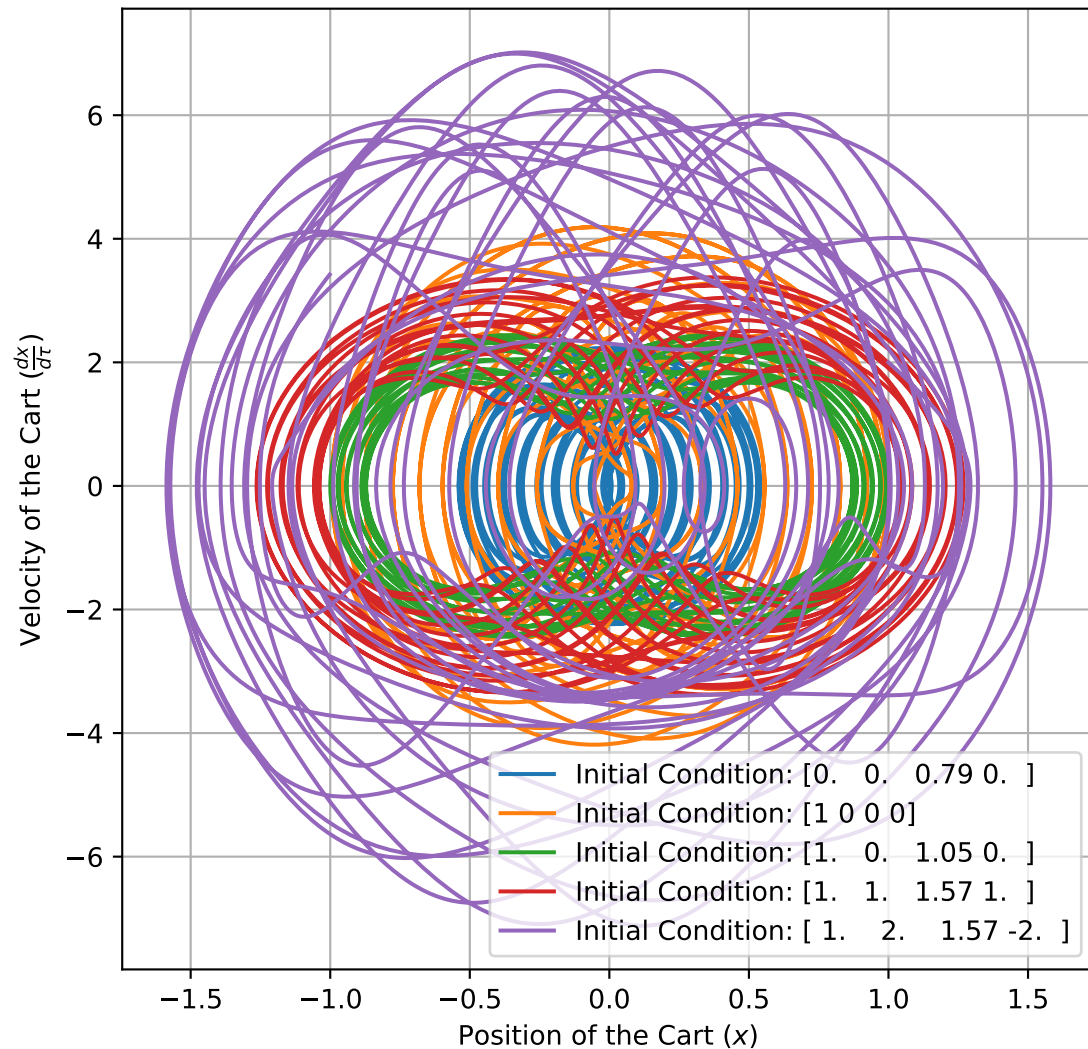


State Space: Cart ($M = 0.5$, $m = 0.5$, $g = 10$, $k = 10$)



State Space: Pendulum ($M = 0.5$, $m = 0.5$, $g = 10$, $k = 10$)

