## Chapter TWO VC-dimension

# Siheng Zhang zhangsiheng@cvte.com

### September 10, 2020

This part corresponds to  $Chapter\ 2-5$  in UML, and mainly answers the following questions:

• The necessary and sufficient condition of PAC learnability.

•

### Contents

1	The VC-dimension
	1.1 Shattering
	1.2 The VC-dimension
	1.2.1 Examples
2	Fundamental theorem of PAC learning
3	Effective size of a hypothesis class
4	Non-uniform learnability
5	Summary
6	Exercises and solutions

#### 1 The VC-dimension

#### 1.1 Shattering

Consider the set of threshold functions over the real line  $\mathcal{H} = \{h_a(x) = \mathbb{1}_{[x \leq a]}, a \in \mathbb{R}\}$ . Let  $a^*$  be the threshold such that  $L_{\mathcal{D}}(h^*) = 0$ . Let  $a_0 < a^* < a_1$  such that:

$$\mathbb{P}_{x \sim \mathcal{D}_x}[x \in (a_0, a^*)] = \mathbb{P}_{x \sim \mathcal{D}_x}[x \in (a^*, a_1)] = \epsilon$$

If  $\mathcal{D}_x(-\infty, a^*) \leq \epsilon$ , we set  $a_0 = -\infty$ , and similarly for  $a_1$ .

Given a training set S, let  $b_0 = \max\{x : (x,1) \in S\}$  (if no example is positive then  $b_0 = -\infty >$ , and  $b_1 = \min\{x : (x,0) \in S\}$  (if no example is negative then  $b_1 = \infty$ ). Let  $b_S$  be the threshold of an ERM hypothesis  $b_S$ , which implies  $b_S \in (b_0, b_1)$ , then we have

$$\mathbb{P}_{S \sim \mathcal{D}^m}[L_{\mathcal{D}}(h_S) < \epsilon] \le \mathbb{P}_{S \sim \mathcal{D}^m}[b_0 < a_0] + \mathbb{P}_{S \sim \mathcal{D}^m}[b_1 > a_1]$$

Each term on the right-side is bounded by  $(1 - \epsilon)^m \le e^{-\epsilon m}$ . Let  $m > \log(2/\delta)/\epsilon$ , then the left-side is bounded by  $\delta$ . As a result, the hypothesis class is PAC-learnable.

The example above shows that: **finiteness is not a necessary condition for learnability**, and hence we turn to the definition of **shattering**, which describes the ability of a hypothesis set to cover the training set.

The definition of VC-dimension is motivated from the No-Free-Lunch theorem: without restricting the hypothesis class, for any learning algorithm, an **adversary** can construct a distribution for which the learning algorithm will perform poorly, while there is another learning algorithm that will succeed on the same distribution. To make any algorithm fail, the **adversary** used the power of choosing a target function from the set of all possible labelling functions.

When considering PAC learnability of a hypothesis class  $\mathcal{H}$ , the **adversary** is restricted to constructing distributions for which some hypothesis  $h \in \mathcal{H}$  achieves a zero risk. Since we are considering distributions that are concentrated on elements of C, we should study how  $h \in \mathcal{H}$  behaves on C.

**Definition** (Restriction of  $\mathcal{H}$  to C): The restriction of  $\mathcal{H}$  to C is the set of functions from C to  $\{0,1\}$  that can be derived from  $\mathcal{H}$ . That is,

$$\mathcal{H}_C = \{ (h(c_1), \cdots, h(c_m)) : h \in \mathcal{H} \}$$
 (1)

where we represent each function from C to  $\{0,1\}$  as a vector in  $\{0,1\}^{|C|}$ .

**Definition** (Shattering): A hypothesis class  $\mathcal{H}$  shatters a finite set  $C \in \mathcal{X}$  if the restriction of  $\mathcal{H}$  to C is the set of all functions from C to  $\{0,1\}$ . That is,  $|\mathcal{H}_C| = 2^{|C|}$ .

Corollary 1 Let  $\mathcal{H}$  be a hypothesis class of functions from  $\mathcal{X}$  to  $\{0,1\}$ . Let m be a training set size. Assume that there exists a set  $C \subset \mathcal{X}$  of size 2m that is shattered by  $\mathcal{H}$ . Then, for any learning algorithm, A, there exist a distribution  $\mathcal{D}$  over  $\mathcal{X} \times \{0,1\}$  and a predictor  $h \in \mathcal{H}$  such that  $L_{\mathcal{D}}(h) = 0$  but with probability of at least 1/7 over the choice of  $S \sim \mathcal{D}^m$  we have that  $L_{\mathcal{D}}(A(S)) \geq 1/8$ .

The corollary shows that whenever if  $\mathcal{H}$  shatters some set  $\mathcal{C}$  of size 2m, then we cannot learn  $\mathcal{H}$  by using m examples. This leads us directly to the definition of the VC dimension.

#### 1.2 The VC-dimension

**Definition** (VC-dimension): The VC-dimension of a hypothesis class  $\mathcal{H}$ , denoted VCdim( $\mathcal{H}$ ), is the maximal size of a set  $C \subset \mathcal{X}$  that can be shattered by  $\mathcal{H}$ . If  $\mathcal{H}$  can shatter sets of arbitrarily large size we say that  $\mathcal{H}$  has infinite VC-dimension.

**Theorem 1** If  $\mathcal{H}$  is a class of infinite VC-dimension, then  $\mathcal{H}$  is not PAC learnable.

#### 1.2.1 Examples

To calculate the VC-dimension for a hypothesis set, we should show that:

- There **exists** a subset of size d that can be shattered;
- Every subset of size d+1 can not be shattered.

#### 1 Threshold functions

$$\mathcal{H} = \{ \mathbb{1}_{x \le a} : a \in \mathbb{R} \}$$

For an arbitrary set  $C = \{c\}$ ,  $\mathcal{H}$  shatters C, therefore  $VCdim(\mathcal{H}) \geq 1$ ; for an arbitrary set  $C = \{c_1, c_2\}$ , where  $c_1 \leq c_2$ , any threshold that assigns 0 to  $c_1$  must assign 0 to  $c_2$ . In other words, not all functions from  $\mathcal{C}$  to  $\{0,1\}$  are included by  $\mathcal{H}_C$ . So,  $\mathcal{H}$  does not shatter C.

#### 2 Intervals

$$\mathcal{H} = \{ \mathbb{1}_{x \in (a,b)} : a < b, a, b \in \mathbb{R} \}$$

Denote the set  $C = \{c_1, c_2\}$ . If we take  $a > c_2$  or  $b < c_2$ , the we have  $h_{a,b}(c_1) = 0$ ,  $h_{a,b}(c_2) = 0$ ; if we take  $c_1 < a < c_2 < b$ , the we have  $h_{a,b}(c_1) = 0$ ,  $h_{a,b}(c_2) = 1$ ; if we take  $a < c_1 < b < c_2$ , the we have  $h_{a,b}(c_1) = 1$ ,  $h_{a,b}(c_2) = 0$ ; if we take  $a < c_1 < c_2 < b$ , then we have  $h_{a,b}(c_1) = 1$ ,  $h_{a,b}(c_2) = 1$ . Therefore,  $\mathcal{H}_C$  is the set of all functions from C to  $\{0,1\}^2$ .

Take the set  $C = \{c_1, c_2, c_3\}$ , without loss of generalization, let the labels be (1, 0, 1), therefore  $\mathcal{H}$  does no shatter C.

Hence,  $VCdim(\mathcal{H}) = 2$ .

#### 3 Axis Aligned Rectangles

$$\mathcal{H} = \{ \mathbb{1}_{(a_1 \le x_1 \le a_2, b_1 \le x_2 \le b_2)} : a_1 < a_2, b_1 < b_2 \}$$

Any set with 4 points can be shattered. Take the set with 5 points. Suppose that there is 1 point (labelled as 0) surrounded by 4 points (labelled as 1), it cannot be shattered. Hence,  $VCdim(\mathcal{H}) = 4$ .

#### 4 Finite class

Let  $\mathcal{H}$  be a finite class. Then, clearly, for any set C we have  $|\mathcal{H}_C| \leq |\mathcal{H}|$  and thus it cannot be shattered if  $|\mathcal{H}| < 2^{|C|}$ . This implies that  $VCdim(\mathcal{H}) < \log_2 |\mathcal{H}|$ .

<u>remark1</u>: In the previous examples, the VC-dimension happened to equal the number of parameters defining. This is not always true. See exercise? for detail.

### 2 Fundamental theorem of PAC learning

**Theorem 2** Let  $\mathcal{H}$  be a hypothesis class of functions from a domain  $\mathcal{X}$  to  $\{0,1\}$  and let the loss function be the 0-1 loss. Then, the following are equivalent:

- 1. The hypothesis class has uniform convergence property.
- 2. Any ERM rule is a successful agnostic PAC learner for the hypothesis class.
- 3. The hypothesis class is agnostic PAC learnable.
- 4. The hypothesis class is PAC learnable.
- 5. Any ERM rule is a successful PAC learner for the hypothesis class.
- 6. The hypothesis class has a finite VC-dimension.

### 3 Effective size of a hypothesis class

### 4 Non-uniform learnability

"non-uniform learnability" allows the sample size to be non-uniform with respect to the different hypotheses with which the learner is competing.

A hypothesis is  $(\epsilon, \delta)$ -competitive with another if

### 5 Summary

#### 6 Exercises and solutions

To be continue...

Chapter 3. Bayesian-PAC

Chapter 4. Generalization in Deep Learning