Yu Chen

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**Education**

**Carnegie Mellon University, School of Computer Science, Robotics Institute 2022.8 – 2024.8**

Master of Science in Robotics

* GPA: 4.19
* Coursework: Kinematics/Dynamics/Control (A+), Introduction to Robot Learning (A+), Machine Learning (A+), Computer Vision (A+), Mechanics of Manipulation (A), Optimal Control & Reinforcement Learning (A), Robot Math (A).
* Research interest: Motion planning, and robotics system design.

**Tongji University, Institute of Rail Transit 2017.9 – 2022.6**

Bachelor in Vehicle Engineering (Railway), Minor in Artificial Intelligence

* GPA: 4.78/5.0 or 92.83/100, rank No.1 in the department.
* Selected awards: Graduation with Honor - College Graduate Excellence Award of Shanghai (top 5%), Outstanding Graduation Project (top 5%), National Scholarship (top 5%), Special Award in Tongji University Challenge Cup (team leader, top 5%), #1 in Tongji University Excellent Scientific Research and Education Competition (team leader, top 1).

**Selected Publications**

1. **[WAFR’24]** Propagative Distance Optimization for Constrained Inverse Kinematics

*Yu Chen*, Yilin Cai, Jinyun Xu, Zhongqiang Ren, Guanya Shi, Howie Choset.

1. **[RAL / Invited to IROS’24 (*Oral*)]** Graph-Propagation-based Kinematic Algorithm for In-pipe Truss Robots

*Yu Chen*, Jinyun Xu, Yilin Cai, Shuo Yang, Ben Brown, Fujun Ruan, Yizhu Gu, Howie Choset, Lu Li.

1. **[IROS’21 (*Oral*)]** Semi-Supervised Vein Segmentation of Ultrasound Images for Autonomous Venipuncture

*Yu Chen*, Yuxuan Wang, Bolin Lai, Zijie Chen, Xu Cao, Nanyang Ye, Zhongyuan Ren, Junbo Zhao, Xiao-Yun Zhou, Peng Qi.

**Selected Research Experiences**

**Biorobotics Lab, Carnegie Mellon University. 2022.9 – present**

*In collaboration with Prof. Howie Choset, Prof. Guanya Shi, and Prof. Zhongqiang Ren Pittsburgh, USA*

* Proposed an efficient framework that efficiently and effectively solving kinematics and motion planning problems for a broad range of articulated robots with complex task constraints using propagative distance optimization.

*In collaboration with Prof. Howie Choset and Mr. Ben Brown* (*Project Scientist*) *Pittsburgh, USA*

* Proposed and formulated an efficient locomotion technique for the confined-and-complex-space traversal of truss robots.
* Devised a computationally efficient kinematic algorithm for truss robots using graph propagation principles.
* Designed and constructed an in-pipe truss robot hardware system capable of navigating straight pipes and pipe elbows.

**Big Data Institute, University of Oxford 2022.6 – 2022.8**

*In collaboration with Prof. Guang-Zhong Yang and Dr. Jian-Qing Zheng Oxford, UK*

* Developed a general compact framework facilitating cross-domain learning in monocular depth and flow estimation.
* Created a novel generative model employing GAN and diffusion techniques for the generation of protein sequences.

**School of Electronics and Information Engineering, Tongji University 2020.6 – 2022.5**

*In collaboration with Dr. Xiao-Yun Zhou and Prof. Peng Qi Shanghai, CN*

* Proposed and formulated an overall hardware-software framework for an autonomous venipuncture robot, including mechanical structure design and the formulation of a semi-supervised learning algorithm for ultrasound-image-based vein detection.

**Selected Patents**

1. [CN113788081B] Multi-terrain Driving Unmanned Vehicle Based on Vehicle Body Deformation

Qing Jia, *Yu Chen*, Rongsheng Zhou, Yijun Jiang, Bowen Liang, Wenyi Cui, Chen Luo.

1. [CN114252178A] Touch Sensor, Pressure Event Detection Method and Device and Intelligent Robot

Peng Qi, *Yu Chen*, Yu Zheng, Zhengyou Zhang, Juhong Wang, Tingting Liu.

1. [CN112109111A] Mechanical Joint, Mechanical Arm and Control Method for Oblique-Section Cylindrical Connection

Peng Qi, *Yu Chen*.

1. [CN112089490A] Full-Automatic Venipuncture Recognition Integrated Robot

Peng Qi, *Yu Chen*, Xu Cao, Yuxuan Wang, Zhiyu Tian.

1. [CN112022293A] Gesture Recognition Venipuncture Method and Device for Intravenous Injection Robot

Peng Qi, *Yu Chen*.

1. [CN112022294A] Operation Trajectory Planning Method of Venipuncture Robot Based on Ultrasonic Image Guidance

Peng Qi, *Yu Chen*.

1. [CN111968097A] Blood Vessel Puncture Image Processing Method and Blood Vessel Puncture Robot

Peng Qi, *Yu Chen*.

**Selected Skills**

Languages: Mandarin, English, German

Programming: C/C++, Python, Matlab, Arduino IDE

Computer-Aided Design: AutoCAD, Solidworks, UG (Unigraphics NX), AD (Altium Designer), Blender

Computer-Aided Engineering: ANSA, HyperMesh, Simulink, LabVIEW