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function[NewEvents] = action3(event, log_file)

%suppose a node has these status:
% 0 - idle
% 1 - idle & just sent an RTS, waiting for CTS (for a potential transmitter)
% 2 - idle & just replied a CTS after receiving a RTS(for a potential receiver)
% 10 - primary sending
% 11 - primary sending and just replied a CTS3(OPPPCTS)
% 12 - primary sending and just replied a CTS(OPCTS)
% 20 - primary receiving
% 21 - primary receiving & just sent an RTSii(to another node)
% 22 - primary receiving & just sent an RTS(to its opposite node)
% 30 - secondary sending;
% 40 - secondary receiving;
% 50 - S-linking
%
%
%
%node(i,1) = x coordinate
%node(i,2) = y coordinate
%node(i,3) = power
%node(i,4) = state
%node(i,5) = k, where k is the node sending to this node.
%event =
%{
% ifdelete = {0,1};
% instant = t;
% node = i;
% pkt.rv = j;
% pkt.type = {unknown,rts,rtsii,cts,cts1,cts2,cts3,ctsn1,ctsn2,ctsn3,data,ack};
% pkt.id = new_id(i,j);

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% pkt.nav
% type = {.....};
%
%}

%event.pkt.type: unknown, rts, rtsii, jamming, cts, .....data, ack

global Event_list;
NewEvents = [];

if event.ifdelete == 1
    return;
end

switch event.type
case 'send_mac'
    t = event.instant;
    i = event.node;
    j = event.pkt.rv;
    event.pkt.id = new_id(i,j); % from i to j
    event.pkt.type = 'unknown'; %????????????????????
    event.pkt.nav = SIFS + cts_tx_time + SIFS + tx_time(event.pkt) + SIFS +
ack_tx_time;%????????????????????nav????????
    if ~isempty(mac_queue(i,j).list)|mac_status(i) %mac queue is not empty or
one pkt is being transmitted.
        mac_queue(i,j).list = [mac_queue(i,j).list; event];
    else %mac queue is already empty
        mac_status(i) = 1;
        newevent = event;
        newevent.instant = t;
        newevent.type = 'wait_for_channel';

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        newevent.node = i;
        NewEvents = [NewEvents; newevent];
        clear newevent;
    end
    %send mac is done: generate a new packet and put it into mac_queue or prepare
    to send it by "wait_for_channel".

    case 'wait_for_channel'
        t = event.instant;
        i = event.node;
        j = event.pkt.rv; %get the information of the packet that will be delivered.
        if node(i,4) == 0 & ifnav(i) == 0; %this node is idle & the sender is not keeping
an NAV
        %backoff
        if backoff_counter(i) > 0 %resume the backoff
            newevent = event;
            newevent.instant = t + slot_time;
            newevent.type = 'backoff';
            newevent.node = i;
            NewEvents = [NewEvents; newevent];
            clear newevent;
        else
            newevent = event;
            newevent.instant = t + DIFS;
            newevent.type = 'backoff_start';
            newevent.node = i;
            NewEvents = [NewEvents; newevent];
            clear newevent;
        end
        elseif node(i,4) == 20 & ifnav(i) == 0; %.....the sender is not keeping an
NAV, this node is receiving
            newevent = event;
            newevent.instant = t;

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        newevent.type
=
'send_phy'%????????????????????????????????????????????????????????????send directly
        if node(i,5) == j
            newevent.pkt.type = 'rts';
        else
            newevent.pkt.type = 'rtsii';
            newevent.node = i;
            NewEvents = [NewEvents; newevent];
            clear newevent;
        elseif ifnav(i) == 1
            newevent = event;
            newevent.instant
=
max(nav(i,:).end);%????????????????????????????????????????????need modifying
            newevent.type = 'wait_for_channel';
            newevent.node = i;
            %newevent.navnode = ?????????????????????????
            NewEvents = [NewEvents; newevent];
            clear newevent;
        end
        %wait_for_channel is done: if the node is idle and not keep an NAV, then backoff;
        if the node is receiving and not keeping an NAV, then 'send_phy' %immediately; if the
        node is keeping an NAV, then continue waiting until NAV is expired, or until an ACK
        invalidated the NAV.

        case 'send_jamming'
            t = event.instant;
            i = event.node;
            if node(i,5) ~= 0 %if some node is sending to this node
                for k = 1:n
                    if k == i | k == node(i,5) %except for this node and the sending node
                        continue;
                    else
                        if (node(k,4) == 1 | node(k,4) == 2 | node(k,4) == 21 | node(k,4)

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== 22) & sig_detect(k,i)
    newevent = event;
    newevent.instant = t + signature_time*3;
    newevent.node = k;
    newevent.type = 'abort_transmission';
    NewEvents = [NewEvents, newevent];
    clear newevent;
    else (node(k,4) == 20 | node(k,4) == 21 | node(k,4) == 22 |
node(k,4) == 30 | node(k,4) == 40 | node(k,5) == 50) & sig_detect(k,i)
        delay_rcv(k, 7.5);
    end
end
end
end
%send_jamming is done: for each node hearing the jamming signal, if it is about to
send, it will "abort_transmission". If it is receiving, it will delay the reception.

case 'abort_transmission'
    t = event.instant;
    i = event.node;
    j = event.pkt.rv;
    %search the transmission events and delete them from the Event_list, i.e.,
send_phy_finish, and change the node status.
    for i = 1:length(Event_list)
        if node == Event_list(i).node & strcmp(event_type,
Event_list(i).type)%.....
            %here: node of different status should delete different event_type. Need to
modify it.
            Event_list(i).ifdelete = 1;
        end
    end
    if node(i,4) == 1 | node(i,4) == 2
        node(i,4) = 0;
    elseif node(i,4) == 21 | node(i,4) == 22

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        node(i,4) = 20;
    end

case 'backoff_start' %after DIFS
    t = event.instant;
    i = event.node;
    j = event.pkt.rv;
    if node(i,4) == 0 & ifnav(i) == 0
        backoff_attempt(i) = 0;
        temp = min(backoff_attempt(i) + CW_min, CW_max);
        backoff_counter(i) = floor((2^temp - 1)*rand);
        newevent = event;
        newevent.instant = t + slot_time;
        newevent.type = 'backoff';
        newevent.node = i;
        NewEvents = [NewEvents, newevent];
        clear newevent;
    else
        newevent = event;
        newevent.instant = t;
        newevent.type = 'wait_for_channel';
        newevent.node = i;
        NewEvents = [NewEvents, newevent];
        clear newevent;
    end
    %backoff_start is done: if node is idle and not keeping NAV, then start...; else wait
for channel again.

case 'backoff'
    t = event.instant;
    i = event.node;
    j = event.pkt.rv;
    if node(i,4) == 0 & ifnav(i) == 0

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if backoff_counter(i) > 1;
    backoff_counter(i) = backoff_counter(i) - 1;
    newevent = event;
    newevent.instant = t + slot_time;
    newevent.type = 'backoff';
    newevent.node = i;
    NewEvents = [NewEvents; newevent];
    clear newevent;
else %ready to send the packet
    backoff_counter(i) = 0; %reset counter for next use
    *****?
    newevent = event;
    newevent.instant = t;
    newevent.type = 'send_phy';
    newevent.pkt.type = 'rts';
    newevent.node = i;
    NewEvents = [NewEvents; newevent];
    clear newevent;
else %ifnav(i) becomes TRUE.
    if backoff_counter(i) > 1
        backoff_counter(i) = backoff_counter(i) - 1;
    else
        %start a new backoff counter when count-down is zero
        backoff_attempt(i) = backoff_attempt(i) + 1;
        temp = min(backoff_attempt(i)+CW_min, CW_max);
        backoff_counter(i) = floor((2^temp - 1)*rand);
    end
    newevent = event;
    newevent.instant = t;
    newevent.type = 'wait_for_channel';
    newevent.node = i;
    NewEvents = [NewEvents; newevent];
    clear newevent;

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end
%backoff is NOT DONE: if the node is idle and not keeping NAVs, then continue
backoff. Else, .....

case 'send_phy' %assume the packet type has been set.
    t = event.instant;
    i = event.node;
    j = event.pkt.rv;
    node(i,3) = event.pkt.power;
    if event.pkt.type == 'data'
        %txtime
        = %*****check table
    else
        txtime = tx_time(event.pkt);
    end
    if node(i,4) == 0 & ifnav(i) == 0 %idle and no nav
        if strcmp(event.pkt.type, 'rts')
            node(i,4) = 1;
        elseif strcmp(event.pkt.type, 'cts')
            node(i,4) = 2;
        end
    elseif node(i,4) == 10 & ifnav(i) == 0
        if strcmp(event.pkt.type, 'cts3')
            node(i,4) = 11;
        elseif strcmp(event.pkt.type, 'cts')
            node(i,4) = 50;
        end
    elseif node(i,4) == 20 & ifnav(i) == 0
        if strcmp(event.pkt.type, 'rtsii')
            node(i,4) = 21;
        elseif strcmp(event.pkt.type, 'rts')
            node(i,4) = 22;
        end
    end
end

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        newevent.node = i;
        NewEvents = [NewEvents; newevent]; clear newevent;
        pending_id(i) = event.pkt.id;
    end
end

case 'recv_phy'
    t = event.instant;
    i = event.pkt.tx;
    j = event.node;
    %node(j,4) = 0;
    if node(j,4) == 0
        [pr snr] = recv_phy(i,j,rmodel);
        t1 = rv_threshold_delta;
        if snr >= (rv_threshold + t1);
            probability_receive = 1;
        elseif snr < (rv_threshold - t1);
            probability_receive = 0;
        elseif rand <= (snr-(threshold-t1))/(t1+t1)
            probability_receive = 1;
        else
            probability_receive = 0;
        end
        if probability_receive
            if event.pkt.rv == j      %broadcast or unicast to j
                newevent = event;
                newevent.instant = t;
                newevent.type = 'recv_mac';
                newevent.node = j;
                NewEvents = [NewEvents; newevent];
                clear newevent;
            elseif event.pkt.nav > 0 % this packet is not for j, but use its
nav.....改.....

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        if nav(i,j).start < t
            nav(i,j).start = t;
        end
        if nav(i,j).end < (t + event.pkt.nav)
            nav(i,j).end = t + event.pkt.nav;
        end
    end
end

case 'recv_mac'
    t = event.instant;
    i = event.pkt.tx;
    j = event.node;
    %if adebug, disp(['recv_mac @ node ' num2str(j)]); end
    %if event.pkt.rv == 0 & strcmp(event.pkt.type, 'data') == 0
        % broadcast but not data packet
        %    error(['recv_mac: node ' num2str(j) ' receives a broadcast packet with a
wrong type: ' event.pkt.type]);
    %end
    %if j == i
        %    % I myself sent this packet, no action
        %    return;
    %end
    switch event.pkt.type
        case 'rts'
            if node(j,4) == 0 & ifnav(j) == 0 & %.....(有给 i 的包)
                % send back a CTS with two Omega & one P(t), attempting for
full-duplex

                newevent = event;
                newevent.instant = t + SIFS + 3*%.....;
                newevent.type = 'send_phy';
                newevent.node = j;
            end
        end
    end
end

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full-duplex

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% keep the data size, rate, and id as RTS packet
newevent.pkt.type = 'cts';
newevent.pkt.tx=j;
newevent.pkt.rv=i;
newevent.pkt.nav=event.pkt.nav - SIFS - cts_tx_time;
NewEvents = [NewEvents; newevent]; clear newevent;
elseif node(j,4) == 0 & ifnav(j) == 0 & %.....(没有给 i 的包)
    % send back a CTS with one Omega & two P(t), attempting for

    newevent = event;
    newevent.instant = t + SIFS + 3*%.....;
    newevent.type = 'send_phy';
    newevent.node = j;
    % keep the data size, rate, and id as RTS packet
    newevent.pkt.type = 'cts';
    newevent.pkt.tx=j;
    newevent.pkt.rv=i;
    newevent.pkt.nav=event.pkt.nav - SIFS - cts_tx_time;
    NewEvents = [NewEvents; newevent]; clear newevent;

elseif node(j,4) == 0 & ifnav(j) ~= 0
    % send back a CTS with two Omega & one P(t), always
    attempting for full-duplex.
    newevent = event;
    newevent.instant = t + SIFS + 3*%.....;
    newevent.type = 'send_phy';
    newevent.node = j;
    % keep the data size, rate, and id as RTS packet
    newevent.pkt.type = 'cts';
    newevent.pkt.tx=j;
    newevent.pkt.rv=i;
    newevent.pkt.nav=event.pkt.nav - SIFS - cts_tx_time;
    NewEvents = [NewEvents; newevent]; clear newevent;
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elseif node(j,4) == 1
    %send back a CTS with one Omega & three P(t), transit to
    secondary transmitting mode
    newevent = event;
    newevent.instant = t + SIFS + 4*%.....;
    newevent.type = 'send_phy';
    newevent.node = j;
    % keep the data size, rate, and id as RTS packet
    newevent.pkt.type = 'cts';
    newevent.pkt.tx=j;
    newevent.pkt.rv=i;
    newevent.pkt.nav=event.pkt.nav - SIFS - cts_tx_time;
    NewEvents = [NewEvents; newevent]; clear newevent;

    %search the sending packet event and change its
    time.*****

end

case 'rtsii'
    if node(j,4) == 0
        %send back a CTS with one Omega and one P(t)
        newevent = event;
        newevent.instant = t + SIFS + 2*%.....;
        newevent.type = 'send_phy';
        newevent.node = j;
        % keep the data size, rate, and id as RTS packet
        newevent.pkt.type = 'cts';
        newevent.pkt.tx=j;
        newevent.pkt.rv=i;
        newevent.pkt.nav=event.pkt.nav - SIFS - cts_tx_time;
        NewEvents = [NewEvents; newevent]; clear newevent;
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case 'data'
    % should check that this is not a duplicated or out-of-order packet
    if event.pkt.rv ~= 0    % send ACK if not broadcast
        % send back an ACK
        newevent = event;
        newevent.instant = t + SIFS;
        newevent.type = 'send_phy';
        newevent.node = j;
        % keep the data size, rate, and id the same as DATA packet
        newevent.pkt.type = 'ack';
        newevent.pkt.tx=j;
        newevent.pkt.rv=i;
        newevent.pkt.nav=0; % not necessary because CTS already did
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        NewEvents = [NewEvents; newevent]; clear newevent;
    end
    % send data up to network layer
    newevent = event;
    % Make sure the ACK is sent out before processing this data packet

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% the upper layers because the upper layers may immediately
% send more packets upon receiving this data packet.
if event.pkt.rv ~= 0,
    newevent.instant = t + SIFS + ack_tx_time + 2*eps;
else
    newevent.instant = t + 2*eps;
end
newevent.type = 'recv_net';
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case 'ctsf'
    if .....exposed    node    和    不    exposed    的    区
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        newevent.node = j;
        NewEvents = [NewEvents; newevent]; clear newevent;
    case
'ack' %*****导致 event list
需要更新

        % make sure the acknowledged packet is the just sent DATA packet
        if pending_id(j) ~= event.pkt.id
            if ddebug, disp(['the received ACK id=' num2str(event.pkt.id) '
does not match the pending DATA id=' num2str(pending_id(j))]); end
            % probably this is a duplicated ACK (same reason as the above
CTS case)

            return;
        end
        % remove pending id for DATA
        pending_id(j) = 0;
        retransmit(j) = 0;
        if ~isempty(mac_queue(j).list)
            % more packets are waiting to be sent
            % newevent.instant = t + turnaround_time; % switch from
receive to transmit

            % if ddebug, disp('recv_mac: after receiving ACK, take the next
packet from mac_queue'); end
            mac_status(j) = 1;
            newevent = mac_queue(j).list(1);
            mac_queue(j).list(1) = [];
            newevent.instant = t + cca_time;
            newevent.type = 'wait_for_channel';
            newevent.node = j;
            % the packet setup is already done in 'send_mac'
            NewEvents = [NewEvents; newevent]; clear newevent;
        else
            mac_status(j) = 0;
        end
    end

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        otherwise
            disp(['recv_mac: Undefined mac packet type: ' event.pkt.type]);
        end

    case 'timeout_rts'
        t = event.instant;
        i = event.node;
        j = event.pkt.rv;
        if adebug, disp(['timeout_rts @ node ' num2str(i)]); end
        if pending_id(i) == event.pkt.id % not acknowledged yet, retransmit
            if cdebug, disp(['timeout_rts: node ' num2str(i) ' pending_id='
num2str(pending_id(i)) ' event_id=' num2str(event.pkt.id)]); end
            retransmit(i) = retransmit(i) + 1;
            if retransmit(i) > max_retries
                % so many retries, drop the packet
                if cdebug, disp(['timeout_rts: node ' num2str(i) ' has retried so
many times to transmit RTS']); end
                retransmit(i) = 0;
                pending_id(i) = 0;
                % question: what if there are waiting packets in mac_queue?
                % answer: should send them anyway as if the current packet is
done.

                % similar to the the operation when ACK is received
                if ~isempty(mac_queue(i).list)
                    % more packets are waiting to be sent
                    % newevent.instant = t + turnaround_time; % switch from
receive to transmit

                    mac_status(i) = 1;
                    newevent = mac_queue(i).list(1);
                    mac_queue(i).list(1) = [];
                    newevent.instant = t + cca_time;    % question: cca_time or

                    other

                    newevent.type = 'wait_for_channel';
                end
            end
        end
    end

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        newevent.node = i;
        % packet setup is already done in 'send_mac' before put into
the mac_queue
        NewEvents = [NewEvents; newevent]; clear newevent;
    else
        % cannot send RTS successfully, reset MAC layer
        mac_status(i) = 0;
    end
    return;
end
if adebug, disp(['timeout_rts: node ' num2str(i) ' to retransmit RTS']);

% retransmit the RTS
newevent = event;
newevent.instant = t + cca_time;    % check channel status
newevent.type = 'wait_for_channel';
newevent.node = i;
NewEvents = [NewEvents; newevent]; clear newevent;
else
    % if pending_id(i) ~= 0 & ddebug, disp(['timeout_rts at node ' num2str(i)
' pending id=' num2str(pending_id(i)) ' does not match the waiting RTS id='
num2str(event.pkt.id)]); end
    end
    case 'timeout_data'
        t = event.instant;
        i = event.node;
        j = event.pkt.rv;
        if adebug, disp(['timeout_data @ node ' num2str(i)]); end
%         if pending_id(i) == event.pkt.id % not acknowledged yet
%         if adebug, disp(['timeout_data: node ' num2str(i) ' failed to transmit
DATA, go back to transmit RTS']); end
%         % remove the pending id for DATA
%         pending_id(i) = 0;

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%         retransmit(i) = 0;
%         % go back to send RTS
%         newevent = event;
%         newevent.instant = t + cca_time;    % check channel status
%         newevent.type = 'wait_for_channel';
%         newevent.node = i;
%         newevent.pkt.type = 'data';
%         newevent.pkt.nav = SIFS + cts_tx_time + SIFS + tx_time(newevent.pkt)
+ SIFS + ack_tx_time;
%         newevent.pkt.type = 'rts';
%         % create a new id for the new RTS
%         newevent.pkt.id = new_id(i);
%         NewEvents = [NewEvents; newevent]; clear newevent;
%         end
        if pending_id(i) == event.pkt.id % not acknowledged yet
            if cdebug, disp(['timeout_data: node ' num2str(i) ' pending_id='
num2str(pending_id(i)) ' event_id=' num2str(event.pkt.id)]); end
            retransmit(i) = retransmit(i) + 1;
            if retransmit(i) > max_retries
                % so many retries, drop the data packet
                if cdebug, disp(['timeout_data: node ' num2str(i) ' has retried so
many times to transmit DATA']); end
                retransmit(i) = 0;
                pending_id(i) = 0;
                if ~isempty(mac_queue(i).list)
                    % more packets are waiting to be sent
                    mac_status(i) = 1;
                    newevent = mac_queue(i).list(1);
                    mac_queue(i).list(1) = [];
                    newevent.instant = t + cca_time;    % question: cca_time or
other
                    newevent.type = 'wait_for_channel';
                    newevent.node = i;

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        NewEvents = [NewEvents; newevent]; clear newevent;
    else
        % Cannot send DATA successfully, reset MAC layer
        mac_status(i) = 0;
    end
    return;
end
if adebug, disp(['timeout_data: node ' num2str(i) ' to retransmit DATA']);
end

% retransmit the DATA
newevent = event;
newevent.instant = t + cca_time;    % check channel status
newevent.type = 'wait_for_channel';
newevent.node = i;
% newevent.pkt.type = 'data';
newevent.pkt.nav = SIFS + ack_tx_time; % necessary for retransmission
because the initial DATA has NAV=0
    NewEvents = [NewEvents; newevent]; clear newevent;
end

case 'send_phy_finish'

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