These Rows Are Made for Sorting and That's Just What We'll Do

Laurens Kuiper CWI, Amsterdam, Netherlands laurens.kuiper@cwi.nl Hannes Mühleisen CWI, Amsterdam, Netherlands hannes.muehleisen@cwi.nl

Abstract-Sorting is one of the most well-studied problems in computer science and a vital operation for relational database systems. Despite this, little research has been published on implementing an efficient relational sorting operator. In this work, we explore the design space of sorting in a relational database system. We use micro-benchmarks to explore how to sort relational data efficiently in analytical database systems, taking into account different query execution engines as well as row and columnar data formats. We show that, regardless of architectural differences between query engines, sorting rows is almost always more efficient than sorting columnar data, even if this requires converting the data from columns to rows and back. Sorting rows efficiently is challenging for systems with an interpreted execution engine, as their implementation has to stay generic. We show that these challenges can be overcome with several existing techniques. Based on our findings, we implement a highly optimized row-based sorting approach in the DuckDB open-source in-process analytical database management system, which has a vectorized interpreted query engine. We compare DuckDB with four analytical database systems and find that DuckDB's sort implementation outperforms query engines that sort using a columnar data format.

Index Terms—relational databases, database query processing, sorting

I. INTRODUCTION

Sorting is one of the most well-studied problems in computer science. Research on efficient sorting algorithms focuses on crucial issues such as cache-efficiency [1], reducing branch mispredictions [2], parallelism [3], and worst-case patterns [4], but is mostly limited to sorting large arrays of integers. Database systems research focuses on many of the same issues [5]-[7], and database systems have some of the most practical use-cases of sorting: The ORDER BY and WINDOW operators explicitly invoke sorting, but other operations such as index construction, merge joins, and inequality joins [8] may implicitly rely on sorting. Therefore, it is crucial to have an efficient sort implementation to provide fast query response times, especially for analytical (OLAP) data management systems. However, sorting relational data is more involved than sorting an array of integers. Very little research has gone into sorting relational data efficiently, especially compared to research on other operators, such as joins [9].

Although relational sorting implementations can reap the benefits from advances in general-purpose sorting algorithms [2]–[4], merely using such an algorithm will not make a relational sorting implementation efficient by default, as we

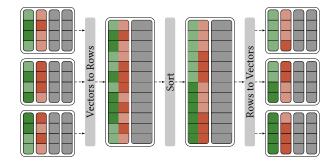


Fig. 1. Converting vectors to rows, sorting them, and converting them back to vectors. The columns that appear in the order clause are colored, and the other selected columns are in gray.

will demonstrate in this paper. Two operations dominate the cost of sorting: Comparing and moving tuples [10]. These two operations are more complex for relational data than for integers. The comparison function that arises from the ORDER BY clause can be arbitrarily complex and contain any of the types that the system supports. The tuples that are then moved can also have any type that the database system supports, and there can be an arbitrary number of columns. Inefficient implementations of these operations will lead to inefficient sorting, even if the sorting algorithm itself is provably efficient.

A system's query execution engine affects how these operations can be implemented and the efficiency of these implementations. The engines of most modern OLAP systems are based on either vectorization, pioneered by VectorWise [5], or data-centric code-generation, pioneered by HyPer [11]. The strengths and weaknesses of these two processing paradigms have been researched in-depth [12], [13], but not in the context of sorting. This work investigates how to sort relational data efficiently under both paradigms. Our experimental results show that, under both paradigms, sorting rows is almost always more efficient than sorting columnar data, even if this requires converting from a columnar to a row format and back. We illustrate this for a vectorized engine in Figure 1.

To compare the differences between sorting a columnar and row data format, as well as the differences between sorting in vectorized and compiled query engines, we could compare the end-to-end runtime of database systems that implement these approaches. However, with full-fledged systems, it is challenging to create an apples-to-apples comparison, as these systems differ in many aspects unrelated to sorting. Therefore, we first implement a relational sorting micro-benchmark to isolate the fundamental differences between these approaches. In Section IV, we evaluate several approaches to sorting relational data in row and columnar format. Then, in Section V, we discuss how the query execution engine affects sorting performance. Our experimental results show that compiled query engines can efficiently sort row data format, while vectorized interpreted engines are hindered by interpretation and function call overhead. We demonstrate that this overhead can be overcome by implementing several existing techniques in Section VI.

Finally, we implement a row-based sort that includes these techniques within DuckDB, our in-process OLAP database management system. DuckDB implements SQL, has columnar storage, and uses a vectorized interpreted execution engine. We compare our implementation in Section VII with four high-performance analytical database systems: ClickHouse [14], MonetDB [15], HyPer [11], and Umbra [16]. The results of this comparison show that DuckDB's interpreted rowbased sort implementation outperforms ClickHouse's and MonetDB's sort implementations, which use a columnar data format, and matches or outperforms HyPer's and Umbra's compiled row-based sort implementations.

II. SORTING RELATIONAL DATA

Database systems use sorting for many purposes [10]. Sorting can be invoked explicitly by specifying a sort order at the end of a query or a window specification, but also implicitly for many purposes such as join algorithms [8], improving run-length encoding compression [17], and zone map [18] effectiveness. Because it is so widely applicable, any database system needs an efficient sorting implementation, especially OLAP systems that aim to have low query response times. Sorting relational data efficiently, however, is more complex than sorting an array of integers, which is the default benchmark for sorting algorithms.

A relational sorting implementation must be able to sort all selected data by one or more predicates, whether sorting is invoked explicitly in an ORDER BY clause or implicitly by other means. Take the following query, for example:

This query specifies which columns to return and how they should be sorted, i.e., it describes how rows should be compared to produce the ordered query result. All columns from the customer table should be returned, sorted by the column <code>c_birth_country</code> in descending order, with <code>NULL</code> values coming last. Where rows have the same value in that column, they should be sorted by <code>c_birth_year</code> in ascending order with <code>NULL</code> values coming first. We will refer to the columns that appear in the <code>ORDER BY</code> clause as <code>key</code> columns and all other selected columns as <code>payload</code> columns, as is common when discussing join algorithms.

As we can see from the example query, describing how rows should be compared is already complex, even though we specify only two key columns. In contrast, comparing integers is done using a comparison operator. For tuples, a straightforward comparator implementation will lead to code with many branches, with serious performance implications. Because the comparator is so frequently used during sorting, it should be implemented as efficiently as possible. For example, quicksort can be sped up significantly by reducing branches [2], but this is only effective if the comparison function is branchless.

How a relational sort implementation physically represents data in memory also affects comparison efficiency. If the keys belonging to a single row are not stored consecutively in memory, which is the case for a columnar data format, comparing tuples causes random access for each compared value, which may cause cache misses. Improving cache locality speeds up many sorting algorithms significantly [1].

Besides determining the order in which to return the tuples by comparing and sorting them, the data must also be physically re-ordered eventually, be it immediately during sorting or later during retrieval of the data in sorted order. This is trivial for an array of integers: We sort the array with an efficient sorting algorithm, which results in the data being in the correct order. It is less obvious for relational data because there are many ways to represent tuples. Sorting is inherently a row-wise operation, but systems with a vectorized engine use a columnar data format during execution. For such systems, it might be beneficial to convert the data to a row format, also called the N-ary Storage Model (NSM), and then convert it back to a columnar format, also called the Decomposition Storage Model (DSM), after completing the sort. Vectorized engines already do this for hash tables in joins and aggregations to improve cache-efficiency [19].

Additionally, we can handle the key and payload columns separately: We can retrieve the payload in the correct order after sorting the key columns. The question is then whether it is efficient to convert either, neither, or both to NSM. This is essentially a trade-off between cache locality and data movement. Converting from DSM to NSM results in a better memory access pattern when retrieving the payload in the correct order because values that belong together are close together in memory. This conversion, however, requires moving all the data from the columnar format to the row format. While payload handling is an essential part of relational sorting, it is outside the scope of this paper. In this paper, we focus on sorting key columns.

As we will see in Section VII, when we discuss the systems under benchmark, many database systems parallelize sorting by generating sorted runs with thread-local sorts, e.g., with morsel-driven parallelism [6]. This so-called "run generation" is followed by a parallel merge sort, which merges the runs to sort the data fully. Comparison-based sorting algorithms such as quicksort and merge sort use on average $\mathrm{O}(n \cdot \log(n))$ comparisons for an input size of size n.

If we generate k sorted runs, the average number of comparisons performed during run generation is

$$\mathrm{comp}_A = k \cdot \frac{n}{k} \cdot \log \Bigl(\frac{n}{k} \Bigr) = n \cdot \log(n) - n \cdot \log(k),$$

as we sort k runs of size $\frac{n}{k}$. The average number of comparisons performed during merge sort is $\operatorname{comp}_B = n \cdot \log(k)$, as we have to $\operatorname{do}(k)$ comparisons to find the smallest value out of k runs, n times. To find the point at which we have more comparisons during merge sort, we can solve the inequality $\operatorname{comp}_A > \operatorname{comp}_B$. The solution to this inequality is $k > \sqrt{n}$. If the data fits in memory, each thread will generally generate one sorted run; therefore, the number of generated runs k equals the number of threads. The input size k can be arbitrarily large; therefore, comp_A is almost always larger than comp_B . For example, for k = 1.000.000 and k = 16, around 80% of the total number of comparisons are performed during run generation, on average. Therefore, we focus specifically on run generation in this paper, as run generation takes up the bulk of the work for many applications of relational sorting.

It is unclear what the most efficient approach will be for a given system without benchmarking different sorting implementations. Differences in execution engine, hardware characteristics like CPU cache size, and functionality requirements all affect how to approach relational sorting. However, implementing a relational operator such as the sort operator in a database system is cumbersome, let alone implementing multiple variations to determine the best-performing one. Therefore, we use micro-benchmarks to evaluate several approaches for sorting relational data to determine their effectiveness.

III. METHODOLOGY

To isolate the fundamental properties of sorting data in row and columnar format, as well as the fundamental properties of sorting in compiled and vectorized interpreted query execution engines, we implement micro-benchmarks. By using micro-benchmarks, we do not measure the time it takes to parse and optimize queries and the overhead of result set serialization [20], which will differ across database systems. We implement several approaches to sorting relational data in C++. All of the approaches use std::sort, an introspective sort [21] implementation. The std::sort algorithm is not state-of-the-art, as it has already been improved upon in various ways [2], [4]. However, we wish to measure the effect of different data formats, tuple comparison methods, and execution engines, regardless of the sorting algorithm. We compare std::sort only against itself and not against other sorting algorithms so that we can isolate the effects of the data formats, comparison methods, and execution engines. To verify whether these effects generalize to other sorting algorithms, we replicate our experiments with std::stable_sort, which is a stable sorting algorithm based on merge sort. Merge sort has a different cache behavior from quicksort, as merge sort uses primarily sequential data access. We also only compare std::stable_sort against itself.

A. Workload

The data for our micro-benchmarks consists of columns of unsigned 32-bit integers. These are generated by sampling from two distributions¹:

Random Random uniform

CorrelatedP Correlated with 128 unique values, with P the correlation probability

We vary the number of key columns from 1 to 4 and the number of rows from 2^{12} to 2^{24} . The Random data distribution has virtually no duplicate values in each column. The CorrelatedP distribution has 128 unique values per column, The first column is distributed uniformly. For subsequent columns, P gives the probability of a column C+1 correlating with column C. For example, in the Correlated0.5 distribution, when we compare two tuples with an equal value in column C, there is a 50% probability that their values in column C+1 will be equal as well. Having duplicate values in the key columns leads to ties when comparing values during sorting, which requires the comparison function to compare the next key column as well. Therefore, depending on the correlation, more comparisons need to be performed. For very high correlations, tuples are more likely to have the exact same values in all key columns, reducing the total number of unique tuples.

As we will demonstrate in the following, memory access patterns, branch mispredictions, and interpretation overhead are the main differentiating factors in the performance of sorting implementations. The memory access patterns of sorting a row and columnar data format that we measure in our microbenchmarks are the same regardless of data type. The same holds for branch mispredictions and interpretation overhead. We purposely keep our micro-benchmarks simple, but we include experiments with other data types in our end-to-end benchmarks in Section VII.

B. Experimental Setup

To measure the runtime of our micro-benchmarks, we use the m5d.metal AWS EC2 instance unless noted otherwise. This instance has an Intel Xeon Platinum 8259CL CPU with 48 cores (96 threads) and 384 GB of RAM. We use Ubuntu 20 as OS and compile our code with Clang 12. We repeat each experiment five times and report only the median runtime.

We use CPU performance counters to further analyze and understand the properties of different approaches. Measuring these counters is impossible on most AWS EC2 instances due to the restrictions of virtual machines. The metal instance does allow reading the performance counters, which is why we have chosen to use it. We obtain performance counters using Linux's perf command. We measure the number of branch mispredictions, and L1 data cache load misses with -e branch-misses, L1-dcache-load-misses. We run the performance counter measurements just once.

In Section VII, we run end-to-end runtime benchmarks to compare the performance of full-fledged database systems.

¹The source code for our micro-benchmarks can be found at https://github.com/lnkuiper/experiments/tree/master/sorting_simulation

Because we are not measuring performance counters, we do not need to use the metal instance, and we use the smaller m5d.8xlarge instance instead. This instance has exactly the same hardware as the m5d.metal instance, but is a virtual machine that uses one-third of its resources.

All instances used in our experiments have NVMe storage. Detailed specifications of the hardware used in our experiments can be found in Table I.

TABLE I SPECIFICATION OF HARDWARE USED IN EXPERIMENTS.

	m5d.metal	m5d.8xlarge
CPU Brand	Intel	Intel
CPU Model	8259CL	8259CL
Architecture	x86	x86
Cores/Threads	48/96	16/32
Clock Rate	2.5-3.5 GHz	2.5-3.5 GHz
L1 Cache	32 KB	32 KB
RAM	384 GB	128 GB

IV. DSM vs. NSM

In this section, we experimentally evaluate the efficiency and performance characteristics of sorting relational data in columnar and row format. We sort only the key columns because we can retrieve the payload in the correct order after sorting the keys to create a fully sorted run. Note that to collect the payload, we need some way of tracking which keys correspond to which payload, e.g., using a pointer or a row ID. Furthermore, we assume that all input has been materialized, i.e., the sort operator has collected all input data already in a row or columnar format, allowing us to isolate raw sorting performance further.

There are two obvious ways of comparing tuples of relational data when there are multiple key columns:

tuple-at-a-time Iterate through the key columns with each comparison. Compare values until we find one that is not equal or until we have iterated through all columns in the order clause.

subsort

Sort everything by the first key column, then identify the tuples with an equal value in this column, and sort these by the second key column. Repeat until all key columns are sorted.

We apply these approaches to both the columnar and row data formats.

A. Sorting Columnar Data

A columnar format necessitates sorting row indices rather than sorting the data in the columns directly because we need to use the indices to access the data in the columns. After sorting, the same sorted indices are used to retrieve the payload in the correct order. An implementation of the tuple-at-a-time approach for the columnar data format using std::sort in C++ could look like the following:

```
// Compare two tuples using their row id
bool compare(l_id, r_id, cols) {
   size_t i = 0;
   for (; i < cols.size() - 1; i++) {</pre>
    if (cols[i][l_id] != cols[i][r_id])
   return cols[i][l id] < cols[i][r id];</pre>
// Sort N row indices by the key column values
std::sort(idxs, idxs + N, [&] (l_id, r_id) {
 return compare(l_id, r_id, cols);
```

Tuples are represented by their indices idxs and compared using their respective values in cols. The subsort implementation works similarly: It also sorts by indices but has a less complex comparison function that only compares one column. Additionally, the subsort approach has to identify tied tuples after each pass and recurse until there are no more ties or until it has passed over all columns.

The tuple-at-a-time sorting approach for the columnar data format has three major drawbacks: 1) Comparing two tuples causes multiple random accesses with each comparison. If the tuples have the same value in the first key column, we need to compare their value in the second key column, and so forth. The more duplicate values there are, the more random access is caused. Therefore, this approach suffers from data distributions with many duplicates and skewed data distributions. 2) The comparison function has branches, namely, whether to compare the values in the next key column if the values in the current key column are equal. Again, this may be difficult to predict depending on the distribution: If there are no duplicates, the branch predictor will correctly predict not to compare the next column. 3) Sorting columnar data sorts indices rather than the data in the key columns itself, i.e., the data in the key columns never actually moves. Sorting algorithms generally move similar values next to each other in memory, which improves cache locality. By not physically moving the data, the columnar approach benefits less from the cache-efficiency of a sorting algorithm.

The subsort approach improves on this by only causing random access in one column at a time, mitigating drawback (1), and comparing a single column at a time and therefore having no branches in the comparison function, eliminating drawback (2). Furthermore, sorting one column at a time reduces the cache pressure because only a single memory region (albeit large) is accessed at a time, which mitigates drawback (3) slightly.

We measure performance counters of both methods in our micro-benchmark and show the results in Table II. There are almost no duplicates in the Random data distribution, and the second column rarely has to be randomly accessed when comparing tuples. Therefore, both approaches operate almost exactly the same and sort the data by only accessing the first column. This explains why the number of cache misses and branch mispredictions are similar. For the correlated data distributions, the *subsort* approach incurs fewer cache misses and branch mispredictions as expected.

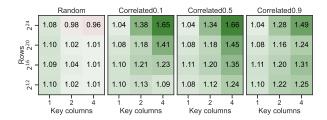


Fig. 2. Relative runtime (higher is better) of the *subsort* approach compared to the *tuple-at-a-time* approach on a columnar data format with **std::sort.**

CPU performance is affected negatively by cache misses and branch mispredictions, which should translate into a worse overall sorting performance. We measure the runtime of both approaches using our micro-benchmark and show the relative runtime of *subsort* compared to the *tuple-at-a-time* approach in Figure 2. A relative runtime of 2.00 means that the *subsort* approach is twice as fast as the *tuple-at-a-time* approach, i.e., it finishes sorting in half the time.

When there is only one key column, the approaches are virtually equal. As expected, the relative runtime is close to 1 for all inputs for the Random data distribution because there are almost no duplicates. For the Correlated distributions, the *subsort* approach is better the more rows and the more key columns there are. When there are more rows and key columns, the *tuple-at-a-time* approach performs relatively worse because the columns no longer fit in the CPU's cache. The increased cache pressure hurts its performance.

Using std::unstable_sort, we replicate this benchmark to verify that our findings generalize to other sorting algorithms. We show the results in Figure 3. With this sorting algorithm, the approaches are much closer, and *subsort* is often slightly slower than *tuple-at-a-time*. The std::unstable_sort implementation is based on merge sort, which mostly does sequential access. Therefore, the worse cache behavior of the *tuple-at-a-time* comparison approach does not hurt its performance as much, comparatively. Based on these findings, we cannot conclude that the *subsort* approach is better than the *tuple-at-a-time* approach on the columnar data format, as the results depend on the sorting algorithm. In the next subsection, we will see how the different comparison strategies will perform on the row data format.

TABLE II L1 CACHE MISSES AND BRANCH MISPREDICTIONS (BOTH IN BILLIONS, LOWER IS BETTER) OF SORTING 2^{24} ROWS OF 4 KEY COLUMNS IN COLUMNAR (C) DATA FORMAT, CORRELATED 0.5 DISTRIBUTION, WITH THE tuple-at-a-time (T) AND subsort (S) APPROACHES, WITH STD::SORT.

Distribution	Cache	Misses	Branch Misses		
	C/T	C/S	C/T	C/S	
Random	0.41	0.45	0.17	0.17	
Correlated0.1	1.48	0.96	0.24	0.19	
Correlated0.5	1.60	1.05	0.20	0.16	
Correlated0.9	1.46	1.11	0.11	0.08	

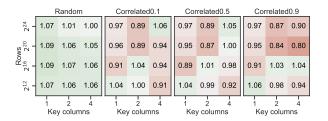


Fig. 3. Relative runtime (higher is better) of the *subsort* approach compared to the *tuple-at-a-time* approach on a columnar data format with std::stable sort.

B. Sorting Row Data

Unlike with the columnar data format, we do not have to use row indices *while* sorting the row data format. We can directly address a row rather than address it by its row index because all values that we compare are co-located. The row indices (or pointers) are still needed to retrieve the payload in the correct order after sorting. We can pack these within the row, which, for example, can be achieved with a struct in C++:

```
struct OrderKey {
   // Key columns
   uint32_t col1;
   uint32_t col2;
   // Index (or pointer) to the payload
   size_t idx;
};
```

The row data format is sorted by calling, e.g., std::sort on an array of the OrderKey structs. The comparison function used to sort is then defined as a comparison function between the key column values in these structs.

Like the columnar data format, we sort the row data format with the *tuple-at-a-time* approach. We can sort rows with the *subsort* approach as well, although, at first glance, it is less intuitive to do this with rows. Like before, *subsort* simplifies the comparison function while sorting, as it does not need branches. The implementation of *subsort* for rows is the same as for columnar data: We sort, identify which tuples are tied, sort the tied tuples by the next column, and so forth.

We measure performance counters of both methods in our micro-benchmark and show the results in Table III. When we compare this with Table II, it is clear that sorting the row data

TABLE III L1 CACHE MISSES AND BRANCH MISPREDICTIONS (BOTH IN BILLIONS, LOWER IS BETTER) OF SORTING 10^{24} ROWS OF 4 KEY COLUMNS IN ROW (R) DATA FORMAT, CORRELATED0.5 DISTRIBUTION, WITH THE tuple-at-a-time (T), AND subsort (S) APPROACHES, WITH STD::SORT.

Distribution	Cache	Misses	Branch Misses		
	R/T	R/S	R/T	R/S	
Random	0.10	0.10	0.18	0.17	
Correlated0.1	0.10	0.17	0.25	0.20	
Correlated0.5	0.10	0.19	0.21	0.17	
Correlated0.9	0.09	0.22	0.11	0.08	

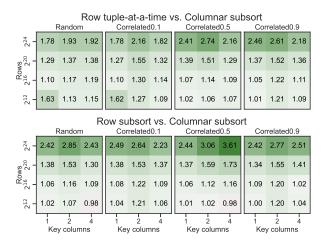


Fig. 4. Relative runtime (higher is better) of the *tuple-at-a-time* and *subsort* approaches on row data format compared to the *subsort* approach on a columnar data format, with **std::sort**.

format incurs an *order of magnitude fewer* cache misses than sorting columnar format data. The number of branch misses is almost exactly the same as was to be expected since the layout does not affect the comparisons to be done with the same sorting algorithm. The *subsort* approach incurs fewer branch mispredictions than the *tuple-at-a-time* approach on every data distribution because there are no branches in the comparison function. The *subsort* approach incurs slightly more cache misses than *tuple-at-a-time*. This is caused by re-scanning the data for tied tuples after each sort.

We measure the runtime of the row format approaches and show the results in Figure 4. We use the columnar *subsort* approach from earlier as a baseline. From the results, it is clear that sorting the row data format is more efficient than sorting the columnar data format, as the relative runtime of the row sorting approaches is greater than 1 for almost all inputs. For smaller input sizes, the data fits in the CPU's cache; therefore, random access is not an issue for either the columnar or row data format. The data does not fit in the CPU's cache for larger input sizes and the improved cache locality of the row data format results in a better performance. Like with the columnar data format, the *subsort* approach is faster for most inputs than the *tuple-at-a-time* approach.

Like before, we replicate this exact experiment with std::stable_sort and show the results in Figure 5. When we compare this to Figure 4, we can see that the results are very similar. However, the relative runtimes are slightly better for std::sort, so the benefit of the row format is higher for this algorithm than for std::stable_sort. Interestingly, the *subsort* approach performs better than *tupleat-a-time* with std::stable_sort on the row data format, which was not the case for the columnar data format.

In summary, NSM (row-wise) tuple representation performs much better when sorting relational data than DSM (column-wise). This is true *regardless of data distribution*, and the

Row tuple-at-a-time vs. Columnar subsort Random Correlated0.1 Correlated0.5 Correlated0.9												
2 ²⁴	1.51	1.31	1.39	1.39	1.57	1.39	1.82	2.32	2.54	1.69	1.94	1.70
ws 2 ²⁰	1.27	1.07	1.24	1.16	1.32	1.26	1.58	1.51	1.82	1.32	1.44	1.32
Rows 2 ¹⁶ 2 ²⁰	1.19	1.00	1.15	1.11	1.23	1.16	1.26	1.08	1.48	1.04	1.07	1.08
212	1.16	0.98	1.14	1.09	1.19	1.16	1.12	1.07	1.32	1.04	1.10	1.09
Row subsort vs. Columnar subsort Random Correlated0.1 Correlated0.5 Correlated0.9												
2 ²⁴	1.82	2.36	2.55	1.68	1.96	1.75	1.81	2.55	3.29	1.68	2.00	1.85
Rows 216 220	1.58	1.57	1.70	1.31	1.49	1.34	1.56	1.77	2.38	1.30	1.55	1.52
2 ¹⁶	1.30	1.09	1.38	1.05	1.07	1.06	1.26	1.05	1.32	1.03	1.02	0.98
212	1.12	1.07	1.20	1.03	1.10	1.07	1.11	1.09	1.21	1.03	1.13	1.01
	1 Ke	2 y colun	4 nns									

Fig. 5. Relative runtime (higher is better) of the *tuple-at-a-time* and *subsort* approaches on row data format compared to the *subsort* approach on a columnar data format, with **std::stable sort**.

performance gain is especially noticeable when sorting a large number of tuples. In a columnar execution engine the use of a row-wise format for the sorting operator requires converting the input to rows, perform the actual sort, and then convert the output to columnar format again. It remains to be seen whether the performance benefits of using a row-wise format for sorting are still apparent considering this additional cost. This will be evaluated in end-to-end benchmarks in Section VII.

V. QUERY ENGINES AND SORTING

The Volcano [22] iterator model for pipelined processing leads to tuple-at-a-time query execution, which causes high interpretation overhead, making it unsuitable for OLAP systems. Two main approaches to address this overhead have emerged: Vectorized query execution [5] amortizes this overhead with vector-at-a-time query execution. Compiled query execution [11] uses just-in-time (JIT) compilation to generate code specialized for the operators and types present in the query, eliminating interpretation overhead. These two fundamentally different models have a similar performance in OLAP workloads [12]. Although the concepts of vectorization and compilation are not strictly orthogonal [13], most systems adopt one of the two models.

In a query execution pipeline, sorting is a so-called "pipeline breaker": The sort operator consumes all input data before outputting any because the last input row could be the first output row. This necessitates materializing the input data. To a certain extent, operators that materialize their input have more 'freedom' than streaming operators. They can internally represent the data in any way they see fit as long as they output their data in a way that is compliant with what the execution engine expects. Although converting the data format from and to a different format comes with a cost, it can significantly speed up query processing [19], [23] because it results in better memory access patterns.

Both vectorized and compiling query engines have to choose how to materialize input data for the sort operator. As we saw in the previous section, the data format directly affects sorting efficiency because it affects the cost of comparing and moving data. However, within a database system, sorting is used for many purposes. How other operators use sorted data internally, such as merge- and inequality joins [8], should also be taken into account. In this section, we discuss the effect that the fundamentally different query execution engines have on sorting.

A. Compiled Sorting

From the previous section, it is clear that sorting a row data format is significantly more efficient than sorting a columnar data format. This is especially true when we sort many tuples by many key columns. Compiling query engines use tuple-at-a-time processing on generated data types [12], such as the OrderKey struct that we used in our micro-benchmarks. An array of such structs is essentially relational data in row data format. This format allows compiling query engines to sort using an efficient iterator, such as the C++ iterator interface that is used for std::sort and many other efficient sort implementations [2], [4]. Furthermore, compiling engines can also compile the comparison function itself, which practically removes all interpretation and function call overhead.

In short, compiling query engines can use highly efficient compiled operations to compare and move values, which are the two main costs of sorting. Compiling query engines can adopt the *tuple-at-a-time* or *subsort* approaches and achieve a very efficient sorting performance, matching the best performance we have seen in our micro-benchmarks so far. However, as elegant as they seem, compiling query engines do require highly complex compiler infrastructure to generate the code for each query, greatly increasing overall system complexity.

B. Vectorized (Interpreted) Sorting

Vectorization amortizes the interpretation and function call overhead of tuple-at-a-time processing and does not require compilation. This approach yields excellent performance in many cases because many relational operations are vectorizable. The same is true for sorting: In a system with a vectorized interpreted engine, the *subsort* approach can be used to interpret the type and ASC/DESC, NULLS FIRST/LAST order only once per key column. However, as we have seen, the columnar *subsort* approach is much less efficient than sorting row data for large input sizes.

Furthermore, some operations in database systems cannot use the *subsort* approach. Examples of this are merge sort, merge joins, and inequality joins [8]. These operations iterate sequentially over sorted runs and compare tuples. For example, in a 2-way merge sort, we iterate over a left and a right sorted run. When merging the runs, the decision of incrementing either the left or right iterator relies on a full tuple comparison, i.e., comparing all key columns. Fully comparing tuples in an interpreted engine requires interpreting a type and a sort order for each key column or performing a function callback

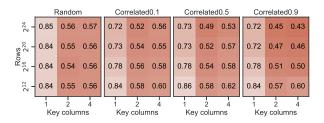


Fig. 6. Relative runtime (higher is better) of a *tuple-at-a-time* approach with a dynamic comparator compared to a static *tuple-at-a-time* comparator on data in row format, with std::sort.

for each key column in the tuple comparison. The former creates interpretation overhead, and the latter creates function call overhead in the comparison function. This overhead is costly [5] and decreases CPU efficiency, especially when called for every tuple, which is necessary for comparing tuples of sorted data.

We illustrate this cost by comparing two *tuple-at-a-time* approaches to sorting the row data format in our microbenchmark. The approaches are identical except that one has a statically compiled comparison function, and the other uses a dynamic function call each time it compares values, incurring function call overhead on every comparison. We show the results of this experiment in Figure 6. As expected, a dynamic function call is always slower than a statically compiled comparison by roughly a factor of 2. This effect is more substantial with more key columns. This benchmark simplifies what would be implemented in a full-fledged database system with a vectorized interpreted engine. However, the experiment accurately illustrates the kind of overhead that interpreted systems face.

From our experiments in the previous section, it is evident that sorting data in a row format is much more efficient than sorting data in a columnar format. In this section, it has become clear that vectorized interpreted execution engines suffer from overheads that hurt sorting efficiency. The *subsort* approach can be used to mitigate this. However, when tuples need to be compared fully, which is often the case when sorted data is used in other relational operations, this approach becomes infeasible. Therefore, vectorized engines need to explore other solutions to overcome this overhead.

VI. SORTING ROWS IN AN INTERPRETED QUERY EXECUTION ENGINE

In this section, we discuss and evaluate techniques to improve the sorting performance on row data format in interpreted query execution engines. These existing techniques have been proposed in the literature, but not together and not in the context of sorting relational data in an interpreted query engine, to the best of our knowledge.

A. Normalized Keys

Key normalization [24] is an encoding technique that produces a single order-preserving string from a sequence of values, which dates back to System R [25].

	c_birth_country c_birth_year	-	
(a)	NETHERLANDS 1992	-	
	GERMANY 1924	-	
	c_birth_country	c_birth_year	
(b)	78 69 84 72 69 82 76 65 78 68 83 0	200 7 0 0	
	71 69 82 77 65 78 89 0	132 7 0 0	
	Normalized Key		_
(c)	177 186 171 183 186 173 179 190 17		
	184 186 173 178 190 177 166 255 25	55 255 255 255 128 0 7 132	

Fig. 7. Key normalization. The original data in (a) is represented byte-by-byte as (b) in-memory on a little-endian machine. The data is encoded as (c) for c_birth_country DESC and c_birth_year ASC.

The technique is illustrated in Figure 7 for the example query in Section II, which orders the customer table by c_birth_country DESC and c_birth_year ASC. The first column, c_birth_country, is of type VARCHAR. The shorter string 'GERMANY' is padded with '0' such that it has the same length as the longer string 'NETHERLANDS' to ensure that the size of each normalized key is the same. The benefit of having the same size for each normalized key is that they can be swapped in place, which avoids indirection and the random access that would be caused by it. It would also be possible to truncate all strings to a fixed length to avoid excessive padding when string lengths are greatly imbalanced. Ties would then need to be resolved separately.

After padding, we flip the bits to get a descending order for this column as specified by the query. The second column, c_birth_year, is of type INTEGER. On a big-endian machine, the most significant byte comes last. To create an order-preserving encoding, we swap the bytes so that the most significant byte comes first. Then, we flip the sign bit such that negative integers appear before positive integers in the ascending sort order. The resulting normalized keys yield the correct order for the example query if we compare them as we would compare binary strings.

String collations (e.g. language-specific comparison rules) are handled by evaluating the collation before encoding the string prefix. NULL values are handled by prefixing each value with an additional byte, denoting whether or not the value is NULL. This byte is flipped depending on whether we are sorting by NULLS FIRST / LAST.

We cannot generate a struct such as OrderKey without JIT compilation. Therefore we have to use memcpy to move the keys. The resulting keys can be compared using the efficient memcmp function from the standard library rather than a complex comparison function.

The conversion from columnar data to normalized keys does not come without cost. However, this conversion can be done efficiently by converting one 'block' of vectors at a time, which likely fits in the CPU's cache, and one vector at a time, amortizing interpretation overhead. The result is a key that can be compared generically and dynamically without any interpretation or function call overhead.

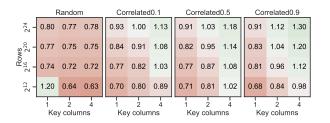


Fig. 8. Relative runtime (higher is better) of a normalized key approach with a dynamic comparator compared to a static *tuple-at-a-time* comparator on data in row format, with std::sort.

We implement this approach and run the same benchmark as before, and show the results in Figure 8. We can directly compare this to Figure 6, as both figures use the same baseline. As we can see, the dynamic normalized keys approach performs much better than the dynamic *tuple-at-a-time* approach. It can match or even outperform the static *tuple-at-a-time* approach, especially with more key columns and for higher correlation factors.

B. Radix Sort

Many database systems use quicksort for run generation, as we will see in the next section when we discuss the sorting implementation of the benchmarked systems. Quicksort, being a comparison-based sort, has a time complexity of $O(n \cdot \log(n))$, where n is the number of rows to be sorted. On the other hand, radix sort is a distribution-based sort with a time complexity of $O(n \cdot k)$, where k is the key size. This is potentially much faster than quicksort when there are many tuples, as k does not depend on the input size. Interestingly, because normalized keys yield the correct sort order when comparing byte-by-byte with memcmp, the keys can also be sorted with a byte-by-byte radix sort. However, radix sort also has downsides: Radix sort may be much slower for a large key size k, especially when nis small. Furthermore, radix sort uses twice as much memory because it needs auxiliary memory of the same size as the input, whereas quicksort sorts in place.

In his survey on implementing sorting in database systems [10], Goetz Graefe remarks that while radix sort may seem like a good option, it has specific shortcomings for database systems: (1) if keys are long and the data contains duplicate keys, many of the passes over the data are unproductive, (2) radix sort is most effective if values are uniformly distributed, (3) if input records are nearly sorted, and the keys have a common prefix, the initial passes of radix sort are rather ineffective, and (4) radix sort has worse cache efficiency than comparison-based sorts.

We implement least significant digit (LSD) radix sort and most significant digit (MSD) radix sort that recurses to insertion sort for buckets with ≤ 24 tuples. We add an optimization to both radix sorts that avoids copying data when all counted values belong to the same bucket, which helps slightly with shortcomings (1) and (3). LSD radix sort is selected when the key size is ≤ 4 bytes, and MSD radix sort is selected

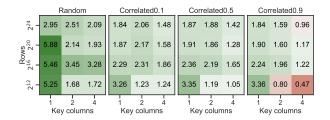


Fig. 9. Relative runtime (higher is better) of sorting normalized keys with radix sort compared to pdqsort with a dynamic memcmp comparator.

otherwise. Radix sort moves data every time it re-distributes using memopy.

For a more fair comparison, we compare our radix sort implementation with the state-of-the-art pdqsort [4], rather than with std::sort. The pdqsort algorithm is a highly optimized comparison-based sort that uses optimizations from BlockQuickSort [2] to reduce branch mispredictions, along with recognizing worst-case patterns that quicksort traditionally does not perform well on. For both algorithms, we create normalized keys. pdqsort uses memcmp dynamically, i.e., with a size parameter that is known at runtime, to get a fair estimation of how well these algorithms would perform in an interpreted execution engine. We show the results of this experiment in Figure 9.

For the Random distribution, radix sort performs better than pdqsort on every input and wins out by a considerable margin when there is only one key column. This is no surprise, as radix sort excels at uniform distributions with a high number of unique values, especially when the number of keys is low.

For the Correlated distributions, radix sort is faster than pdqsort for almost all inputs, except some of the highly correlated ones. Radix sort comparatively does not perform well on those inputs, because of the reasons mentioned earlier in this section. pdqsort, on the other hand, excels at these inputs, because it is able to detect patterns. Despite this, radix sort is faster for most inputs, because pdqsort suffers from comparing tuples with a dynamic comparison function, while radix sort does not perform any comparisons.

We measure performance counters of both sorting approaches for a single input and show them in Figure 10. As expected, radix sort has a worse cache performance than pdqsort. We use 4 key columns; therefore, our radix sort implementation chooses MSD radix sort, which has a much better cache performance than LSD radix sort. Radix sort performs better than pdqsort when it comes to branch mispredictions: It is a mostly branchless algorithm.

In conclusion, our micro-benchmarks show that normalized keys and radix sort are promising to address the performance drawbacks of interpreted query engines. In the next section, we investigate if those observations hold up in end-to-end benchmarks on real-world systems.

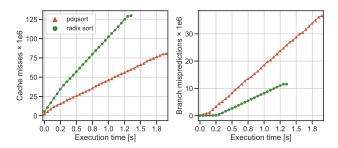


Fig. 10. Cumulative L1 cache misses and branch mispredictions of sorting 2^{24} rows with 4 key columns, Correlated0.5 distribution, with pdqsort with a dynamic comparison function and radix sort.

VII. EVALUATION

In the previous sections, we applied several existing techniques to sorting relational data and evaluated them in microbenchmarks. Our results suggest that these techniques can vastly improve the performance of relational sorting in systems with an interpreted query execution engine. Based on these findings, we implemented an efficient relational sort within our analytical database system, DuckDB, which has a vectorized interpreted execution engine. In this section, we first describe DuckDB's sort implementation in detail. Then, we describe the sort implementations of the four other systems under benchmark. Finally, we evaluate and discuss their performance on sorting integers/floats and a relational sort benchmark based on the TPC-DS [26] data generator.

DuckDB's fully parallel sorting pipeline [27] is shown in Figure 11. DuckDB uses morsel-driven parallelism [6]; therefore, each thread collects roughly the same amount of data in parallel. Key and payload columns are converted separately to row formats, with key columns being converted to normalized keys. This conversion is performed by copying one 'block' of vectors at a time, one vector at a time, making this an efficient and mostly cache-resident process. Both row formats use 8-byte alignment, as we have found that this improves the performance of memcpy. The rows have a fixed size: Variable-sized types like strings are stored separately. Therefore, we encode only a prefix of variable-sized types like strings in our normalized keys: We compare the rest of the string only if the prefixes are equal. For strings, we encode the first n bytes, with n chosen at runtime based on the available statistics on string length, but at most 12. When the amount of data collected by a thread reaches a threshold, we create a sorted run by first sorting the normalized keys with a threadlocal radix sort, or pdqsort if there are strings, with memcmp as the comparison function. We use a version of pdqsort that is modified to specifically handle our normalized keys, such that we can use inlined tuple comparisons². Then, we reorder the payload, creating fully sorted runs of data that are added to a thread-global state.

 $^2\mathrm{The}$ DuckDB source code can be found at https://github.com/duckdb/duckdb

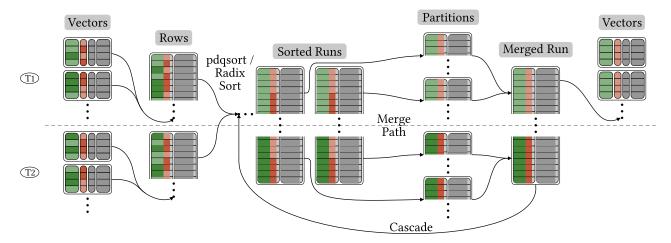


Fig. 11. Full sorting pipeline in DuckDB. Incoming vectors from worker threads (illustrated as T_1 and T_2 in the figure) are converted to 8-byte aligned row formats. Key columns are normalized and stored separately from the payload. The normalized keys are sorted with radix sort or pdqsort, creating sorted runs. The sorted runs are then partitioned and merged in parallel until one run remains. Finally, the result is converted back to vectors.

After all the input data has been added to the global state, we start a 2-way cascaded merge sort. This is trivial to parallelize when there are many more sorted runs than threads, as we can assign each thread to merge two sorted runs. However, as the runs get merged, parallelization degrades until a single thread merges the last two sorted runs available. Therefore, we also parallelize this phase using the Merge Path [3] algorithm. Merge Path creates partitions that can be merged independently and, therefore, in parallel. The partition boundaries are efficiently computed with a binary search that searches for the 'intersection' of two sorted runs. During merge sort, we compare full tuples with memcmp.

We compare DuckDB's sorting performance with four other OLAP/HTAP engines: ClickHouse [14], MonetDB [15], Hy-Per [11], and Umbra [16]. OLTP-focused systems like PostgreSQL and MySQL cannot deliver competitive performance in sorting large datasets. Despite their row-major data layouts, their execution engines suffer from large per-value overheads.

ClickHouse uses a columnar format throughout the sort and performs thread-local sorts with radix sort if sorting by a single integer column; otherwise, it uses pdqsort using a tuple-at-a-time comparison approach. JIT compilation is used to reduce some of the interpretation overhead. After the threadlocal sorts are done, the sorted runs are merged using a kway merge. MonetDB also uses a columnar format throughout the sort, using a single-threaded quicksort implementation. A subsort approach is used when sorting by multiple key columns. After sorting the key columns, the payload is collected in sorted order. HyPer and Umbra have a compiled, row-based sorting implementation similar to what is described in [6]: Threads perform a thread-local quicksort that is similar to pdqsort. The results are then merged using a parallel kway merge. This merge is performed on pointers rather than physically moving the data. The data is physically collected in the sorted order when reading the output of the sort operator.

A. Benchmarking Relational Sorting

Although sorting can easily dominate the runtime of a query, *isolating* the sorting performance of a database system in a benchmark is difficult because we can only reliably observe end-to-end query runtime without access to the source code. In addition, streaming query execution interleaves the execution of multiple operators, which further complicates isolating sorting performance, even if the system has a query profiler. Measuring end-to-end query runtime introduces unwanted overhead unrelated to sorting, e.g., parsing, optimizing, scanning base tables, and transferring the result set through a client protocol. Especially the latter is costly and can easily dominate the query execution time for large result sets [20].

Therefore, we want to use a query that produces a small result set and where execution time is dominated by sorting. A full sort is often optimized out of the query plan if it is not strictly needed. For example, ORDER BY ... LIMIT 1 will typically trigger a specialized top N operator rather than the "normal" sort operator. If we instead aggregate over a subquery that sorts, the sort will likely be discarded by the optimizer because it is irrelevant to the aggregate. We can circumvent this by disabling the optimizer, which is often possible using a configuration setting. This is inadvisable, however, as disabling it may impact performance differently across systems. Instead, we outmaneuver the optimizer with the following query:

```
SELECT count (payload_column),
FROM (SELECT payload_column
FROM input_table
ORDER BY key_column1,
key_column2,
...
OFFSET 1);
```

In this query, the count aggregate reduces the size of the result set to 1, making the result set serialization negligible. The count aggregate reads the sorted subquery, forcing systems

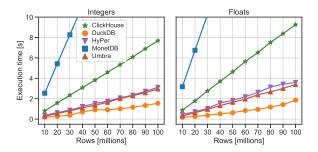


Fig. 12. Execution times (lower is better) of sorting 10 to 100 million random integers and floats in increments of 10 million.

that lazily collect a sorted payload to collect it fully. This is an important detail that ensures that all systems under benchmark perform the same work. The count aggregate is cheap to compute and therefore does not add noticeable overhead to the query. Finally, we add the OFFSET 1, because we found that then the optimizers in the systems we benchmarked do not optimize the ORDER BY in the subquery away³. We repeat this query 5 times and report only the median end-to-end runtime.

B. Random Integers & Floats

For our first benchmark, we measure raw, single-key sorting performance. We generate two sets of 10 tables containing 10 to 100 million rows in increments of 10 million. The first set contains 32-bit integers from 0 to 99.999.999, shuffled. The second set contains 32-bit floating point numbers between -1e9 and 1e9, sampled from a random uniform distribution. Comparing floats is more expensive than comparing integers; therefore, we expect integer sorting to be slightly faster. Following the findings in our micro-benchmarks, we also expect the performance of the columnar approaches of ClickHouse and MonetDB to degrade more quickly with the number of tuples than the row-based approaches due to a worse cache performance. We benchmark the sorting performance of all systems using the m5d.8xlarge AWS EC2 instance.

We show the results of this benchmark in Figure 12. MonetDB is much slower than the other systems; therefore, we cut off the figure to make the differences between the other systems more clearly visible. MonetDB's single-threaded sort takes 29.18s and 36.39s for 100 million integers and floats, respectively. For reference, when limited to a single thread, DuckDB takes 10.41s for the integers and 9.14s for the floats. As expected, all systems sort floats slightly slower than integers due to the more expensive comparison function of floats, except DuckDB. DuckDB does not suffer from this because it encodes both the floats and integers as normalized keys, then sorts them precisely the same. In this benchmark specifically, DuckDB sorts the floats faster than the integers because the floats have a more uniform distribution, making radix sort more effective.

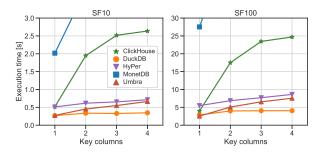


Fig. 13. Execution times (lower is better) at scale factor 10 and 100 of sorting 1 to 4 key columns (cs_warehouse_sk, cs_ship_mode_sk, cs_promo_sk, cs_quantity) of the catalog_sales table.

ClickHouse's sort is competitive with DuckDB, HyPer, and Umbra at 10 million integers, but as the data size increases, its performance degrades more quickly than the other three systems. This is in line with our expectations, as the columnar format that ClickHouse uses has a worse cache performance. DuckDB, HyPer, and Umbra, all of which use a more cache-efficient row-based approach to sorting, show strong scaling with the number of tuples. DuckDB sorts 100 million integers in 1.55s. HyPer and Umbra, which have similar implementations, have a very similar performance on this benchmark, with Umbra being slightly faster than HyPer.

C. TPC-DS Catalog Sales Table

For our second benchmark, we measure how well the systems deal with multiple key columns, which should increase the cost of comparing tuples. Our micro-benchmarks would suggest that the performance of columnar sorting approaches degrades more with additional key columns because they cause more random access than row-based approaches. We use the largest table from TPC-DS, catalog_sales, at scale factors 10 and 100. The cardinality of this table can be found in Table IV. We select only cs_item_sk, and sort it by up to four key columns: cs_warehouse_sk, cs_ship_mode_sk, cs_promo_sk, and cs_quantity.

We show the results of sorting the catalog_sales table in Figure 13. Again, MonetDB's performance is much slower than the other systems; therefore, we cut off the figure. MonetDB is around 3x slower when sorting by four key columns than by one key column. ClickHouse has a competitive sorting performance when sorting by one key column because it only has random access in one column and uses radix sort. However, when sorting by two key columns, ClickHouse slows down by around 4x compared to

TABLE IV CARDINALITY OF TPC-DS TABLES.

S	F	catalog_sales	customer
1	0 00 00	14.401.261 143.997.065	2.000.000 5.000.000

 $^{^3} The$ source code for our end-to-end benchmarks can be found at https://github.com/lnkuiper/experiments/tree/master/sorting. Thanks to André Kohn for suggesting the <code>OFFSET 1</code> trick.

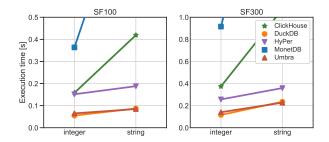


Fig. 14. Execution times (lower is better) at scale factor 100 and 300 of sorting the c_birth_year, c_birth_month, and c_birth_day columns (integer), and the c_last_name and c_first_name columns (string) of the customer table.

sorting by one column because it switches from radix sort to pdqsort with a tuple-at-a-time comparison function that has branches and causes random access in both key columns. As expected, DuckDB's, HyPer's, and Umbra's row-based sorting approaches lose less performance here, as they have good cache performance when comparing subsequent key columns. The cost of the comparison function, however, does still matter for the row-based approaches: Umbra is up to 2.43x and 2.96x slower when sorting four key columns than when sorting one key column at scale factors 10 and 100, respectively, while DuckDB and HyPer are only around 1.5x slower.

D. TPC-DS Customer Table

For our third benchmark, we measure how well the systems sort by fixed- vs. variable-sized types. Comparing strings is much more costly than comparing integers; therefore, we expect that sorting strings will be slower. We use the customer table from TPC-DS at scale factors 100 and 300. The cardinality of this table can be found in Table IV. We select c_customer_sk from this table, and sort it by either c_birth_year, c_birth_month, and c_birth_day, all three of which are INTEGER columns, or by c_last_name and c_first_name, both of which are VARCHAR columns.

We show the results of sorting the customer table in Figure 14. We have again cut off the figure so the differences between the systems are more visible. On the x-axis we have the two categories: integer and string. As expected, sorting strings is slower than sorting integers for all five systems. For ClickHouse and MonetDB, this difference is around 3x. For the other systems, the difference is much smaller.

VIII. CONCLUSION

In this paper, we have discussed the challenges of sorting relational data efficiently in OLAP systems. Following this discussion, we have evaluated different approaches to sorting data using micro-benchmarks. These approaches differed in their row and columnar data formats, their interpreted and compiled execution engines and tuple comparison method. We have found that sorting data in a row format is almost always better than sorting columnar data, mostly due to better cache performance.

Following these findings, we have identified that database systems with a compiling query execution engine can efficiently sort row data format by generating query-specific data types and a comparison function. In systems with a vectorized interpreted engine, however, the efficiency of sorting rows is hindered by interpretation and function call overhead in the comparison function. To overcome this overhead, we have proposed using key normalization and both radix sort and pdqsort for fixed-with and variable-width data types, respectively.

Finally, we implemented these techniques in DuckDB, which has a vectorized interpreted query execution engine. We evaluated our implementation with end-to-end sorting benchmarks. We compared our results on this benchmark with four other analytical database management systems, which have a different execution engine. This comparison showed that our sort implementation matches or outperforms all other systems under benchmark and, therefore, that the proposed techniques effectively overcome the interpretation and function call overhead that systems with an interpreted execution engine theoretically would be at a disadvantage of. Our implementation has been part of every DuckDB release since version 0.3 and is widely used.

IX. FUTURE WORK

DuckDB uses pdqsort in its thread-local sorts when strings are present; otherwise, it uses radix sort. Variables other than the data type affect the efficiency of these algorithms, for example, key size, number of tuples, the estimated number of unique values, and other statistics. A heuristic that takes these variables into account could improve the algorithm choice. Additionally, pdqsort could be used within the recursive calls to MSD radix sort, which may improve sorting performance even further.

Besides the sort operator, the aggregate, join, and window operators are also blocking operators. They materialize their input because they cannot stream data, i.e., all input data must be consumed and processed before data can be output. In DuckDB, these operators use a unified row format. However, DuckDB's vectorized engine moves vectors between operators. When we chain blocking operators, for example, when we aggregate over the output of a join or sort the output of an aggregate, the data is converted from rows to vectors and back to rows again. We could prevent these unnecessary conversions by allowing the execution engine to pass data in row data format between operators.

The same blocking operators risk running out of memory because they must materialize their input. When the data size exceeds the memory limit, many main-memory database systems either cannot complete the query or switch to an out-of-core strategy, orders of magnitude slower than the inmemory strategy. This could be overcome by designing these operators so that their performance gracefully degrades as the data size exceeds the memory limit. Utilizing DuckDB's row format to be able to offload the data to secondary storage in a unified way could enable this.

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