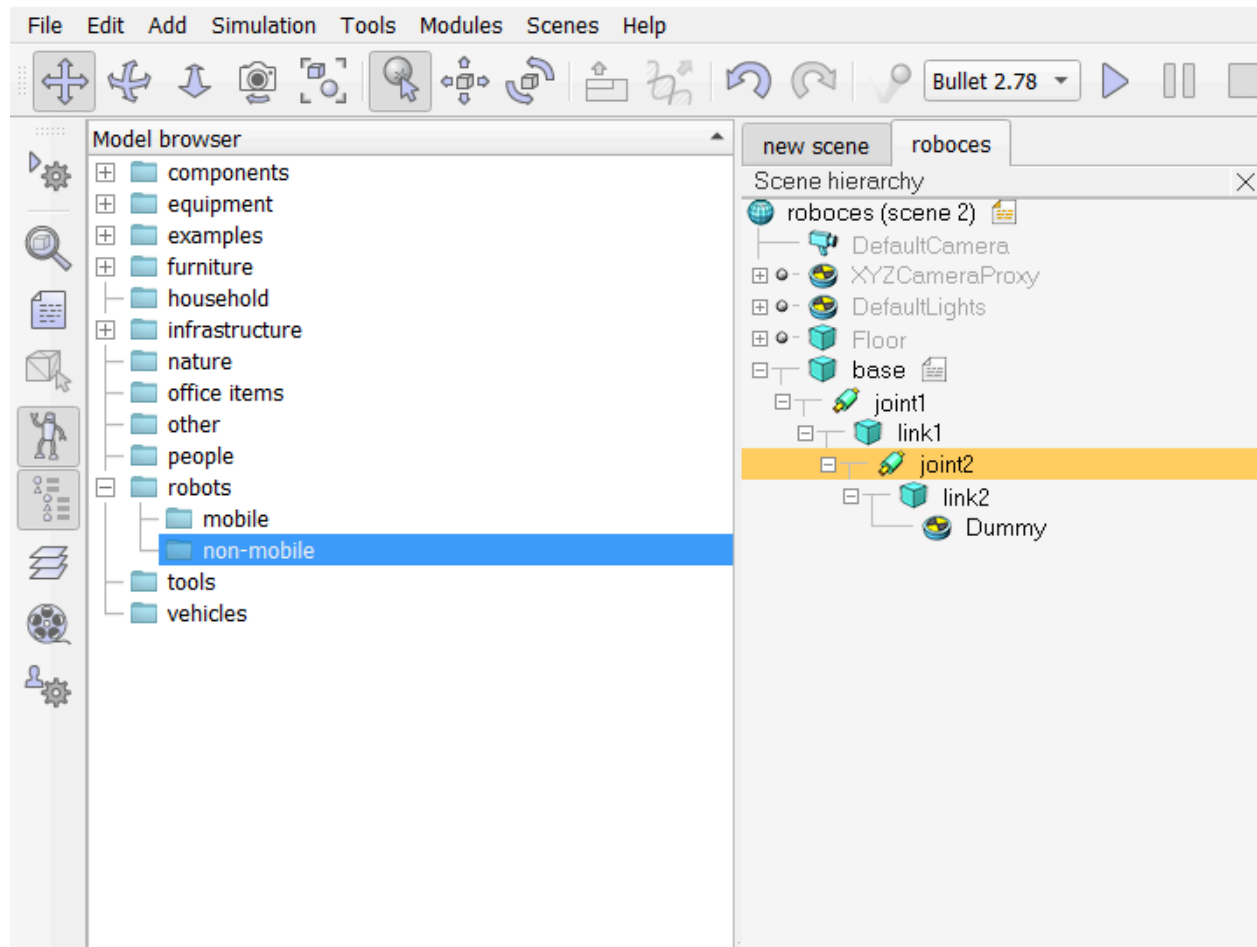


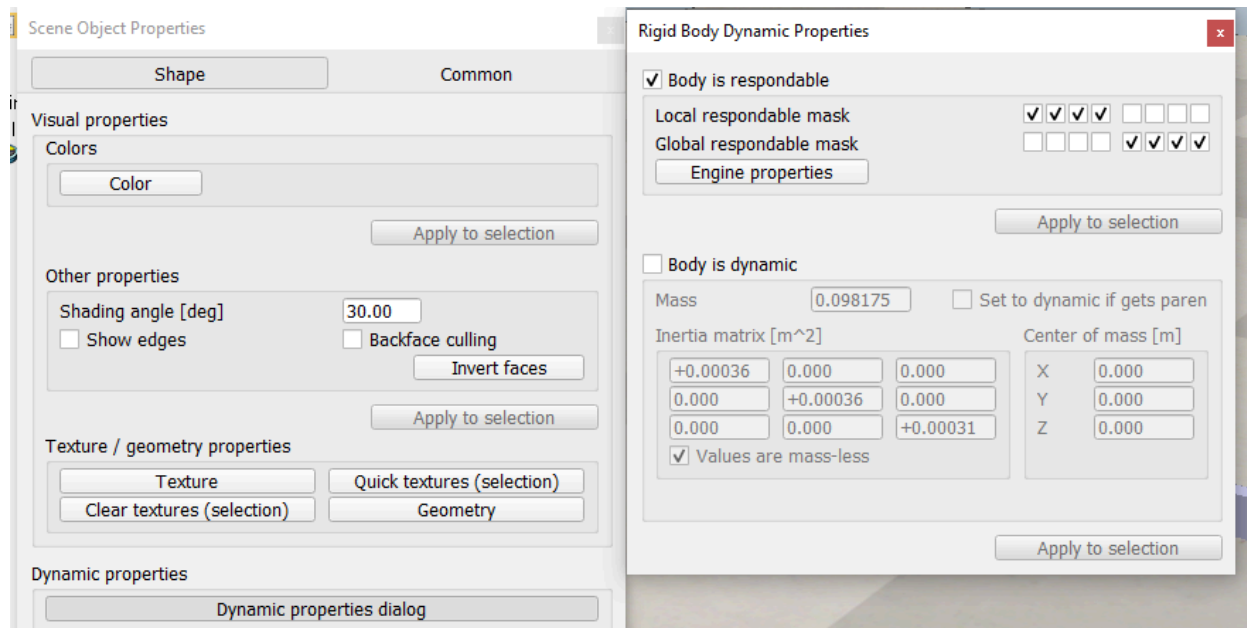
Néstor Batista Díaz

Robótica con Python - CoppeliaSim

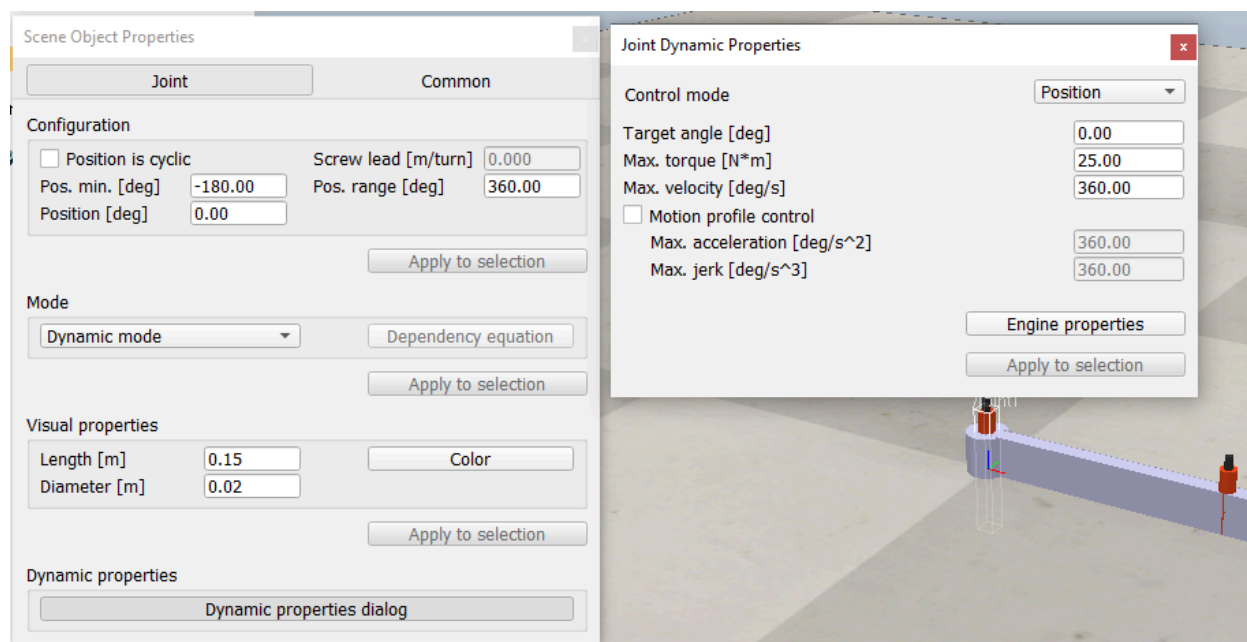
Estructura final



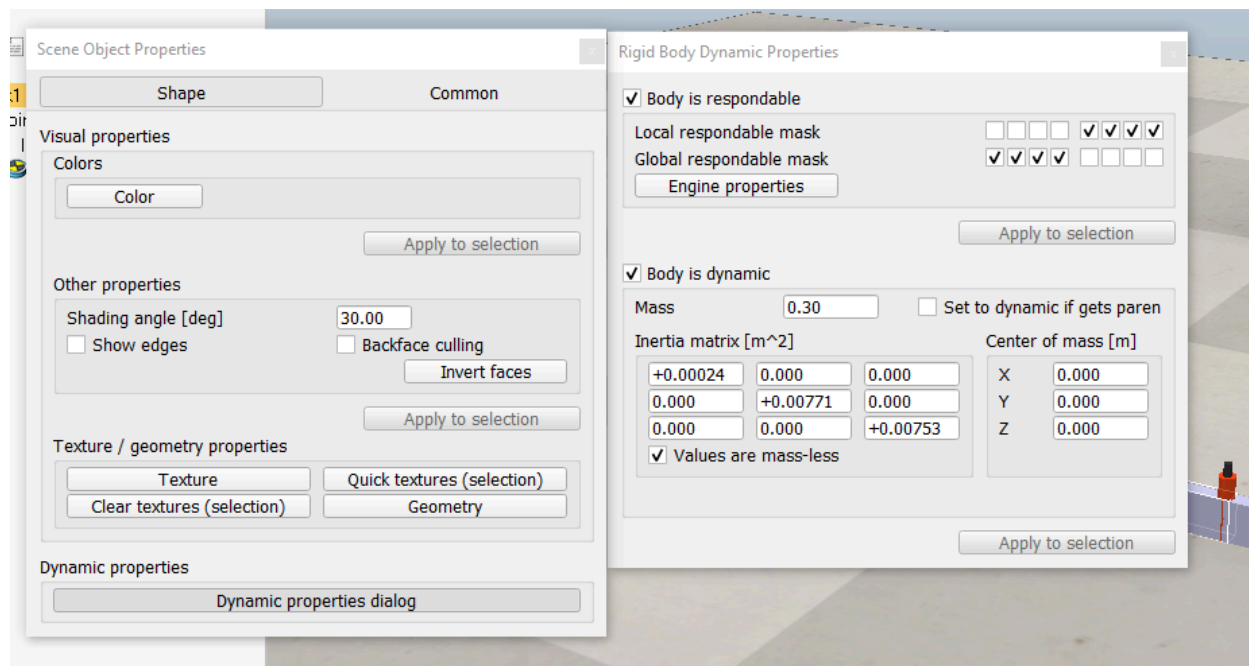
Propiedades de la base



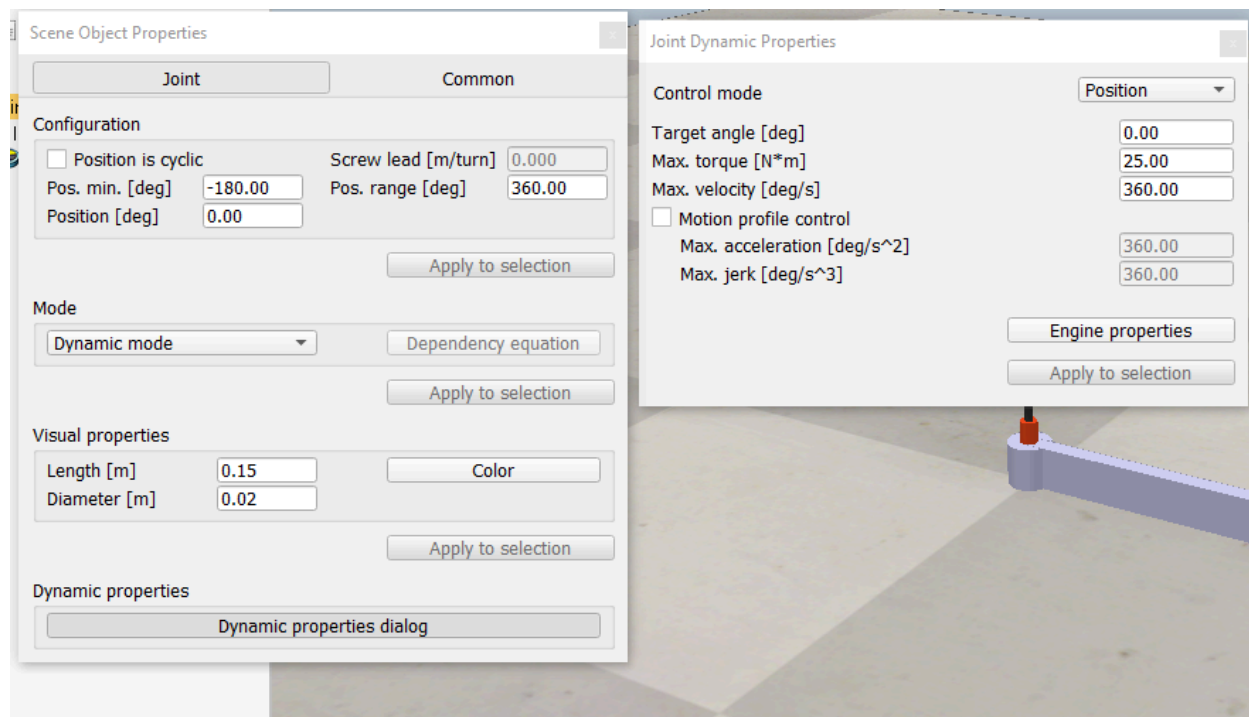
Propiedades de join1



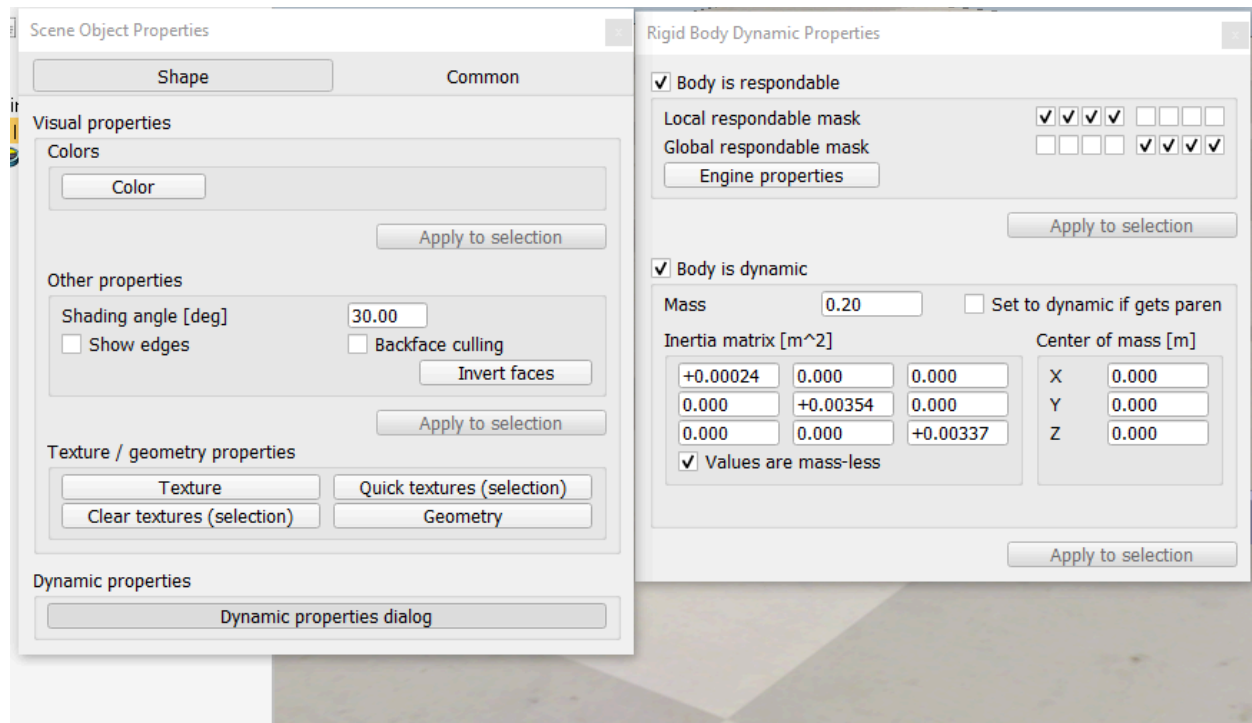
Propiedades de link1



Propiedades de join2



Propiedades de link2



Propiedades de Dummy

