## Chapter 5 Smoothness and convexity

# Siheng Zhang zhangsiheng@cvte.com

### 2021年11月1日

This part corresponds to Chapter 1,3,4 of PRML, Chapter of UML. It mainly introduces some important properties regarding with functions: convexity, smoothness, strong convexity and Lipschitzness, which are basis for the next chapters.

## 目录

1	Convexity	2
2	Strong convexity	3
3	Lipschitzness	4
4	Smoothness	5

#### 1 Convexity

**Definition 5.1 (convex set)** A set C in a vector space is convex if for any two vectors  $\mathbf{u}$ ,  $\mathbf{v}$  in C, the line segment between them is in C, that is, for any  $\alpha \in [0,1]$ ,  $\alpha \mathbf{u} + (1-\alpha)\mathbf{v} \in C$ .

**Definition 5.2 (convex function)** Let C be a convex set. A function  $f:C\to \mathcal{R}$  is convex if for all  $\mathbf{u},\mathbf{v}\in C$  and  $\alpha\in[0,1]$ ,

$$f(\alpha \mathbf{u} + (1 - \alpha)\mathbf{v}) \le \alpha f(\mathbf{u}) + (1 - \alpha)f(\mathbf{v})$$

Claim 5.1 local minimum of convex function is global minimum

Proof Let  $B(\mathsf{u},r)=\{\mathsf{v}:\|\mathsf{v}-\mathsf{u}\|\leq r\}$ , we say that  $f(\mathsf{u})$  is a local minimum if there exists some r>0 such that  $\forall \mathsf{v}\in B(\mathsf{u},r), f(\mathsf{v})\geq f(\mathsf{u})$ . Then for any  $\mathsf{v}$  (not necessarily in B), there exists a small enough  $\alpha>0$  such that  $\mathsf{u}+\alpha(\mathsf{v}-\mathsf{u})\in B(\mathsf{u},r)$ , and therefore  $f(\mathsf{u})\leq f(\mathsf{u}+\alpha(\mathsf{v}-\mathsf{u}))$ . If f is convex, we also have  $f(\mathsf{u}+\alpha(\mathsf{v}-\mathsf{u}))\leq (1-\alpha)f(\mathsf{u})+\alpha f(\mathsf{v})$ , which leads to  $f(\mathsf{u})\leq f(\mathsf{v})$  and hence is a global minimum.

Claim 5.2 For a convex function f, we can construct a tangent at any point that lies below the function everywhere. If f is differential, then we have

$$\forall \mathsf{u}, f(\mathsf{u}) \geq f(\mathsf{v}) + \nabla f(\mathsf{v})^{\top} (\mathsf{u} - \mathsf{v})$$

To generalize this inequality to non-differential functions, we should study for sub-gradient.

**Definition 5.3 (sub-gradient)** Define the sub-gradient of a function f at  $\mathbf{x}$  to be a vector  $\mathbf{g} \in \mathcal{R}^d$  which satisfies that  $f(\mathbf{y}) \geq f(\mathbf{x}) + \mathbf{g}^\top(\mathbf{y} - \mathbf{x}), \forall \mathbf{y} \in \mathcal{R}^d$ .

Theorem 5.1 Let f be a differential function, then f is convex iff.  $\nabla f$  is monotonically non-decreasing, and iff.  $\nabla^2 f$  is non-negative.

Ex1  $f(\mathbf{x}) = \mathbf{x}^{\top}\mathbf{x}$  is convex. To see this, note that  $\nabla f(\mathbf{x}) = 2\mathbf{x}$  and  $\nabla^2 f(\mathbf{x}) = 2$ .

Ex2 Consider scalar function  $f(x) = \log(1 + \exp(x))$ . It is convex since  $f'(x) = \frac{1}{1 + \exp(-x)}$ , which is the sigmoid function, and  $f''(x) = \frac{\exp(-x)}{(1 + \exp(-x))^2} > 0$ .

Claim 5.1 (linear transformation preserves convexity) Assume that  $g: \mathcal{R}^d \to \mathcal{R}$  can be written as  $g(\mathbf{w}) = f(\mathbf{w}^\top \mathbf{x} + b)$ , for some  $\mathbf{x} \in \mathcal{R}^d$ ,  $b \in \mathcal{R}$ . Then, if f is convex, g is convex too.

Proof For  $\mathbf{w}_1, \mathbf{w}_2 \in \mathcal{R}^d$ , and  $\alpha \in (0,1)$ 

$$g(\alpha \mathbf{w}_1 + (1 - \alpha)\mathbf{w}_2) = f(\alpha \mathbf{w}_1^\top \mathbf{x} + (1 - \alpha)\mathbf{w}_2^\top \mathbf{x} + b)$$

$$= f(\alpha(\mathbf{w}_1^\top \mathbf{x} + b) + (1 - \alpha)(\mathbf{w}_2^\top \mathbf{x} + b))$$

$$\leq \alpha f(\mathbf{w}_1^\top \mathbf{x} + b) + (1 - \alpha)f(\mathbf{w}_2^\top \mathbf{x} + b) = \alpha g(\mathbf{x}_1) + (1 - \alpha)g(\mathbf{x}_2)$$

Following Claim5.1,

Ex3  $f(\mathbf{w}) = (\mathbf{w}^{\top}\mathbf{x} - b)^2$  is convex.

Ex4 
$$f(\mathbf{w}) = \log(1 + \exp(-y\mathbf{w}^{\mathsf{T}}\mathbf{x}))$$
 is convex.

Claim 5.2 (Pointwise supremum of convex functions is convex) For  $i=1,\cdots,r$ , let  $f_i:\mathcal{R}^d\to\mathcal{R}$  be a convex function, then  $g(\mathbf{x})=\max_i f_i(\mathbf{x})$  is convex.

Proof For  $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{R}^d$ , and  $\alpha \in (0, 1)$ 

$$\begin{split} g(\alpha \mathbf{x}_1 + (1-\alpha)\mathbf{x}_2) &= \max_i f_i(\alpha \mathbf{x}_1 + (1-\alpha)\mathbf{x}_2) \leq \max_i [\alpha f_i(\mathbf{x}_1) + (1-\alpha)f(\mathbf{x}_2)] \\ &\leq \alpha \max_i f_i(\mathbf{x}_1) + (1-\alpha) \max_i f_i(\mathbf{x}_2) = \alpha g(\mathbf{x}_1) + (1-\alpha)g(\mathbf{x}_2) \end{split}$$

Following Claim5.2,

Ex5  $g(\mathbf{x}) = |\mathbf{x}|$  is convex. Since  $f_1(\mathbf{x}) = \mathbf{x}$ ,  $f_2(\mathbf{x}) = -\mathbf{x}$  are both convex, and  $g(\mathbf{x}) = \max\{f_1(\mathbf{x}), f_2(\mathbf{x})\}$ .

Claim 5.3 (linear combination with non-negative weights preserves convexity) For  $i=1,\cdots,r$ , let  $f_i:\mathcal{R}^d\to\mathcal{R}$  be a convex function, then  $\forall w_i\geq 0, i\in[1,r], g(\mathbf{x})=\sum_i w_i f_i(\mathbf{x})$  is convex.

Proof For  $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{R}^d$ , and  $\alpha \in (0,1)$ 

$$g(\alpha \mathbf{x}_{1} + (1 - \alpha)\mathbf{x}_{2}) = \sum_{i} w_{i} f_{i}(\alpha \mathbf{x}_{1} + (1 - \alpha)\mathbf{x}_{2}) \leq \sum_{i} w_{i}(\alpha f_{i}(\mathbf{x}_{1}) + (1 - \alpha)f(\mathbf{x}_{2}))$$

$$= \alpha \sum_{i} w_{i} f_{i}(\mathbf{x}_{1}) + (1 - \alpha) \sum_{i} w_{i} f(\mathbf{x}_{2}) = \alpha g(\mathbf{x}_{1}) + (1 - \alpha)g(\mathbf{x}_{2})$$

Theorem 5.2 Jensen's Inequality Let  $f: \mathcal{R}^d \to \mathcal{R}$  be a measurable convex function and  $x \in \mathcal{R}^d$ ,  $\mathbb{E}[\S]$  exists. Then

$$\mathbb{E}[f(\mathbf{x})] \ge f(\mathbb{E}[\mathbf{x}])$$

Ex6 Consider function f(x) = |x|, then the sub-differential set  $\partial f(x)$  is

$$\partial f(x) \begin{cases} \{1\}, \ x > 0 \\ [-1, 1], \ x = 0 \\ \{-1\}, \ x < 0 \end{cases}$$

Ex7 Sub-gradient of Hinge loss. Consider the loss  $l(x) = \max(1 - \mathbf{z}^{\top}\mathbf{x}, 0)$ , then the sub-differential set is

$$\partial f(x) \left\{ \begin{aligned} \{\mathbf{0}\}, \ 1 - \mathbf{z}^{\top} \mathbf{x} < 0 \\ \{-\alpha \mathbf{z}, \alpha \in [0, 1]\}, \ 1 - \mathbf{z}^{\top} \mathbf{x} = 0 \\ \{-\mathbf{z}\}, \ 1 - \mathbf{z}^{\top} \mathbf{x} > 0 \end{aligned} \right.$$

#### 2 Strong convexity

**Definition 5.5 (strongly convex function)** A function f is  $\lambda$ -strongly convex if for all  $u, v \in C$  and  $\alpha \in [0, 1]$ ,

$$f(\alpha \mathbf{u} + (1 - \alpha)\mathbf{v}) \le \alpha f(\mathbf{u}) + (1 - \alpha)f(\mathbf{v}) - \frac{\lambda}{2}\alpha(1 - \alpha)\|\mathbf{u} - \mathbf{v}\|_2^2$$

Theorem 5.3 If f is  $\lambda$ -strongly convex then for every  $\mathbf{u}, \mathbf{v}$  and  $\mathbf{g} \in \partial f(\mathbf{v})$  we have

$$f(\mathbf{v}) \geq f(\mathbf{u}) + \mathbf{g}^{ op}(\mathbf{u} - \mathbf{v}) + rac{\lambda}{2} \|\mathbf{u} - \mathbf{v}\|_2^2$$

Proof According to the definition,

$$\begin{split} f(\mathbf{u}) &\geq \frac{f(\alpha \mathbf{u} + (1-\alpha)\mathbf{v})}{\alpha} - \frac{1-\alpha}{\alpha} f(\mathbf{v}) + \frac{\lambda}{2} (1-\alpha) \|\mathbf{u} - \mathbf{v}\|_2^2 \\ &\geq \frac{f(\mathbf{v}) + \mathbf{g}^\top (\alpha \mathbf{u} + (1-\alpha)\mathbf{v}) - \mathbf{v})}{\alpha} - \frac{1-\alpha}{\alpha} f(\mathbf{v}) + \frac{\lambda}{2} (1-\alpha) \|\mathbf{u} - \mathbf{v}\|_2^2 \qquad \textit{(Claim 5.2)} \\ &= \frac{f(\mathbf{v}) + \alpha \mathbf{g}^\top (\mathbf{u} - \mathbf{v})}{\alpha} - \frac{1-\alpha}{\alpha} f(\mathbf{v}) + \frac{\lambda}{2} (1-\alpha) \|\mathbf{u} - \mathbf{v}\|_2^2 \\ &= f(\mathbf{v}) + \mathbf{g}^\top (\mathbf{u} - \mathbf{v}) + \frac{\lambda}{2} (1-\alpha) \|\mathbf{u} - \mathbf{v}\|_2^2 \end{split}$$

Note that it holds for all  $\alpha \in [0,1]$ , setting  $\alpha = 0$  leads to the conclusion.

Corollary 5.1 Following this theorem, if f is  $\lambda$ -strongly convex and  $\mathbf{v}$  is a minimizer of f, then for any  $\mathbf{u}$ ,  $f(\mathbf{v}) \geq f(\mathbf{u}) + \frac{\lambda}{2} \|\mathbf{u} - \mathbf{v}\|_2^2$ .

Ex8  $f(\mathbf{x}) = \|\mathbf{x}\|_2^2$  is 2-strongly convex,  $f(\mathbf{x}) = \lambda \|\mathbf{x}\|_2^2$  is  $2\lambda$ -strongly convex. Note that  $f(\mathbf{x}') = \lambda \|\mathbf{x}' - \mathbf{x} + \mathbf{x}\|_2^2 = \lambda \|\mathbf{x}\|_2^2 + 2\lambda \mathbf{x}^\top (\mathbf{x}' - \mathbf{x}) + \lambda \|\mathbf{x}' - \mathbf{x}\|_2^2$ , in which  $2\lambda \mathbf{x}$  is the gradient of  $f(\mathbf{x})$ .

Claim 5.4 If f is  $\lambda$ -strongly convex and g is convex, then f+g is  $\lambda$ -strongly convex.

Following Claim 5.4, if we will to optimize a convex loss function, then with  $l_2$ -norm regularization, the loss function becomes strongly convex. This speeds up the convergence of learning procedure, which we will see in the next chapter.

#### 3 Lipschitzness

#### Definition 5.6 (dual norm)

One way to understand 'dual norm' is that it is a way to measure how "big" are linear functionals. For example, consider the linear function f, we want to try to understand how big it is. So, we can measure 1 that is we measure how big is the output of the linear functional compared to its input x, where x is measured with some norm. Now, you can show that the above is equivalent to the dual norm of x. The definition of dual norm immediately implies  $\mathbf{w}^{\mathsf{T}}\mathbf{x} \leq \|\mathbf{w}\|_* \|\mathbf{x}\|$ .

Ex9 Dual norm of  $l_2$ -norm is itself.

Definition 5.7 (Lipschitzness) A function  $f: \mathcal{R}^d \to \mathcal{R}^k$  is  $\rho$ -Lipschitz over set C if for every  $\mathbf{w}_1, \mathbf{w}_2 \in C$ ,  $\|f(\mathbf{w}_1) - f(\mathbf{w}_2)\|_* \le \rho \|\mathbf{w}_1 - \mathbf{w}_2\|$ .

In this chapter, we just focus on  $l_2$ -norm. According to the mean value theorem, we have  $f(\mathbf{w}_1) - f(\mathbf{w}_2) = g^{\top}(\mathbf{w}_1 - \mathbf{w}_2)$ , where  $\mathbf{g} \in \partial f(\mathbf{u})$ ,  $\mathbf{u}$  is some point between  $\mathbf{w}_1$  and  $\mathbf{w}_2$ . This leads to the following theorem.

Theorem 5.4 If f is Lipschitz w.r.t  $l_2$ -norm, iff. for all  $g \in \partial f(x)$ , we have  $\|g\|_2 \le \rho$ .

- Ex10 The function f(x) = |x| is 1-Lipschitz over  $\mathcal{R}$ , since  $|x_1| |x_2| = |x_1 x_2 + x_2| |x_2| \le |x_1 x_2| + |x_2| |x_2| = |x_1 x_2|$ .
- Ex11 The function  $f(x) = \log(1 + \exp(x))$  is 1-Lipschitz over  $\mathcal{R}$ , since  $|f'(x)| = |\frac{1}{1 + \exp(-x)}| \le 1$ .
- Ex12 The function  $f(x)=x^2$  is not  $\rho$ -Lipschitz over  $\mathcal R$  for any  $\rho$ . However, over the set  $C=\{x:|x|\leq \frac{\rho}{2}\}$ , this function is  $\rho$ -Lipschitz. Indeed, for any  $x_1,x_2\in C$ ,  $|x_1^2-x_2^2|=|x_1+x_2||x_1-x_2|\leq 2\cdot \frac{\rho}{2}\cdot |x_1-x_2|=\rho|x_1-x_2|$ .
- Ex13 Linear function  $f(\mathbf{x}) = \mathbf{w}^{\top} \mathbf{x} + b$  is  $\|\mathbf{w}\|$ -Lipschitz following Cauchy-Schwartz inequality  $|f(\mathbf{x}_1) f(\mathbf{x}_2)| = |\mathbf{w}^{\top} (\mathbf{x}_1 \mathbf{x}_2)| \le \|\mathbf{w}\|_2 \|\mathbf{x}_1 \mathbf{x}_2\|_2$ .

Claim 5.5 (Lipschitzness preserves on compound functions) Let  $f(\mathbf{x}) = g_1(g_2(\mathbf{x}))$ , where  $g_1$  is  $\rho_1$ -Lipschitz and  $g_2$  is  $\rho_2$ -Lipschitz. Then, f is  $(\rho_1\rho_2)$ -Lipschitz. In particular, if  $g_2$  is the linear function,  $g_2(\mathbf{x}) = \mathbf{w}^{\top}\mathbf{x} + b$ , then f is  $(\rho_1\|\mathbf{w}\|_2)$ -Lipschitz.

Proof

$$|f(\mathbf{x}_1) - f(\mathbf{x}_2)| \leq \rho_1 \|g_2(\mathbf{x}_1) - g_2(\mathbf{x}_2)\| \leq \rho_1 \rho_2 \|\mathbf{w}_1 - \mathbf{w}_2\|_2$$

Ex14 For binary classification  $y \in \{-1,1\}$ ,  $f(\mathbf{w}) = y(\mathbf{w}^{\top}\mathbf{x} + b)$  is  $\|\mathbf{x}\|_2$ -Lipschitz following  $|f(\mathbf{x}_1) - f(\mathbf{x}_2)| = |y\mathbf{w}_1^{\top}\mathbf{x} - y\mathbf{w}_2^{\top}\mathbf{x}_2| \le \|y\mathbf{x}\|_2 \|\mathbf{w}_1 - \mathbf{w}_2\|_2$ . Hence,  $\log \log f(\mathbf{w}) = \log(1 + \exp(-y\mathbf{w}^{\top}\mathbf{x}))$  is  $\|\mathbf{x}\|_2$ -Lipschitz.

## 4 Smoothness

**Definition 5.8 (smooth function)** A differentiable function f is  $\beta$ -smooth if its gradient is  $\beta$ -Lipschitz

remark1. 1

4.4 According to definition, the dual norm of  $\|\cdot\|_p (p\geq 1)$  is  $\|\theta\|_*=\max_{\mathbf{x}:\|\mathbf{x}\|_p\leq 1}\langle\theta,\mathbf{x}\rangle$ . Using the Hölder inequality

$$\|\langle \mathbf{z}, \mathbf{x} \rangle\|_1 \leq \|\mathbf{x}\|_q \|\mathbf{z}\|_p$$

where  $\frac{1}{p} + \frac{1}{q} = 1$ , we have that:

$$\|\theta\|_* \leq \|\mathbf{x}\|_a \|\mathbf{z}\|_p \leq \|\mathbf{x}\|_a$$

So the dual norm is  $\|\cdot\|_q$  , where  $\frac{1}{p}+\frac{1}{q}=1$ .

4.5 Start from strong convexity, we have that

$$\sum_{t=1}^T l_t(\mathbf{x}_t) - \sum_{t=1}^T l_t(\mathbf{u}) \leq \sum_{t=1}^T \left( \frac{1}{2\eta_t} \|\mathbf{x}_t - \mathbf{u}\|_2^2 - \frac{1}{2\eta_t} \|\mathbf{x}_{t+1} - \mathbf{u}\|_2^2 - \frac{\mu_t}{2} \|\mathbf{x}_t - \mathbf{u}\|_2^2 + \frac{\eta_t}{2} \|\mathbf{g}_t\|_2^2 \right)$$

Let all  $mu_t \le \mu$ , choose  $\eta_t = 1/\mu t$ . Given that the loss functions are Lipschitz, we can further bound the regret to be

$$\sum_{t=1}^T l_t(\mathbf{x}_t) - \sum_{t=1}^T l_t(\mathbf{u}) \leq \sum_{t=1}^T \frac{\eta_t}{2} \|\mathbf{g}_t\|_2^2 = \frac{L^2}{2\mu} \sum_{t=1}^T \frac{1}{t}$$

Since that the loss functions are smooth, t can be rewrite as  $t \geq \sum_{i=1}^t \frac{L \|\mathbf{x} - \mathbf{u}\|_2^2}{\|l_i(\mathbf{x}) - l_i(\mathbf{u})\|_2^2} \geq \frac{L}{M} \sum_{i=1}^t \frac{\|\mathbf{g}_i\|_2^2}{\|l_i(\mathbf{x}) - l_i(\mathbf{u})\|_2^2}$ , so  $\frac{1}{t} \leq \frac{M}{L} \frac{1}{\sum_{i=1}^t \frac{\|\mathbf{g}_i\|_2^2}{\|l_i(\mathbf{x}) - l_i(\mathbf{u})\|_2^2}}$ .

Now using the fact that  $\sum_{t=1}^T \frac{1}{t} \leq 1 + \ln T$ , we can also make integral by  $\|l_i(\mathbf{x}) - l_i(\mathbf{u})\|_2^2$  and get that

$$\sum_{t=1}^T l_t(\mathbf{x}_t) - \sum_{t=1}^T l_t(\mathbf{u}) \leq O(\ln(1 + [\sum_{t=1}^T l_t(\mathbf{x}_t) - \sum_{t=1}^T l_t(\mathbf{u})] \sum_{t=1}^T \sum_{t=1}^T l_t(\mathbf{u})))$$

Using the fact that  $x \leq a \ln(1+bx) + c$  leads to  $x \leq a \ln(2ab \ln(ab) + 2bc + 2) + c$ , it leads to

$$\sum_{t=1}^{T} l_t(\mathbf{x}_t) - \sum_{t=1}^{T} l_t(\mathbf{u}) \le O(1 + \ln \sum_{t=1}^{T} l_t(\mathbf{u})$$

which is the  $O(1 + \ln L^*)$  bound.

4.6 With regard to  $\|\cdot\|_2$ , we need to prove that

$$||l''(\mathbf{x}_1)||_2 \le \frac{1}{4}$$

Note that

$$l'(\mathbf{x}) = \frac{-y\mathbf{z}e^{-y\langle\mathbf{z},\mathbf{x}\rangle}}{1+e^{-y\langle\mathbf{z},\mathbf{x}\rangle}} = -y\mathbf{z}(1-\exp(-l(\mathbf{x})))$$

$$l''(\mathbf{x}) = y\mathbf{z} \exp(-l(\mathbf{x}))(1 - \exp(-l(\mathbf{x})))$$

Since  $y \in \{-1, 1\}$  and  $\|\mathbf{z}\|_2 \le 1$ , we can bound it by

$$||l''(\mathbf{x}_1)||_2 \le |\exp(-l(\mathbf{x}))(1 - \exp(-l(\mathbf{x})))|$$

Note that  $l(\mathbf{x}) > 0$ , so  $0 < \exp(-l(\mathbf{x})) < 1$ , so the upper bound is 1/4.