## ALGORITHM UPDATE FOR 3D BAR ELEMENTS

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- ESTRUCTURES AEROESPACIALS -

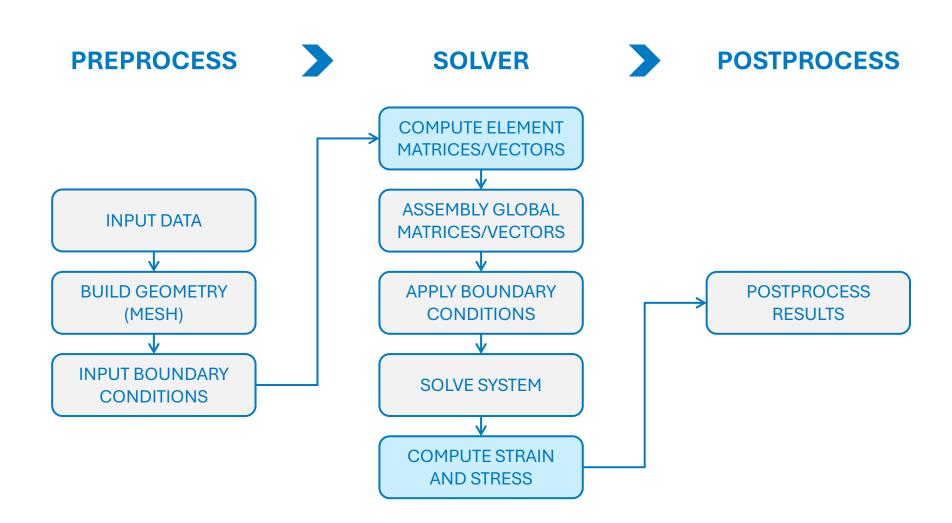
## Global algorithm



#### Global algorithm

Compute element matrices/vectors

Compute strain and stress



# Elements (nel

## Compute element matrices/vectors



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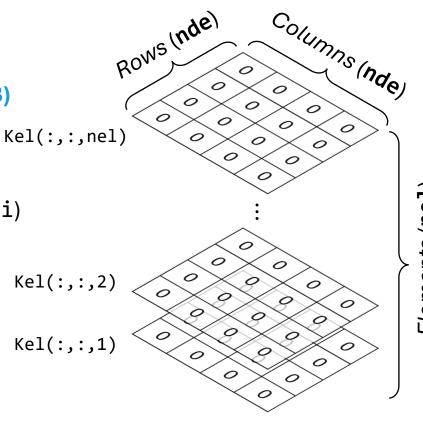


xnod, Tnod, mat, Tmat, fixnod, fdata ... (other data)

#### **Dimensions:**

- **nnod** = Number of nodes
- ni = Number of DOFs per node (for this case ni=3)
- **nel** = Number of elements
- **nne** = Number of nodes per element
- **ndof** = Total number of DOFs (ndof = nnod  $\times$  ni)
- **nde** = Number of DOFs per element (nde =  $nne \times ni$ )
- 1. Initialize **element matrices** and **vectors**:

$$Kel = [0]_{nde} \times nde \times nel$$
  
 $fel = [0]_{nde} \times nel$ 



ROWS (nde)

### Compute element matrices/vectors



Global algorithm

## Compute element matrices/vectors

Compute strain and stress

- 2. Loop over each **element** (from e = 1 to ne1)
  - 2.1 From **xnod** and **Tnod**, get element nodal coordinates:  $x_1$ ,  $y_1$ ,  $z_1$ ,  $x_2$ ,  $y_2$ ,  $z_2$
  - 2.2 From mat and Tmat, get element material properties: E, A,  $\sigma_0$
  - 2.3 Compute element length:

$$l = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

2.4 Compute rotation matrix

$$c_{x} = (x_{2} - x_{1})/l$$

$$c_{y} = (y_{2} - y_{1})/l$$

$$c_{z} = (z_{2} - z_{1})/l$$

$$[R] = \begin{bmatrix} c_{x} & c_{y} & c_{z} & 0 & 0 & 0\\ 0 & 0 & 0 & c_{x} & c_{y} & c_{z} \end{bmatrix}$$

## Compute element matrices/vectors



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2.5 Compute element force vector

$$fel(:,e) = -\sigma_0 A[\mathbf{R}]^T \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

2.6 Compute element stiffness matrix

$$Kel(:,:,e) = EA/l[\mathbf{R}]^{T}\begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix}[\mathbf{R}]$$

## Compute strain and stress



Global algorithm

Compute element matrices/vectors

Compute strain and stress

- 1. Loop over each **element** (from e = 1 to nel)
  - 1.1 From **xnod** and **Tnod**, get element nodal coordinates:  $x_1, y_1, z_1, x_2, y_2, z_2$
  - 1.2 From **mat** and **Tmat**, get element material properties: E,  $\sigma_0$
  - 1.3 From **Tnod** and **ni**, get element global DOFs: **I** (alternatively, get them from **Tdof**)
  - 1.4 Compute element length and rotation matrix: l, [R]
  - 1.5 Get axial displacements of element:  $u_1'$ ,  $u_2'$
  - 1.6 Compute element strain

$$\varepsilon = (u_2' - u_1')/l$$

1.6 Compute element stress

$$sig(e,1) = \sigma_0 + E\varepsilon$$

Element nodal displ. Element nodal displ. in *global* coordinates in *local* coordinates

