

$$Y_k = CX_k + Z_k$$

Y = observation
 Z = measurement noise

C relates to what you choose to measure, etc:
 $C = [1 \ 0]$, $C = [0 \ 1]$, $x = \begin{bmatrix} x \\ y \end{bmatrix}$

Lecture 15: State matrix 2-D

Same thing w/ more variables. Already generalized this to $n \times n$ matrices.

Lecture 16: Control variable matrix in 2D

Same thing...

Lecture 15: Trivial computations. Same w/ lecture 16, 17

Lecture 16: The covariance matrix

$$P_k = AP_{k-1}A^T + Q$$

P = state covariance matrix

$$K_k = \frac{P_k H^T}{HP_k H^T + R}$$

Q = process noise covariance matrix

$R \rightarrow 0 \Rightarrow K \rightarrow 1$ (adjust primarily w/ measurement update)

R = Measurement (variance matrix) (error in measurement)

K = Kalman gain

$R \rightarrow \infty$, $K \rightarrow 0$ (adjust by prediction state)

If $P \rightarrow 0$ measurement updates mostly ignored

Lecture 19: What is covariance matrix

$$\Sigma_{ij} = \text{cov}(X_i, X_j) = E[(X_i - E[X_i])(X_j - E[X_j])]$$

$$\sigma_x \sigma_y = \frac{\sum_{i=1}^N (\bar{x} - x_i)(\bar{y} - y_i)}{N}$$

Probability Primer

Lecture 1.1 (just talk about basic ideas, no Lebesgue)

Banach-Tarski paradox

- non-measurable sets: the measure is not preserved

Under translation. These sets cannot be assigned a unique

1.2 Measure theory: sigma algebra

Def: Given a set Ω , a σ algebra on Ω is a collection $\mathcal{A} \subset 2^\Omega$ (power set of Ω) s.t. \mathcal{A} is nonempty and \mathcal{A} is:

- (i) closed under complements ($E \in \mathcal{A} \Rightarrow E^c \in \mathcal{A}$)
- (ii) closed under countable unions ($E_1, \dots, E_n \in \mathcal{A} \Rightarrow \bigcup_{i=1}^{\infty} E_i \in \mathcal{A}$)
by (i) by (ii)

Proof (1) $\Omega \in \mathcal{A}$ since $E \in \mathcal{A} \Rightarrow E^c \in \mathcal{A} \Rightarrow$
 $E \cup E^c \in \mathcal{A} \Rightarrow \Omega \in \mathcal{A}$

(2) $\emptyset \in \mathcal{A}$ since $\Omega^c = \emptyset \in \mathcal{A}$

(3) \mathcal{A} is closed under countable intersections

Suppose E_1, E_2, \dots
 $\bigcap_{i=1}^{\infty} E_i = \left(\bigcup_{i=1}^{\infty} E_i^c \right)^c = \left(\bigcup_{i=1}^{\infty} E_i^c \right)^c \in \mathcal{A}$

Pr 1.3

Def: Given $\mathcal{C} \subset 2^\Omega$, the σ -algebra generated by \mathcal{C} written $\sigma(\mathcal{C})$ is the "smallest" σ -alg containing \mathcal{C} .

$$\text{that is } \sigma(\mathcal{C}) = \bigcap_{\substack{\mathcal{A} \supset \mathcal{C} \\ \mathcal{A} \text{ is } \sigma\text{-alg}}} \mathcal{A}$$

Proof: $\sigma(\mathcal{C})$ always exists because:

- (i) 2^Ω is a σ -algebra
- (ii) any intersection of σ algs is a σ alg

Examples (1) $\mathcal{A} = \{\emptyset, \Omega\}$

(2) $\mathcal{A} = \{\emptyset, E, E^c, \Omega\}$

(3) If $\Omega = \mathbb{R}$, the Borel σ -alg is $\mathcal{B} = \sigma(\mathcal{C})$

where $\mathcal{C} = \{\text{open sets of } \mathbb{R}\}$. If \mathcal{A} is any topological σ -alg, defined in the same way

Defn: A measure μ on \mathcal{A} with σ -alg \mathcal{A} is a

fun $\mu: \mathcal{A} \rightarrow [0, \infty)$ s.t.

(i) $\mu(\emptyset) = 0$ (less rigorous than real variables)

(ii) $\mu(\bigcup_{i=1}^{\infty} E_i) = \sum_{i=1}^{\infty} \mu(E_i)$ for any $E_1, E_2, \dots \in \mathcal{A}$
 pairwise disjoint sets
 ↳ countable additivity

Defn: A probability measure is a measure P s.t.

$$P(\Omega) = 1$$

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Ex of
measure

Kolmogorov's axioms

Examples:

(1) (finite set) $\Omega = \{1, \dots, n\}$ $\mathcal{A} = 2^\Omega$

$P(\{k\}) = \frac{1}{n} \quad \forall k \in \Omega$ (uniform distribution)

$$P(\{1, 2, 4\}) = P(\{1\} \cup \{2\} \cup \{4\}) = P(\{1\}) + P(\{2\}) + P(\{4\})$$

(2) (countably infinite) $\Omega = \{1, 2, 3, \dots\}$ $\mathcal{A} = 2^\Omega$

$$P(\{k\}) = \text{prob it takes } k \text{ (coin flips to get heads)} \\ = \alpha (1-\alpha)^{k-1} = \left(\frac{1}{2}\right) \left(1 - \frac{1}{2}\right)^{k-1}$$

(geometric distribution)

(3) (uncountable) $\Omega = [0, \infty)$, $\mathcal{A} = \mathcal{B}([0, \infty))$

$$P([0, x]) = 1 - e^{-x} \quad \forall x > 0 \quad \text{exponential distribution}$$

$$\text{Note } P(\{x\}) = 0 \quad \forall x > 0$$

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Basic
properties
of measure

(4) Lebesgue measure (on \mathbb{R}) $\Omega = \mathbb{R}$, $\mathcal{A} = \mathcal{B}(\mathbb{R})$

$$\mu([a, b]) = b - a \quad \text{for any } a, b \in \mathbb{R}, a < b$$

- not a probability measure

Theorem (basic properties of measures)

Let $(\Omega, \mathcal{A}, \mu)$ be a measure space

(i) Monotonicity: if $E, F \in \mathcal{A}$ and $E \subset F$ then $\mu(E) \leq \mu(F)$

(ii) Subadditivity: if $E_1, \dots \in \mathcal{A}$ then $\mu(\bigcup_{i=1}^{\infty} E_i) \leq \sum_{i=1}^{\infty} \mu(E_i)$

PP 1.6

(iii) Continuity from below: if $E_1, \dots \in \mathcal{A}$, $E_i \subset E_{i+1}$
 then $\mu(\bigcup_{i=1}^{\infty} E_i) = \lim_{i \rightarrow \infty} \mu(E_i)$

(iv) continuity from above $E_1, \dots, E_n \in \mathcal{A}$ and $E_1 \supset E_2 \supset \dots$
and $\mu(E_1) < \infty$, then $\mu(\bigcap_{i=1}^{\infty} E_i) = \lim_{i \rightarrow \infty} \mu(E_i)$

PP 1.7 Facts let (Ω, \mathcal{A}, P) be a prob measure

with $E, F, E_i \in \mathcal{A}$

(1) $P(E \cup F) = P(E) + P(F)$ if $E \cap F = \emptyset$

(2) $P(E \cup F) = P(E) + P(F) - P(E \cap F)$

(3) $P(E) = 1 - P(E^c)$

(4) $P(E \cap F^c) = P(E) - P(E \cap F)$

(5) (inclusion-exclusion formula)

$$P(\bigcup_{i=1}^n E_i) = \sum_i P(E_i) - \sum_{i < j} P(E_i \cap E_j)$$

$$+ \sum_{i < j < k} P(E_i \cap E_j \cap E_k) - \dots + (-1)^{n+1} P(E_1 \cap E_2 \cap \dots \cap E_n)$$

(6) $P(\bigcup_{i=1}^n E_i) \leq \sum_{i=1}^n P(E_i)$ and $P(\bigcap_{i=1}^n E_i) \geq \sum_{i=1}^n P(E_i) - (n-1)$ — all subadditivity

PP 1.8 Def $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ (a, b)

Def A Borel measure μ is a measure on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$

and Borel probability measure) Def CDF (cumulative distribution function) is a function $F: \mathbb{R} \rightarrow \mathbb{R} \in [0, 1]$

(i) F is non decreasing ($x \leq y \Rightarrow F(x) \leq F(y)$)

(ii) F is right continuous ($\lim_{x \downarrow a} F(x) = F(a)$)

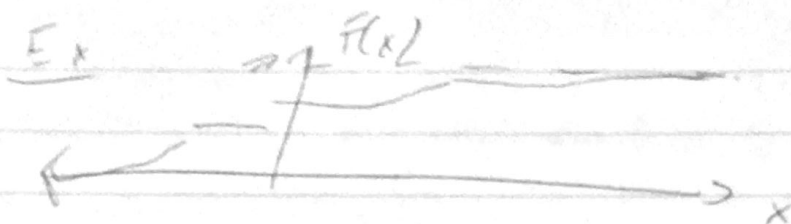
(iii) $\lim_{x \rightarrow \infty} F(x) = 1$

(iv) $\lim_{x \rightarrow -\infty} F(x) = 0$

Thm 1.1 If F is CDF then \exists a unique Borel prob measure on \mathbb{R} s.t. $P((-a, x]) = F(x)$ $\forall x \in \mathbb{R}$

(ii) If P is a Borel prob measure on \mathbb{R} then \exists a unique CDF F s.t. $F(x) = P((-a, x])$ $\forall x \in \mathbb{R}$

Next is, there is an equivalence between CDFs and
Borel prob measures



References

- Rudin's Principles of Math Analysis
- Jacob and Peter "Probability Essentials"
 - main ideas for first exposure
- Durrett "Prob. Theory and Examples"
 - a bit more advanced, somewhat informal
- Folland's "Real Analysis"
- Rudin "Real and Complex Analysis" - skips measure