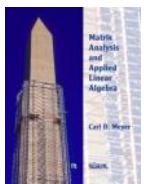


Lecture 12: Projections (class)

Admin:



5.13



no HW today

3.1-3.3

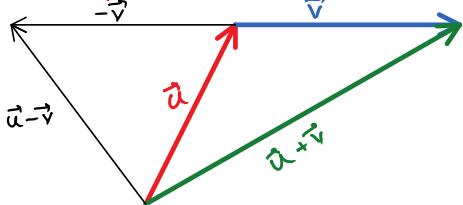
no class next Thursday
exam instead

Recall:

Inner product: $\vec{u} \cdot \vec{v} = \sum u_i^* v_i$ complex conjugate

Length: $\|\vec{u}\| = \sqrt{\vec{u} \cdot \vec{u}}$

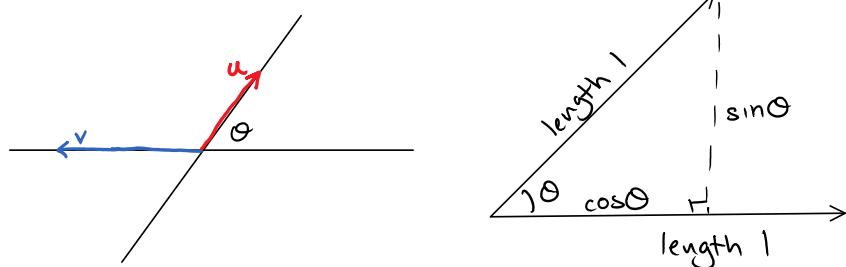
Triangle inequality: $\|\vec{u} + \vec{v}\| \leq \|\vec{u}\| + \|\vec{v}\|$



Corollary: $\|u\| \leq \|v\| + \|u-v\|$
 $\Rightarrow \|u-v\| \geq \|u\| - \|v\|$

Angles: angle between lines $\text{Span}(u)$ and $\text{Span}(v)$

$$\cos \theta = \frac{|\vec{u} \cdot \vec{v}|}{\|\vec{u}\| \cdot \|\vec{v}\|}$$

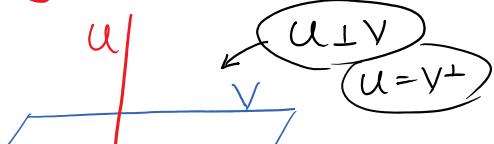


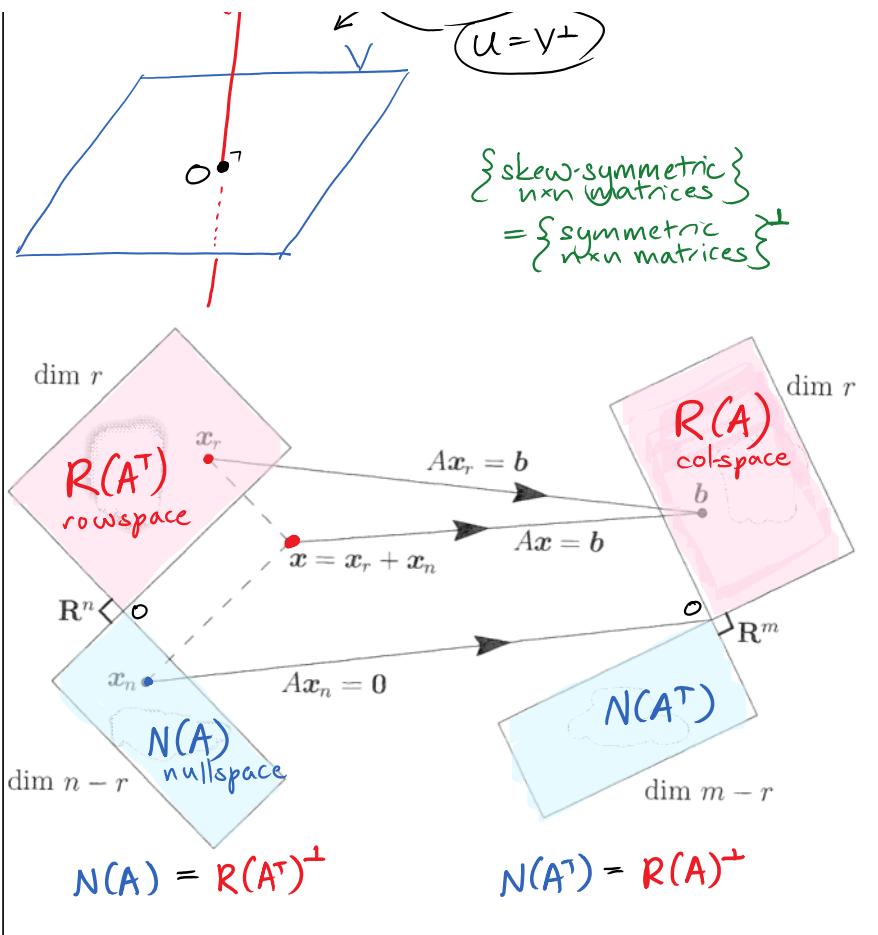
Cauchy-Schwarz inequality: $|\vec{u} \cdot \vec{v}| \leq \|\vec{u}\| \cdot \|\vec{v}\|$
(with equality iff collinear)

$$\begin{aligned} \text{Example: } \sum_{i=1}^n u_i &= (1, 1, \dots, 1) \cdot \vec{u} \\ &\leq \|(1, \dots, 1)\| \cdot \|\vec{u}\| \\ &= \sqrt{n} \cdot \|\vec{u}\| \end{aligned}$$

Orthogonal vectors: $\vec{u} \perp \vec{v} \iff \vec{u} \cdot \vec{v} = 0$

Orthogonal subspaces & orthogonal complements:





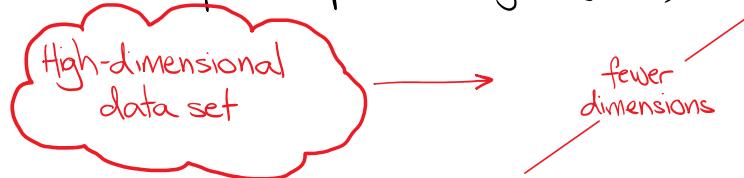
Consequences:

- * $\{x \mid Ax = b\}$ is an $(n-r)$ -dim affine space.
- * Any subspace U can be described either
 - by a basis for U ($\dim U$ vectors), or
 - by a basis for U^\perp ($n - \dim U$ vectors)

Today: Projections and orthogonal bases

PROJECTIONS

Motivation: Principal component analysis (PCA)



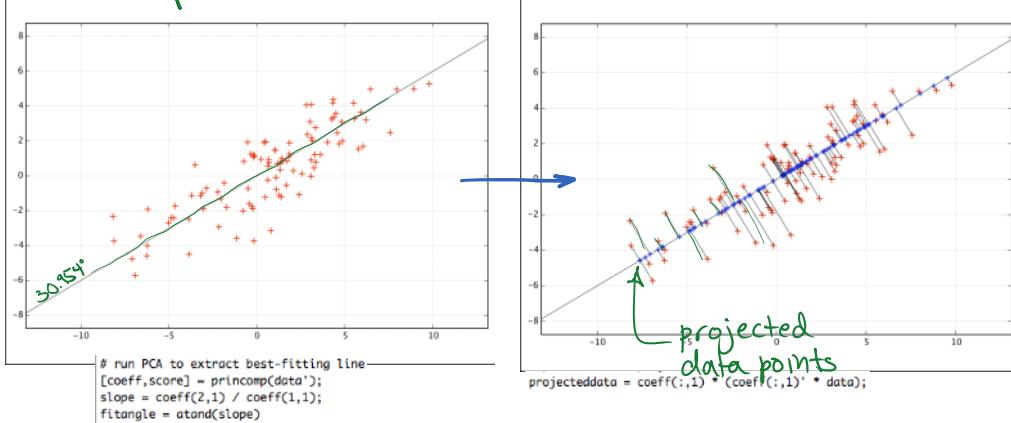
Example:

```
generate_noisy_data:
n = 100; largersddev = 5; rotationangle = 30;
c = cos(rotationangle); s = sin(rotationangle);
data = [c, -s, s, c] * [largersddev, 0, 0, 1] * randn(2, n);
```

- ① Find best-fitting low-dim subspace
- ② Project data to subspace



subspace



Applications: Machine learning, statistics, data analysis, compression,...

We'll cover PCA when we get to the singular-value decom.

Problem: How can we make all these

PROJECTIONS?

Definition: Let V be a subspace of \mathbb{R}^n (or \mathbb{C}^n)

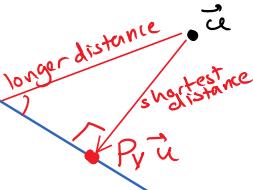
The orthogonal projection onto V maps (not a finite field!)

any point $\vec{u} \in \mathbb{R}^n$ → the closest point in V

$$V \quad \vec{u} \quad \text{projection of } \vec{u} \text{ onto } V$$

$$\text{Tr } A \equiv \sum_i A_{ii}$$

Observe: 1. $(P_V \vec{u} - \vec{u}) \perp V$.



$$\begin{aligned} & \text{3a. Rank}(P_V) \\ &= \dim V \end{aligned}$$

$$\begin{aligned} & \text{3b. Tr}(P_V) = \dim V \end{aligned}$$

2. If $\vec{u} \in V$, $P_V \vec{u} = \vec{u}$.

3. $P_V^2 = P_V$

why? b/c for any $\vec{u}, \vec{v} \in V$

$$\begin{aligned} & \Rightarrow P_V(P_V \vec{u}) = P_V \vec{u} \\ & \Rightarrow P_V^2 = P_V \end{aligned}$$

4. Projections are linear transformations

$$(P_V(\alpha \vec{u}) = \alpha P_V \vec{u}), P_V(\vec{u} + \vec{w}) = P_V \vec{u} + P_V \vec{w})$$

5. $I - P_V = P_{V^\perp}$ projection onto V^\perp

where $V^\perp = \{\text{all vectors } \perp \text{ to } V\}$, the "orthogonal complement" of V . Recall $\dim(V^\perp) = n - \dim(V)$.

$$P_V + P_{V^\perp} = I$$

$$\downarrow \text{Tr} \quad \downarrow \text{Tr}$$

$$\begin{aligned} & n - \dim V = \dim V^\perp \end{aligned}$$

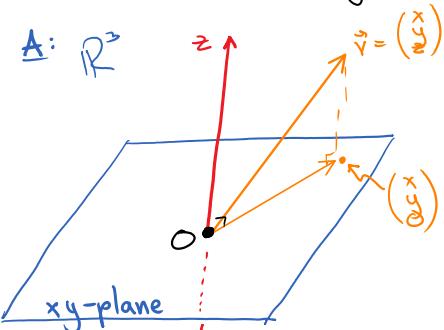
→ We'll prove these properties later!

→ We'll prove these properties later!

n-dimensional

Intuition: Projection to a coordinate subspace

Q: What is the projection from \mathbb{R}^3 to the xy-plane?



The matrix
 $P_V = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$
discards the z-coordinate of any point.

$$P_V \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} = \begin{pmatrix} v_1 \\ v_2 \\ 0 \end{pmatrix}$$

More generally

$$P_V = \underbrace{\begin{pmatrix} 1 & & & & 0 \\ 0 & 1 & & & 0 \\ \vdots & \ddots & \ddots & & 0 \\ 0 & 0 & 0 & \ddots & 0 \end{pmatrix}}_{n-k} \quad \text{in } \mathbb{R}^n.$$

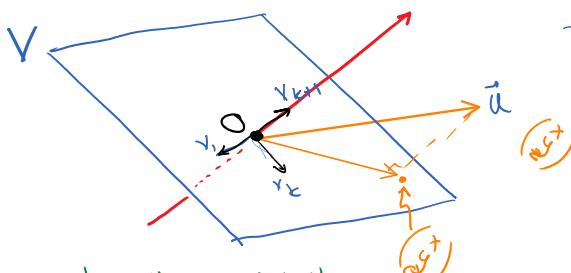
$V = \text{Span}\{\vec{e}_1, \dots, \vec{e}_k\}$

$$P_V \vec{u} = \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_k \\ 0 \\ \vdots \\ 0 \end{pmatrix}$$

More generally:

Projecting onto an arbitrary subspace V

- Change basis to orthogonal coordinate system starting with basis for V
- Discard the coordinates \perp to V



We'll next explain this in detail...

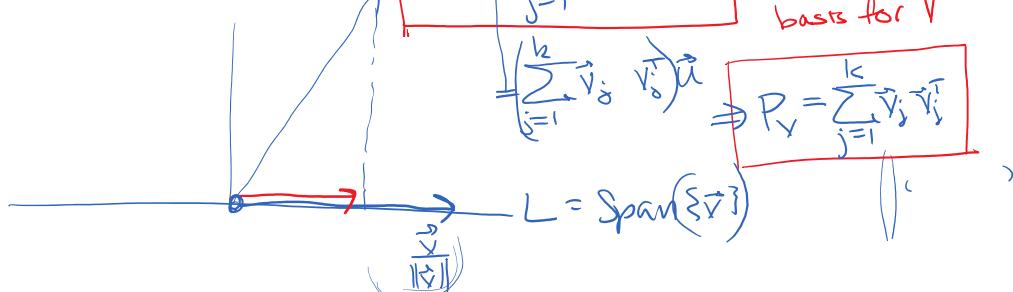
Let $\vec{v}_1, \dots, \vec{v}_k$ be an orthonormal basis for V ($k = \dim V$)

Extend this $\vec{v}_{k+1}, \dots, \vec{v}_n$ o.n. basis for \mathbb{R}^n

coordinates of $P_V \vec{u}$ are $\vec{v}_1 \cdot \vec{u}, \vec{v}_2 \cdot \vec{u}, \dots, \vec{v}_k \cdot \vec{u}, \vec{v}_{k+1} \cdot \vec{u}, \dots, \vec{v}_n \cdot \vec{u}$

$$\Rightarrow P_V \vec{u} = \sum_{j=1}^k (\vec{v}_j \cdot \vec{u}) \vec{v}_j \quad \text{if } \vec{v}_1, \dots, \vec{v}_k \text{ is an orthonormal basis for } V$$

$$\left(\sum_{j=1}^k \vec{v}_j \vec{v}_j^\top \right) \vec{u} \Rightarrow P_V = \sum_{j=1}^k \vec{v}_j \vec{v}_j^\top$$



\vec{u} projection of \vec{u} onto the line $\text{Span}(\vec{v}) = (\vec{v} \cdot \vec{u}) \vec{v}$ if $\|\vec{v}\| = 1$

$$P_L \vec{u} = \left(\frac{\vec{v}}{\|\vec{v}\|} \cdot \vec{u} \right) \frac{\vec{v}}{\|\vec{v}\|} = \frac{1}{\|\vec{v}\|^2} \vec{v} (\vec{v} \cdot \vec{u})$$

Lemma: The projection of \vec{u} onto the line $\text{Span}(\vec{v})$ is $= \frac{1}{\|\vec{v}\|^2} \vec{v} (\vec{v}^\top \vec{u})$

$\text{Span}(\vec{v})$

$$P_L \vec{u} = \frac{(\vec{v} \cdot \vec{u})}{\|\vec{v}\|^2} \vec{v}$$

Lemma: The projection of \vec{u} onto the line $\text{Span}(\vec{v})$ is

$$(\vec{v} \cdot \vec{u}) \vec{v} \quad \text{if } \|\vec{v}\|=1$$

(★)

$$\frac{\vec{v} \vec{v}^T}{\|\vec{v}\|^2} \vec{u} = \frac{(\vec{v} \cdot \vec{u})}{\|\vec{v}\|^2} \vec{v} \quad \text{in general}$$

(★)

$$= \frac{1}{\|\vec{v}\|^2} \vec{v} (\vec{v}^T \vec{u})$$

$$= \left(\frac{1}{\|\vec{v}\|^2} \vec{v} \vec{v}^T \right) \vec{u}$$

The matrix that projects onto $\text{Span}(\vec{v})$ is

$$\frac{\vec{v} \vec{v}^T}{\|\vec{v}\|^2}$$

an $n \times n$ matrix
if \vec{v} is $n \times 1$

-since $(\vec{v} \vec{v}^T) \vec{u} = \vec{v} (\vec{v}^T \vec{u}) = \vec{v} (\vec{v} \cdot \vec{u})$ ✓
 $\|\vec{u}\| \cos \theta$

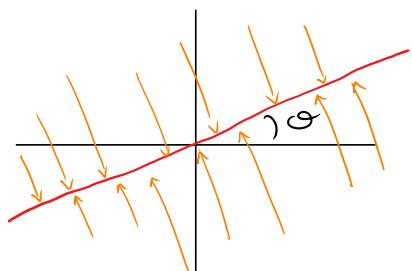
Example: \mathbb{R}^3 :

$$\vec{e}_x = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \vec{e}_y = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \vec{e}_z = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\vec{e}_y \vec{e}_y^T = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

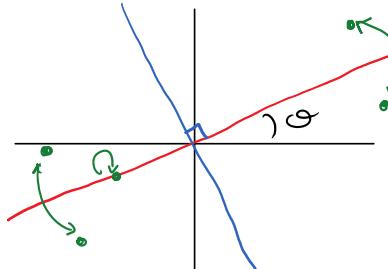
$$\vec{e}_y \vec{e}_y^T \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ y \\ 0 \end{pmatrix}$$

Example: Projection onto the line at angle θ


$$\vec{v} = \begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix}$$
$$\begin{pmatrix} \cos \theta \\ \sin \theta \end{pmatrix} (\cos \theta, \sin \theta)$$
$$= \begin{pmatrix} \cos^2 \theta & \cos \theta \sin \theta \\ \sin \theta \cos \theta & \sin^2 \theta \end{pmatrix}$$

P_θ

Example: Reflection about the line at angle θ


$$P_\theta - (I - P_\theta)$$

leaves vector in red space unchanged

puts a minus sign on vectors in the orthogonal blue line

$$= 2P_\theta - I = \begin{pmatrix} 2\cos^2 \theta - 1 & 2\cos \theta \\ 2\cos \theta & 2\sin^2 \theta - 1 \end{pmatrix}$$
$$= \begin{pmatrix} \cos 2\theta & \sin 2\theta \\ \sin 2\theta & -\cos 2\theta \end{pmatrix}$$

Example: Projection onto $(1, 1, \dots, 1)$

$$P = \frac{1}{n} \begin{pmatrix} 1 & 1 & \dots & 1 \end{pmatrix} \cdot \frac{1}{n} \begin{pmatrix} 1 & 1 & \dots & 1 \end{pmatrix}^T = \frac{1}{n} \begin{pmatrix} 1 & 1 & \dots & 1 \\ 1 & 1 & \dots & 1 \\ \vdots & \vdots & \ddots & \vdots \end{pmatrix}$$

$$P = \frac{1}{\sqrt{n}} \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix} \cdot \frac{1}{\sqrt{n}} (1, 1, \dots, 1) = \frac{1}{n} \begin{pmatrix} 1 & 1 & \cdots & 1 \end{pmatrix}$$

Observe: $P_v = (\text{avg. of } v\text{'s coords}) \cdot \begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix}$

Example: Projection to $(1, 1, \dots, 1)^\perp = R \begin{pmatrix} -2 & 1 & 1 \\ 1 & -2 & 1 \\ 1 & 1 & -2 \end{pmatrix}$.
 $= I - P$

Exercise: What is the projection of

$$\vec{u} = (2, -2, 3)$$

onto the line

$$L = \left\{ (x, y, z) \mid \begin{array}{l} x + 2y + 3z = 0 \\ x - y + 2z = 0 \end{array} \right\} ?$$

Answer:

① First find a basis for L.

$$L = N \begin{pmatrix} 1 & 2 & 3 \\ 1 & -1 & 2 \end{pmatrix} = N \begin{pmatrix} 1 & 0 & 2 \\ 0 & 3 & 1 \end{pmatrix} \\ = \text{Span} \begin{pmatrix} -7/3 \\ -1/3 \\ 1 \end{pmatrix} = \text{Span} \begin{pmatrix} 7 \\ 1 \\ -3 \end{pmatrix}$$

② Normalize it:

③ Project

$$P_L \vec{u} = \vec{v} \vec{v}^T \vec{u} \\ = \vec{v} (\vec{v} \cdot \vec{u}) \\ = \frac{1}{\sqrt{59}} \begin{pmatrix} 7 \\ 1 \\ -3 \end{pmatrix} \cdot \left(\begin{pmatrix} 7 \\ 1 \\ -3 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -2 \\ 3 \end{pmatrix} \right) \\ = \boxed{\frac{3}{\sqrt{59}} \begin{pmatrix} 7 \\ 1 \\ -3 \end{pmatrix}}$$

④ Check the answer:

$$\frac{3}{\sqrt{59}} (7, 1, -3) \in L: \checkmark \text{ since it is a multiple of } \vec{v}, \\ \text{ and yes } x + 2y + 3z = 0 \\ x - y + 2z = 0.$$

$$(\vec{u} - P_L \vec{u}) \perp L:$$

$$(2, -2, 3) - \frac{3}{\sqrt{59}} (7, 1, -3) = \frac{1}{\sqrt{59}} (97, -121, 186) \\ (97, -121, 186) \cdot (7, 1, -3) = 0 \checkmark$$

Exercise: What is the projection of

$$\vec{u} = (4, 0, 3)$$

onto the line

$$L = \left\{ (x, y, z) \mid \begin{array}{l} x + 2y + 3z = 0 \\ x - y + 2z = 0 \end{array} \right\} ?$$

Answer:

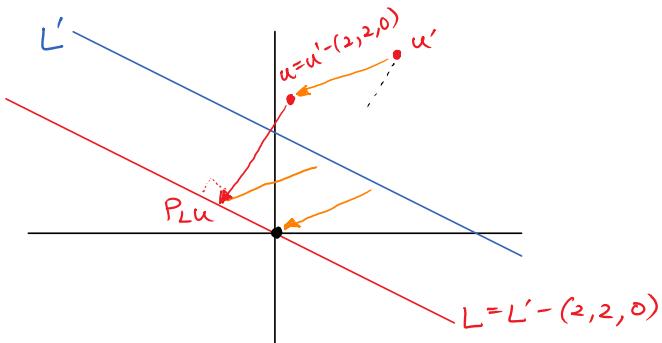
$$L' \quad | \quad x - y + 2z = 0$$

Answer:

① Find a constructive formulation for L' :

General principle: To work with an affine subspace,

- A. translate everything so it goes through 0
- B. work there
- C. translate back!



Since $L' - (2, 2, 0) = L$ (from above)

and $u' - (2, 2, 0) = u$,

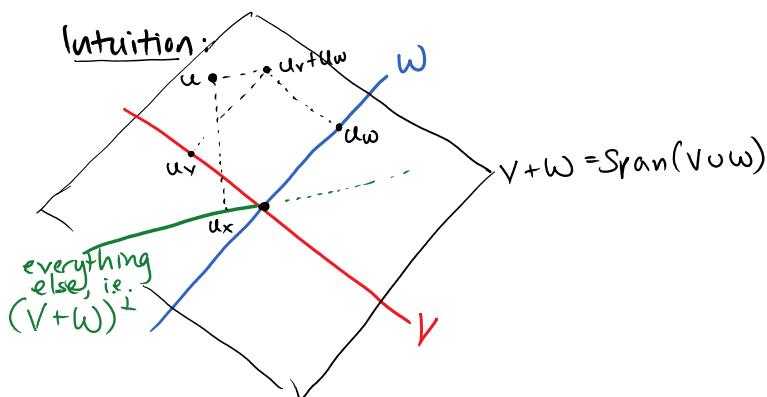
the projection of u' onto L' is

$$(2, 2, 0) + \frac{3}{59}(7, 1, -3) = \frac{1}{59}(139, 121, -9)$$

Problem: How can we construct the projector?

Key property: If $V \perp W$, onto higher-dim. subspaces

$$P_V + P_W = P_{V+W}$$



any vector \vec{u} can be expanded as

$$\vec{u} = \vec{u}_v + \vec{u}_w + \vec{u}_x$$

where $\vec{u}_v \in V$, $\vec{u}_w \in W$, $\vec{u}_x \in (V + W)^\perp$

$$P_V \vec{u} \quad P_W \vec{u} \quad P_X \vec{u}$$

$$P_{V+\omega} \vec{u} = \vec{u}_V + \vec{u}_\omega$$

Examples & counterexamples:

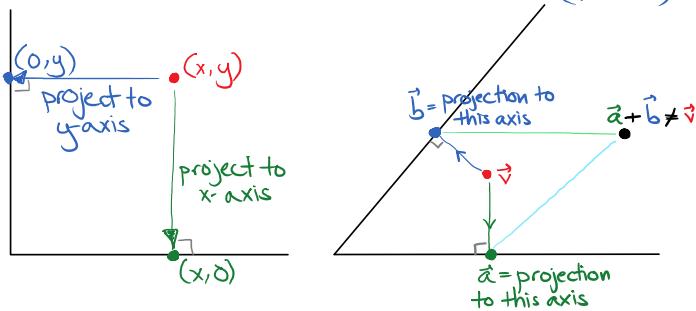
$$P_{e_1} =$$

$$Pe_2 =$$

$$P_{e_1} + P_{e_2} =$$

This does not work if V is not \perp to W :

$$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + \begin{pmatrix} \cos^2\theta & \cos\theta\sin\theta \\ \cos\theta\sin\theta & \sin^2\theta \end{pmatrix} = ? \text{ not a projection } (\theta^2 \neq ?)$$



It only works because $e_1 \perp e_2$!

$$(c, s) = (\cos \theta, \sin \theta)$$

$$\begin{aligned} & \begin{pmatrix} c \\ s \end{pmatrix} (c \ s) + \begin{pmatrix} s \\ -c \end{pmatrix} (s \ -c) \\ &= \begin{pmatrix} c^2 & cs \\ cs & s^2 \end{pmatrix} + \begin{pmatrix} s^2 & -cs \\ -cs & c^2 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \checkmark \end{aligned}$$

⇒ To project onto V , it is enough to have a basis of pairwise orthogonal vectors for V ...

FACT: For a subspace $V \subseteq \mathbb{R}^n$ with orthonormal basis

$\{\vec{v}_1, \dots, \vec{v}_k\}$,
orthogonal projection onto V

$$P_{\text{U}} = \boxed{\sum_{j=1}^k \underbrace{\vec{v}_j \vec{v}_j^T}_{n \times n \text{ matrix}}}$$

$$\text{Proof: } P_Y = P_{\text{Span}\{\mathbf{v}_1, \dots, \mathbf{v}_{k-1}\}} + P_{\text{Span}\{\mathbf{v}_k\}}$$

\Downarrow
 $\mathbf{v}_k \mathbf{v}_k^T$

Claim: For subspaces $V, V^\perp \subseteq \mathbb{R}^n$,

$$P_V + P_{V^\perp} = I$$

Proof :

Example: This can save a lot of time!

Let $A = \begin{pmatrix} 2 & -1 & -1 & \dots \\ -1 & 2 & -1 & \dots \\ -1 & -1 & 2 & \dots \\ \vdots & \vdots & \vdots & \ddots \end{pmatrix}_{n \times n}$, and $\vec{v} \in \mathbb{R}^n$. $A = A^T$

Compute $P_{R(A)}\vec{v}$.

Answer 1: Recall that $\text{Rank}(A) = n-1$,

$$N(A) = \text{Span} \left(\begin{pmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{pmatrix} \right)$$

basis for $R(A) : \{\vec{e}_1 - \vec{e}_2, \vec{e}_2 - \vec{e}_3, \vec{e}_3 - \vec{e}_4, \dots, \vec{e}_n - \vec{e}_1\}$

$$R(A) = \{\vec{v} \mid \sum_j v_j = 0\} = N(I - \vec{1}\vec{1}^T)$$

~~X~~ compute an orthonormal basis

Better answer:

$$\text{Remember } P_V = I - P_{V^\perp}$$

\Downarrow

$$P_{R(A)} = I - P_{N(A)}$$

$$= I - \frac{\vec{1}\vec{1}^T}{\|\vec{1}\|^2} = I - \frac{\vec{1}\vec{1}^T}{n}$$

$$\begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ \vdots & \vdots & \vdots \end{pmatrix}$$

In general, if $\dim V$ is close to n , then using $P_V = I - P_{V^\perp}$ will often simplify your calculations.

Recipe: How to make projections in Matlab

Problem: Given vectors $\vec{v}_1, \vec{v}_2, \dots, \vec{v}_k$, how do we project onto their span?

- ① $A = \begin{pmatrix} \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_k \end{pmatrix}_{n \times k}$ $V = R(A)$
- ② $B = \text{orth}(A)$ in Matlab
- ③ projection matrix = $B B^T$ B is $n \times \text{rank}(A)$ matrix

Why?

$$\begin{aligned} B &= \begin{pmatrix} 1 & 1 & \dots & 1 \\ \vec{v}_1 & \vec{v}_2 & \dots & \vec{v}_k \end{pmatrix} \quad d \leq k \\ &= \sum_{j=1}^d \vec{u}_j \vec{e}_j^T \end{aligned}$$

from above

$$P_V = \sum_j \vec{u}_j \vec{u}_j^T$$

$$B B^T = \sum_{j,k=1}^n u_j e_j^T e_k u_k^T = \underbrace{\sum_{j,k=1}^n}_{e_j \cdot e_k = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{if } j \neq k \end{cases}} u_j u_k$$

Exercise:

Compute the projection of \vec{z} , onto a random 100-dimensional subspace V of \mathbb{R}^{10000} .

Also: What is the expected squared length of the projection?

Answer:

```
n = 10000;
d = 100;
e1 = zeros(n,1); e1(1) = 1;
A = randn(n, d);
B = orth(A);
```

~~projection = B * B' * e1;~~ ← don't do this

projection = B * (B' * e1);

```
>> format long
>> norm(projection)^2
```

ans =

$$0.009994012962916 \approx .01 = \frac{d}{n} \quad \text{Why?}$$

neither in Matlab

nor in hand calculations

Name	Size	Bytes
P	10000x10000	800000000
B	10000x100	8000000

>> whos P needs n^2 memory
 >> whos B needs $n \times d$ memory

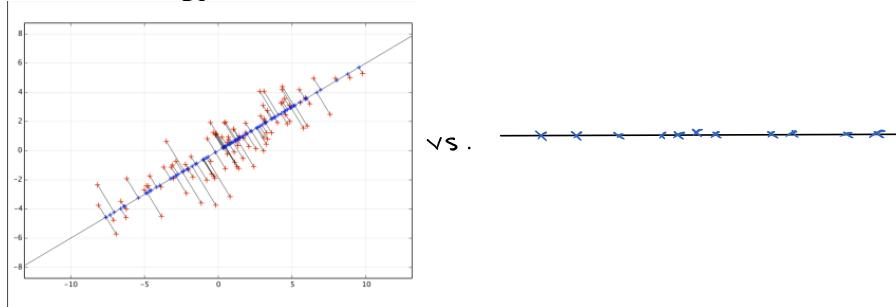
Gram-Schmidt orthogonalization

(see the other notes)

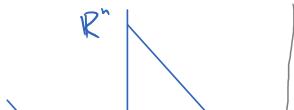
More examples of projections

① Find the shortest \vec{x} solving $A\vec{x} = \vec{b}$

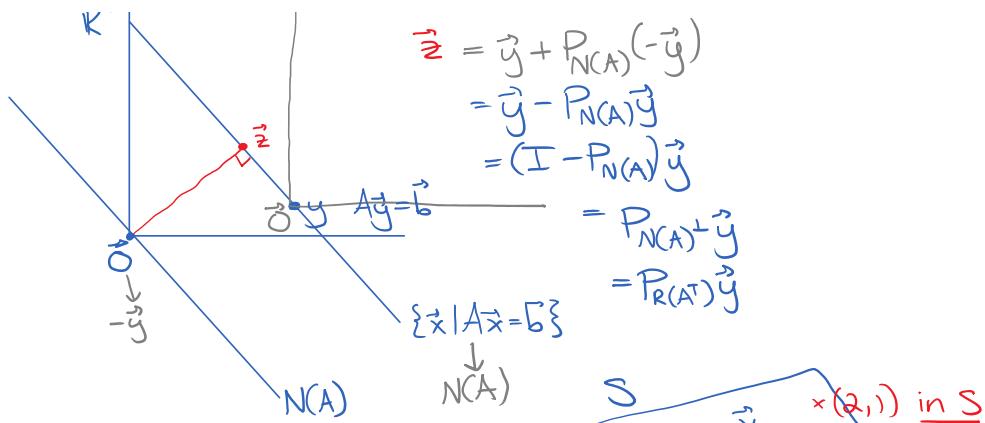
② Working with projected data



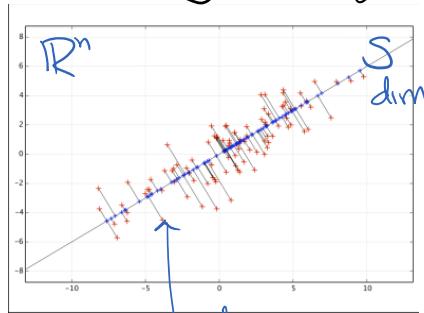
① Find the shortest \vec{x} solving $A\vec{x} = \vec{b}$



$$\vec{z} = \vec{y} + P_{N(A)}(-\vec{y}) \\ = \vec{y} - P_{\perp N(A)}\vec{y}$$



② Working with projected data

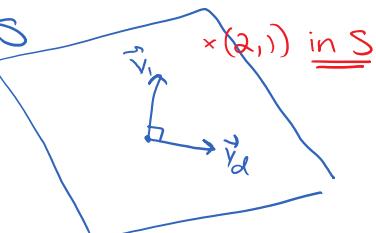


$$P_S \vec{x} = \sum_{j=1}^d \vec{v}_j (\vec{v}_j^T \vec{x})$$

$$\dim(S) = d$$

vs.

if $\vec{v}_1, \dots, \vec{v}_d \in \mathbb{R}^n$
are an orthonormal basis
for S



keep only the d coords
within S

$$Q_S \vec{x} = \begin{pmatrix} \vec{v}_1 \cdot \vec{x} \\ \vec{v}_2 \cdot \vec{x} \\ \vdots \\ \vec{v}_d \cdot \vec{x} \end{pmatrix} = \sum_{j=1}^d \vec{e}_j (\vec{v}_j^T \vec{x}) = \left(\sum_{j=1}^d \vec{e}_j \vec{v}_j^T \right) \vec{x}$$

$\left(\begin{array}{c} \vec{v}_1^T \\ \vec{v}_2^T \\ \vdots \\ \vec{v}_d^T \end{array} \right)$

Example: Image completion

Original image



Erased 40% of the coordinates



Solved to minimize

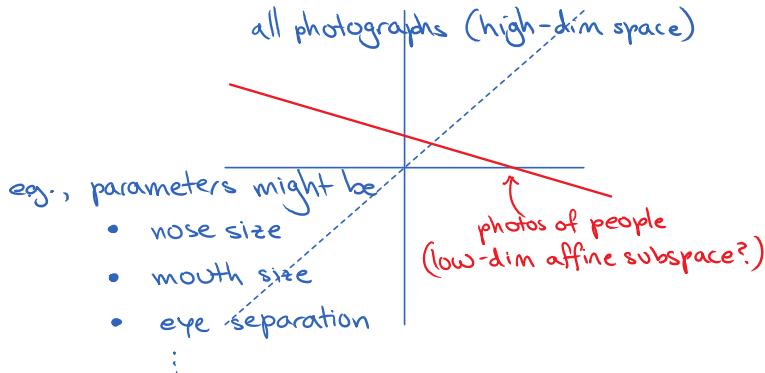
$\| \vec{x}_{\text{haar}} \|_2^2$ with constrained
coordinates

Experiment: How many degrees of freedom are there in a face?

Hypothesis: Not many! (?)

Idea:

photograph $\in \mathbb{R}^{\text{number of pixels}}$



Approach:

- ① Scrape 100+ photos from <http://faceresearch.org/>
Resize and convert to grayscale (for simplicity)



- ② Load images into Matlab as vectors

```
files = {'001_03.jpg', '002_03.jpg', '003_03.jpg', '004_03.jpg', '005_03.jpg', '006_03.jpg', '007_03.jpg',
'008_03.jpg', '009_03.jpg', '010_03.jpg', '011_03.jpg', '012_03.jpg', '013_03.jpg', '014_03.jpg', '016_03.jpg',
'017_03.jpg', '018_03.jpg', '019_03.jpg', '020_03.jpg', '021_03.jpg', '022_03.jpg', '024_03.jpg', '025_03.jpg',
'026_03.jpg', '027_03.jpg', '029_03.jpg', '030_03.jpg', '031_03.jpg', '032_03.jpg', '033_03.jpg', '034_03.jpg',
'036_03.jpg', '037_03.jpg', '038_03.jpg', '039_03.jpg', '041_03.jpg', '042_03.jpg', '043_03.jpg', '044_03.jpg',
'045_03.jpg', '061_03.jpg', '062_03.jpg', '063_03.jpg', '064_03.jpg', '066_03.jpg', '067_03.jpg', '068_03.jpg',
'069_03.jpg', '070_03.jpg', '081_03.jpg', '082_03.jpg', '083_03.jpg', '086_03.jpg', '087_03.jpg', '088_03.jpg',
'090_03.jpg', '091_03.jpg', '092_03.jpg', '094_03.jpg', '096_03.jpg', '097_03.jpg', '099_03.jpg', '100_03.jpg',
'101_03.jpg', '102_03.jpg', '103_03.jpg', '104_03.jpg', '105_03.jpg', '107_03.jpg', '108_03.jpg', '111_03.jpg',
'112_03.jpg', '113_03.jpg', '114_03.jpg', '115_03.jpg', '117_03.jpg', '118_03.jpg', '119_03.jpg', '120_03.jpg',
'121_03.jpg', '122_03.jpg', '123_03.jpg', '124_03.jpg', '125_03.jpg', '126_03.jpg', '127_03.jpg', '128_03.jpg',
'129_03.jpg', '130_03.jpg', '131_03.jpg', '132_03.jpg', '134_03.jpg', '135_03.jpg', '136_03.jpg', '137_03.jpg',
'138_03.jpg', '139_03.jpg', '140_03.jpg', '141_03.jpg', '142_03.jpg', '143_03.jpg', '144_03.jpg', '172_03.jpg',
'173_03.jpg'};
```

```
n = length(files); % n = 103
imagesize = size(imread(files(1))) % 100 x 75
m = imagesize(1) * imagesize(2) % 100 * 7500
platters 100x75 array into
7500x1 column vector
```

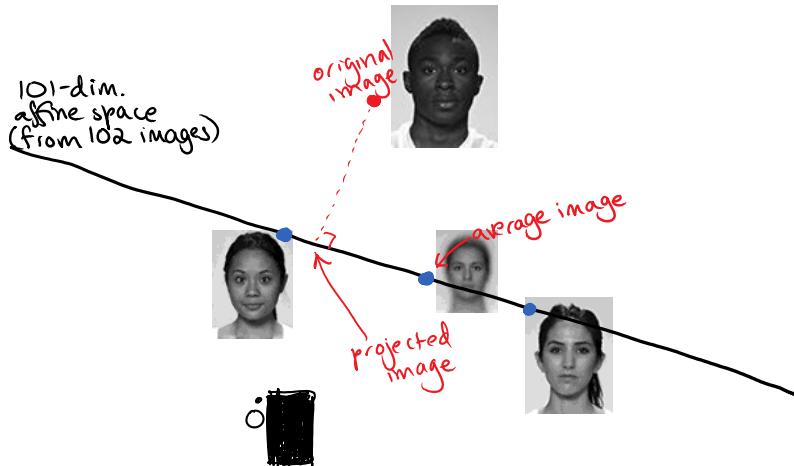
```

n = length(files); % n = 103
imagesize = size(imread(files[1])) % 100x 75
m = imagesize(1) * imagesize(2) % M = 7500

% platters 100x75 array into
% 7500x1 column vector
images = zeros(m,n);
for i=1:n % Remove a random image
    image = imread(files[i]);
    % pick a random image to remove
    randomindex = randi(n);
    randomimage = images(:,randomindex); % select and remove that image
    images(:,randomindex) = [];
    n = n - 1; % and decrement n
    imwrite(reshape(randomimage, imagesize(1), imagesize(2)/255, 'randomimage.png');

```

④ Project it onto the affine span of the others



```

% recenter about the mean image
meanimage = sum(images,2) / n; % sum(A,2) adds up the columns of A (i.e., the second dimension)
for i = 1:n
    images(:,i) = images(:,i) - meanimage;
end

O = orth(images); % size(O) is 7500x102
projectedimage = meanimage + O' * (O * (randomimage-meanimage));
imwrite(reshape(projectedimage, imagesize(1), imagesize(2)/255, 'projectedimage.png');

```

Idea: If faces form a low-dimensional affine subspace,
then the projection should be close to the original image.

Result:

