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Teaching-learning-based artificial bee colony

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1 Introduction

- **Problem:** continue function optimization

$$\min f(x)$$

$$s.t. \quad x_{min} \leq x \leq x_{max}$$

- **Metaheuristic algorithms**

- nature inspired optimization strategies
- received much attention regarding their potential as global optimization techniques



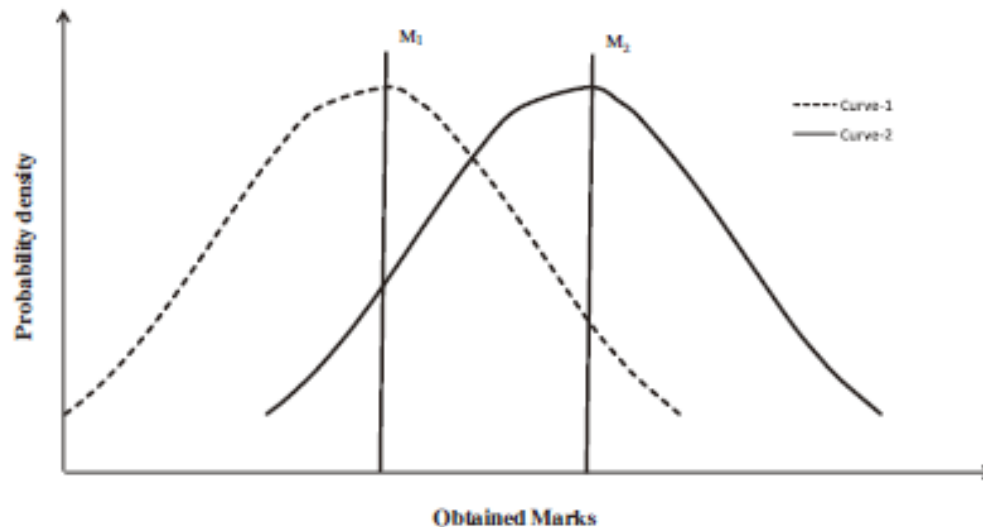
2 TLBO and ABC

- Our paper focuses on two metaheuristic algorithms
 - **Teaching-learning-based optimization (TLBO)**
 - Inspired by the teaching and learning process of a class
 - Two operators: teacher phase and learner phase
 - **Artificial bee colony (ABC)**
 - Inspired by the intelligent foraging behavior of honey bees
 - Three kinds of bees: employed bees, onlooker bees, and scout bees

2.1 TLBO

- **Teaching-learning-based optimization (TLBO)**
 - **Two operators**: teacher phase and learner phase
 - **Teacher phase**: the teacher provides knowledge to the learners to increase the mean result of the class.

$$\mathbf{x}_i^{new} = \mathbf{x}_i^{old} + \mathbf{rand} \cdot (\mathbf{x}_{teacher} - T_F \cdot \mathbf{x}_{mean})$$



2.1 TLBO

- **Teaching-learning-based optimization (TLBO)**
 - **Two operators**: teacher phase and learner phase
 - **Learner phase**: each learner randomly interacts with other different learners to further improve his result

$$\begin{aligned} & \mathbf{x}_i^{new} \\ &= \begin{cases} \mathbf{x}_i^{old} + rand \cdot (\mathbf{x}_i - \mathbf{x}_j), & \text{if } f(\mathbf{x}_i) \leq f(\mathbf{x}_j) \\ \mathbf{x}_i^{old} + rand \cdot (\mathbf{x}_j - \mathbf{x}_i), & \text{if } f(\mathbf{x}_j) > f(\mathbf{x}_i) \end{cases} \end{aligned}$$

Remark: In both teacher phase and learner phase, if \mathbf{x}_i^{new} is better than \mathbf{x}_i^{old} , then use \mathbf{x}_i^{new} to replace \mathbf{x}_i^{old} .

2.2 ABC

■ Artificial bee colony (ABC)

- ❑ Inspired by the intelligent foraging behavior of honey bees
- ❑ Three kinds of bees: employed bees, onlooker bees, and scout bees
- ❑ **Employed bees:** responsible for seeking out better food sources and passing quality information of the food sources to onlooker bees by dancing.
- ❑ **Onlooker bees:** select good food sources found by employed bees to further search for better food source.
- ❑ **Scout bees:** abandon the exhausted food sources, and regenerate a new food source.



3 Proposed Teaching-learning-based Artificial Bee Colony

■ Motivation

- ❑ **TLBO**: Good exploitation, poor exploration
- ❑ **ABC**: Good exploration, poor exploitation
- ❑ Design a hybrid metaheuristic algorithm based on TLBO and ABC.

■ Question

- ❑ How to effectively combine TLBO and ABC?



3 Proposed Teaching-learning-based Artificial Bee Colony

- **Teaching-learning-based Artificial Bee Colony (TLABC)**
 - **Method**: Combine the search equations of TLBO with the search framework of ABC
 - Three hybrid search phases
 - (1) **Exploration**: teaching-based employed bee phase
 - (2) **Exploitation**: learning-based onlooker bee phase
 - (3) **Restart**: generalized oppositional scout bee phase



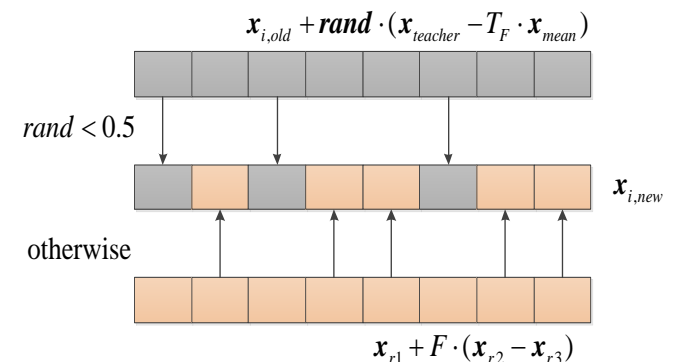
3 Proposed Teaching-learning-based Artificial Bee Colony

■ Teaching-based employed bee phase

- Exploration phase
- Each employed bee use an hybrid TLBO teaching strategy to update the position

$$u_{i,d} = \begin{cases} x_{i,d}^{old} + rand_2 \cdot (x_{teacher,d} - T_F \cdot x_{mean,d}) & \text{if } rand_1 < 0.5 \\ x_{r1,d} + F \cdot (x_{r2,d} - x_{r3,d}) & \text{else} \end{cases}$$

Remark: The hybrid TLBO teaching strategy can improve the **exploration** of the original TLBO teaching strategy.



3 Proposed Teaching-learning-based Artificial Bee Colony

■ Learning-based onlooker bee phase

- Exploitation phase
- Each onlooker bee select a solution based on the fitness

$$fit(\mathbf{x}_i) = \begin{cases} \frac{1}{1+f(\mathbf{x}_i)} & \text{if } f(\mathbf{x}_i) \geq 0 \\ 1 + |f(\mathbf{x}_i)| & \text{otherwise} \end{cases}$$

- Use the TLBO learning strategy to update the position

$$\begin{aligned} & \mathbf{x}_i^{new} \\ &= \begin{cases} \mathbf{x}_i^{old} + rand \cdot (\mathbf{x}_i - \mathbf{x}_j), & \text{if } f(\mathbf{x}_i) \leq f(\mathbf{x}_j) \\ \mathbf{x}_i^{old} + rand \cdot (\mathbf{x}_j - \mathbf{x}_i), & \text{if } f(\mathbf{x}_j) > f(\mathbf{x}_i) \end{cases} \end{aligned}$$

3 Proposed Teaching-learning-based Artificial Bee Colony

■ Generalized oppositional scout bee phase

- Restart phase
- Each exhausted solution re-initializes using a generalized opposition based learning (GOBL)

$$\mathbf{x}_i = \begin{cases} \mathbf{x}_i, & \text{if } f(\mathbf{x}_i) \leq f(\mathbf{x}_i^{GO}) \\ \mathbf{x}_i^{GO}, & \text{if } f(\mathbf{x}_i) > f(\mathbf{x}_i^{GO}) \end{cases}$$

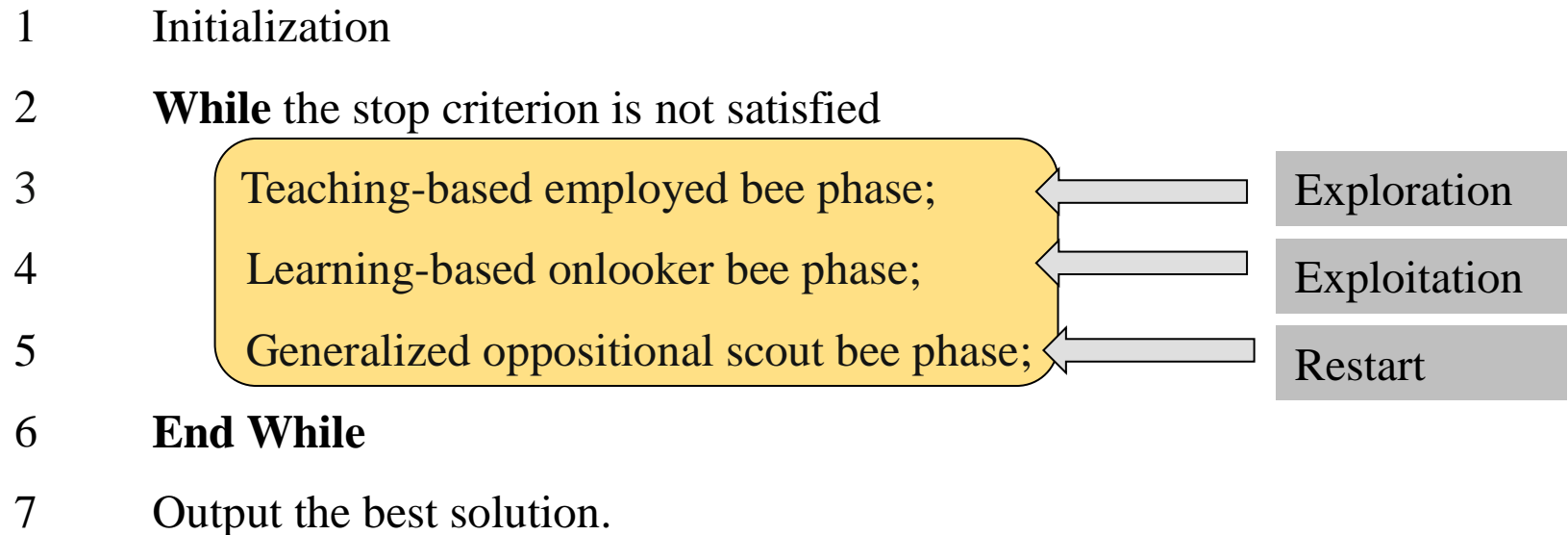
where $\mathbf{x}_i = (x_{i1}, \dots, x_{ij}, \dots, x_{iD})$, $\mathbf{x}_i^{GO} = (x_{i1}^{GO}, x_{i2}^{GO}, \dots, x_{iD}^{GO})$

$$x_{ij}^{GO} = k \cdot (x_{\min,j} + b_{\max,j}) - x_{ij}$$

3 Proposed Teaching-learning-based Artificial Bee Colony

■ Framework of TLABC

Algorithm 1. Teaching-learning artificial bee colony algorithm



4 Experimental Results and Analysis

■ Benchmarks

- CEC2014 test functions
- G1: unimodal functions (F01–F03);
- G2: simple multimodal functions (F04–F16);
- G3: hybrid functions (F17–F22);
- G4: composition functions (F23–F30).

■ Comparisons

- Four TLBO : TLBO, NIWTLBO, LETLBO and GOTLBO
- Four ABC: ABC, GABC, MABC and GBABC

4 Experimental Results and Analysis

■ Compared with TLBO algorithms

Table The win-draw-loss statistics results between TLABC and the compared TLBO algorithms based on Wilcoxon rank-sum test

TLABC vs	TLBO	NIWTLBO	LETLBO	GOTLBO
G1	3-0-0	3-0-0	3-0-0	2-1-0
G2	9-2-2	9-2-2	7-3-3	8-3-2
G3	3-2-1	3-0-3	3-1-2	2-3-1
G4	5-2-1	3-2-3	6-2-0	1-2-5
Total	20-6-4	18-4-8	19-6-5	13-9-8

- (i) TLABC shows the best performance on the unimodal functions, simple multimodal functions and hybrid functions.
- (ii) On composition functions, GOTLBO shows the best performance, TLABC the second.

4 Experimental Results and Analysis

■ Compared with ABC algorithms

Table The win-draw-loss statistics results between TLABC and the compared ABC algorithms based on Wilcoxon rank-sum test

TLABC vs	ABC	GABC	MABC	GBABC
G1	3-0-0	3-0-0	2-1-0	3-0-0
G2	3-2-8	3-2-8	5-2-6	3-2-8
G3	5-0-1	5-0-1	3-0-3	3-3-0
G4	7-0-1	6-2-0	5-2-1	4-3-1
Total	18-2-10	17-4-9	15-4-11	13-8-9

- (i) TLABC shows the best performance on the unimodal functions, hybrid functions, and composition functions.
- (ii) For the simple multimodal functions, the performance of TLABC is not very satisfactory, but it also gets the best results on some multimodal functions.

4 Experimental Results and Analysis

■ Multiple-problem statistical comparison

Table Results of Multiple-problem Wilcoxon test between TLABC and the compared TLBO and ABC algorithms

Algorithm	R+	R-	p-value	$\alpha=0.05$	$\alpha=0.1$
TLABC vs TLBO	375	60	3.32E-04	Yes	Yes
TLABC vs NIWTLBO	318	117	2.91E-02	Yes	Yes
TLABC vs LETLBO	331	104	1.29E-02	Yes	Yes
TLABC vs GOTLBO	328	107	1.57E-02	Yes	Yes
TLABC vs ABC	331	134	4.27E-02	Yes	Yes
TLABC vs GABC	311	154	1.09E-01	No	No
TLABC vs MABC	284	181	≥ 0.2	No	No
TLABC vs GBABC	256	209	≥ 0.2	No	No

4 Experimental Results and Analysis

■ Multiple-problem statistical comparison

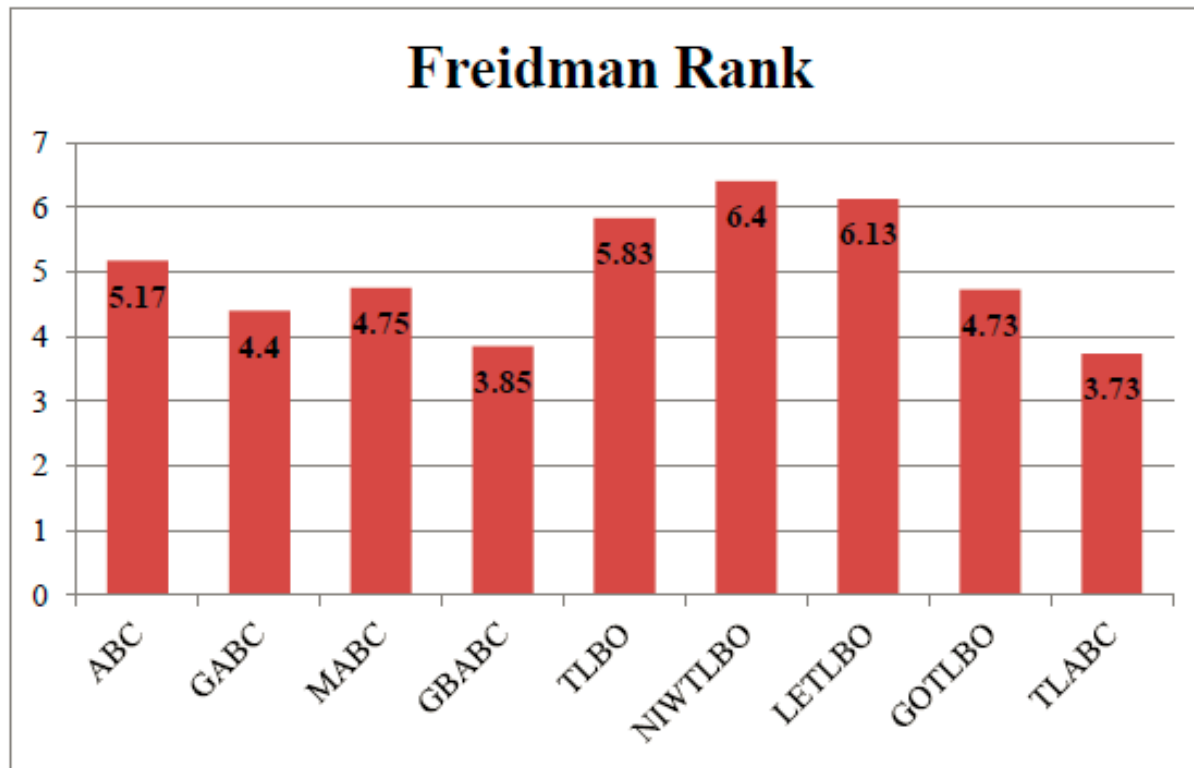


Figure Friedman rank of TLABC and the compared algorithms.

4 Experimental Results and Analysis

■ Convergence graphs

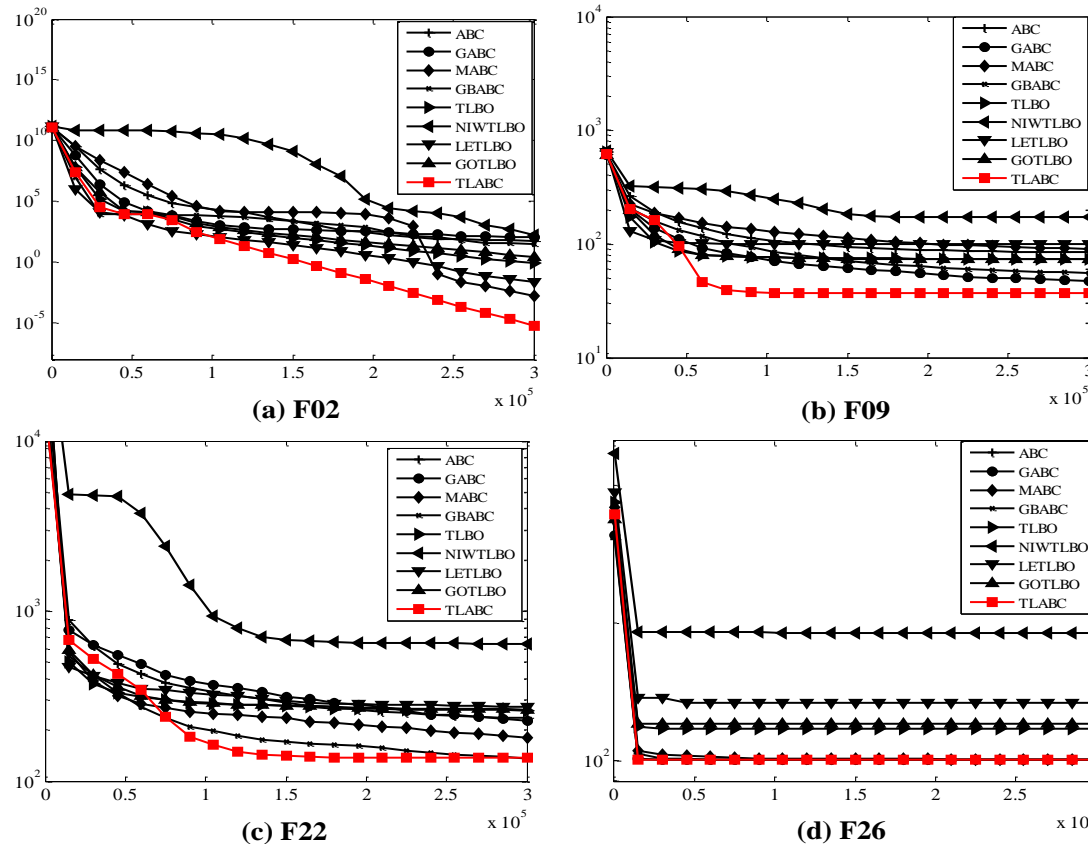


Figure Convergence graphs of TLABC and the compared algorithms on four typical functions

5 Conclusion

- A hybrid TLABC algorithm based on TLBO and ABC is proposed.
- TLABC combines good exploitation of TLBO and good exploration of ABC.
- TLABC provides a better balance between exploration and exploitation compared with the previous TLBO and ABC algorithms.
- TLABC is better than the compared TLBO and ABC algorithms on most of CEC2014 benchmark functions.



The End.

Thanks for Your Attentions.

