# Augmented Annotations

Final Presentation



Augmented Annotations (AA) is a 3D data capture utility on iOS. Users scan their environment while simultaneously annotating objects with labeled bounding boxes.



# Introduction



#### **Motivation**

- 3D data annotation is a slow, tedious process
- Efficient solutions require infrastructure
  - Mechanical Turk
  - Undergrads
- Huge, unspoken time sink in research
- Expensive to make custom datasets

| Dataset   | Bounding<br>Boxes |  |  |
|-----------|-------------------|--|--|
| SUN RGB-D | 64,595            |  |  |
| KITTI     | 80,256            |  |  |



## **Key insight**

- Realtime SLAM accuracy >= human accuracy
- Scanning has been commodified
  - Cheaper, portable sensors
  - Augmented reality (AR)



AR application mock-up



Intel Realsense D435



#### **Our solution**

- Consolidate scanning and annotation processes
- Platform: iOS device (iPad)
- Scan with Occipital's Structure Sensor
- Add/edit bounding boxes as AR objects



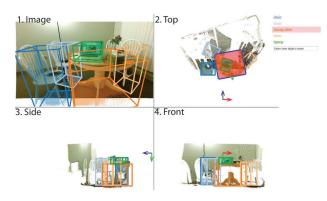
Structure sensor mounted on an iPad

# **Related Works**



#### **Traditional methods**

- Digital annotation software + outsourced labor
  - Mechanical Turk, oDesk
- Downsides
  - Infrastructure requirement
  - User training requirement
  - Quality-assurance difficult



Screenshots from SUN RGB-D's annotation tool



## **Augmented reality**

- Main workflow: placing localized objects in the world
- Heavy reliance on real-time SLAM
  - Scans are immediately discarded



Popular mobile AR libraries



Example of localized object placement



# Augmented reality meets computer vision



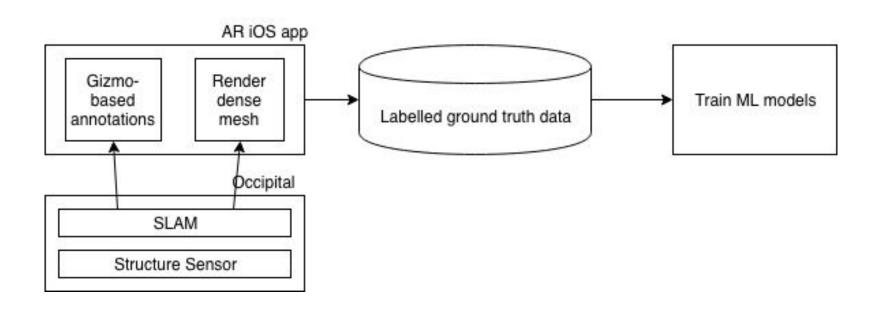
Real scene augmented with synthetic cars (Ours)

Popular mobile AR libraries

# **Methods**



## **Architecture**





# Scanning

## Occipital Structure Sensor

Developed by Occipital Inc. in collaboration with Prime Sense

| Parameter or specifications | Value or description                               |  |  |
|-----------------------------|--|--|--|
| Length×Width×Height         | 119.2 mm × 27.9 mm × 29.0 mm                       |  |  |
| Min/Max sensing distance    | 40/350 cm  |  |  |
| Resolution for depth data   | VGA (640×480) QVGA (320×240)                       |  |  |
| Frame rate                  | 30/60 fps  |  |  |
| Power source                | USB charged battery with 3–4 h of active sensing   |  |  |
| Data transfer               | Wi-Fi/USB  |  |  |
| Field of view               | 58° Horizontal and 45° Vertical stand-<br>ard lens |  |  |
| System on a chip (SOC)      | Prime Sense chip (Heindl 2014)                     |  |  |



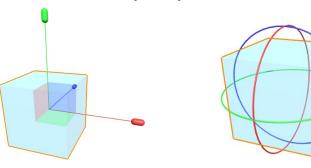


## **Annotation: 3D bounding boxes**

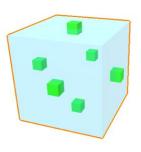
- Gizmos: touch-and-drag control modules
- Based off of industry 3D manipulation tools

Rotate tool

Unity, Maya, etc.



Position tool

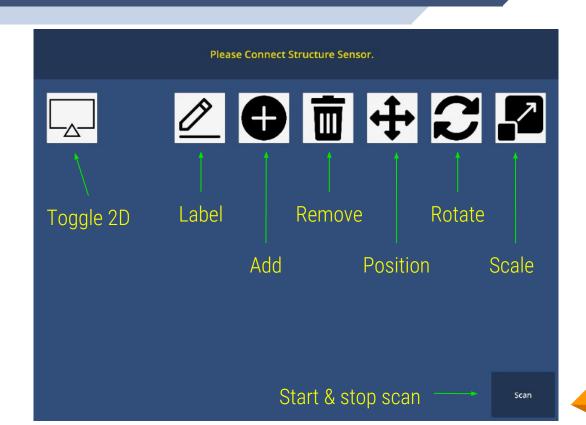


Scale tool

| Functionality |  |
|---------------|--|
| Add           |  |
| Remove        |  |
| Position      |  |
| Rotate        |  |
| Scale         |  |
| Label         |  |

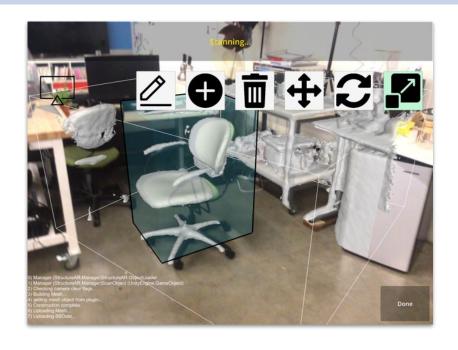


#### **Annotation: user interface**





## **Annotation: example usage**

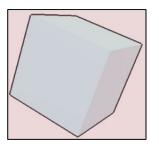


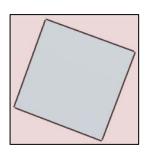


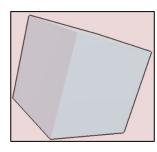


#### **Annotation: 2D bounding boxes**

- Can project 3D  $\rightarrow$  2D bounding box for any perspective
  - Pro: High convenience / speed of producing data
  - ▶ **Con**: 2D bounding boxes larger than necessary





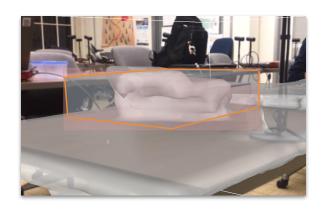


2D bounding boxes at different perspectives

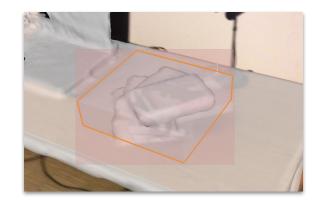


# **Annotation: 2D bounding boxes**

■ Different perspectives → different 2D bounds





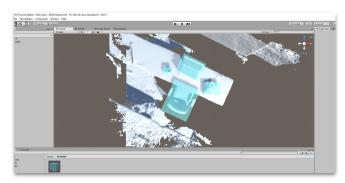


# Results



#### **Comparison with SUN RGB-D**

- Conducted trials comparing SUN RGB-D's method to our app
- Recorded time to completion
- Task: create and label bounding boxes over 4 objects



Unity editor, used for desktop trials



Physical setup for scanning



#### **User feedback**

#### Pros

- Intuitive task and control scheme
- Easy to view boxes from different perspectives

#### Cons

- Require lots of physical movement
- Gizmo controls occasionally unwieldy/unstable



Example output from our app



# **Comparison with SUN RGB-D**

| Trial       | 1    | 2    | 3    | Average |
|-------------|------|------|------|---------|
| SUN RGB-D S | 0:46 | 0:46 | 0:46 |         |
| SUN RGB-D A | 4:20 | 4:04 | 4:57 | 5:13    |
| AAS+A       | 2:58 | 3:23 | 4:05 | 3:28    |

S: Scanning

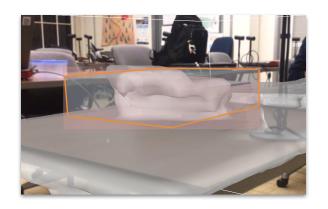
A: Annotation

33.5% reduction in time!

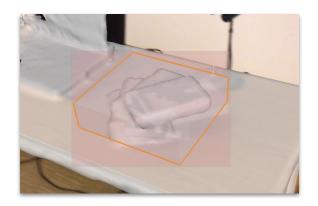


# Annotation: 2D bounding boxes

Dramatically faster for 2D bounding boxes!







# Conclusion



#### **Summary**

- Developed an application to combine the scanning and annotation processes of 3D data collection
- Conducted user studies on the effectiveness of our method
- Shown to be faster than desktop-based annotation systems



#### **Future work**

- Intelligent bounding box placement
  - Applying corrections faster than starting from scratch
- Smoothing out user experience
- Applying same strategy to other annotation types
  - Semantic segmentation