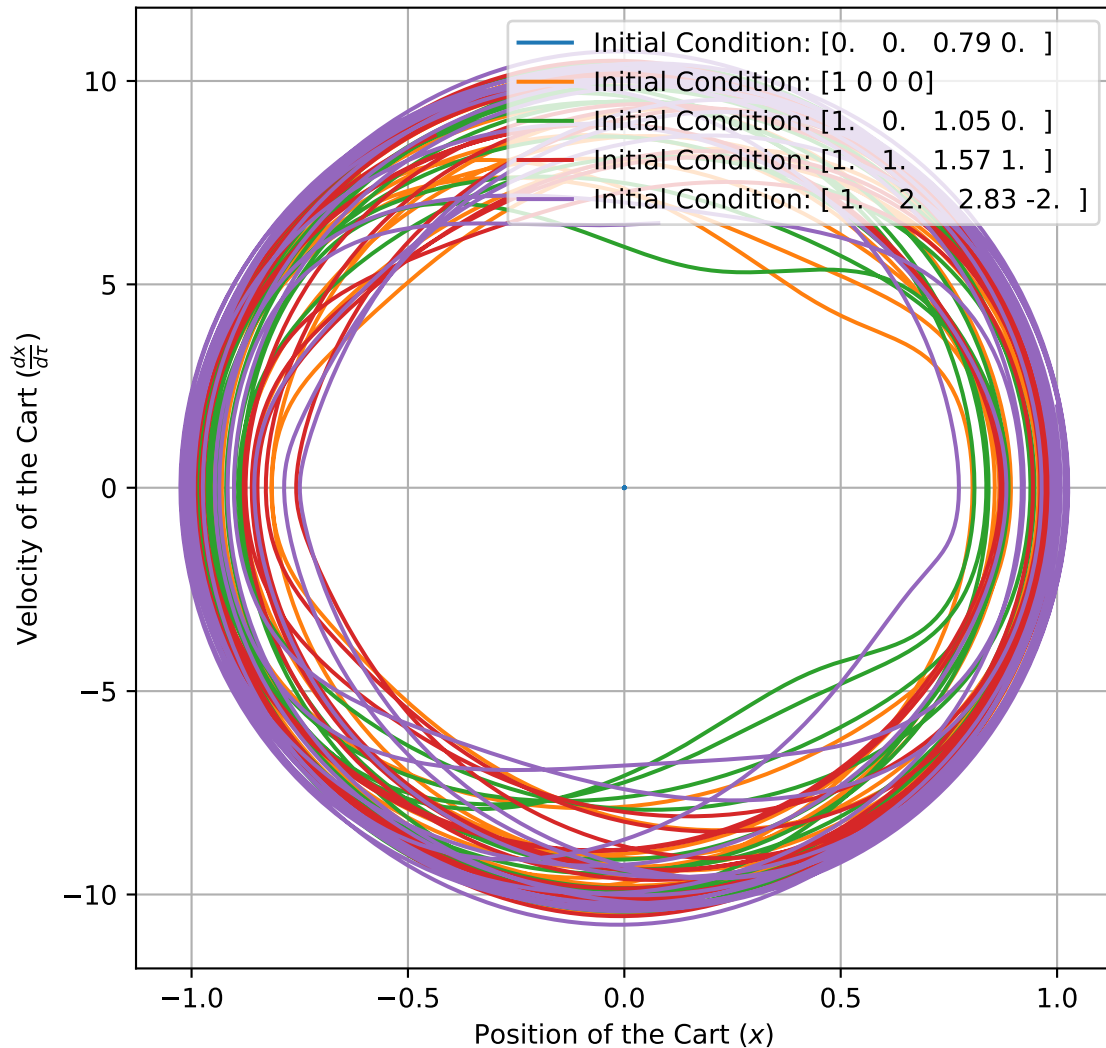


State Space: Cart ($M = 0.91$, $m = 0.09$, $g = 1$, $k = 100$)



State Space: Pendulum ($M = 0.91$, $m = 0.09$, $g = 1$, $k = 100$)

