

Neutrino Oscillations in Vacuum and Matter ¹

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Notes for neutrino oscillations in vacuum and dense matter.

Vacuum Oscillations

Schrodinger equation is

$$i\partial_t |\Psi\rangle = \mathbf{H} |\Psi\rangle, \quad (1)$$

where for relativistic neutrinos, the energy is²

$$\mathbf{H}^m = \begin{pmatrix} \sqrt{p^2 + m_1^2} & 0 & 0 \\ 0 & \sqrt{p^2 + m_2^2} & 0 \\ 0 & 0 & \sqrt{p^2 + m_3^2} \end{pmatrix},$$

² They all have the same momentum but different mass. The thing is we assume they have the same velocity since the mass is very small. To have an idea of the velocity difference, I can calculate the distance travelled by another neutrino in the frame of one neutrino. **To Be Done!**

in which the energy terms are simplified using the relativistic condition

$$p\sqrt{1 + \frac{m_i^2}{p^2}}$$

$$\approx p(1 + \frac{1}{2} \frac{m_i^2}{p^2}). (2)$$

In general the flavor eigenstates are the mixing of the mass eigenstates with a unitary matrix \mathbf{U} , that is

$$|\nu_\alpha\rangle = U_{\alpha i} |\nu_i\rangle, \quad (3)$$

where the α s are indices for flavor states while the i s are indices for mass eigenstates.

To find out the equation of motion for flavor states, plugin in the unitary transformation,

$$iU_{\alpha i}\partial_t |\nu_i\rangle = U_{\alpha i}H_{ij}^m |\nu_j\rangle. \quad (4)$$

I use index m for representation of Hamiltonian in mass eigenstates. Applying the unitary condition of the transformation,

$$\mathbf{I} = \mathbf{U}^\dagger \mathbf{U}, \quad (5)$$

I get

$$iU_{\alpha i}\partial_t |\nu_i\rangle = U_{\alpha i}H_{ij}^m U_{j\beta}^\dagger U_{\beta k} |\nu_k\rangle, \quad (6)$$

which is simplified to

$$i\partial_t |\nu_\alpha\rangle = \mathbf{H}_{\alpha\beta}^f |\nu_\beta\rangle, \quad (7)$$

since the transformation is time independent.

The new Hamiltonian in the representations of flavor eigenstates reads

$$\mathbf{H}_{\alpha\beta}^f = \mathbf{U}^\dagger \quad (8)$$

2 Flavor States

For 2 flavor neutrinos the Hamiltonian in the representation of propagation states,

$$\mathbf{H} = \begin{pmatrix} E_1 & 0 \\ 0 & E_2 \end{pmatrix} = \begin{pmatrix} p_1 + \frac{1}{2} \frac{m_1^2}{p_1} & 0 \\ 0 & p_2 + \frac{1}{2} \frac{m_2^2}{p_2} \end{pmatrix}.$$

The equation of motion in matrix form is

$$i\partial_t \begin{pmatrix} \nu_1 \\ \nu_2 \end{pmatrix} = \begin{pmatrix} p_1 + \frac{1}{2} \frac{m_1^2}{p_1} & 0 \\ 0 & p_2 + \frac{1}{2} \frac{m_2^2}{p_2} \end{pmatrix} \begin{pmatrix} \nu_1 \\ \nu_2 \end{pmatrix} \quad (9)$$

The flavor eigenstate is a mixing of the propagation eigenstates,

$$\begin{pmatrix} \nu_a \\ \nu_b \end{pmatrix} = \begin{pmatrix} \cos \theta_v & \sin \theta_v \\ -\sin \theta_v & \cos \theta_v \end{pmatrix} \begin{pmatrix} \nu_1 \\ \nu_2 \end{pmatrix} \quad (10)$$

Denote the rotation matrix using \mathbf{U} , the transformation can be written as

$$|\nu_\alpha\rangle = \mathbf{U}_{\alpha i} |i\rangle, \quad (11)$$

where α is for the flavor eigenstates and i is for the mass eigenstates.

3 Flavor States

Oscillations in Dense Medium