GOA COLLEGE OF ENGINEERING FARMAGUDI, GOA

DEPARTMENT OF ELECTRONICS & TELECOMMUNICATION ENGINEERING

2016 - 2017



HUMAN IDENTIFICATION USING GAIT RECOGNITION

by

Azfar Khoja (P.R.No.: 201305838) John George (P.R.No.: 201305821) Mrinal Shinde(P.R.No.: 201305759) Neviya Prakash (P.R.No.: 201305942)

A project submitted in partrial fulfilment of the requirements for the degree of Bachelor of Engineering

in

Electronics and Telecommunication Engineering GOA UNIVERSITY

under the guidance of

Prof. MILIND FERNANDES

Assistant Professor,

Electronics & Telecommunication Department Goa College of Engineering

CERTIFICATE

This is to certify that the project entitled

"HUMAN IDENTIFICATION USING GAIT RECOGNITION"

submitted by

Azfar Khoja P.R. No.: 201305838

	John George	P.R. No.: 201305821		
	Mrinal Shinde	P.R. No.: 201305759		
	Neviya Prakash	P.R. No.: 201305942		
has been successfully	completed in the ac	ademic year 2016-2017 as a partial fulfilment of		
· ·	_	ELOR OF ENGINEERING in Electronics and		
-		follege of Engineering, Farmagudi.		
	r	3 2 3 3 4 3		
(Internal Examiner)		(External Examiner)		
Place: Farmagudi, Po	onda, Goa			
Date:				

PROJECT APPROVAL SHEET



The project entitled

"HUMAN IDENTIFICATION USING GAIT RECOGNITION"

by

 Azfar Khoja
 P.R. No.: 201305838

 John George
 P.R. No.: 201305821

 Mrinal Shinde
 P.R. No.: 201305759

 Neviya Prakash
 P.R. No.: 201305942

completed in the year 2016-2017 is approved as a partial fulfilment of the requirements for the degree of **BACHELOR OF ENGINEERING** in **Electronics and Telecommunication Engineering** and is a record of bonafide work carried out successfully under our guidance.

(Project Guide)
Milind Fernandes
Assistant Professor,
ETC Dept.

(Head of Department)
Dr. H. G. Virani
Professor, ETC Dept.

(Principal)
Dr. V. N. Shet
Goa College of Engineering

Place: Farmagudi, Ponda, Goa

Date:

Acknowledgement

The success of our work is incomplete unless we mention the names of our respected taechers who made it possible, whose guidance and encouragement served to beacon light and crowned our efforts with success.

Next paragraph

Next paragraph

Contents

1	Intr	Introduction					
	1.1	Preamble	1				
	1.2	Motivation	2				
	1.3	Objective	2				
2	Lite	Literature Review					
	2.1	Introduction	4				
		2.1.1 This is a sub section	4				
	2.2	Conclusion	5				
		2.2.1 This is a sub section	5				
3 Design/Implementation(whichever applicable)							
	3.1	Problem Statement	6				
		3.1.1 This is a sub section	6				
4	Sys	em Analysis					
	4.1	Observations	9				
		4.1.1 This is a sub section	9				
	4.2	Results	9				
	4.3	Discussion	10				
5	Cor	nclusion	11				
	5.1	General Conclusion	11				
		5.1.1 This is a sub section	11				
	5.9	Challenges	11				

5.3 Future Work	. 12
Appendices	15
A Appendix	16
B Data Sheets	18

List of Figures

List of Tables

Abstract

In recent years, biometric recognition and authentication has attracted a significant attention due to its potential applicability in social security, surveillance systems, forensics, law enforcement, and access control. A biometric system can be defined as a pattern-recognition system that can recognize individuals based on the characteristics of their physiology or behaviour. One biometric technique for unintrusive identification is gait recognition which basically identifies people by the way they walk. In former work, gait recognition is mainly achieved with camera systems. In this study, we present an approach for gait recognition using Microsoft Kinect V2, a peripheral for the gaming console XBOX One, which provides us with marker less tracking of human motion in real time. We extract and evaluate a number of static and kinematic features and present the results of various classification algorithms for person identification.

Chapter 1

Introduction

Compared to other biometric features such as the iris and fingerprint. Gait has some inherent advantages 1) Perceivable at a distance, on-contact, non-invasive 2) Doesnt require user cooperation 3) Gives fairly accurate readings under low light conditions. Also disguising, hiding ones gait or imitating some other persons gait is practically impossible. As a result it has fascinated several security-sensitive environments such as classified research and nuclear labs, military, banks etc. Gait recognition is particularly useful in crime scenes where other biometric traits (such as face or fingerprint) might be obscured intentionally.

Two common categories of gait recognition are appearance-based and model-based approaches. Among the two, the appearance-based approaches suffer from changes in the appearance owing to the change of the viewing or walking directions. Model based ones are view and scale invariant and reflect in the kinematic characteristics of walking manner. In this study we present a model based approach using the Microsoft Kinect sensor which offers us a 3D model of the human skeleton with capability to track up to 25 joints of the human

body.

1.1 Motivation

The initial motivation to build a gait recognition system developed after watching the Gait Analysis scene in the movie Mission Impossible Rogue Nation (2015) where it was used for authentication for security purposes. Although at that time it felt as a futuristic technology, through research we realised that existing gait recognition approaches mostly use standard video cameras for capturing and recording the movement of walking persons. Here, the main difficulty lies in the extraction of characteristic features that can be used for identification. The challenges of existing gait recognition system and the possibilities Kinect offers lead to the assumption that the problem of gait recognition could be simplified using the Kinect sensor.

1.2 Proposed Idea

In this paper we propose a skeleton model based approach (provided by Microsoft Kinect Sensor) for gait recognition and person identification. Our system consists of three components: The first component records the skeletal data offered by Kinect using the SDK provided by Microsoft. The second component processes on this data using MATLAB for feature extraction. Finally we use different classification algorithms available in MATLAB Classification Toolbox to identify a person using previously recorded training data and compare their performance and accuracy. This is a prototypic implementation of a gait recognition

system, where we evaluate the possibilities of gait recognition using the Microsoft Kinect.

Chapter 2

Literature Review

2.1 Introduction

Hey you!! Trying if the header and footer works for the second chapter

2.1.1 This is a sub section

Yes, true, It is indeed a subsection.

will be trying now to continue this chapter to the next page to see if the header and footer appear there on the second page too.

Hey this is supposed to be the next page. See if header and footer are there.

Please feel free to add intermediate sections according to your project requirement.

2.2 Conclusion

Trying if the header and footer works for the second chapter

2.2.1 This is a sub section

Yes, true, It is indeed a subsection.

Chapter 3

Design/Implementation(whichever applicable)

3.1 Problem Statement

This is the first section of the third chapter.

3.1.1 This is a sub section

Yes, true, It is indeed a subsection.

will be trying now to continue this chapter to the next page to see if the header and footer appear there on the second page too.

Please feel free to add intermediate sections according to your project require-

ment. Work done: Block diagram, design(software, hardware), Implementation

Hey this is supposed to be the next page. See if header and footer are there.

Chapter 4

System Analysis

4.1 Observations

This is the first section of the fourth chapter.

4.1.1 This is a sub section

will be trying now to continue this chapter to the next page to see if the header and footer appear there on the second page too.

4.2 Results

This is the second section of the fourth chapter.

4.3 Discussion

This is the third section of the fourth chapter.

Chapter 5

Conclusion

5.1 General Conclusion

This is the first section of the fifth chapter.

5.1.1 This is a sub section

will be trying now to continue this chapter to the next page to see if the header and footer appear there on the second page too.

5.2 Challenges

This is the second section of the fifth chapter.

5.3 Future Work

This is the third section of the fifth chapter.

Bibliography

- [1] Kenneth J. W. Taylor, Peter N. Burns, Peter N. T. Wells. Clinical Applications of Doppler Ultrasound Second Edition, pages 1-3.
- [2] http://www.genesis-ultrasound.com/history-of-ultrasound.html
- $[3] \ https://wiki.engr.illinois.edu/display/BIOE414/History+of+Color+Doppler+Ultrasound for the color of t$
- [4] William R. Hendee and E. Russell Ritenour. Medical Imaging Physics, Fourth Edition, pages 344 - 346, 2002.

second page of bibliography

Appendices

Appendix A

Appendix

First page of Appendix A

Second page of Appendix A.

Appendix B

Data Sheets

Put your data sheets here.

second page of Appendix B.