

# SimCortex: Collision-free Simultaneous Cortical Surfaces Reconstruction

**SimCortex: Collision-Free Simultaneous Cortical Surfaces Reconstruction**

Kaveh Moradkhani<sup>1</sup> , R Jarrett Rushmore<sup>2</sup>, and Sylvain Bouix<sup>1</sup>

<sup>1</sup> Department of Software Engineering and Information Technology, École de technologie supérieure, Montreal, QC, Canada  
kaveh.moradkhani.1@ens.etsmtl.ca, sylvain.bouix@etsmtl.ca

<sup>2</sup> Department of Anatomy and Neurobiology, Boston University School of Medicine, Boston, MA, USA  
rushmore@bu.edu

**Abstract.** Accurate cortical surface reconstruction from magnetic resonance imaging (MRI) data is crucial for reliable neuroanatomical analyses. Current methods have to contend with complex cortical geometries, strict topological requirements, and often produce surfaces with overlaps, self-intersections, and topological defects. To overcome these shortcomings, we introduce SimCortex, a deep learning framework that simultaneously reconstructs all brain surfaces (left/right white-matter and pial) from T1-weighted (T1w) MRI volumes while preserving topological properties. Our method first segments the T1w image into a nine-class tissue label map. From these segmentations, we generate subject-specific, collision-free initial surface meshes. These surfaces serve as precise initializations for subsequent multi-scale diffeomorphic deformations. Employing stationary velocity fields (SVFs) integrated with scaling-and-squaring, our approach ensures smooth, topology-preserving transformations with significantly reduced surface collisions and self-intersections. Evaluations on standard datasets demonstrate that SimCortex dramatically reduces surface overlaps and self-intersections, surpassing current methods while maintaining state-of-the-art geometric accuracy.

**Keywords:** Cortical Surface Reconstruction · Brain Segmentation · Geometric Deep Learning · Brain MRI · 3D Deep Learning

**1 Introduction**

Accurate cortical surface reconstruction from MRI data enables precise measurement of key morphometric features—cortical thickness, curvature, and sulcal depth—that are invaluable for neuroimaging analyses. However, the inherent complexity of cortical geometry, compounded by partial volume effects (PVE) [1] and stringent spherical topology [5] requirements, poses substantial challenges to achieving anatomically and topologically accurate surface reconstructions.

Traditional methods, such as FreeSurfer [7], BrainSuite [17], and CIVET [13], rely on voxel-based segmentation pipelines followed by explicit mesh-based modeling. These methods are computationally intensive and require multiple hours of processing. The authors(a), under exclusive license to Springer Nature Switzerland AG 2026

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Kaveh Moradkhani



R Jarrett Rushmore



Sylvain Bouix



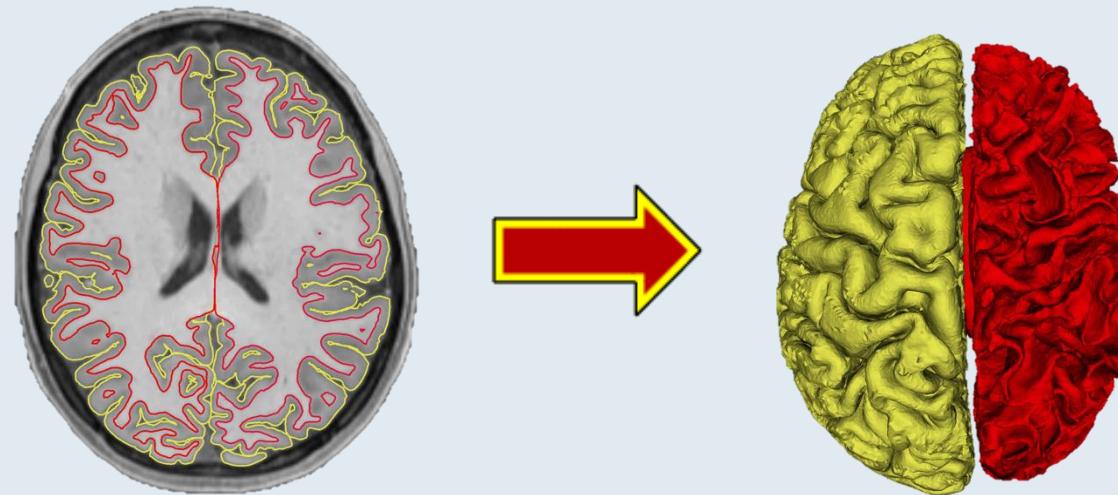
# What is cortical surface reconstruction (CSR)?

**Goal:** Convert a brain MRI into accurate **3D meshes** of the cortex

**Two surfaces per hemisphere:**

- **White surface** = boundary between **Gray Matter** (cortex) and **White Matter**
- **Pial Surface:** boundary between **Gray Matter** and the **Cerebrospinal Fluid**

**Total:** 4 surfaces LH/RH white & pial



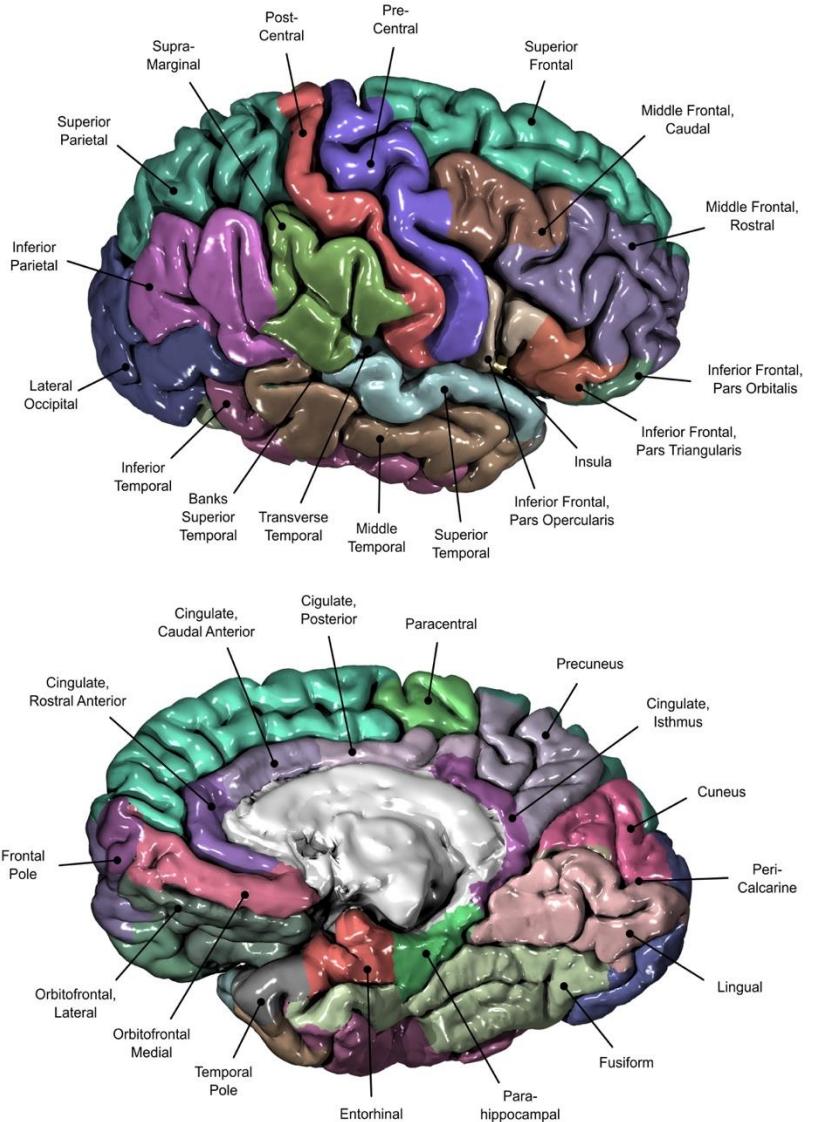
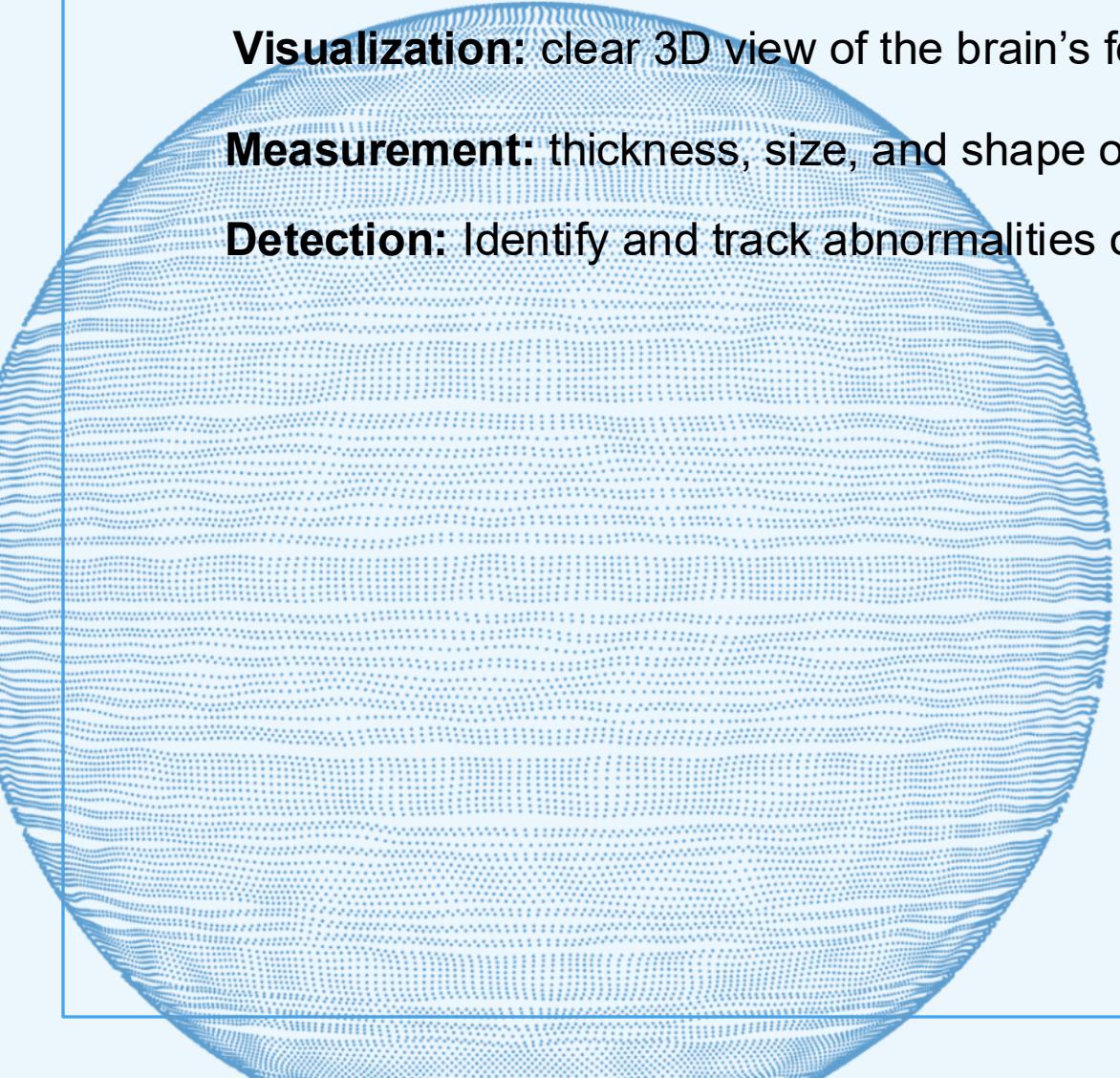
# Why CSR is important!

2

**Visualization:** clear 3D view of the brain's folds

**Measurement:** thickness, size, and shape of the cortex

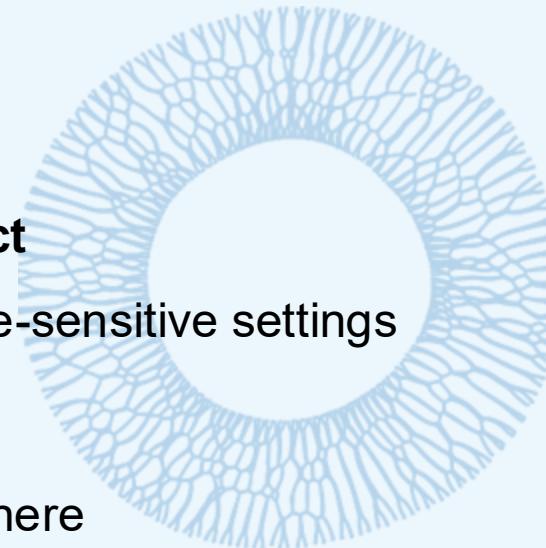
**Detection:** Identify and track abnormalities over time



# Main Problems

**Traditional (FreeSurfer[1], BrainSuite[2], CIVET[3])**

- **Computationally intensive:** often hours **per subject**
- **Poor scalability:** hard to use in large cohorts or time-sensitive settings



**Deep learning-based**

- **Independent reconstructions:** per surface/hemisphere  
**no explicit coupling** → **white–pial** and **left–right** collisions (e.g., *CorticalFlow[4]*, *CortexODE[5]*)
- **No topology guarantees:** **self-intersections/holes** can appear (e.g., *Vox2Cortex[6]*, *V2C-Flow[7]*)

**SimCortex (our)**

- **Jointly estimates all four surfaces (LH/RH white & pial) in one deformation space**  
**preserves geometric relationships, significantly reducing collisions and self-intersections**



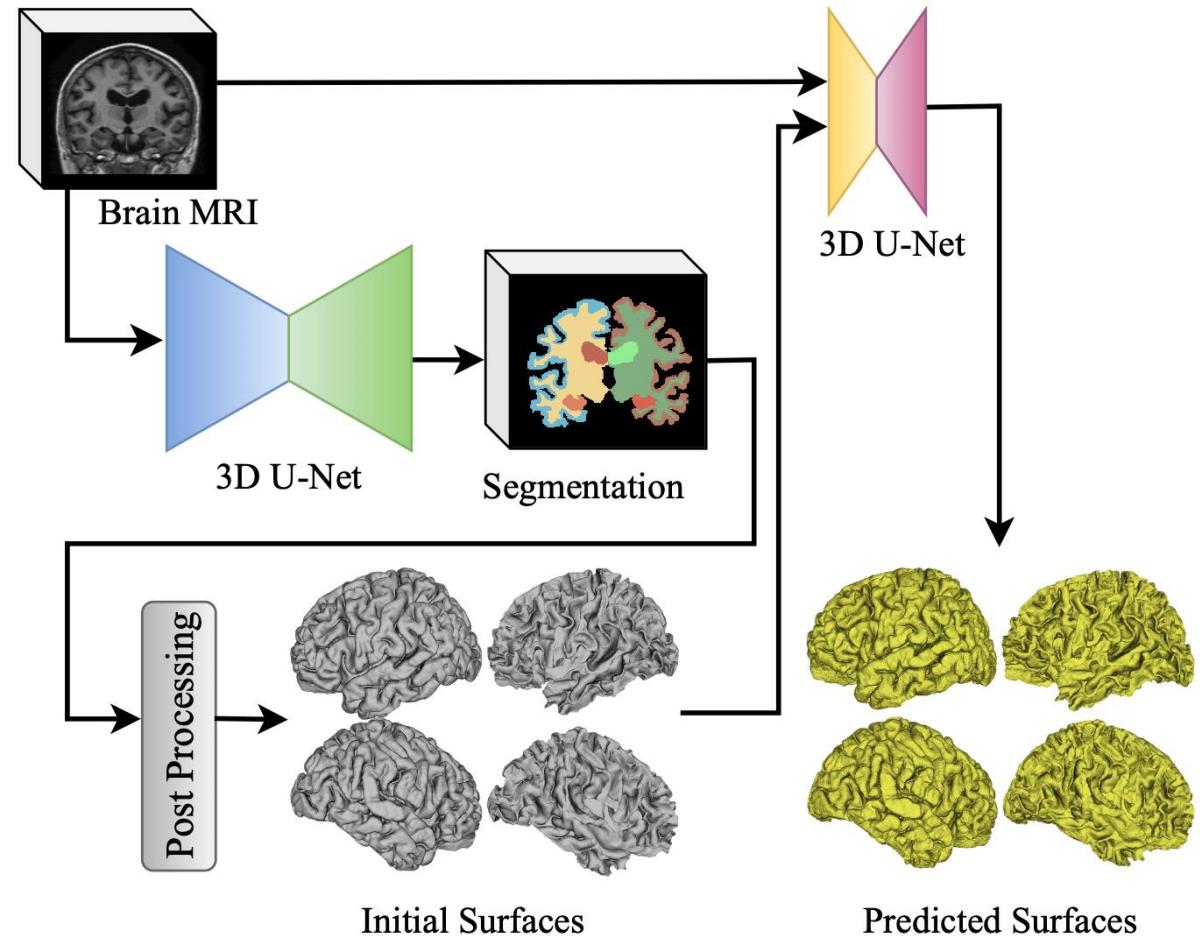
# Method Overview

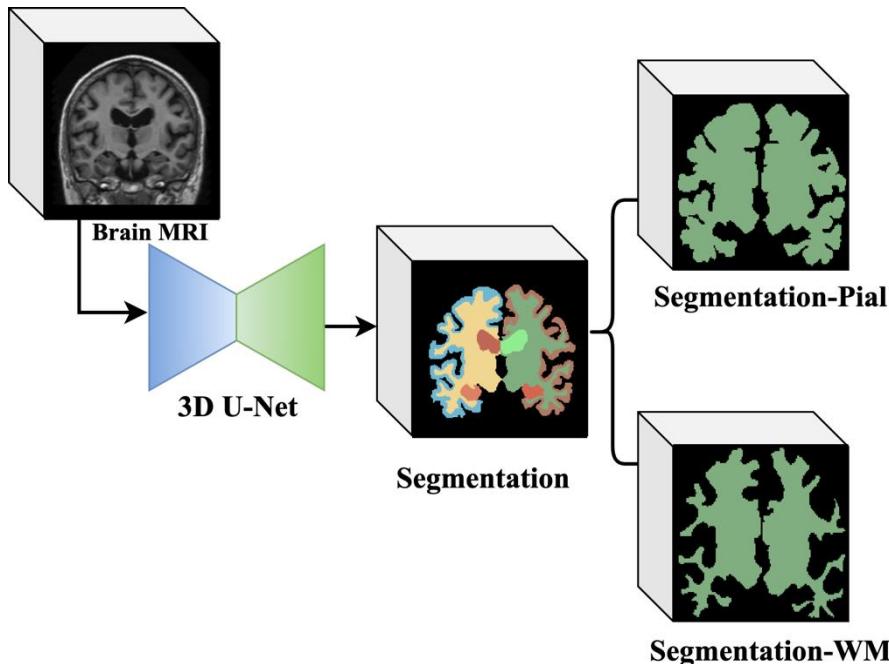
**Input:** T1 MRI → 3D U-Net segmentation

**Init meshes:** initialize 4 non-overlapping, genus-0 cortical meshes

**Joint refinement:** second U-Net predicts one smooth deformation

**Output:** four final surfaces, accurate with near-zero collisions and low self-intersections





## Multi-Class Segmentation

**Architecture:** 3D U-Net-lite

**Channels:** (16, 32, 64, 128, 128) encoder levels

**Parameters:**  $\approx 1.34$  M

**Output classes:** 9 (BG + LH/RH WM, pial, ventricle, amyg-hip)

**Optimizer:** Adam ( $lr = 1 \times 10^{-4}$ )

**Loss:** Cross-Entropy

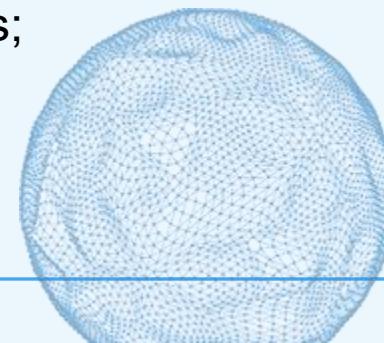
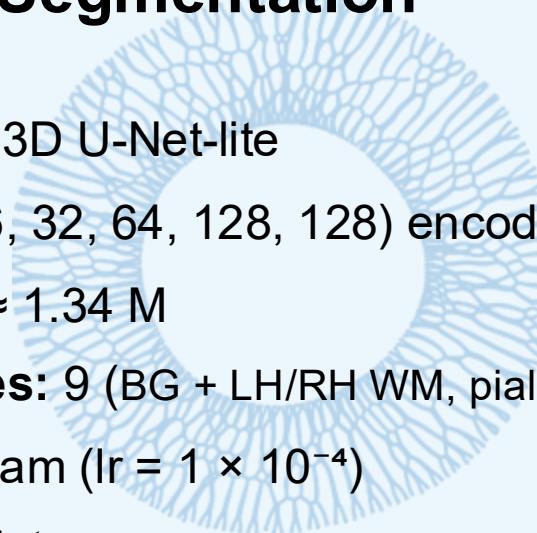
**Epochs:** 1000

**Device:**  $2 \times$  RTX A6000 (48 GB each)

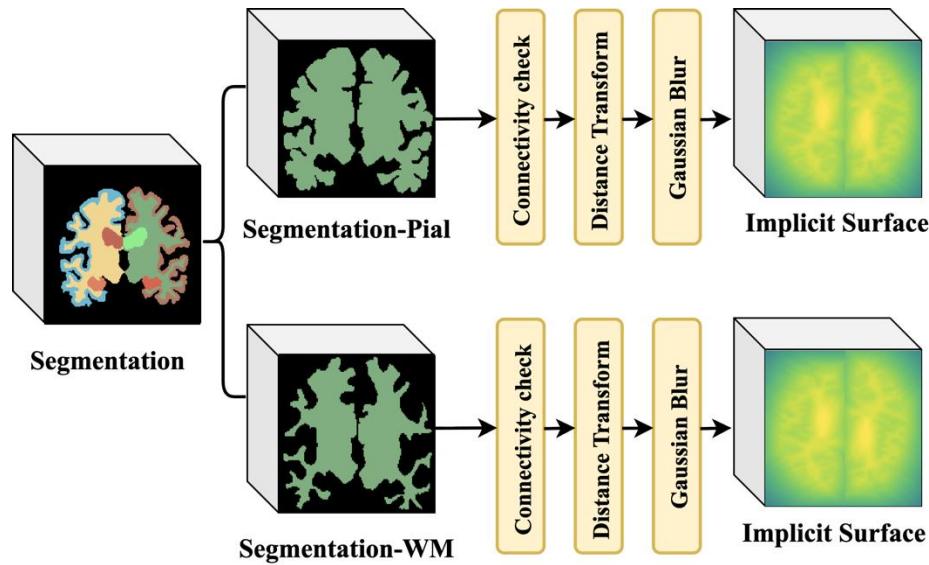
**Mean Dice:** 0.90 (on validation)

**Make two masks per hemisphere:**

Pial = WM + Cortex + Ventricles;  
White = WM + Ventricles



# Initial Surface Generation (SDF)



## Inputs:

**Pial** = WM  $\cup$  Cortex  $\cup$  Ventricles

**White** = WM  $\cup$  Ventricles

## Connectivity check:

Keep **largest 3D component** (remove small islands)

## Distance transform $\rightarrow$ SDF:

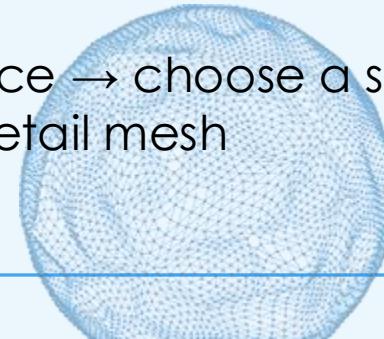
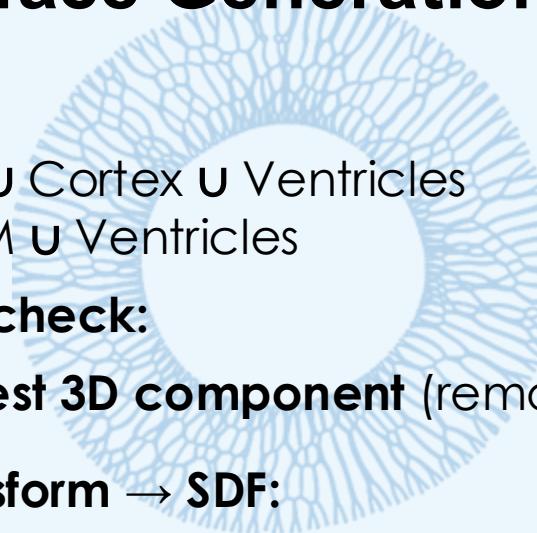
**Signed distance to boundary**  
(inside **negative**, outside **positive**)

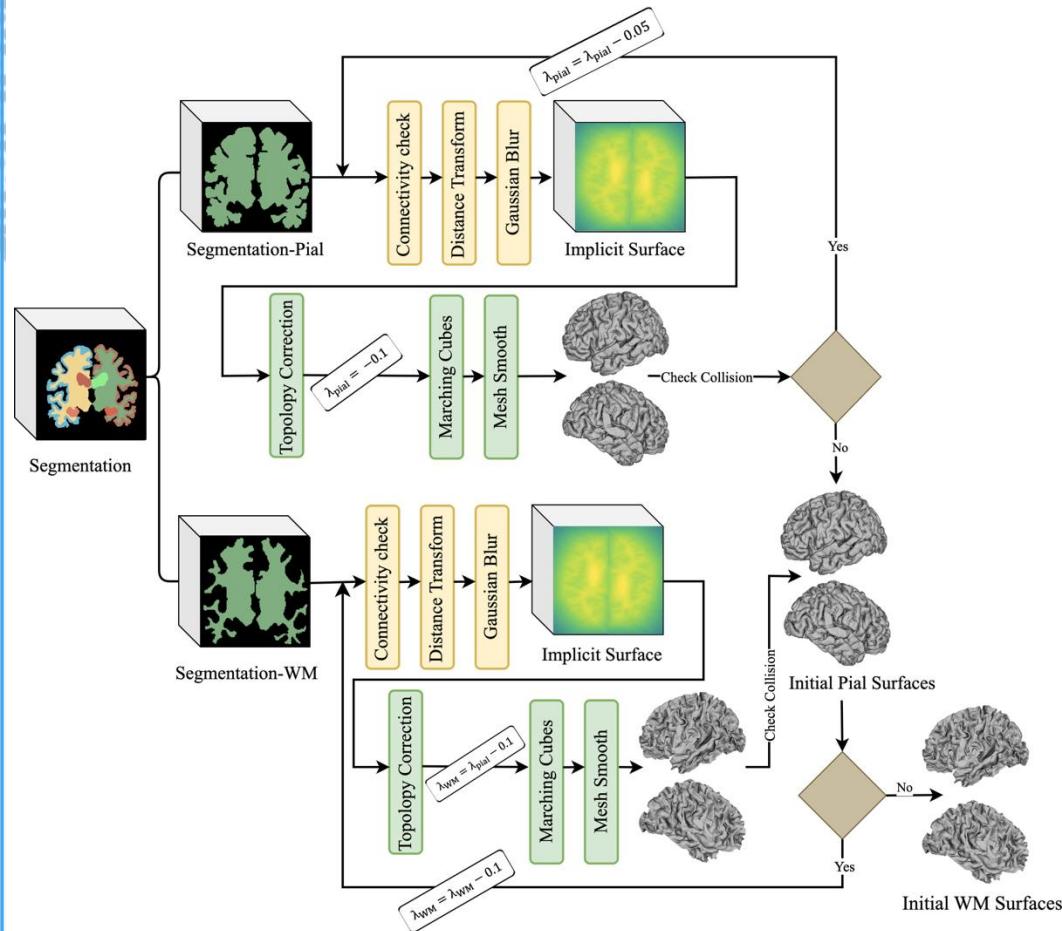
## Gaussian smoothing ( $\sigma \approx 1 \text{ mm}$ ):

Smooth the field  $\rightarrow$  **stable, noise-robust** SDF

## Why SDF?

A smooth continuous surface  $\rightarrow$  choose a surface level ( $\lambda$ ) to create a fine-detail mesh





## Initial Surface Generation (Collision Checks)

**Topology correction:** enforce **genus-0** on the SDF

**Isosurface extraction:** Marching Cubes at SDF level  $\lambda +$  smoothing

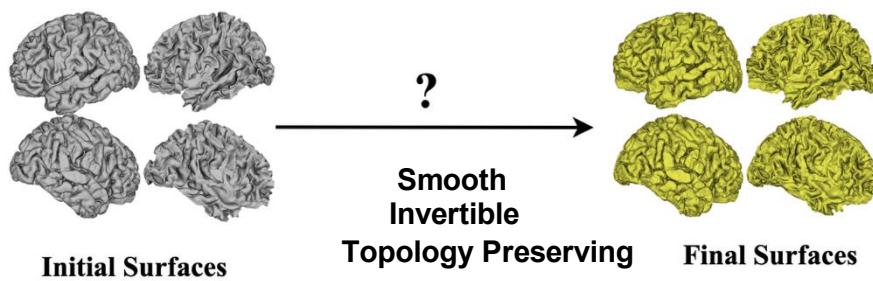
**Pial first:** start  $\lambda_{\text{pial}} = -0.1 \rightarrow$  if any **LR pial-pial** collision, step **-0.05** and re-extract

**White next:**  $\lambda_{\text{WM}} = \lambda_{\text{pial}} - 0.1 \rightarrow$  if **white-pial** or **LR white-white** collision, step **-0.1**

**Collision checks:** pairwise overlaps via **trimesh.CollisionManager**

**Outcome:** 4 non-overlapping, **genus-0** meshes (LH/RH **white & pial**) ready for deformation

## From Initial Templates to Final Surfaces



**Start:** four **collision-free, genus-0**

**deformation must:**

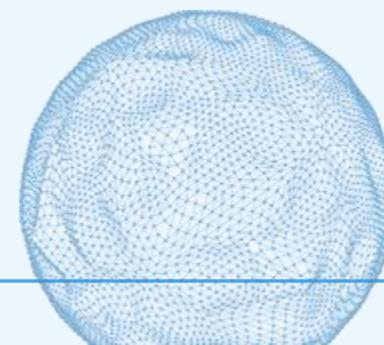
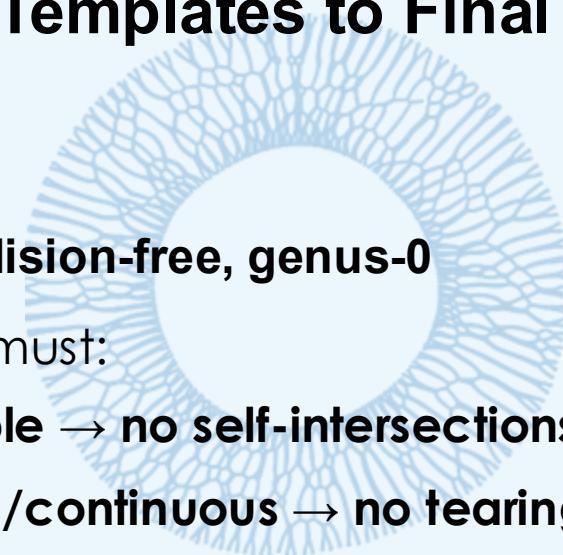
be **invertible** → **no self-intersections**

be **smooth/continuous** → **no tearing**

be **topology preserving** → **no folds or holes**

be **joint for all four surfaces** → preserves **geometric relationships**; avoids **white-pial** and **L/R** collisions

**Our choice:** a **diffeomorphic** deformation  $\phi$



# Joint Diffeomorphic Deformation

**Input:** MNI152 T1 + 4 collision-free, genus-0 templates (LH/RH white & pial)

**3D U-Net → SVFs: L=4 stationary velocity fields (coarse→fine)**

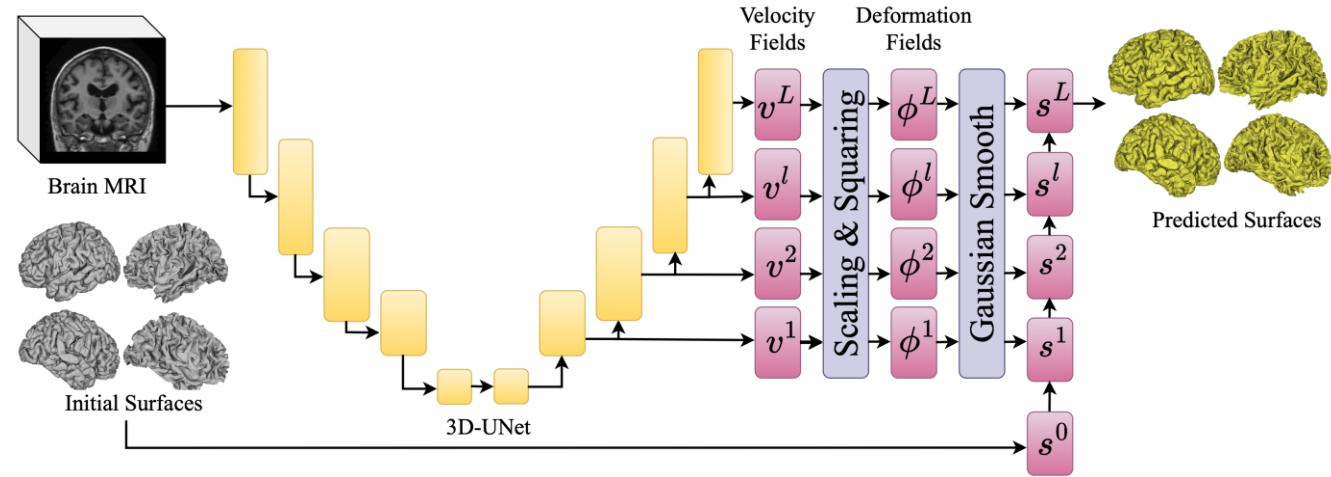
**Integrate (diffeo):**  $\phi^\ell = \exp(v^\ell)$  via scaling-and-squaring; compose  $\phi = \phi_1 \circ \dots \circ \phi_L$

**Joint apply : same  $\phi$  to all four meshes (one deformation space)**

**Loss (multi-scale): Chamfer + Edge + Normals;** sample 150k pts/mesh

**Train:** AdamW 1e-4, batch ≈5, 250 epochs (~28 h)

**Outcome:** topology preserved, near-zero collisions, minimal self-intersections



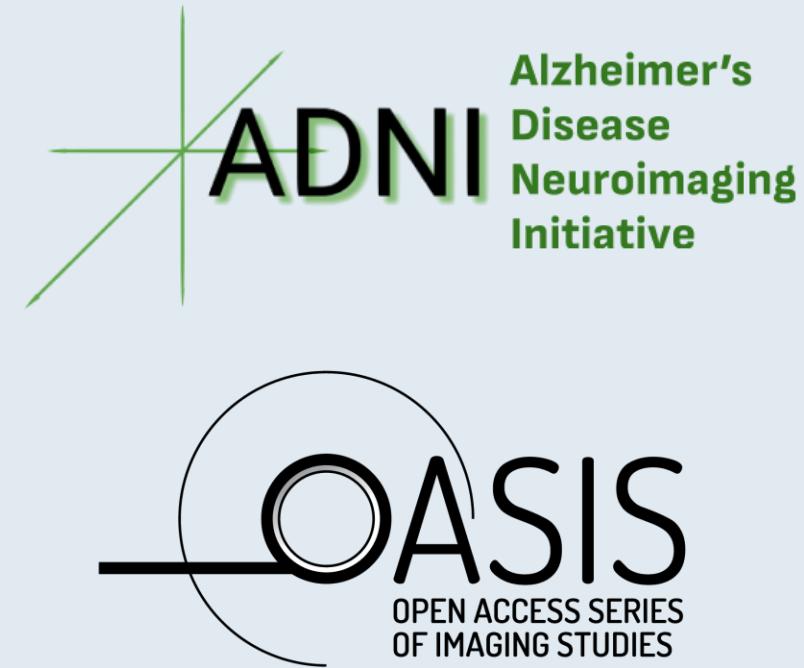
# Datasets

**HCP<sup>1</sup> + OASIS-1<sup>2</sup>** → T1w, MNI152, FreeSurfer 7.4.1 GT

- Train 356 (61 HCP, 295 OASIS)
- Val 102 (26 HCP, 76 OASIS)
- Test 51 (13 HCP, 38 OASIS)

**CNP<sup>3</sup>** → T1w, MNI152, FreeSurfer 7.4.1 GT

- Test 51 (used **only for evaluation**, not for training)



1. Human Connectome Project (HCP)

2. Open Access Series of Imaging Studies (OASIS)

3. UCLA Consortium for Neuropsychiatric Phenomics (CNP)

# Evaluation Metrics

## Geometric accuracy

**Chamfer (CH)** – mean bidirectional nearest-point distance

**ASSD** – average symmetric surface distance

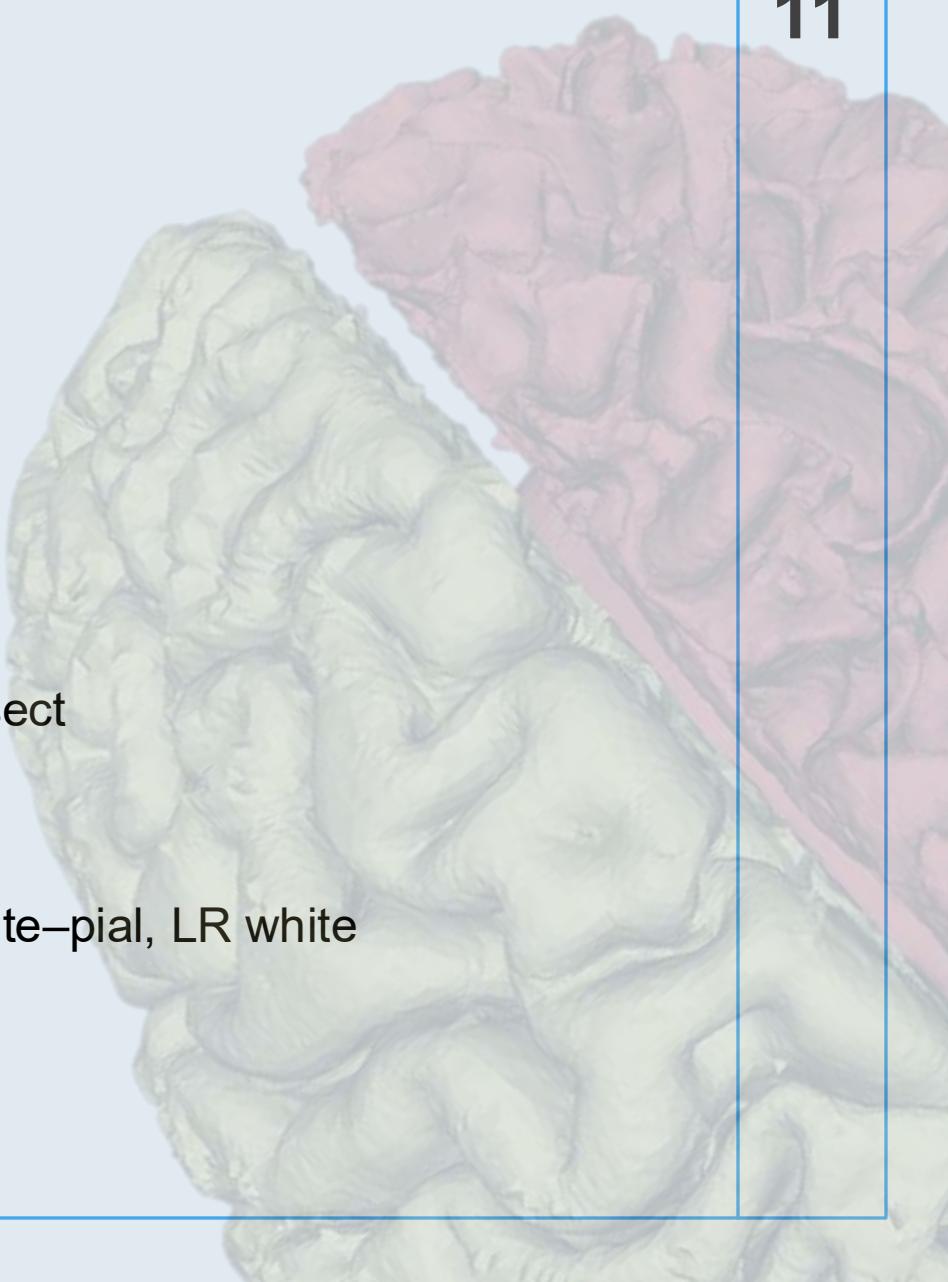
**HD** – Hausdorff distance

## Topology quality

**Self-Intersection Fraction (%SIF)** – % of faces that self-intersect

## Collisions

**Pairwise intersections** for 4 pairs: LR pial, L white–pial, R white–pial, LR white



# Results: Surface Collisions

12

Outcome:

>90% lower collisions vs CFPP and V2C  
near-zero overlaps

Table 1: Pairwise Surface Collision Percentages (%Face) for HCP-OASIS and CNP Datasets. Mean (M) and standard deviation (SD) for four surface pairs. Lower %Face indicates fewer intersections. Bold indicates best performance.

Dataset	Model	Pial L vs R		WM L vs R		L Pial vs WM		R Pial vs WM	
		M	SD	M	SD	M	SD	M	SD
HCP-OASIS	SimCortex	<b>0.004</b>	<b>0.005</b>	<b>0.001</b>	<b>0.002</b>	<b>0.183</b>	<b>0.157</b>	<b>0.218</b>	<b>0.177</b>
	CFPP	0.268	0.071	0.132	0.028	0.664	0.101	0.720	0.103
	V2C	0.188	0.078	0.159	0.034	0.728	0.074	0.806	0.076
CNP	SimCortex	<b>0.015</b>	<b>0.017</b>	<b>0.003</b>	<b>0.005</b>	<b>0.084</b>	<b>0.055</b>	<b>0.116</b>	<b>0.081</b>
	CFPP	0.286	0.064	0.113	0.039	0.559	0.077	0.574	0.100
	V2C	0.131	0.047	0.147	0.034	0.711	0.071	0.846	0.069

# Results: Topology & Geometry (CNP)

## Topology:

**%SIF = 0.13%** ( $\approx \frac{1}{2}$  CFPP 0.24%;  
 $\approx 5\times$  lower than V2C 0.68%)

## Geometry (avg):

CFPP best CH/ASSD;  
 SimCortex close; V2C best HD

## Per-surface highlight:

SimCortex lowest HD on pial

Table 2: Surface Reconstruction Metrics for CNP Dataset (51 Subjects). Mean (M) and standard deviation (SD) compare SimCortex against CFPP and V2C across four cortical surfaces, with averages in the last row. Bold indicates best performance.

Surface	Model	Chamfer(mm)		ASSD(mm)		HD(mm)		SIF(%)	
		M	SD	M	SD	M	SD	M	SD
LH Pial	SimCortex	1.36	0.61	0.39	0.10	<b>7.19</b>	<b>1.27</b>	<b>0.03</b>	<b>0.02</b>
	CFPP	<b>1.19</b>	<b>0.65</b>	<b>0.29</b>	<b>0.13</b>	7.66	1.74	0.25	0.14
	V2C	1.84	0.49	0.52	0.09	7.89	0.94	1.20	0.47
LH WM	SimCortex	1.55	1.15	0.41	0.14	7.44	1.75	0.23	0.14
	CFPP	<b>0.91</b>	<b>0.67</b>	<b>0.26</b>	<b>0.10</b>	7.39	1.62	<b>0.07</b>	<b>0.05</b>
	V2C	0.95	0.33	0.34	0.07	<b>6.58</b>	<b>1.36</b>	0.15	0.15
RH Pial	SimCortex	1.44	0.66	0.40	0.10	<b>7.58</b>	<b>1.39</b>	<b>0.03</b>	<b>0.02</b>
	CFPP	<b>1.13</b>	<b>0.58</b>	<b>0.28</b>	<b>0.11</b>	7.93	1.66	0.45	0.20
	V2C	1.85	0.62	0.51	0.09	8.29	1.12	1.27	0.48
RH WM	SimCortex	1.69	1.38	0.43	0.18	7.84	2.18	0.22	0.16
	CFPP	<b>0.89</b>	<b>0.62</b>	<b>0.26</b>	<b>0.09</b>	7.68	1.57	0.18	0.11
	V2C	0.96	0.40	0.34	0.07	<b>6.89</b>	<b>1.66</b>	<b>0.10</b>	<b>0.11</b>
Average	SimCortex	1.51	0.69	0.41	0.10	7.51	1.10	<b>0.13</b>	<b>0.06</b>
	CFPP	<b>1.03</b>	<b>0.63</b>	<b>0.27</b>	<b>0.11</b>	7.66	1.43	0.24	0.10
	V2C	1.40	0.45	0.43	0.07	<b>7.41</b>	<b>0.90</b>	0.68	0.25

# Results: Topology & Geometry (HCP–OASIS)

## Topology:

**%SIF = 0.04% ( $\approx \frac{1}{3}$  CFPP)**  
 0.13%; **>10x** lower than **V2C**  
 0.54%)

## Geometry (avg):

**CFPP best CH/ASSD**

**SimCortex** close

**HD (avg): V2C lowest**

**SimCortex** 6.86; **CFPP** 6.88  
 (all very close)

## Per-surface highlight:

**SimCortex** lowest **CH** on **LH** pial  
 and lowest **%SIF** on both pial

Table 3: Surface Reconstruction Metrics for HCP-OASIS Dataset (51 Subjects). Mean (M) and standard deviation (SD) compare SimCortex against CFPP and V2C across four cortical surfaces, with averages in the last row. Bold indicates best performance.

Surface	Model	Chamfer(mm)		ASSD(mm)		HD(mm)		SIF(%)	
		M	SD	M	SD	M	SD	M	SD
LH Pial	SimCortex	<b>1.10</b>	<b>0.27</b>	0.33	0.08	7.15	1.30	<b>0.01</b>	<b>0.01</b>
	CFPP	1.13	0.32	<b>0.32</b>	<b>0.11</b>	<b>6.79</b>	<b>1.23</b>	0.15	0.11
	V2C	1.60	0.29	0.49	0.07	7.49	1.01	1.02	0.69
LH WM	SimCortex	1.26	2.37	0.32	0.21	6.52	2.36	0.08	0.07
	CFPP	<b>0.79</b>	<b>0.14</b>	<b>0.24</b>	<b>0.05</b>	6.89	1.46	<b>0.06</b>	<b>0.06</b>
	V2C	0.83	0.09	0.32	0.05	<b>5.66</b>	<b>1.00</b>	0.06	0.06
RH Pial	SimCortex	1.11	0.20	0.33	0.05	7.41	1.78	<b>0.01</b>	<b>0.01</b>
	CFPP	<b>1.09</b>	<b>0.15</b>	<b>0.31</b>	<b>0.06</b>	<b>6.90</b>	<b>0.91</b>	0.23	0.15
	V2C	1.55	0.17	0.48	0.04	7.63	0.78	1.00	0.71
RH WM	SimCortex	0.98	0.51	0.30	0.09	6.37	2.17	0.07	0.09
	CFPP	<b>0.80</b>	<b>0.15</b>	<b>0.25</b>	<b>0.06</b>	6.92	1.47	0.10	0.08
	V2C	0.83	0.10	0.32	0.05	<b>5.53</b>	<b>0.94</b>	<b>0.06</b>	<b>0.06</b>
Average	SimCortex	1.11	0.62	0.32	0.07	6.86	1.16	<b>0.04</b>	<b>0.03</b>
	CFPP	<b>0.95</b>	<b>0.15</b>	<b>0.28</b>	<b>0.06</b>	6.88	0.83	0.13	0.08
	V2C	1.21	0.13	0.40	0.04	<b>6.58</b>	<b>0.57</b>	0.54	0.35

# Computation Time

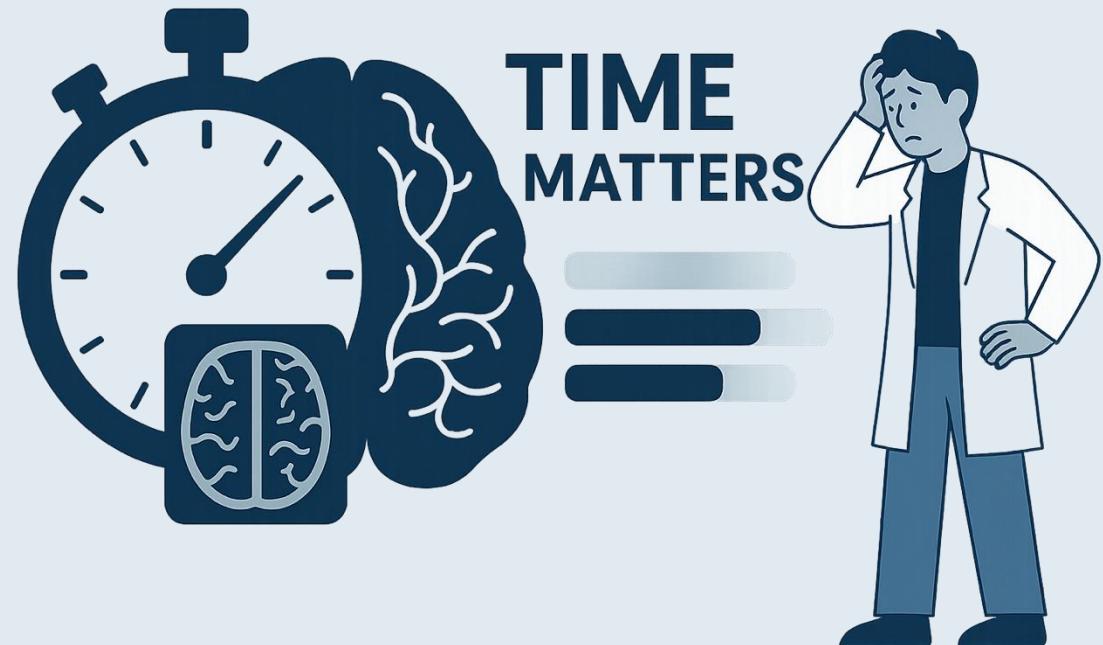
15

**Training:** 250 epochs  $\approx$  **28 hours** (our hardware)

**Inference (per subject, all 4 surfaces):**

**SimCortex:** **0.28 s** (simultaneous LH/RH white & pial)

**CFPP:** **0.70 s** (0.35 s LH + 0.34 s RH; processed separately)



# Visual Analysis (Geometry Accuracy)

## SimCortex:

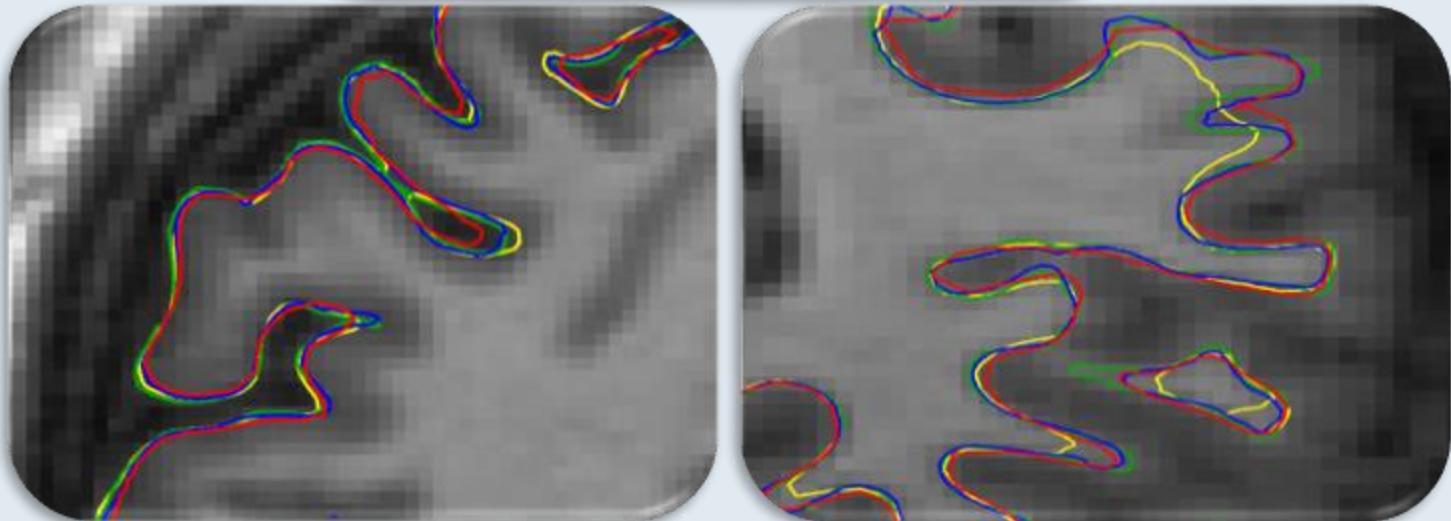
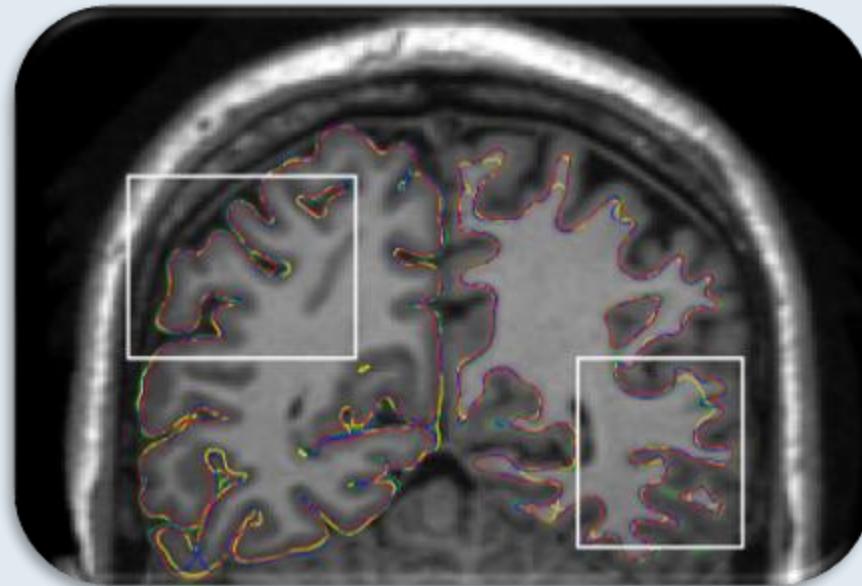
deeper sulci in some regions; sometimes **smoother/less detailed curvature**.

## CFPP:

generally **closest geometry**, more sulcal detail (esp. white matter).

## V2C:

overall **less precise** than CFPP/SimCortex.



SimCortex (yellow), CFPP (blue), V2C (red), and ground truth (green)

# Visual Analysis (Collisions)

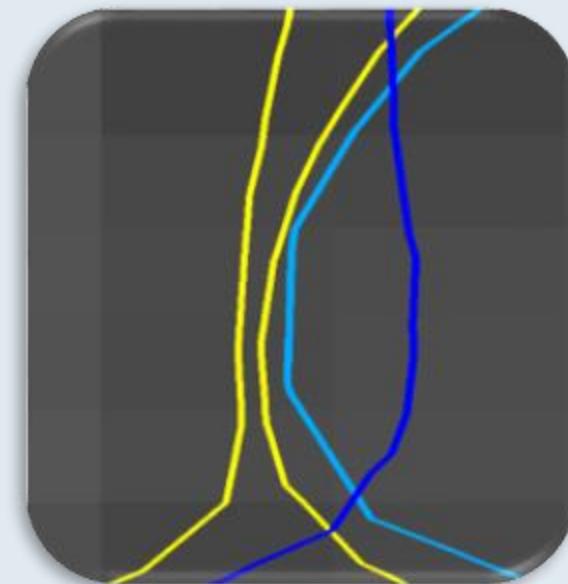
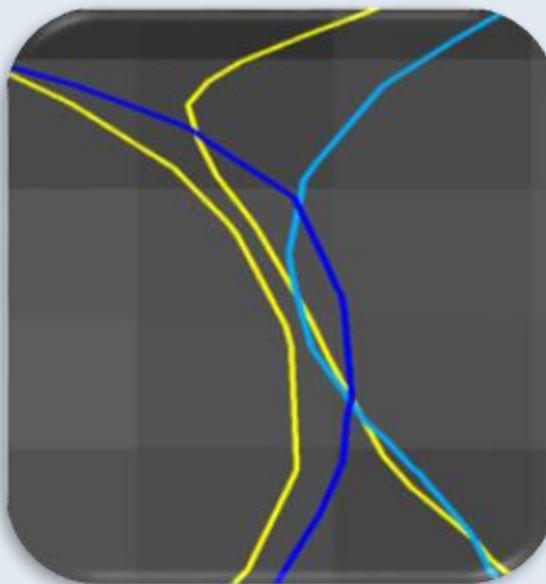
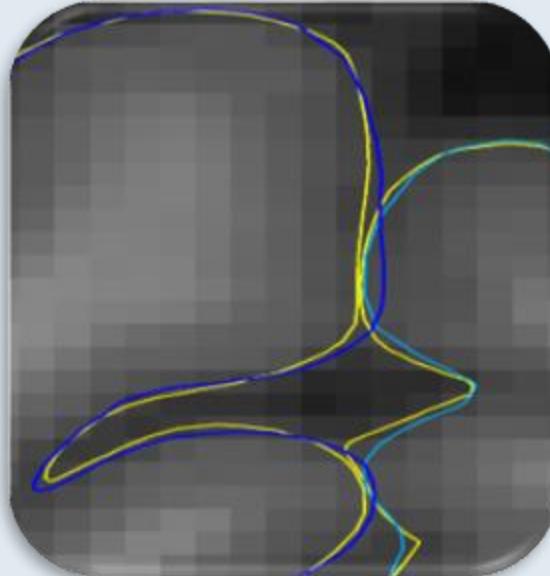
17

**SimCortex (yellow):**

avoids left-right collisions.

**CFPP (dark/light blue L/R):**

visible LR collisions.



## What we built:

SimCortex reconstructs all four cortical surfaces jointly using a single diffeomorphic deformation, starting from collision-free, genus-0 templates

## Key results:

>90% fewer collisions, lowest %SIF, competitive CH/ASSD/HD, ~0.28 s/subject

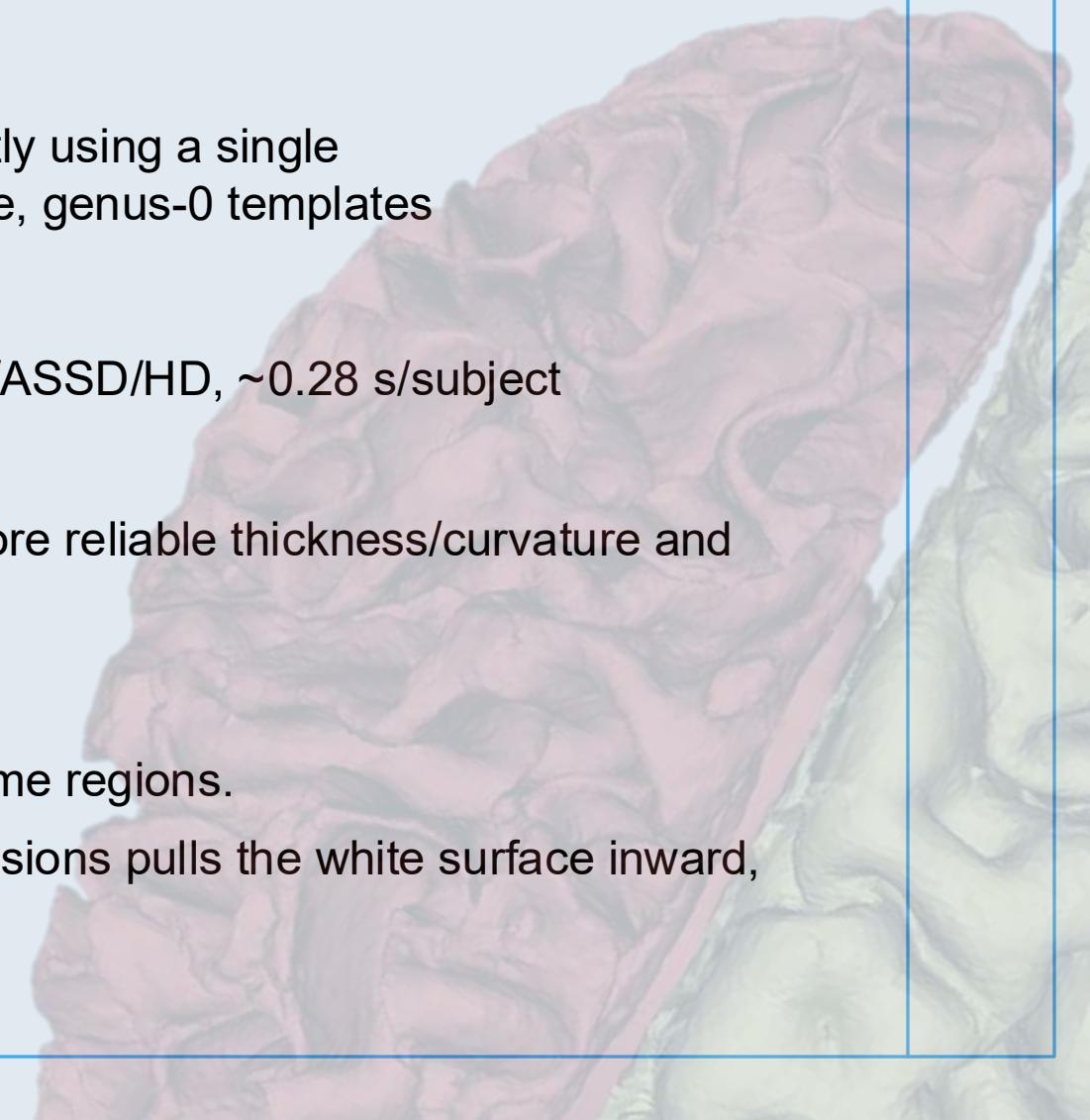
## Why it matters:

Topology-correct, near-zero-collision surfaces → more reliable thickness/curvature and scalable studies

## Limitation:

Slightly smoother/shallower white-matter sulci in some regions.

**Why:** In tight white–pial gaps,  $\lambda$ -tuning to avoid collisions pulls the white surface inward, and smoothing reduces fine detail



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19

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**THANK YOU!**