



NESTML Tutorial

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Usage of the NESTML Infrastructure

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Starting eclipse:

```
cd /home/nest/eclipse_nestml
./eclipse
```

Working folder for the code generation:

```
/home/nest/nestml_workshop/nestml_workshop_project
```

Console-tool for the codegeneration

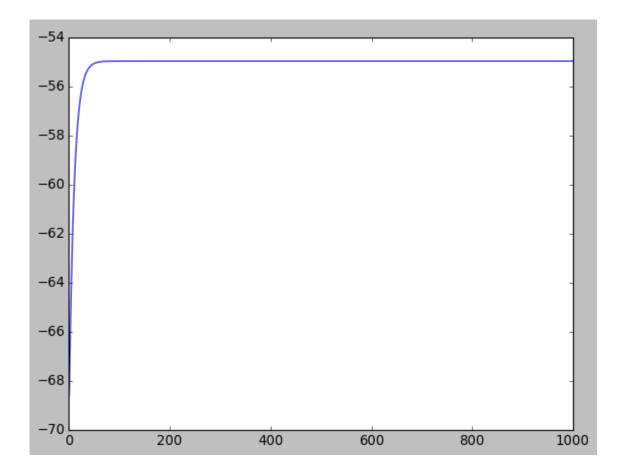
```
java -jar nestml-core-0.0.3-SNAPSHOT-jar-with-
dependencies.jar pathToFile.nestml
```

- Optional parameters:
 - --target generationPath (current directory if omitted)
- Change to the generated folder
 - cd codegeneration\neuron level 1 (or _2, _3 for particular task)
- Execute the following 3 commands (enter them individually)

```
sh bootstrap.sh
./configure --with-nest=${NEST_INSTALL_DIR}/bin/nest-config
make && make install
```

Task 1: Simple Case Integrate neuron 1/2

- Implement a simple integrate neuron
 - The neuron doesn't spike, but integrates over the time



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Task 1: Simple Case Integrate neuron 2/2

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- Use the template neuron_level_1.nestml
 - Fix errors showed by the editor
 - Fill/extend TODO
- The dynamics is described as:

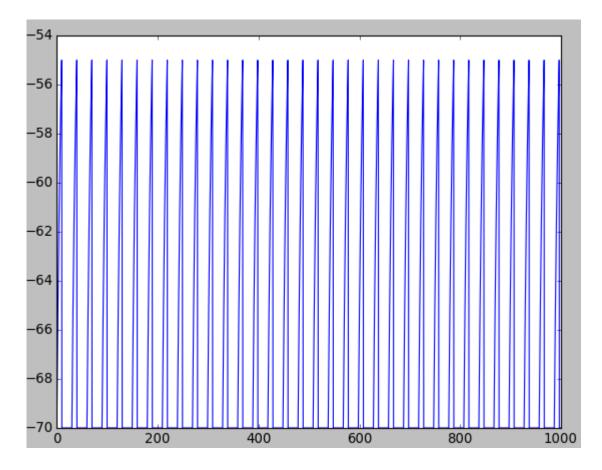
$$G := \frac{E}{tau_syn} * t * exp(\frac{-1}{tau_syn} * t)$$

$$\frac{d}{dt}V := \frac{-1}{Tau} * V + \frac{1}{C_m} * G + I_e + cur$$

Use tester_workshop_neuron_level_1.py to test

Task 2: Threshold Integrate and fire neuron 1/2

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- Add the threshold test in the dynamics
- Increase the refractory time to 20 ms



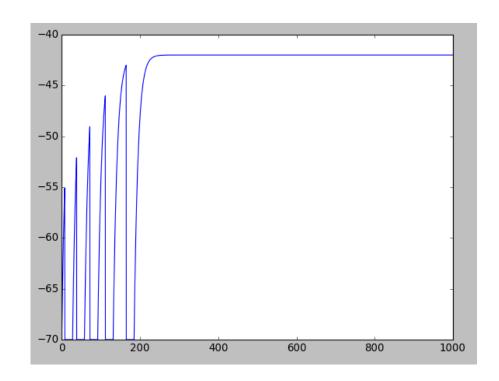
Task 2: Threshold Integrate and fire neuron 2/2

- Use the template neuron_level_2.nestml
 - Fill/extend TODOs
- Implement threshold crossing using the variable thresholdTheta
- Use python tester_workshop_neuron_level_2.py to test

Task 3: Adaptive Threshold 1/2

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Make an adaption of the threshold after each spiking



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Task 3: Adaptive Threshold 2/2

- Use the template neuron_level_3.nestml
 - Fill/extend TODO

- Use a threshold adaption, e.g. Theta = Theta + 3 after spiking
- Use tester_workshop_neuron_level_3.py to test

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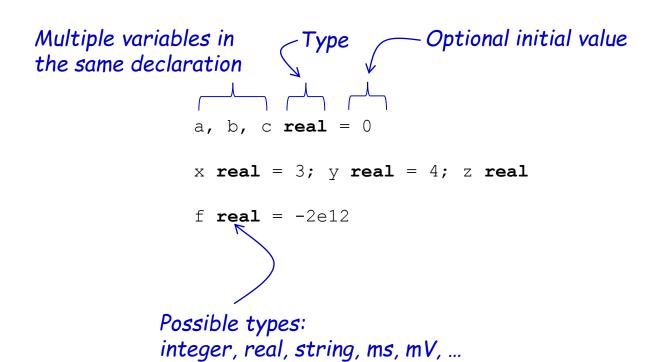
Language Concepts

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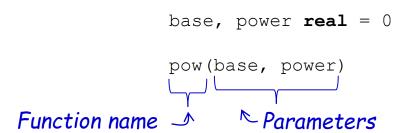
Procedural Language: Declarations



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Simple Programming Language Function Calls

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Important pre-defiend functions:

```
emitSpike(): emits spike exp(x): Returns the base-e exponential function of x, which is e raised to the power x: e^x pow(base, power): raises base to the power exponent.
```

Constants:

E: Euler's number

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Simple Programming Language: Control flow 1/2

```
x real
\times real
                                          for x in 1 ... 5 step 2:
for x in 1 ... 5 :
                                          end
end
                                           x, y real
                                           x = 1
x real
                                           y = 2
for x in 1 ... -5.6 step 0.1:
                                           while \times <= 10:
                                               y = x * 2
end
                                               x = x+1
                                           end
```

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NESTML Model structure

```
neuron name
Package name. Relevant for
model crossreferences. package testing:
                        neuron WorkingNeuron:
                          state:
                                                    Declarations are possible,
                                         mV
                                                    same for parameter, internals
                          end
    Mandatory part
    describing inputs
                          input:
                                            <- inhibitory excitatory spike</pre>
                            spikeBuffer
                          end
     Mandatory part
                          output: spike
     describing outputs
   Dynamics definition
                          dynamics timestep(t ms):
                                                      Entire SPL code is possible
                          end
                        end
```

Buffer Blocks

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```
"spike" and "current" are possible
```

```
input:
  bufferName <- inhibitory excitatory spike
end</pre>
```

"inhibitory", "excitatory", both or none are possible

"spike" and "current" are possible output: spike

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Simple Programming Language Differential Equations

```
dynamics timestep(t ms):
    ODE:
    G_:= E/tau_syn) * t * exp(-1/tau_syn*t) (zero or more)

d/dt V := -1/Tau * V + 1/C_m * G + I_e + cur
end
end

One ore more differential equations
```