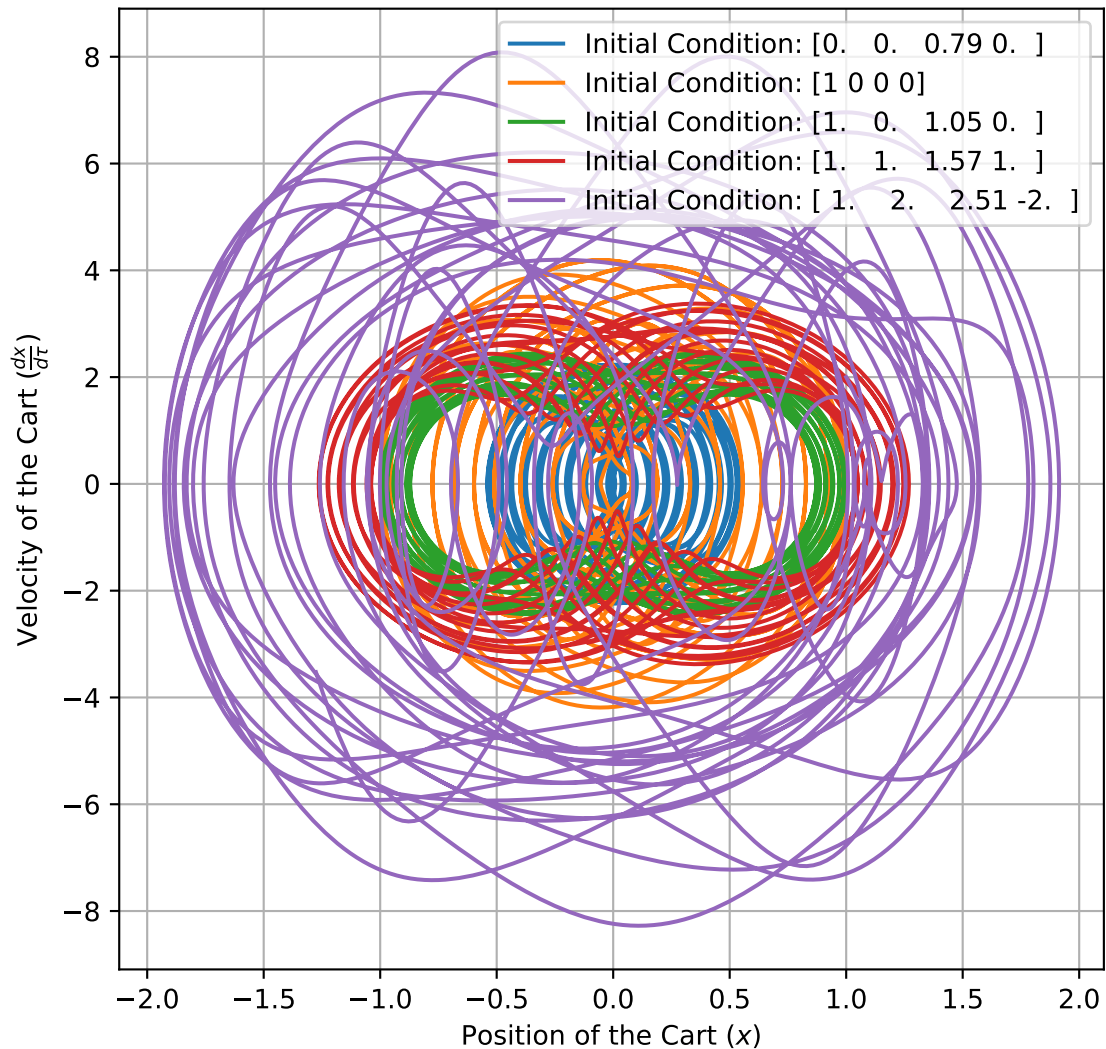


State Space: Cart (M = 0.5, m = 0.5, g = 10, k = 10)



State Space: Pendulum (M = 0.5, m = 0.5, g = 10, k = 10)

