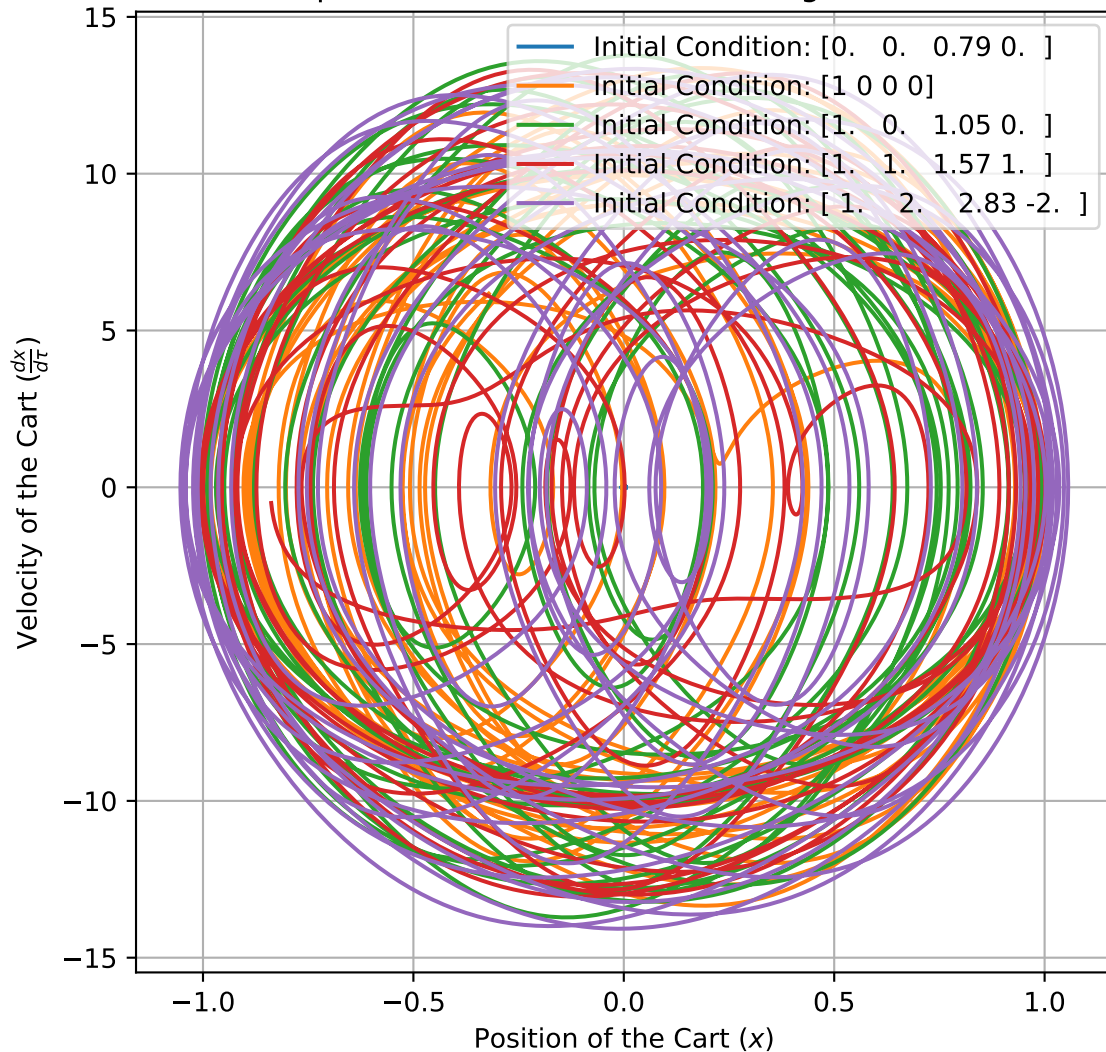


State Space: Cart (M = 0.5, m = 0.5, g = 1, k = 100)



State Space: Pendulum (M = 0.5, m = 0.5, g = 1, k = 100)

