

Homework 2

① What is the complexity of using Gaussian elimination to solve $Ax = b$, where A is an $n \times n$ tridiagonal matrix? Is it $O(n)$? $O(n^2)$? $O(n^3)$? Justify your answer!

② Find the degree-three polynomial $p(x) = ax^3 + bx^2 + cx + d$ with

$$p(1) = 4 \quad p'(-1) = 0$$

$$p(2) = 2 \quad p'(2) = 6$$

- First solve for p by using Gaussian elimination on a set of linear equations.

Show your work. Please use compact matrix notation to simplify grading.

- Now enter the matrix into Matlab, Mathematica, or equivalent software, and solve the equations there. Again, show your work (commands and results).

③ By hand (not using a computer), find all solutions to the equations:

$$\begin{aligned} x_1 + x_2 + 2x_3 &= 1 \\ 3x_1 + 3x_3 + 3x_4 &= 6 \\ 2x_1 + 2x_2 - x_3 + x_4 &= 3 \end{aligned}$$

④ Determine, by hand, which of the following systems of equations has at least one solution.

(Jargon: If a system of equations has at least one solution, we say it is "consistent." It is "inconsistent" if there are no solutions.)

$$\begin{aligned} &x + 2y + z = 2, & &2x + 2y + 4z = 0, \\ \text{(a)} \quad &2x + 4y = 2, & \text{(b)} \quad &3x + 2y + 5z = 0, \\ &3x + 6y + z = 4. & &4x + 2y + 6z = 0. \end{aligned}$$

$$\begin{aligned} &x - y + z = 1, & &x - y + z = 1, \\ \text{(c)} \quad &x - y - z = 2, & \text{(d)} \quad &x - y - z = 2, \\ &x + y - z = 3, & &x + y - z = 3, \\ &x + y + z = 4. & &x + y + z = 2. \end{aligned}$$

$$\begin{aligned} &2w + x + 3y + 5z = 1, & &2w + x + 3y + 5z = 7, \\ \text{(e)} \quad &4w + 4y + 8z = 0, & \text{(f)} \quad &4w + 4y + 8z = 8, \\ &w + x + 2y + 3z = 0 & &w + x + 2y + 3z = 5 \end{aligned}$$

$$(e) \quad \begin{aligned} 4w + 4y + 8z &= 0, \\ w + x + 2y + 3z &= 0, \\ x + y + z &= 0. \end{aligned}$$

$$(f) \quad \begin{aligned} 4w + 4y + 8z &= 8, \\ w + x + 2y + 3z &= 5, \\ x + y + z &= 3. \end{aligned}$$

- ④ By hand (not using a computer), find all polynomials $p(x) = a + bx + cx^2 + dx^3$ that satisfy $p(1) = 2$, $p'(3) = 1$ and $p''(2) = 0$.

- ⑤ Use the Gauss-Jordan method to find the 4×2 matrix B satisfying

$$\begin{pmatrix} 1 & 2 & 3 & 4 \\ 2 & 4 & 2 & 2 \\ 3 & 2 & 1 & 1 \\ 1 & 2 & 0 & 0 \end{pmatrix} B = \begin{pmatrix} 50 & 60 \\ 38 & 48 \\ 21 & 28 \\ 7 & 10 \end{pmatrix}$$

Do it by hand, and show your work.

- ⑦ By hand, compute the LU decomposition of

$$A = \begin{pmatrix} 1 & 2 & 0 & 0 \\ 3 & 4 & 5 & 0 \\ 0 & 6 & 7 & 8 \\ 0 & 0 & -22 & 9 \end{pmatrix}$$

In general, it is easy to see that the L, U factors of a tridiagonal matrix are themselves tridiagonal. [See problem 3.10.6.] This makes solving $Ax = b$ using the LU decomposition very fast. On the other hand, A^{-1} can be dense — as it is in this example — so naively multiplying out $A^{-1}b$ takes quadratic time, much slower than using the LU decomposition!

⑧ Let $A = \begin{pmatrix} 1 & 4 & 5 \\ 4 & 18 & 26 \\ 3 & 16 & 30 \end{pmatrix}$.

- a) Determine the LU factors of A .
(Do this, and the following parts, by hand, not computer.)
- b) Use the LU factors to solve $A\vec{x} = \vec{b}$ and $A\vec{y} = \vec{c}$, where
- $$\vec{b} = \begin{pmatrix} 6 \\ 0 \\ -6 \end{pmatrix}, \quad \vec{c} = \begin{pmatrix} 6 \\ 6 \\ 12 \end{pmatrix}.$$

c) Use the LLL factors to determine A^{-1} .

⑨ A blurry camera:

Let's pretend you have a 64×64 pixel grayscale camera. As if that isn't bad enough, the camera's sensor is blurry; some of the light from each pixel spreads into the neighboring pixels.

More precisely, let $I_{x,y}$ be the amount of light that hits pixel (x,y) . Here x and y are both from 1 to 64.

The camera records

$$C_{x,y} = \frac{1}{2} \times I_{x,y} + \frac{1}{8} \times (I_{x-1,y} + I_{x+1,y} + I_{x,y-1} + I_{x,y+1}).$$

That is, it gets $\frac{1}{2}$ times what you want, but also $\frac{1}{8}$ times the light from the neighboring pixels.

Note: If (x,y) is on the boundary, then there will be fewer than four neighboring pixels. For example,

$$C_{1,1} = \frac{1}{2} \times I_{1,1} + \frac{1}{8} \times (I_{1,2} + I_{2,1})$$

because the corner pixel $(1,1)$ has only two neighbors.

Here's a picture that your camera took:



By setting up and solving 64^2 equations in the 64^2 variables $I_{1,1}, \dots, I_{64,64}$, recover the correct image I .

Technical notes:

The blurred image file is available as "blurryimage.mat". To load it, run the commands

```
load('blurryimage.mat');
```

```
imshow(blurryimage);
```

← this should display the blurry image

To turn it into a vector of length n^2 , you can use *the blurry image* **Python**

```
b = reshape(blurryimage, n^2, 1);
```

where $n=64$.

Then run the following code:

```
A = sparse(n^2, n^2);
%% fill in here commands to set up the sparse matrix A,
    each row containing an equation for one of the pixels
x = A \ b;
recoveredimage = reshape(x, n, n);
imshow(recoveredimage);
save('recoveredimage.mat', 'recoveredimage');
```

As in class, the following function for converting a pair of indices (x, y) to one index from 1 to n^2 , should be helpful:

```
% returns an integer from 1 to n^2; x, y should be
    from 1 to n
function j = xytoj(x, y, n)
    j = 1 + (x-1) + n * (y-1);
end
```

Deliverable: Print out your code and the image.

```
import numpy as np
import matplotlib.pyplot as plt
import scipy.sparse
import scipy.sparse.linalg
import scipy.io

mat = scipy.io.loadmat('blurryimage.mat')
blurryimage = mat['blurryimage']

plt.imshow(blurryimage, cmap='gray')
plt.show()

n = blurryimage.shape[0]
b = blurryimage.flatten()

A = scipy.sparse.lil_matrix((n**2, n**2))
# fill in here commands to set up A
A = A.tocsr()

x = scipy.sparse.linalg.bicg(A, b)[0]
recoveredimage = np.reshape(x, (n,n))
plt.imshow(recoveredimage, cmap='gray')
plt.show()
```