## **Linear Programming**

### TO MAXIMISE PROFITS, WE NEED TO MINIMISE THE COST OF PRODUCTION

- Objective Function: The quantity to be maximised / minimised
- Linear Constraints: Set of linear inequalities restricting the possible solutions.
- There may be a unique solution, infinitely many solutions or no solution

Maximise: 2x + 3ySubject to:  $3x + 2y \le 15$   $2y - x \le 5$   $x + 2y \le 7$  $x, y \ge 0$ 

Example: A company creates its smoothies using:

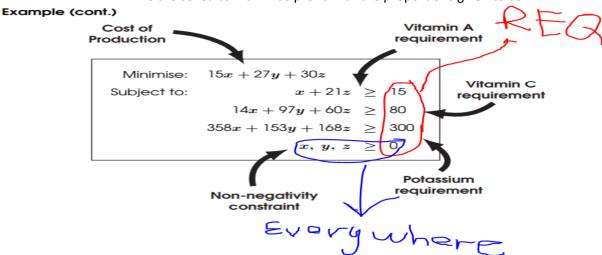


Each smoothie must contain at least 15% RDA of Vitamin A, at least 80% RDA of Vitamin C, and at least 300mg of potassium.

- 100g of Banana contains 1% of the RDA of Vitamin A, 14% of the RDA of Vitamin C, 358mg of potassium and costs 15p.
- 100g of Strawberrycontains no Vitamin A, 97% of the RDA of Vitamin C, 153mg of potassium and costs 27p.
- 100g of Mango contains 21% of the RDA of Vitamin A, 60% of the RDA of Vitamin C, 168mg of potassium and costs 30p.

### What proportion of ingredients would maximise profits?

We are asked to maximise profit with the proportions given to us



TO FIND A PRICE OF A PRODUCT IN THIS CASE SMOOTHIE, WE HAVE:

TO FIND SOLUTION WE CAN STICK THE CONSTRAINTS INTO THE LP SOLVER AND IT WILL COME UP WITH OPTIMAL SOLUTION THAT SATISFIES THE MINIMISE CONSTRAINT.

WITH THE PRICE OF EACH SMOOTHIE OF 35.59p

Optimal Solution  $x = 0.365, \quad y = 0.341, \quad z = 0.697$ 

To solve **LPs**, it is helpful to write them in a **Standard Form**:

- This reduces the number of cases we must consider
- We can design algorithms that are highly specialised for a particular input format (this is why
  we use CNF as the 'standard form' for SAT problems)

#### LP Standard Form

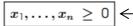
#### STANDARD FORM FOR LINEAR PROGRAMS

- The criteria must be to maximise the objective function
   IT DOES NOT ACCEPT MINIMISE NEED TO CONVERT MINIMISE TO MAXIMISE.
- All **linear constraints** must be of the form 'less-than or-equal-to' <

$$|a_1x_1+a_2x_2+\cdots+a_nx_n|\leq c$$

(where  $a_1, \ldots, a_n$  and c are constants)

 We seek a non-negative solution with the additional constraint – we don't want to be searching over the whole space negative and positive numbers so all must be non-negative.



## **Converting to STANDARD FORM**

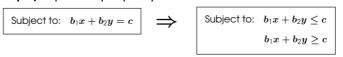
Step 1) Change the criteria for the objective function (IF REQUIRED)

So, you basically add a negative '- 'next to all coefficients



(minimising F is the same as maximising -F)

Step 2) Replace any 'equality constraints'



(A=c if and only if  $A\leq c$  and  $A\geq c$ )

to Standard Form?

Maximise: 2x+y Subject to:  $2x+y \le 2$   $x-y \le 5$ 

 $x,y \geq 0$ 

standard form 🗸

But how do we convert

not standard form XMaximise: 2x - 3y

Minimise: 3y - 2x

 $2y-x \geq -4$ 

 $x,y \geq 0$ 

Subject to:

Subject to:  $x+y \leq 7$   $-x-y \leq -7$   $x-2y \leq 4$   $x,y \geq 0$ 

**Step 3)** Negate any 'greater-than-or-equal-to' constraints

Subject to: 
$$b_1x+b_2y\geq c$$
 Subject to:  $-b_1x+-b_2y\leq -c$ 

( $A \geq c$  if and only if  $-A \leq -c$ )

Step 4) Ensure all variables are required to be non-negative (this may require introducing additional variables)

Case 4.1) If we have the constraint like  $x \le 0$ 

Replace Add constraint 
$$x:=(-x')$$
  $x'\geq 0$ 

Case 4.2) If there is no constraint on a variable  $oldsymbol{x}$  at all

Replace 
$$x:=(x'-x'') \hspace{1cm} {\sf Add\ constraints} \\ x',x''\geq 0$$

If we have a constraint that x must be a negative value, we won't throw it away, but we need to re-write/ replace it with new one. 4.1 have restriction you are flipping it, 4.2 you enforce some restriction,

So, case 4.2 must enforce some restriction that we wont search entire search-space and we don't have any constraints for X thus we create X' and X" which will act like a bound, allowing to getting negative value when x' is lower than x' or positive value when x" is lower than x'. This restricts the x to be above negative search space but still allowing to have negative and positive values. In a way that it does not restrict our value X. We claim solution if we want to retrieve X back we just need to take X' - X'' = X

## LP Standard Form

#### **SLACK FORM**

So, after getting all constraints into the same format we can introduce Slack Form, which introduces the variable which says how far off from that bound I am I. For example, we know that "x - 2y <= 4" 4 is less by we don't know by how much, and that's why we will introduce SLACK VARIABLE into equation.

**Step 1)** Replace any 'less-than-or-equal' constraints

Subject to: 
$$b_1x+b_2y\leq c$$
 Subject to:  $b_1x+b_2y+s=c$ 

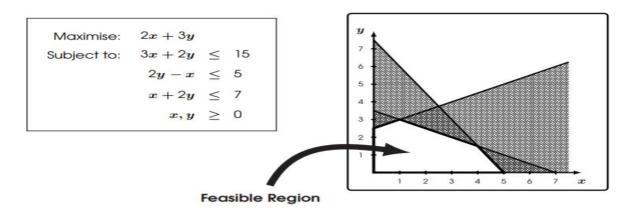
Step 3) Replace any 'greater-than-or-equal' constraints (IF WE DIDN'T GET RID OFF THEM YET)

Subject to: 
$$b_1x+b_2y\geq c$$
 Subject to:  $b_1x+b_2y-s=c$ 

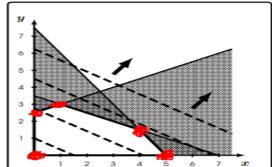
Where s is a SLACK VARIABLE.

## Visualising a Solution

What does a solution to an LP look like?



- The Feasible Region is the set of all possible solutions satisfying the linear constraints.
- Since the objective function is linear, its maximum / minimum value must occur along the boundary of the feasible region.
- In fact, it is enough to examine only
  the **corners** of the feasible region.



 If the objective function is parallel to some contraint, there may be infinitely many solutions along some edge.

Evaluate each corner and see which one gives us the highest value when evaluating the objective function and pick up the best. In a bigger criterion there will be many intersections and that can be tricky.

### The Simplex Method

### Simplex Method is used where they are many boundaries to check.

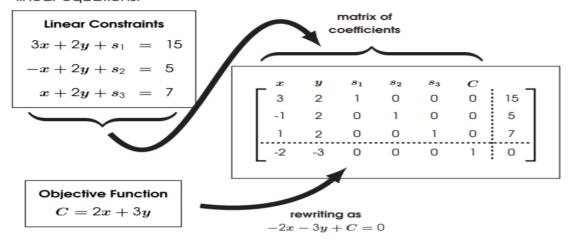
The **Simplex Method** greedily explores the boundary of the feasible region to find an optimal solution.

### The Simplex Method (concept)

- Start at the origin, with all variables set to zero,
- Select the variable that leads to the greatest increase in the objective function,
- Increase until you hit a constraint,
- Move along the constraint if doing so leads to an increase in the objective function,
- Repeat, moving around the boundary of the feasible region.

#### Introducing Tableaux

 A Tableau (plural Tableaux) is a matrix representation of a system of linear equations:



### SIMPLEX METHOD

**STEP 1) Construct** the **initial tableau** from the slack form of the linear program. We are rewriting objective function by adding C constraint.

**STEP 2)** Identify the column with the **most negative** coefficient in the final row – FIND MOST NEGATIVE VALUE IN THE BOTTOM ROW IN TABLE.

**STEP 3)** Calculate the **row quotients** by dividing each of the entries in the final column by the entries in the pivot column. BASICALLY, DIVIDE ALL ENTRIES IN THE RIGHTMOST COLUMN BY ALL ENTRIES in the PIVOT COLUMN.

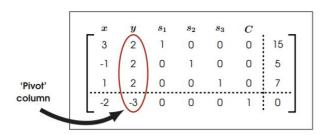
**STEP 4)** The row with the **smallest positive** row quotient is the first constraint that is violated when increasing the pivot variable. SELECT SMALLES ONE, THIS ONE IS A PIVOT ROW IT CROSSES WITH PIVOT ROW.

## STEP 5) Apply the row transformation that

- Leaves a 1 in the **pivot row** of the pivot column
- Leaves a 0 in all other rows of the pivot column INCLUDING THE FINAL ROW.
- WE LOOK FOR OPERATION THAT CAN BE PERFORMED TO BRING THE VALUE TO EITHER 1 or 2 and THEN WE PERFORM THE SAME OPERATION ON ENTIRE ROW, THEN GOING TO NEXT ROW

### Simplex Method Example

**Step 1)** Construct the **initial tableau** from the slack form of the linear program.



**Step 2)** Identify the column with the **most negative** coefficient in the final row.

Step 5) Apply the row transformation that

- leaves a 1 in the pivot row of the pivot column,
- leaves a 0 in all other rows of the pivot column

$$\begin{bmatrix} x & y & s_1 & s_2 & s_3 & C \\ 3 & 2 & 1 & 0 & 0 & 0 & 15 \\ -1 & 2 & 0 & 1 & 0 & 0 & 5 \\ 1 & 2 & 0 & 0 & 1 & 0 & 7 \\ -2 & -3 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$$R_1 \leftarrow (R_1 - R_2)$$
 ,  $R_2 \leftarrow \frac{1}{2}R_2$  ,  $R_3 \leftarrow (R_3 - R_2)$  ,  $R_4 \leftarrow (R_4 + \frac{3}{2}R_2)$ 

Step 5) Repeat until the final row contains only positive coefficients.

$$\begin{bmatrix} x & y & s_1 & s_2 & s_3 & C \\ 0 & 0 & 1 & 1 & -2 & 0 & 6 \\ 0 & 1 & 0 & 0.25 & 0.25 & 0 & 3 \\ \hline 1 & 0 & 0 & -0.5 & 0.5 & 0 & 1 \\ 0 & 0 & 0 & -0.25 & 1.75 & 1 & 11 \end{bmatrix}$$

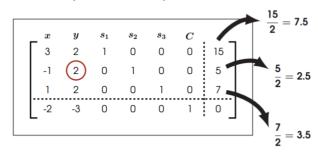
$$R_1 \leftarrow (R_1 - 2R_3)$$
 ,  $R_2 \leftarrow (R_2 + \frac{1}{4}R_3)$  ,  $R_3 \leftarrow \frac{1}{2}R_3$  ,  $R_4 \leftarrow (R_4 + \frac{7}{4}R_3)$ 

 $\textbf{Step 5)} \quad \text{Repeat until the final row contains only positive coefficients}.$ 

$$\begin{bmatrix} x & y & s_1 & s_2 & s_3 & C \\ 0 & 0 & 1 & 1 & -2 & 0 & 6 \\ 0 & 1 & -0.25 & 0 & 0.75 & 0 & 1.5 \\ 1 & 0 & 0.5 & 0 & -0.5 & 0 & 4 \\ \hline 0 & 0 & 0.25 & 0 & 1.25 & 1 & 12.5 \\ \end{bmatrix}$$

 $R_1 \leftarrow R_1$  ,  $R_2 \leftarrow (R_1 - \frac{1}{4}R_1)$  ,  $R_3 \leftarrow (R_3 + \frac{1}{2}R_1)$  ,  $R_4 \leftarrow (R_4 + \frac{1}{4}R_1)$ 

Step 3) Calculate the row quotients by dividing each of the entries in the final column by the entries in the pivot column



**Step 4)** The row with the **smallest** *positive* row quoteint is the first constraint that is violated when increasing the pivot variable.

Step 5) Repeat until the final row contains only positive coefficients.

$$\begin{bmatrix} x & y & s_1 & s_2 & s_3 & C \\ 4 & 0 & 1 & -1 & 0 & 0 & 10 \\ -0.5 & 1 & 0 & 0.5 & 0 & 0 & 2.5 \\ \hline 2 & 0 & 0 & -1 & 1 & 0 & 2 \\ -3.5 & 0 & 0 & 1.5 & 0 & 1 & 7.5 \end{bmatrix}$$

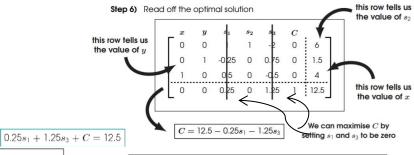
$$R_1 \leftarrow (R_1 - 2R_3)$$
 ,  $R_2 \leftarrow (R_2 + \frac{1}{4}R_3)$  ,  $R_3 \leftarrow \frac{1}{2}R_3$  ,  $R_4 \leftarrow (R_4 + \frac{7}{4}R_3)$ 

Step 5) Repeat until the final row contains only positive coefficients.

$$\begin{bmatrix} x & y & s_1 & s_2 & s_3 & C \\ 0 & 0 & 1 & 1 & -2 & 0 & 6 \\ 0 & 1 & 0 & 0.25 & 0.25 & 0 & 3 \\ 1 & 0 & 0 & -0.5 & 0.5 & 0 & 1 \\ 0 & 0 & 0 & -0.25 & 1.75 & 1 & 11 \end{bmatrix}$$

$$R_1 \leftarrow R_1$$
 ,  $R_2 \leftarrow (R_1 - \frac{1}{4}R_1)$  ,  $R_3 \leftarrow (R_3 + \frac{1}{2}R_1)$  ,  $R_4 \leftarrow (R_4 + \frac{1}{4}R_1)$ 

The Simplex Method (cont.)



Optimal Solution x=4 y=1.5  $s_1=0$   $s_2=6$   $s_3=0$  C=12.5

### Branch-and-Bound for Integer Programming

#### **Integer Program**

Linear Program + Require Integer solution

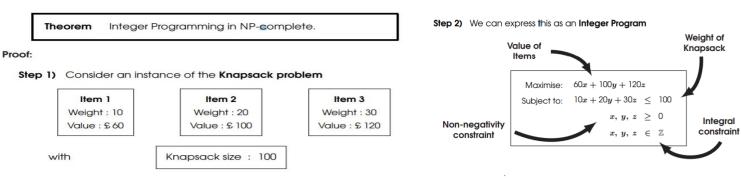
Example:

Maximise: 2x+3ySubject to:  $3x+2y \leq 15$   $2y-x \leq 5$   $x+2y \leq 7$   $x, y \geq 0$  $x, y \in \mathbb{Z}$ 

(this is the same example as earlier, but with the additional integral requirement)

1.5 is not good for example because we want number of students, that's why we require the x, y to be integers Z.

### Integer Programming is NP-complete



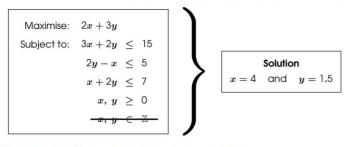
We will express this instance of the Knapsack problem as an Integer Program Since Knapsack is NP-complete, so too must be Integer Programming.

IF YOU CAN SOLVE INTEGER PROBLEM QUICKLY YOU CAN SOLVE ALL NP-COMPLETE PRBLEMS. AND THIS CAN BE THE PROOF BECAUSE IT IS POLYNOMIALY REDUICBLE TO KNAP SACK PROBLEM WHICH IS A NP-COMPLETE

#### Branch-and-Bound

#### Branch-and-Bound Algorithm

# Step 1) Solve the 'continuous/linear relaxation' using the Simplex Method (remove the requirement that solution must be integers)

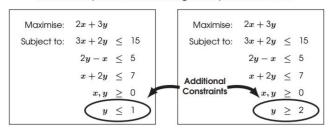


**Step 2)** If all values are integral then we are done!

We can just **return the solution** that we have found!

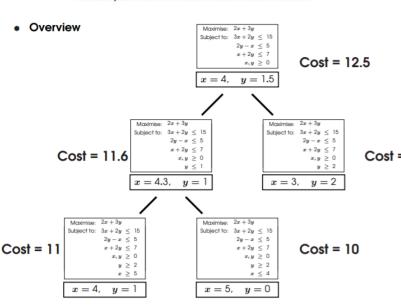
#### Branch-and-Bound Algorithm (cont.)

**Step 3)** Else, **branch** to two sub-**pro**blems with the variable **bounded** above and below by the floor and ceiling of the previous solution



**Step 4)** Recursively apply Branch-and-Bound to both sub-problems and return solution which **maximises** the objective function.

(this is yet another example of Divide-and-Conquer)



That is why Linear programming is in P class and Integer

Programming is in NP because following simplex method it

would constantly spit out fractional numbers not satisfying our

constraints, we can use Branch-and-Bound for this and in some cases it will find a solution in relatively quick time, however

there are still cases where it would have to explore the entire

tree that is why it is in NP class.

• Hence the solution to our Integer Program is

$$x=3$$
 and  $y=2$ 
 $\longrightarrow$  Cost = 12

Cost = 12 • The solution to the Integer Program is always less optimal than the solution to its continuous/linear relaxation.

Solution

 We can cut corners by only branching on those children whose are no worse than the best integer solution found so far!

(if we had evaluated the right-child before the left-child, we could have stopped early since 11.6 < 12)

Other Variants of Linear Programming

- Mixed Integer Linear Programming (MILP)
  - Hybrid of an Integer Program and a classical Linear Program,
  - Some variable are required to be integers,
  - Others are allowed to take non-integral values.
- Zero-one Integer Programming
  - A restriction of Integer Progamming,
  - All variables can be either zero or one,