>>> hoc.execute('hoc statement')
oc> nrnpython("python statement")

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Native Hoc/Python interaction

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- Native Hoc/Python interaction
- Installation

>>> hoc.execute('hoc statement')
oc> nrnpython("python statement")

- Native Hoc/Python interaction
- Installation
- Numpy

>>> import neuron

>>> import neuron

Linux i686 x86_64

Mac OS $X_{10.5}^{10.4}$

MSWin

>>> import neuron

Linux i686 x86_64

2.3

Mac

OS X 10.4 10.5 Python 2.4 2.5

MSWin

Linux i686

i686 x86_64

Mac

OS X $\frac{10.4}{10.5}$

>>> import neuron

2.3 Python 2.4

2.5

MSWin

Launch NEURON Python

MSWin

Linux i686

i686 x86_64

2.3 2.10.4 Python 2.4

>>> import neuron

2.5

Mac OS $\times 10.4 \\ 10.5$

Cygwin MinGW

Launch NEURON Python

Linux i686

i686 x86_64

OS $\times 10.4_{10.5}$

2.3 Python 2.4

>>> import neuron

2.5

MSWin

Mac

Cygwin MinGW

Launch NEURON Python

NumPy

```
sec a = numpy.arange(0,10.0,0.00001)
```

- 0.02 b = numpy.array(a)
- v = neuron.Vector(a)
- 43.7 a = numpy.array(v)

```
a = numpy.arange(0,10.0,0.00001)
 sec
 0.02
       b = numpy.array(a)
21.2
       v = neuron.Vector(a)
       a = numpy.array(v)
43.7
 0.01
       b = numpy.array(a)
 0.14
       v = neuron.Vector(a)
```

0.07

b = v.to_python(numpy.zeros(v.size()))

```
a = numpy.arange(0,10.0,0.00001)
 sec
 0.02
       b = numpy.array(a)
21.2
       v = neuron.Vector(a)
       a = numpy.array(v)
43.7
 0.01
       b = numpy.array(a)
 0.14
       v = neuron.Vector(a)
       b = v.to_python(numpy.zeros(v.size()))
 0.07
       a = range(0, 1000000)
 0.16
       b = numpy.array(a)
 0.06
       v = neuron.Vector(a)
 0.04
       b = v.to_python()
```

nrniv –python

nrniv –python
import neuron
h = neuron.h
print h
TopLevelHocInterpreter

```
nrniv –python
import neuron
h = neuron.h
print h
 TopLevelHocInterpreter
h(""
 a=5
 objref vec
 vec = new Vector()
 strdef s
 s = "string"
 func f() { return $1 * $1 }
```

print h.a, h.vec, h.s, h.f(3) 5.0 Vector[0] string 9.0

print h.a, h.vec, h.s, h.f(3) 5.0 Vector[0] string 9.0

s = h.s h.s = 'hello' print s, h.s string hello

print h.a, h.vec, h.s, h.f(3) 5.0 Vector[0] string 9.0

s = h.s
h.s = 'hello'
print s, h.s
 string hello

f = h.f
print f, f(5)
 f() 25.0

```
print h.a, h.vec, h.s, h.f(3)
    5.0 Vector[0] string 9.0
h.vec.resize(4)
h.vec.indgen().add(10).printf()
    10     11     12     13
    4.0
```

```
print h.a, h.vec, h.s, h.f(3)
 5.0 Vector[0] string 9.0
h.vec.resize(4)
h.vec.indgen().add(10).printf()
     11 12
 10
 4.0
vx = h.vec.x
print h.vec, vx, vx[2]
 Vector[0] Vector[0].x[?] 12.0
```

import neuron
h = neuron.h
from nrn import *

import neuron
h = neuron.h
from nrn import *

```
soma = Section()
soma.L = 10
soma(0.5).diam = 10
soma.insert('hh')
```

```
import neuron
h = neuron.h
from nrn import *
```

```
soma = Section()
soma.L = 10
soma(0.5).diam = 10
soma.insert('hh')
```

```
stim = neuron.IClamp(soma, 0.5)
# Thanks Andrew.
stim.delay = 1
stim.dur = 0.2
stim.amp = 0.5
```

```
v = neuron.Vector()
soma.push()
v.record(h.ref(soma(0.5).v))
h.pop_section()
```

```
v = neuron.Vector()
soma.push()
v.record(h.ref(soma(0.5).v))
h.pop_section()

h.load_file('stdrun.hoc')
h.run()
v.printf()
```

Mitral-Granule reciprocal synapse

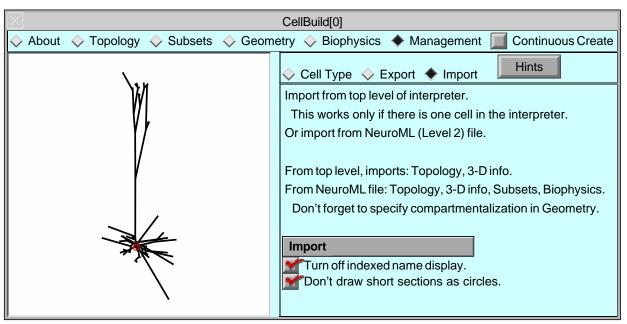
weight snapshot file src tar w

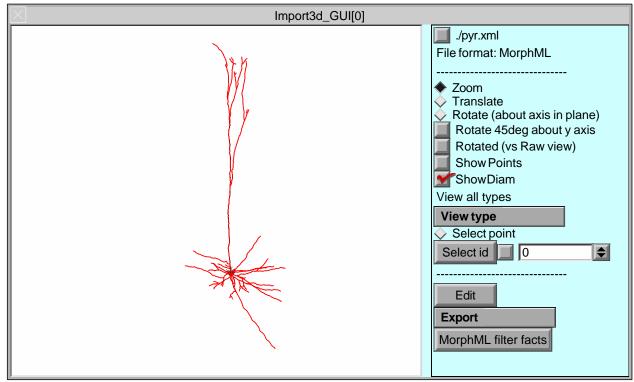
No way to efficiently derive the MGRS from the src, tar.

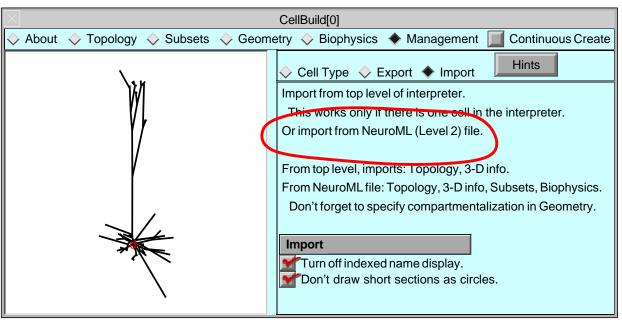
```
objref p, map
p = new PythonObject()
nrnpython(\
  "newmap = lambda key, value : {key:value}")
map = p.newmap(-1,0)
```

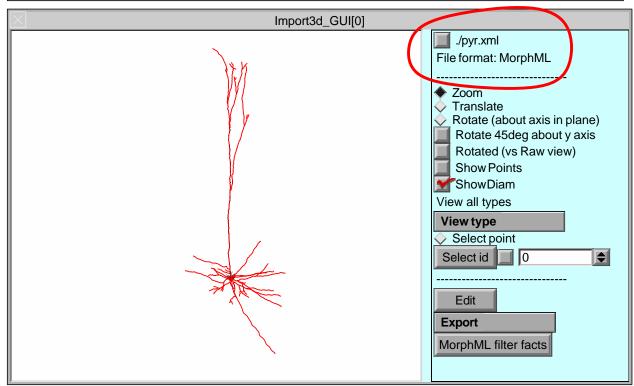
```
objref p, map
p = new PythonObject()
nrnpython(\
 "newmap = lambda key, value : {key:value}")
map = p.newmap(-1.0)
for <lines in file> {
 map.update(p.newmap(gid, w))
```

```
objref p, map
p = new PythonObject()
nrnpython(\
 "newmap = lambda key, value : {key:value}")
map = p.newmap(-1,0)
for <lines in file> {
 map.update(p.newmap(gid, w))
for <all MGRS> {
 w = map.[gid]
```









begintemplate Import3d_MorphML public parsed

begintemplate Import3d_MorphML public parsed

```
proc input() {
  nrnpython("import rdxml")
  p = new PythonObject()
  p.rdxml.__setattr__("i3d", this)
  sprint(tstr, "rdxml.rdxml('%s')", $s1)
  nrnpython(tstr)
  p.rdxml.__setattr__("i3d", nil)
}
```

begintemplate Import3d_MorphML public parsed

```
proc input() {
  nrnpython("import rdxml")
  p = new PythonObject()
  p.rdxml.__setattr__("i3d", this)
  sprint(tstr, "rdxml.rdxml('%s')", $s1)
  nrnpython(tstr)
  p.rdxml.__setattr__("i3d", nil)
}
```

proc parsed() { ...

python/rdxml.py

```
import xml i3d = 1
```

```
def rdxml(fname) :
   xml.sax.parse(fname, MyContentHandler())
```

python/rdxml.py

```
import xml
i3d = 1
def rdxml(fname):
 xml.sax.parse(fname, MyContentHandler())
class Point Cable CableGroup BioParm BioMech
class MyContentHandler(xml.sax.ContentHandler):
 def endDocument(self):
  i3d.parsed(self)
```

```
proc parsed() { ...
 cables = $01.cables
 points = $01.points
 cableid2index = $01.cableid2index
 for i=0, cables.__len__() - 1 {
  cab = cables. [i]
  sec = new Import3d_Section(cab.first_, cab.pcnt_)
  if (cab.parent_cable_id_ >= 0) {
   ip = $01.cableid2index [cab.parent cable id ]
```