

# Gromov–Hausdorff distance between clouds of special type

Calculating distance to cloud of bounded metric spaces

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# Gromov–Hausdorff distance

1

# Clouds

The Gromov–Hausdorff distance is a generalized pseudometric on the class of all metric spaces.

Example:  $d_{GH}(\Delta_1, \mathbb{R}) = \infty$ .

**Clouds**: all metric spaces that are at a finite distance from each other.  $[X]$  — cloud containing  $X$ .

# Cloud of bounded metric spaces

$$|X, \Delta_1| = \frac{1}{2} \text{diam } X$$

Cloud  $[\Delta_1]$  — cloud of all bounded metric spaces.

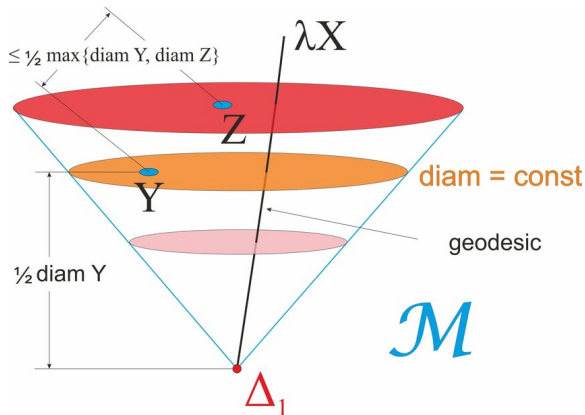
Ultrametric inequality:

$$|X, Y| \leq \max \{|X, \Delta_1|, |Y, \Delta_1|\}$$

Geodesic:

$$|\lambda X, \mu X| = |\lambda - \mu| |X, \Delta_1|$$

# Cloud of bounded metric spaces



# Stabilizer group

Multiplying spaces by  $\lambda > 0$  can produce interesting results. The distance  $|X, \lambda X|$  can be infinite. For example, if  $X$  is a geometric progression.

**Stabilizer group:** all  $\lambda > 0$  such that  $[X] = [\lambda X]$ .

**Trivial:**  $\text{St}([X]) = \{1\}$ .

**Center:** metric space  $X$ , such that  $X = \lambda X$  for all  $\lambda \in \text{St}([X])$ .

# Gromov–Hausdorff distance between clouds

Metric spaces are sets by definition.

Clouds are not sets, they are proper classes. They contain sets of arbitrary cardinality.

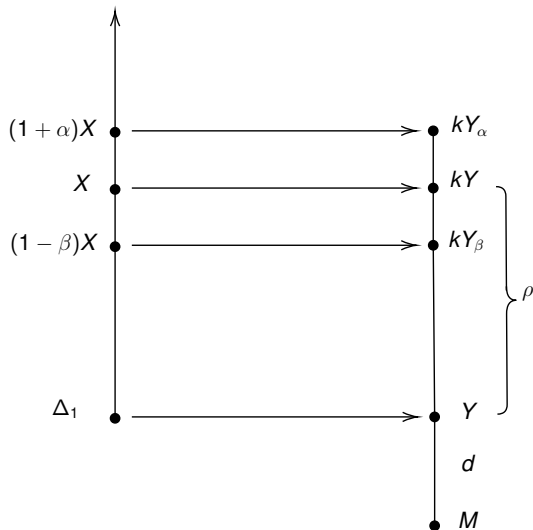
Definition of Gromov–Hausdorff distance is modified.

# Center image Theorem

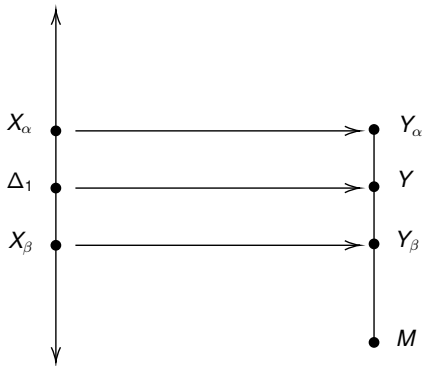
Clouds  $[M], [\Delta_1], [M]$  has a nontrivial stabilizer and  $M$  — center.  $R$  — correspondence between them,  $\text{dis } R = \epsilon < \infty$ . Then  $|R(\Delta_1), M| \leq 2\epsilon$ .



# Center image Theorem



# Center image Theorem



# Distance theorem

A cloud has a nontrivial stabilizer, and there are two spaces which break the ultrametric inequality. Then it's distance to  $[\Delta_1]$  is infinite.

$M$  is the center of  $[M]$ ,  $Y_1$  and  $Y_2$  are such metric spaces that

$$|Y_1, M| \leq \rho,$$

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$$|Y_1, Y_2| > \rho.$$

# Distance Theorem

$$X_1 = R^{-1}(Y_1), X_2 = R^{-1}(Y_2)$$

