

Part 2

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$$(a) \quad X_{t+1} = mX_t + C$$

$$X = mX + C$$

$$-C = (m-1)X$$

$$X = -\frac{C}{m-1} \text{ if } m \neq 1$$

$$(b) \quad X_{t+1} = mX_t + C$$

$X_0$ : initial value

$$X_1 = mX_0 + C$$

$$\begin{aligned} X_2 &= mX_1 + C \\ &= m(mX_0 + C) + C \end{aligned}$$

$$= m^2X_0 + mC + C$$

$$\begin{aligned} X_3 &= mX_2 + C \\ &= m(m^2X_0 + mC + C) + C \\ &= m^3X_0 + m^2C + mC + C \end{aligned}$$

$\vdots$

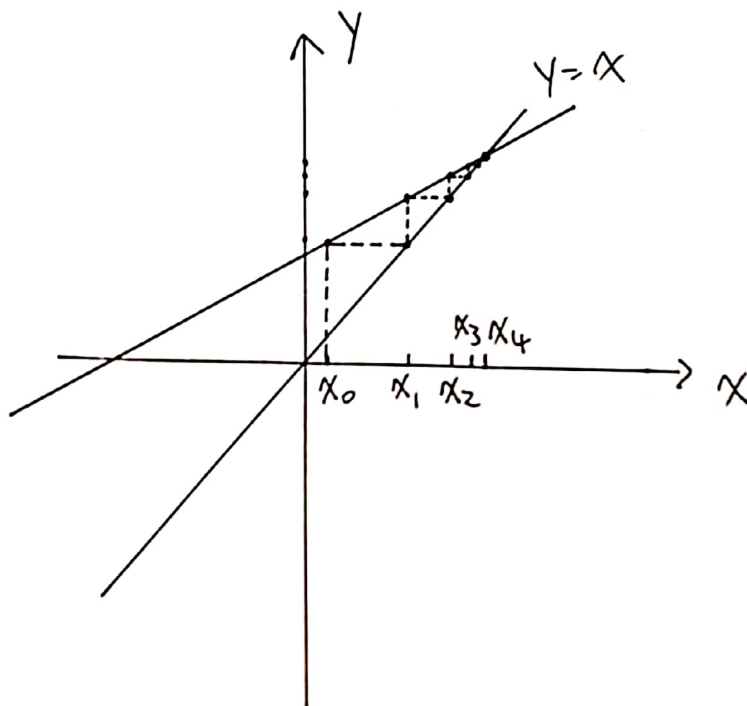
$$X_n = m^n X_0 + m^{n-1}C + m^{n-2}C + \dots + m^1C + m^0C$$

$$\begin{aligned} \text{So } f(X_0, t) &= m^t X_0 + m^{t-1}C + m^{t-2}C + \dots + m^1C + m^0C \\ &= m^t X_0 + \sum_{i=0}^{t-1} m^i C \end{aligned}$$

(C)

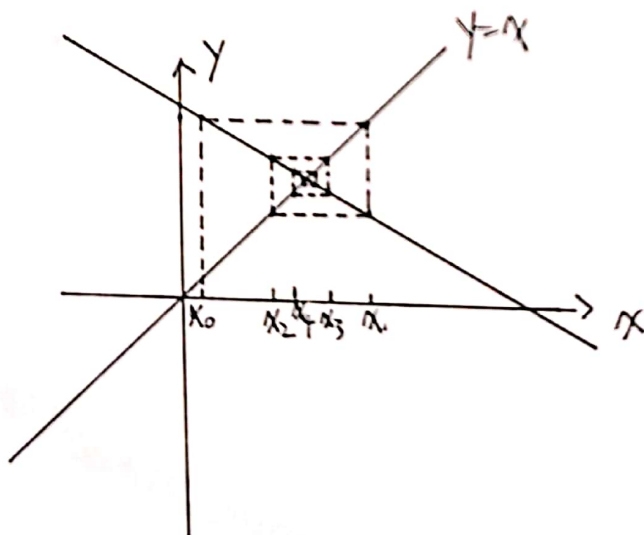
Case 1:  $|m| < 1$   $-1 < m < 1$

①  $0 < m < 1$



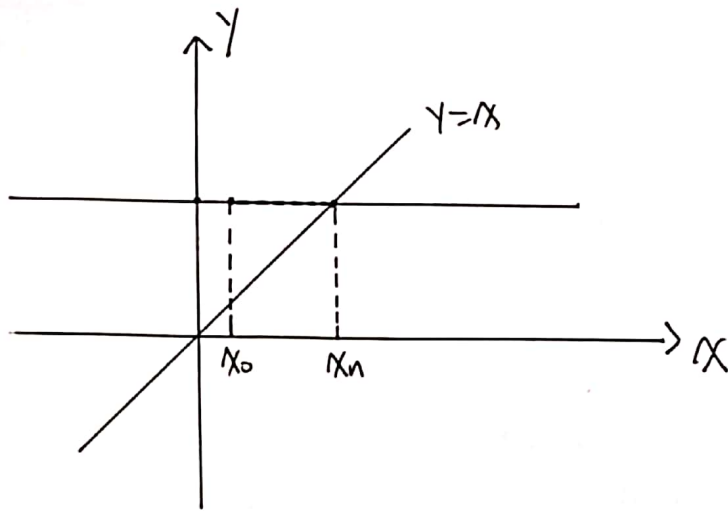
System will converge to a fixed point after  $n$  iterations.

②  $-1 < m < 0$



System will converge to a fixed point after  $n$  iterations.

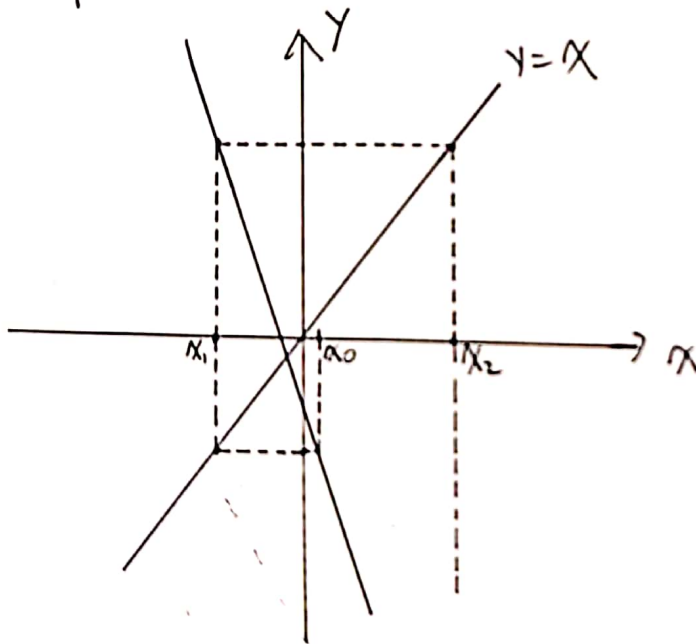
③  $m=0$



System will converge to a fixed point after  $n$  iterations

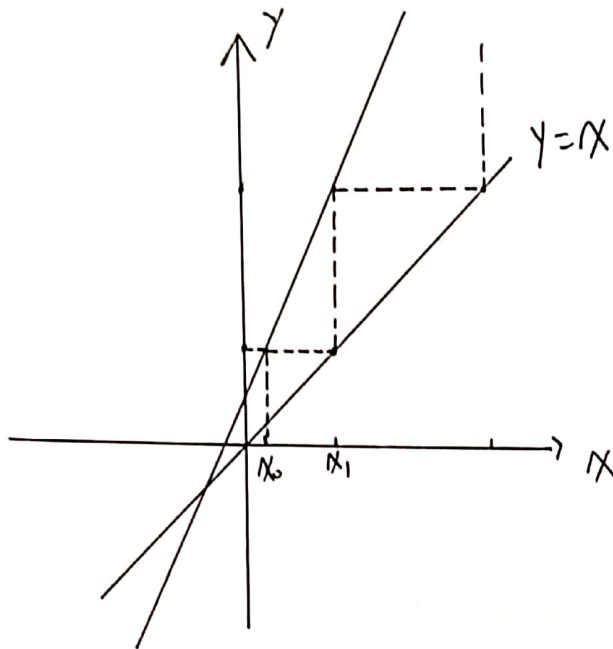
Case 2:  $|m| > 1$

①  $m < -1$



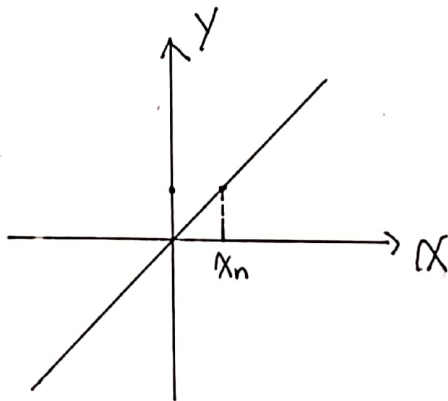
System will not converge, remain unstable.

(2)  $m > 1$



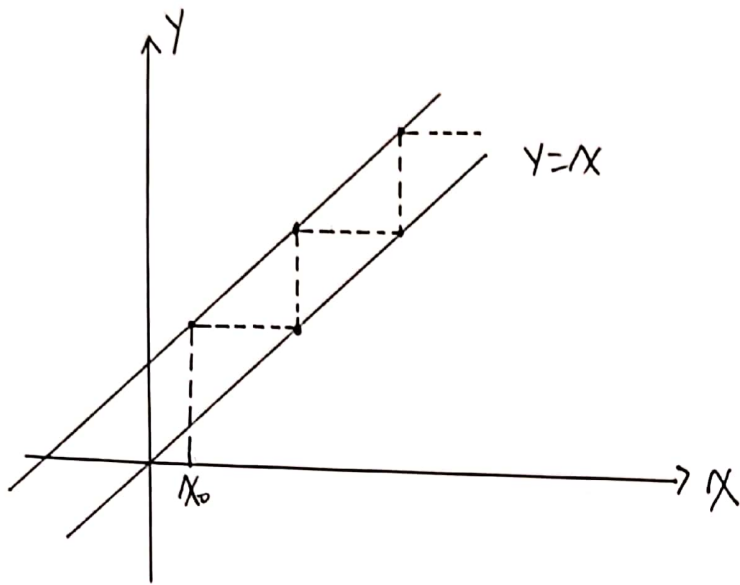
System will not converge, remain unstable.

Case 3:  $m=1, c=0$



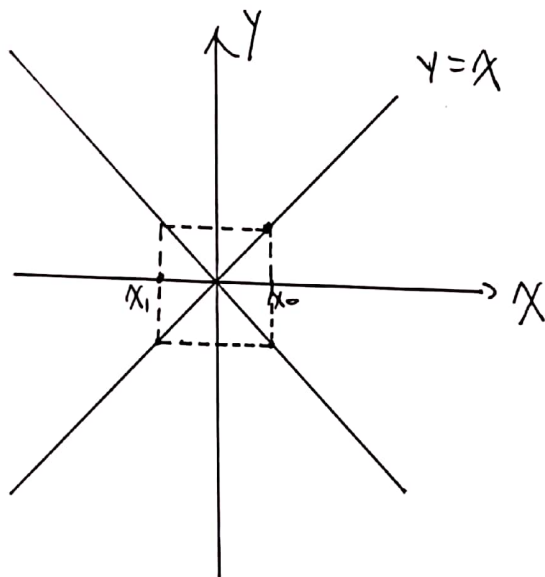
All points are same, system is stable.

Case 4:  $m=1, c \neq 0$



System will not converge, remain unstable.

Case 5:  $m=-1$



Divergent oscillation, system remain unstable.

(d)

$$x_{t+1} = f(x_t)$$

$$x_{t+1} = mx_t + c$$

$$\text{So } f(x_t) = mx_t + c$$

Perform a Taylor series expansion on  $f(x_t)$

$$f(x_t) \approx f(x^*) + f'(x^*)(x_t - x^*)$$

$$x_{t+1} = f(x^*) + f'(x^*)(x_t - x^*)$$

$$x_{t+1} = f'(x^*)x_t + (f(x^*) - f'(x^*)x^*)$$

$$x_{t+1} = mx_t + c$$

$$\text{where } m = f'(x^*) \text{ and } c = f(x^*) - f'(x^*)x^*$$

from our finding of Part 2c, when  $|m| < 1$  and  $m \neq 1, c \neq 0$ ,  
our system is stable.

Since  $f$  is a non-linear function,  $f$  is said to be locally  
stable if  $|f'(x^*)| < 1$