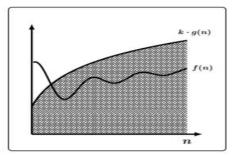
## Asymptotic Notation - Big Oh

- Big Oh Notation (upper bounds)
  - Let f(n) and g(n) be any real-valued function. We say that g eventually dominates f if there is some constant k>0 such that

$$f(n) \leq k \cdot g(n)$$
 for all 'large'  $n$ 

• We say that f(n) belongs to the class O(g(n)), read 'big oh of g', if f(n) is eventually dominated by g(n).

$$f(n) = O(g(n))$$
 or  $f(n) \in O(g(n))$ 



## Complexity Classes P and NP

# EVERYTHING THAT IS EXPONENTIAL CAN NOT BE SOLVED IN POLYNOMIAL TIME

- Polynomial Time Problems
  - ♣ A decision problem **X** is said to be *decidable/solvable* in **polynomial time** if there is a **deterministic Turing Machine** *M* such that:
    - M accepts X
    - $T(n) \in O(n \land k)$  is dominated by a polynomial function, where

T(n) = number of steps required to terminate on input of length n

- The complexity class P is the class of all problems that are decidable in polynomial time
  - P all problems decidable in polynomial time
  - **NP** all problems decidable in non-deterministic polynomial time.

.

- Non-deterministic Polynomial Time Problems
  - The class of **non-deterministic polynomial time** problems is defined similarly but replacing **M** with a non-deterministic **TM**, for which

T(n) - number of steps required to terminate on input of length  $\mathbf{n}$  for some possible computation

- **P** all problems decidable in polynomial time.
- **NP** all problems decidable in non-deterministic polynomial time.
- ♣ Problems that belong to NP are those for which we can verify solution in polynomial time you only need to show a single computation that accepts the input. However, to find the solution may require an exhaustive search of all possible computations

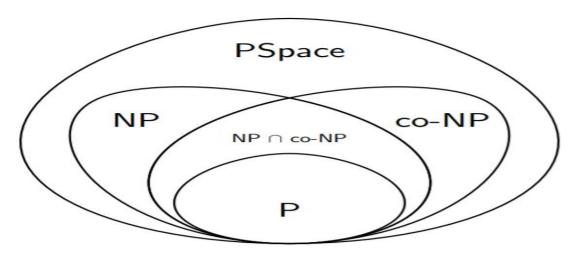
#### Complexity Class PSpace

- Polynomial Space Problems
  - A decision problem **X** is said to be **decidable/solvable** in **polynomial space** if there is a **deterministic Turing machine M** such that:
    - <u>M</u> accepts <u>X</u>
    - $S(n) \in O(n \land k)$  is dominated by a polynomial function where

S(n) = amount of tape used for an input of length n

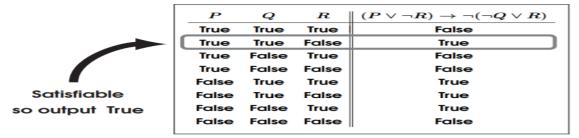
- The complexity class P is the class of all problems that are decidable in polynomial time
  - **PSpace** = all problems decidable in polynomial space

#### Complexity hierarchy



The Boolean Satisfiability Problem

The Boolean Satisfiability Problem SAT Input) A propositional formula FOutput) True if and only if F is satisfiable



This problem can be solved using power of parallel computation on non-deterministic Turing Machine,

# Theorem:

The Boolean Satisfiability Problem SAT belongs to the class NP
 (there is a non-deterministic algorithm for SAT that runs in polynomial time)

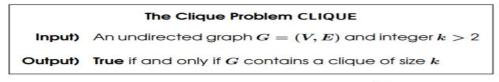
# **Proof:**

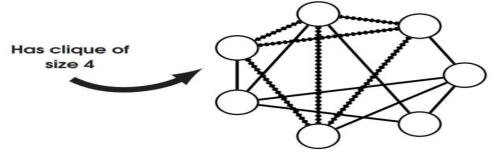
- **Step 1)** Given a propositional formula **F**, we can decide whether **F** is **satisfiable** by computing the **truth table**.
  - O However, the truth table content contains 2 ^ n rows **NOT polynomial!**
- **Step 2)** However a non-deterministic algorithm can evaluate each row in a separate **parallel processor**, each of which takes at most **polynomial time**.

Q.E.D

# The Clique Problem

**Checking** if all **K** nodes are connected together





#### Theorem:

• The Clique Problem **CLIQUE** belongs to the class **NP**. (there is a non-deterministic algorithm for **CLIQUE** that runs in polynomial time)

#### **Proof:**

- **Step 1**) Given an *undirected graph* **G** = **(V, E)** and integer **k** > **2**, we can decide whether **G** contains a clique of size **k** by checking every subset of vertices of size **k**. (BASICALLY BRUTE-FORCING the answer)
  - However, there are n ^ n possible subsets NOT polynomial!
- **Step 2)** However, a non-deterministic algorithm can check every possible subset of vertices in **parallel**, each of which takes at most **polynomial time**.

### **Polynomial Reduction**

- Polynomial Reduction
  - lack 4 A **polynomial reduction** from a problem **A** to a problem **B** is a function  $f: \Sigma^* \to \Sigma^*$  Computable in polynomial time, that maps instances of **A** to instances of **B** such that



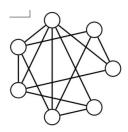
We say that A is reducible to B and write A <= B</p>

## Nota Bene:

For mapping reduction, we did not care about the time taken to compute the function f since we
were not concerned about efficiency, since we were only interested in whether a problem was
decidable.

#### **Polynomial Reduction**

- The Graph Colouring Problem COLOURING
  - Input) An undirected graph G = (V, E) and set of colours C
  - **Output) True** if and only if **V** can be coloured so that adjacent vertices are different colours



G = { Blue B, Green G, Red R }

**Theorem** The Graph Colouring problem is polynomially reducible to the Boolean Satisfiability Problem. *i.e.* **COLOURING**  $\leq_p$  **SAT**.

Proof:

- Step 1) Let G=(V,E) be an undirected graph and  $C=\{B,G,R\}$  be any set of colours (we are using three here for illustration)
- **Step 2)** For each vertex  $v \in V$  and each colour  $i \in C$  designate a propositional variable  $P_{v,i}$  that says

 $P_{v,i} \ = \ \mathsf{vertex} \ v \ \mathsf{can} \ \mathsf{be} \ \mathsf{coloured} \ \mathsf{with} \ i.$ 

- **Step 3)** We can write down a **set of formulas**  $F_G$  that say that the graph can be coloured with only colours from C,
  - Every vertex must be coloured with some colour

$$ig(P_{v,\mathsf{B}}ee P_{v,\mathsf{G}}ee P_{v,\mathsf{R}}ig) \qquad ext{for all } v\in V$$

No vertex can be coloured with more than one colour

$$\neg (P_{v,\mathsf{B}} \land P_{v,\mathsf{G}}) \land \neg (P_{v,\mathsf{B}} \land P_{v,\mathsf{R}}) \land \neg (P_{v,\mathsf{G}} \land P_{v,\mathsf{R}}) \qquad \text{for all } v \in V$$

Adjacent vertices should be different colours

$$\neg \big(P_{v,\mathsf{B}} \land P_{u,\mathsf{B}}\big) \land \neg \big(P_{v,\mathsf{G}} \land P_{u,\mathsf{G}}\big) \land \neg \big(P_{v,\mathsf{R}} \land P_{v,\mathsf{R}}\big) \qquad \text{for all } (u,v) \in E$$

**Step 3)** This set of formulas  $F_G$  is **satisfiable** if and only if the graph G can be coloured with k colours

 $G \in \mathsf{COLOURING} \quad \Longleftrightarrow \quad F_G \in \mathsf{SAT}$ 

(this is a polynomial reduction from COLOURING to SAT)

### **Polynomial Reductions**

**Theorem** The Boolean Satisfiability problem is polynomially reducible to the Clique finding problem. *i.e.* SAT  $\leq_p$  CLIQUE

**Proof:** Given a formula F with k clauses, we want to construct a graph  $G_F$  such that F is satisfiable if and only if  $G_F$  has a k-clique.

**Step 1)** Let  $G_F=(V,E)$  where

 $V = \{L^i : L ext{ is a literal appearing in the } i ext{th clause of } F \ \}$ 

**Step 2)** Connect each vertex to all literals appearing in **different** clauses **UNLESS** they are the negation of the literal

$$(L_1^i, L_2^j) \in E \qquad \Longleftrightarrow \qquad i 
eq j ext{ and } L_1 
ot\equiv 
eg L_2$$

**Step 3)** Note the following two observations:

Obv 1) Any clique of size k must contain a **lifteral from each clause** (since literals in the same clause are not connected with an edge)

Obv 2) A clique does not contain a literal and its negation.

(since literals and their negations are not connected with an edge)

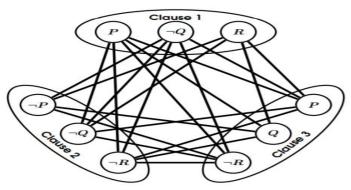
Step 5) Hence, it follows that

 $G_F$  contains a k-clique  $\iff$  F is satisfiable

(just make all the literals in the clique 'true')

Q.E.D.

### **Polynomial Reductions**



$$F = (P \vee \neg Q \vee R) \wedge (\neg P \vee \neg Q \vee \neg R) \wedge (P \vee Q \vee \neg R)$$

#### **NP-Completeness**

+b

#### NP-hardness

 A problem X is said to be NP-hard if every problem in NP can be polynomially reduced to it.

$$Y \leq_p X$$
 for all  $Y \in X$ 

( X is at least as hard as every NP-problem)

# NP-completeness

- A problem X is said to be NP-complete if
  - (i) X is NP-hard (lower bound),
  - (ii) X also **belongs** to the class NP (upper bound).

## **NP-completeness**

**Theorem** If Y is NP-hard and  $Y \leq_p X$ , then X is NP-hard.

Proof:

**Step 1)** If Y is **NP**-hard, then by definition

$$Z \leq_p Y$$
 for all  $Z \in \mathsf{NP}$ 

**Step 2)** But we also have that  $Y \leq_p X$ , so that

$$Z \leq_p Y \leq_p X$$
 for all  $Z \in \mathsf{NP}$ 

Q.E.D.

A typical approach to demonstrating that a problem is **NP**-hard is to show that **SAT** is reducible to it. *i.e.* that **SAT**  $\leq_p X$ .

# **List of NP-complete Problems**

- (Incomplete) List of NP-complete Problems
  - ♣ The Boolean Satisfiability Problem SAT
  - ♣ The Graph Colouring Problem COLOURING
  - The Clique Problem CLIQUE
  - The Hamilton Cycle Problem HAMILTON CYCLE
  - The Travelling Salesman Problem TSP
  - ♣ The Knapsack Problem KNAPSACK

# **NP-Complete**

NP-Complete is a complexity class which represents the set of all problems X in NP for which it is possible to reduce any other NP problem Y to X in polynomial time.

Intuitively this means that we can solve y quickly if we know how to solve x quickly. Precisely, y is reducible to x, if there is a polynomial time algorithm f to transform instances y of y to instances x = f(y) of x in polynomial time, with the property that the answer to y is yes, if and only if the answer to f(y) is yes.

# **Example**

3-SAT. This is the problem wherein we are given a conjunction (ANDs) of 3-clause disjunctions (ORs), statements of the form

```
(x_v11 OR x_v21 OR x_v31) AND
(x_v12 OR x_v22 OR x_v32) AND
... AND
(x_v1n OR x_v2n OR x_v3n)
```

where each  $x_{vij}$  is a Boolean variable or the negation of a variable from a finite predefined list (x 1, x 2, ... x n).

It can be shown that *every NP problem can be reduced to 3-SAT*. The proof of this is technical and requires use of the technical definition of NP (*based on non-deterministic Turing machines*). This is known as *Cook's theorem*.

What makes NP-complete problems important is that if a deterministic polynomial time algorithm can be found to solve one of them, every NP problem is solvable in polynomial time (one problem to rule them all).

# **NP-hard**

Intuitively, these are the problems that are at least as hard as the NP-complete problems. Note that NP-hard problems do not have to be in NP, and they do not have to be decision problems.

The precise definition here is that a problem *x* is *NP-hard*, if there is an *NP-complete* problem *y*, such that *y* is reducible to *x* in polynomial time.

But since any NP-complete problem can be reduced to any other NP-complete problem in polynomial time, all NP-complete problems can be reduced to any NP-hard problem in polynomial time. Then, if there is a solution to one NP-hard problem in polynomial time, there is a solution to all NP problems in polynomial time.

# **Example**

The *halting problem* is an NP-hard problem. This is the problem that given a program P and input I, will it halt? This is a decision problem, but it is not in NP. It is clear that any NP-complete problem can be reduced to this one. As another example, any NP-complete problem is NP-hard.

To show a problem is NP complete, you need to:

#### Show it is in NP

In other words, given some information c, you can create a polynomial time algorithm v that will verify for every possible input x whether x is in your domain or not.

#### Example

Prove that the problem of vertex covers (that is, for some graph G, does it have a vertex cover set of size k such that every edge in G has at least one vertex in the cover set?) is in NP:

- our input x is some graph G and some number k (this is from the problem definition)
- $\bullet$  Take our information c to be "any possible subset of vertices in graph g of size k "
- Then we can write an algorithm v that, given G, k and C, will return whether that set of vertices is a vertex cover for G or not, in **polynomial time**.

Then for every graph G, if there exists some "possible subset of vertices in G of size k" which is a vertex cover, then G is in NP.

**Note** that we do **not** need to find c in polynomial time. If we could, the problem would be in `P.

**Note** that algorithm v should work for **every** G, for some C. For every input there should **exist** information that could help us verify whether the input is in the problem domain or not. That is, there should not be an input where the information doesn't exist.

## Prove it is NP Hard

This involves getting a known NP-complete problem like <u>SAT</u>, the set of boolean expressions in the form:

(A or B or C) and (D or E or F) and  $\dots$ 

where the expression is satisfiable, that is there exists some setting for these booleans, which makes the expression true.

Then reduce the NP-complete problem to your problem in polynomial time.

That is, given some input x for SAT (or whatever NP-complete problem you are using), create some input x for your problem, such that x is in SAT if and only if y is in your problem. The function x is x -> y must run in **polynomial time**.

In the example above, the input Y would be the graph G and the size of the vertex cover k.

For a *full proof*, you'd have to prove both:

- that x is in SAT => Y in your problem
- and y in your problem => x in SAT.

marcog's answer has a link with several other NP-complete problems you could reduce to your problem.

Footnote: In step 2 (**Prove it is NP-hard**), reducing another NP-hard (not necessarily NP-complete) problem to the current problem will do, since NP-complete problems are a subset of NP-hard problems (that are also in NP).