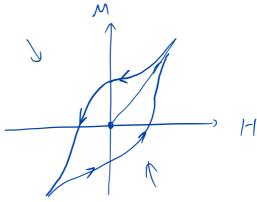
$$MH_{f} = MH_{g} = B.$$

$$\beta_{c} Hdl = NI$$

$$\beta_{d} = \beta_{d} = \beta_{d} = \beta_{d} = \frac{NI}{\frac{2\pi r - lg}{M} + \frac{lg}{M}}$$

(b). 
$$H_f = \frac{B}{\mu} = \cdots$$

(c) If 
$$g = \frac{B}{\mu_0} = \cdots$$



# **Behavior of Magnetic Materials**

- 1. **Diamagnetic**, if  $\mu_r \lesssim 1$  ( $\chi_m$  is a very small negative number)
- 2. **Paramagnetic**, if  $\mu_r \gtrsim 1$  ( $\chi_m$  is a very small positive number)
- 3. **Ferromagnetic**, if  $\mu_r\gg 1$  ( $\chi_m$  is a large positive number)

### **Boundary Conditions for Magnetostatic Fields**

1. The normal component of B is continuous across an interface,

which is 
$$\begin{array}{c|c}
1 & \beta_1 & \beta_2 \\
\hline
& \beta_2 & \beta_2
\end{array}$$

$$\begin{array}{c|c}
B_{1n} = B_{2n} \\
\hline
& \beta_1 & \beta_2
\end{array}$$

$$\begin{array}{c|c}
B_{1n} = B_{2n} \\
\hline
& \beta_2 & \beta_2
\end{array}$$

$$\begin{array}{c|c}
C & \beta_2 & \beta_2 & \beta_2
\end{array}$$

$$\begin{array}{c|c}
\mu_1 H_{1n} = \mu_2 H_{2n}
\end{array}$$
(10)

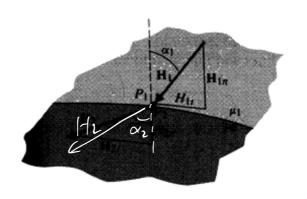
2. The tangential component of the  ${\cal H}$  field is discontinuous across an interface where a free surface current exists.

$$\mathbf{a_n} \times (H_1 - H_2) = J_s \tag{11}$$

When the conductivities of both media are finite, currents are defined by volume current densities and free surface currents do not exist on the interface. Hence  $J_s=0$ , the tangential component of H is continuous across the boundary of almost all physical media; it is discontinuous only when an interface with an ideal perfect conductor or a superconductor is assumed.

## Exercise

Two magnetic media with permeabilities  $\mu_1$  and  $\mu_2$  have a common boundary, as shown in the following figure. The magnetic field intensity in medium 1 at the point  $P_1$  has a magnitude  $H_1$  and makes an angle  $\alpha_1$  with the normal. Determine the magnitude and the direction of the magnetic field intensity at point  $P_2$  in medium 2.

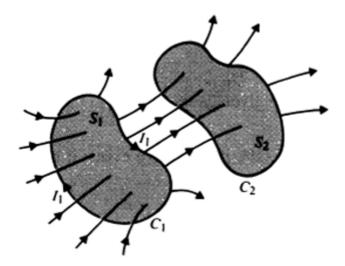


$$\alpha_{2} = \operatorname{arctan} \left( \frac{\mu_{i}}{\mu_{i}} \operatorname{tan} \alpha_{i} \right).$$

$$|H_2| = |H_1| \sqrt{\sin^2 \alpha_1 + (\frac{M_1}{N_2} \cos \alpha_1)^2}$$

#### **Inductances and Inductors**

For two loops  $C_1$ ,  $C_2$ :



For linear media where permeability does not change with  $I_1$ ,

$$L_{12} = \frac{\Lambda_{12}}{I_1} \tag{12}$$

where  $\Lambda_{12}$  is the flux linkage,  $L_{12}$  is the mutual inductance between loops  $C_1$  and  $C_2$ . A more general definition for  $L_{12}$  is then:

$$L_{12} = \frac{d\Lambda_{12}}{dI_1} \tag{13}$$

The total flux linkage with  $C_1$  caused by  $I_1$  is calculated as:

$$\Lambda_{11} = N_1 \Phi_{11} > N_1 \Phi_{12} \tag{14}$$

The self-inductance of loop  $C_1$  could be calculated as:

$$L_{11} = \frac{\Lambda_{11}}{I_1} \tag{15}$$

For linear medium, in general:

$$L_{11} = \frac{d\Lambda_{11}}{dI_1} \tag{16}$$

A conductor arranged in an appropriate shape (e.g., a conducting wire wound as a coil) to supply a certain amount of self-inductance is called an inductor. It can store magnetic energy.

Method to determine the self-inductance of an inductor:

- 1. Choose an appropriate coordinate system for the given geometry.
- 2. Assume a current *I* in the conducting wire.
- 3. Find B from I by Ampere's circuital law,

$$\oint_C B \cdot dl = \mu_0 I \tag{17}$$

if symmetry exists; if not, Biot-Savart law

$$B = \frac{\mu_0 I}{4\pi} \oint_{C'} \frac{dl' \times \mathbf{a}_R}{R^2} \tag{18}$$

must be used.

4. Find the flux linking with each turn,  $\Phi$ , from B by integration:

$$\Phi = \int_S B \cdot ds$$
 get the thix (19)

where S is the area over which B exists and links with the assumed current.

- 5. Find the flux linkage  $\Lambda$  by multiplying  $\Phi$  by the number of turns.
- 6. Find L by taking the ratio  $L=\frac{\Lambda}{I}$ .

To determine the mutual inductance  $L_{12}$  between two circuits, after choosing an appropriate coordinate system, assume  $I_1 \to \operatorname{Find} B_1 \to \operatorname{Find} \Phi_{12}$  by integrating  $B_1$  over surface  $S_2 \to \operatorname{Find}$  flux linkage  $\Lambda_{12} = N_2 \Phi_{12} \to \operatorname{Find} L_{12} = \frac{\Lambda_{12}}{I_1}$ .

In high-frequency applications, current tends to concentrate in the "skin" of the inner conductor as a surface current, internal self-inductance tends to zero. Neumann formula for mutual inductance:

$$L_{12} = L_{21} = \frac{\mu_0}{4\pi} \oint_{C_1} \oint_{C_2} \frac{dl_1 \cdot dl_2}{R} \tag{20}$$

# **Magnetic Energy**

For a system of N loops carrying currents,

$$W_m = rac{1}{2} \sum_{j=1}^{N} \sum_{k=1}^{N} L_{jk} I_j I_k$$
 (21)

For a single inductor,

$$W_m = \frac{1}{2}LI^2 \tag{22}$$

$$W_m = \frac{1}{2} \sum_{k=1}^N I_k \Phi_k \tag{23}$$

# Magnetic Energy In Terms of Field Quantities

Generally,

$$W_m = \frac{1}{2} \int_{V'} \mathbf{\underline{A} \cdot \underline{J}} \, dv' = \frac{1}{2} \int_{V'} \mathbf{\underline{H} \cdot \underline{B}} \, dv' = \frac{1}{2} \int_{V'} \frac{B^2}{\mu} \, dv' = \frac{1}{2} \int_{V'} \mu H^2 \, dv' \quad (24)$$

If we define a magnetic energy density  $w_m$  such that

$$W_m = \int_{V'} w_m \, dv' \tag{25}$$

then

$$w_m = \frac{1}{2}\mathbf{H} \cdot \mathbf{B} = \frac{B^2}{2\mu} = \frac{1}{2}\mu H^2$$
 (26)

And we have

$$L = \frac{2W_m}{I^2} \tag{27}$$

### Reference

- Fan Hu, RC Slides, VE230
- Nana Liu, Slides, VE230

#### Thanks!

