Module Interface Specification for 4TB6 - Mechatronics Capstone

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1 Revision History

Date	**Version**	**Notes**
Date 1	1.0	Notes
Date 2	1.1	Notes

2 Symbols, Abbreviations and Acronyms

See SRS Documentation here.

Contents

3 Introduction

The following document details the Module Interface Specifications for SmartLock, a bluetooth-driven bike lock brough to you by the Locked & Loaded team. The SmartLock allows users to unlock their bike remotely using Bluetooth.

Complementary documents include the System Requirement Specifications and Module Guide. The full documentation and implementation can be found in the GitHub repo.

4 Notation

[You should describe your notation. You can use what is below as a starting point. —SS]

The structure of the MIS for modules comes from Hoffman and Strooper (1995), with the addition that template modules have been adapted from Ghezzi et al. (2003). The mathematical notation comes from Chapter 3 of Hoffman and Strooper (1995). For instance, the symbol := is used for a multiple assignment statement and conditional rules follow the form $(c_1 \Rightarrow r_1 | c_2 \Rightarrow r_2 | ... | c_n \Rightarrow r_n)$.

The following table summarizes the primitive data types used by 4TB6 - Mechatronics Capstone.

Data Type	**Notation**	**Description**
character	char	a single symbol or digit
integer	$\mathbb{Z}$	a number without a fractional component in (-∞, ∞)
natural number	$\mathbb{N}$	a number without a fractional component in [1, ∞)
real	$\mathbb{R}$	any number in (-∞, ∞)

The specification of 4TB6 - Mechatronics Capstone uses some derived data types: sequences, strings, and tuples. Sequences are lists filled with elements of the same data type. Strings are sequences of characters. Tuples contain a list of values, potentially of different types. In addition, 4TB6 - Mechatronics Capstone uses functions, which are defined by the data types of their inputs and outputs. Local functions are described by giving their type signature followed by their specification.

5 Module Decomposition

The following table is taken directly from the Module Guide document for this project.

Level 1	**Level 2**
Hardware-Hiding Module	
Behaviour-Hiding Module	Input Parameters Module Output Parameters Module Engage Status Signal Module Disengage Signal Module Battery Status Module Location Module Lock Frame Module
Software Decision Module	Load Power Signal Module Battery Module Electromagnet Module Locking Mechanism Module

Table 1: Module Hierarchy

6 MIS of [Module Name —SS]

[Use labels for cross-referencing —SS]

[You can reference SRS labels, such as R**??**. —SS]

[It is also possible to use LaTeXfor hypperlinks to external documents. —SS]

6.1 Module

[Short name for the module —SS]

6.2 Uses

6.3 Syntax

6.3.1 Exported Constants

6.3.2 Exported Access Programs

Name	In	Out	Exceptions
[accessProg —SS]	-	-	-

6.4 Semantics

6.4.1 State Variables

[Not all modules will have state variables. State variables give the module a memory. —SS]

6.4.2 Environment Variables

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

6.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

6.4.4 Access Routine Semantics

[accessProg —SS]():

- inputs:
- transition: [if appropriate —SS]

- output: [if appropriate —SS]
- exception: [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

6.4.5 Local Functions

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

7 MIS of M4

7.1 Engage Status Signal Module

As described in the MG document, the Engage Status Signal Module (M4) is responsible for trasmitting the engagement status of the lock from the Arduino to the mobile app.

7.2 Uses

7.3 Syntax

7.3.1 Exported Constants

N/A

7.3.2 Exported Access Programs

N/A

7.4 Semantics

7.4.1 State Variables

[Not all modules will have state variables. State variables give the module a memory. —SS]

7.4.2 Environment Variables

[This section is not necessary for all modules. Its purpose is to capture when the module has external interaction with the environment, such as for a device driver, screen interface, keyboard, file, etc. —SS]

7.4.3 Assumptions

[Try to minimize assumptions and anticipate programmer errors via exceptions, but for practical purposes assumptions are sometimes appropriate. —SS]

7.4.4 Access Routine Semantics

[accessProg —SS]():

- : inputs
- transition: [if appropriate —SS]
- output: [if appropriate —SS]
- exception: [if appropriate —SS]

[A module without environment variables or state variables is unlikely to have a state transition. In this case a state transition can only occur if the module is changing the state of another module. —SS]

[Modules rarely have both a transition and an output. In most cases you will have one or the other. —SS]

7.4.5 Local Functions

[As appropriate —SS] [These functions are for the purpose of specification. They are not necessarily something that is going to be implemented explicitly. Even if they are implemented, they are not exported; they only have local scope. —SS]

8 MIS of M5

8.1 Disengage Signal Module

As described in the MG document, the Disengage Signal Module (M5) is responsible for transmitting the signal to disengage the lock from the mobile app to the arduino on the mobile app implementation, and recieving the signal to disengage the lock from the Arduino implementation end.

8.2 Uses

8.3 Syntax

8.3.1 Exported Constants

N/A

8.3.2 Exported Access Programs

N/A

8.4 Semantics

8.4.1 State Variables

[Not all modules will have state variables. State variables give the module a memory. —SS]

8.4.2 Environment Variables

- e_BTService, type: BLEService
- e_DisengageCharacteristic; type: BLEByteCharacteristic

8.4.3 Assumptions

- Arduino is powered on

8.4.4 Access Routine Semantics

BTconnect():

This routine creates a BlueTooth connection between the mobile app and the Arduino so that they can send and receive signals from each other. This routine will need an implementation both for the Arduino, and for the mobile app, where the Arduino will act as the peripheral device, and the mobile app will act as the central device.

- inputs: none
- transition: BTconnected() upon successful connection
- output: none
- exception: connection status will appear on the mobile app. Therefore, the user will be aware of the connection status, whether that be successful or unsuccessful.

8.4.5 Local Functions

none

9 MIS of M7

9.1 Load Power Signal Module

As described in the MG document, the Load Power Signal Module (M7) is responsible for sending a high power/ON signal to the transistor once a disengage signal is written to the Arduino. An ON signal to the transistor acts as a switch ON, and will power the electromagnet to disengage the lock.

9.2 Uses

9.3 Syntax

9.3.1 Exported Constants

N/A

9.3.2 Exported Access Programs

N/A

9.4 Semantics

9.4.1 State Variables

[Not all modules will have state variables. State variables give the module a memory. —SS]

9.4.2 Environment Variables

- e_BTService, type: BLEService
- e_DisengageCharacteristic; type: BLEByteCharacteristic

Note that the environment variables are the same as that of M5, as an established Bluetooth connection is a prerequisite of M7, and these variables must still be used to keep the BlueTooth connection active.

9.4.3 Assumptions

None.

9.4.4 Access Routine Semantics

loadPower():

- inputs: e_DisengageCharacteristic

- transition: none
- output: if e_DisengageCharacteristic has a nonzero value (i.e., the disengage button on the app GUI is pressed), write a HIGH signal to the Arduino pin wired to the corresponding transistor terminal
- exception: none

9.4.5 Local Functions

None

References

Carlo Ghezzi, Mehdi Jazayeri, and Dino Mandrioli. *Fundamentals of Software Engineering*. Prentice Hall, Upper Saddle River, NJ, USA, 2nd edition, 2003.

Daniel M. Hoffman and Paul A. Strooper. *Software Design, Automated Testing, and Maintenance: A Practical Approach*. International Thomson Computer Press, New York, NY, USA, 1995. URL http://citeseer.ist.psu.edu/428727.html.

10 Appendix

[Extra information if required —SS]