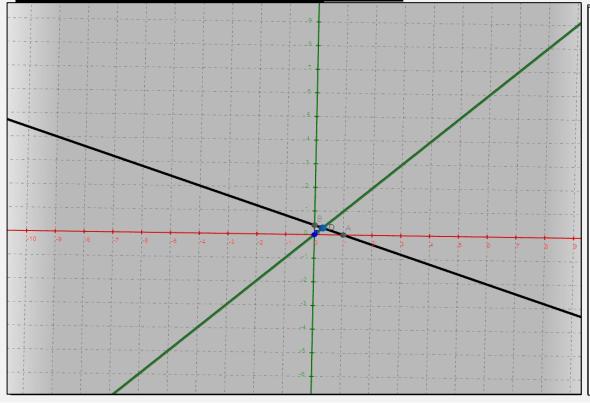
LINEAR ALGEBRA > **SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS** > **Problem Statement**

$$a_1x_1 + a_2x_2 + a_3x_3 + ... + a_{n-1}x_{n-1} + a_nx_n = b$$

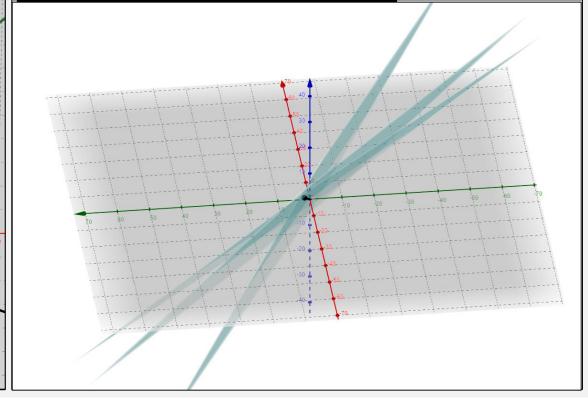
$$2x_1 + 5x_2 = 2 --- (1)$$

$$x_1 - x_2 = 0 --- (2)$$



$$x_1 + 2x_2 + 3x_3 = 1 --- -(1)$$

 $4x_1 + 4x_2 + 5x_3 = 3 --- -(2)$
 $6x_1 + 7x_2 + 7x_3 = -1 --- -(3)$





LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS >

Application of Matrix Inverse

$$\begin{cases} x_{1} + 2x_{2} + x_{3} = 1 \\ 4x_{1} + 4x_{2} + 5x_{3} = 3 \\ 6x_{1} + 7x_{2} + 7x_{3} = -1 \end{cases} \longrightarrow \begin{cases} 1x_{1} + 2x_{2} + 1x_{3} = 1 \\ 4x_{1} + 4x_{2} + 5x_{3} = 3 \\ 6x_{1} + 7x_{2} + 7x_{3} = -1 \end{cases}$$

$$\begin{bmatrix} 1 & 2 & 1 \\ 4 & 4 & 5 \\ 6 & 7 & 7 \end{bmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \end{bmatrix} = \begin{bmatrix} 1x_{1} + 2x_{2} + 1x_{3} \\ 4x_{1} + 4x_{2} + 5x_{3} \\ 6x_{1} + 6x_{2} + 7x_{3} \end{bmatrix}$$

$$\longrightarrow AX = b$$

$$\longrightarrow AX = b$$

$$\longrightarrow A^{-1}AX = A^{-1}b$$

$$\longrightarrow X = A^{-1}b$$

LINEAR ALGEBRA > SYSTEM OF LIN

Gaussian Elimination Method

$$-3x_1 + 2x_2 + x_3 = 1 - - - (1)
-5x_2 + 5x_3 = 1 - - - (2)
-60x_3 = -26 - - - (3)$$

$$-3x_1 + 2\left(\frac{13}{30}\right) = 1 \qquad -3x_2 = \frac{7}{30}$$

$$-3x_1 + 2\left(\frac{7}{30}\right) + \frac{13}{30} = 1 \qquad -3x_1 = \frac{1}{30}$$

 $Number\ of\ pivots\ positions=n$

Number of pivots positions < n

LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS >

Gaussian Elimination Method

$$\begin{cases} -x_1 + 2x_2 = 1 \\ x_1 - 2x_2 = 4 \end{cases}$$

$$\downarrow$$

$$\begin{bmatrix} -1 & 2 & 1 \\ 1 & -2 & 4 \end{bmatrix} r_1 \sim \begin{bmatrix} -1 & 2 & 1 \\ 0 & 0 & 5 \end{bmatrix} r_2 = r_2 + r_1$$

$$- \rightarrow \begin{cases} -x_1 + 2x_2 = 1 \\ 0 = 5 \end{cases}$$

$$\begin{cases} 500x_1 + 800x_2 + 900x_3 = 100\\ 500x_1 + 200x_2 + 700x_3 = 200\\ 2500x_1 + 1000x_2 + 3500x_3 = 1000 \end{cases}$$

$$\begin{bmatrix} 500 & 800 & 900 & 100 \\ 500 & 200 & 700 & 200 \\ 2500 & 1000 & 3500 & 1000 \end{bmatrix} \begin{matrix} r_1 \\ r_2 \\ r_3 \end{matrix} \sim \begin{bmatrix} 5 & 8 & 9 & 1 \\ 5 & 2 & 7 & 2 \\ 25 & 10 & 35 & 10 \end{bmatrix} \begin{matrix} r_2 \\ r_2 \\ r_3 \\ \hline \end{cases} = \frac{r_1}{100}$$

$$4x_1 + 2x_2 + 1x_3 - x_4 = 0$$
$$2x_2 + 7x_3 - x_4 = 0$$
$$5x_1 + 1x_2 + 35x_3 - x_4 = -1$$
$$x_1 + 1x_2 + 3x_3 - x_4 = -8$$



LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS >

Gaussian Elimination Method

In Class Exercise 2.1 SOLUTION

$$\begin{bmatrix} 4 & 2 & 1 & -1 \\ 0 & 2 & 7 & -1 \\ 5 & 1 & 35 & -1 \\ 1 & 1 & 3 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ -1 \\ -8 \end{bmatrix} \longrightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \frac{1}{76} \begin{bmatrix} 21 \\ 573 \\ 14 \\ 1244 \end{bmatrix}$$

LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS >

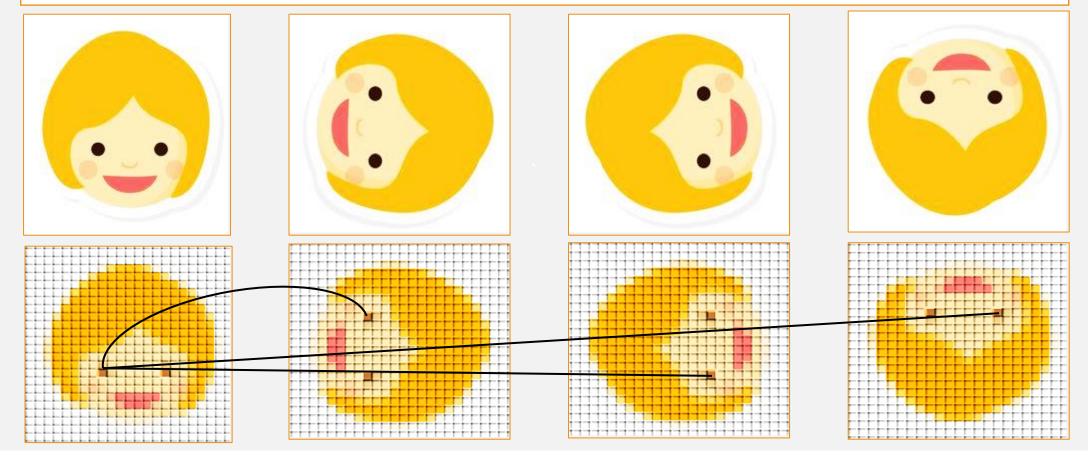
Transformations

$$T: \mathfrak{R}^{m} \to \mathfrak{R}^{n}$$

$$x \mapsto y = f(x)$$

$$T(x_{1} + x_{2}) = T(X_{1}) + T(X_{2})$$

$$T(ax) = aT(x), a \in \mathfrak{R}$$





LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS

Linear Transformations

$$\begin{array}{ll} \textit{T} \colon \Re^3 & \to \Re^2 \\ \mbox{with } T(x_1, x_2, x_3) = (x_1 + x_2, x_1 - x_3) \end{array}$$

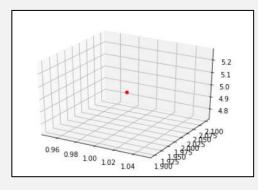
$$T(X_1 = (x_1, x_2, x_3)) = (x_1 + x_2, x_1 - x_3) \qquad T(X_2 = (x_1', x_2', x_3')) = (x_1' + x_2', x_1' - x_3')$$

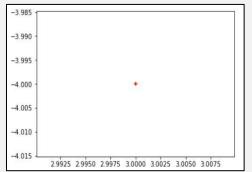
$$T(X_1 + X_2) = T((x_1 + x_1', x_2 + x_2', x_3 + x_3'))$$

$$= ([x_1 + x_1' + x_2 + x_2'], ([x_1 + x_1' - x_3 - x_3']) = \begin{pmatrix} x_1 + x_1' + x_2 + x_2' \\ x_1 + x_1' - x_3 - x_3' \end{pmatrix}$$

$$T(X_1) + T(X_2) = \begin{pmatrix} x_1 + x_2 \\ x_1 - x_3 \end{pmatrix} + \begin{pmatrix} x_1' + x_2' \\ x_1' - x_3' \end{pmatrix} = \begin{pmatrix} x_1 + x_1' + x_2 + x_2' \\ x_1 + x_1' - x_3 - x_3' \end{pmatrix}$$

$$T(X_1 = (1, 2, 5)) = {1+2 \choose 1-5} = {3 \choose -4}$$





In Class Exercise 2.2

Complete the proof of T(X) being a linear transformation



LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS >

Linear Transformations

In Class Exercise 2.2

SOLUTION

$$T(ax) = aT(x), a \in \Re$$

$$T(aX_1 = (ax_1, ax_2, ax_3)) = {ax_1 + ax_2 \choose ax_1 - ax_3}$$

$$aT(X_1 = (x_1, x_2, x_3)) = a {x_1 + x_2 \choose x_1 - x_3} = {ax_1 + ax_2 \choose ax_1 - ax_3}$$



LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS

Transformation Matrix

$$T(x_{1}, x_{2}, x_{3}, x_{4}) = (x_{1} + x_{2}, x_{1} + x_{2} + x_{3}, x_{1} + x_{2} + x_{3} + x_{4}, x_{4})$$

$$= \begin{pmatrix} x_{1} + x_{2} \\ x_{1} + x_{2} + x_{3} \\ x_{1} + x_{2} + x_{3} + x_{4} \end{pmatrix}$$

$$= \begin{pmatrix} 1x_{1} + 1x_{2} + 0x_{3} + 0x_{4} \\ 1x_{1} + 1x_{2} + 1x_{3} + 0x_{4} \\ 1x_{1} + 1x_{2} + 1x_{3} + 1x_{4} \end{pmatrix}$$

$$= \begin{pmatrix} 1 & 1 & 0 & 0 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 0 \\ 1 & 1 & 1 & 1 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{bmatrix} x_{1} \\ x_{2} \\ x_{3} \\ x_{4} \end{bmatrix} = AX$$

$$T(1, 0, 0, 0) = (1 + 0, 1 + 0 + 0, 1 + 0 + 0 + 0, 0) = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \end{bmatrix}$$

$$T(0,1,0,0) = (0+1,0+1+0,0+1+0+0,0) = \begin{bmatrix} 1\\1\\1\\0 \end{bmatrix}$$

$$T(0,0,1,0) = (0+0,0+0+1,0+0+1+0,0) = \begin{bmatrix} 0\\1\\1\\0 \end{bmatrix}$$

$$T(0,0,0,1) = (0+0,0+0+0,0+0+0+1,1) = \begin{bmatrix} 0\\0\\1\\1 \end{bmatrix}$$

$$- \rightarrow A = \begin{bmatrix} 1 & 1 & 0 & 0\\1 & 1 & 1 & 0\\1 & 1 & 1 & 1\\0 & 0 & 0 & 1 \end{bmatrix} T(1,3,4,0) = \begin{bmatrix} 1 & 1 & 0 & 0\\1 & 1 & 1 & 0\\1 & 1 & 1 & 1\\0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1\\3\\4\\8\\0 \end{bmatrix}$$

$$T(1,3,4,0) = (1+3,1+3+4,1+3+4+0,0) = (4,8,8,0)$$

In Class Exercise 2.3 Find the Transformation Matrix of the Transformation $T: \Re^3 \to \Re^2$ defined as:

$$T(x_1, x_2, x_3) = (x_1 - 6x_2, x_1 + x_2 + 4x_3)$$



LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS >

Transformation Matrix

In Class Exercise 2.3 SOLUTION

$$T(1,0,0) = (1-6(0), 1+0+4(0)) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$T(0,1,0) = (0-6(1),0+1+4(0)) = \begin{bmatrix} -6\\1 \end{bmatrix}$$

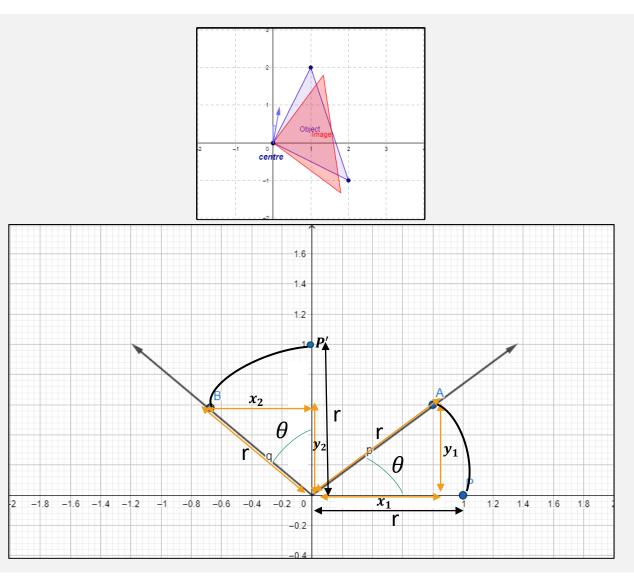
$$T(0,0,1) = (0-6(0),0+0+4(1)) = \begin{bmatrix} 0\\4 \end{bmatrix}$$

$$-\rightarrow A = \begin{bmatrix} 1 & -6 & 0 \\ 1 & 1 & 4 \end{bmatrix}$$



LINEAR ALGEBRA > SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS >

Special Transformation Matrices



$$\begin{cases} \begin{bmatrix} 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{cases}$$

$$\cos\theta = \frac{x_1}{r} \longrightarrow x_1 = r\cos\theta = 1\cos\theta$$

$$\sin\theta = \frac{y_1}{r} \longrightarrow y_1 = r\sin\theta = 1\sin\theta$$

$$- \to T(1,0) = (\cos\theta, \sin\theta)$$

$$\sin\theta = \frac{-x_2}{r} \longrightarrow x_2 = -r\sin\theta = -1\sin\theta$$

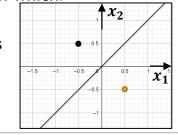
$$\cos\theta = \frac{y_2}{r} \longrightarrow y_2 = r\cos\theta = 1\cos\theta$$

$$- \to T(0,1) = (-\sin\theta, \cos\theta) \longrightarrow A = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

In Class Exercise 2.4

Find the transformation matrix of a transformation which:

Takes a vector in \Re^2 and outputs a vector which is its reflection through the axis $x_2 = x_1$





LINEAR ALGEBRA > **SYSTEM OF LINEAR EQUATIONS AND TRANSFORMATIONS** > Special Transformation Matrices

In Class Exercise 2.4 **SOLUTION**

$$A = \begin{bmatrix} \mathbf{0} & \mathbf{1} \\ \mathbf{1} & \mathbf{0} \end{bmatrix}$$

