

Advanced Mathematics - Linear Algebra

Chapter 2: Matrix algebra

Department of Mathematics
The FPT university

Chapter 2 Introduction

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Topics:

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2.1 Matrix operations: Addition, Scalar multiplication, Transposition

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2.2 Matrix multiplication

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- 2.3 Matrix inverses

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- 2.5 Matrix transformations

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- 2.3 Matrix inverses
- 2.5 Matrix transformations
- 2.7 Applications

2.1 Matrix addition, Scalar multiplication, and Transposition

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A matrix is an array consisting of m rows and n columns:

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \cdots & \cdots & a_{ij} & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

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- If $m = n$ then we say A is a **square matrix**.

Matrix Addition and Scalar multiplication

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Addition and Subtraction

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$$\begin{bmatrix} a & b & c \\ x & y & z \end{bmatrix} \pm \begin{bmatrix} A & B & C \\ X & Y & Z \end{bmatrix} = \begin{bmatrix} a \pm A & b \pm B & c \pm C \\ x \pm X & y \pm Y & z \pm Z \end{bmatrix}$$

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Scalar multiplication

$$k \begin{bmatrix} a & b & c \\ x & y & z \end{bmatrix} = \begin{bmatrix} ka & kb & kc \\ kx & ky & kz \end{bmatrix}, \text{ where } k \text{ is a real number}$$

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Theorem

- $A + B = B + A$
- $A + 0 = 0 + A = A$
- $A + (B + C) = (A + B) + C$
- $k(A + B) = kA + kB$
- $kA + pA = (k + p)A$
- $k(pA) = (kp)A$
- $1.A = A$

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Example. Find A such that:

$$\left(2A^T + \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \right)^T = \begin{bmatrix} 1 & -1 \\ 2 & 3 \end{bmatrix}$$

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Question.

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Question. Is the sum of two symmetric matrices symmetric?

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Examples.

$$\begin{bmatrix} a & b & c \\ x & y & z \end{bmatrix} \begin{bmatrix} M & N \\ P & Q \\ U & V \end{bmatrix} = \begin{bmatrix} aM + bP + cU & aN + bQ + cV \\ xM + yP + zU & xN + yQ + zV \end{bmatrix}$$

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$$\begin{bmatrix} 2 \\ 3 \\ 4 \end{bmatrix} \begin{bmatrix} a & b & c \end{bmatrix} = \begin{bmatrix} 2a & 2b & 2c \\ 3a & 3b & 3c \\ 4a & 4b & 4c \end{bmatrix}$$

The **identity** matrix I_n is the $n \times n$ matrix with 1 on the diagonal and 0 everywhere else.

The **identity** matrix I_n is the $n \times n$ matrix with 1 on the diagonal and 0 everywhere else.

Theorem

Let A, B, C be matrices of sizes such that the indicated operations can be performed. I denotes an identity matrix, and k a real number.

- $AI = IA = A$
- $AB \neq BA$, in general
- $A(BC) = (AB)C$
- $A(B + C) = AB + AC$
- $(B + C)A = BA + CA$
- $k(AB) = (kA)B = A(kB)$
- $(AB)^T = B^T A^T$

Block multiplication

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$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 3 & 4 & 0 & 0 \\ 1 & 0 & 5 & 6 \\ 0 & 1 & 7 & 8 \end{bmatrix} \begin{bmatrix} 9 & 10 \\ 11 & 12 \\ 0 & 0 \\ 0 & 0 \end{bmatrix} =$$

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$$= \begin{bmatrix} A & 0 \\ I & B \end{bmatrix} \begin{bmatrix} C \\ 0 \end{bmatrix} = \begin{bmatrix} AC \\ C \end{bmatrix} = \begin{bmatrix} 31 & 34 \\ 71 & 78 \\ 9 & 10 \\ 11 & 12 \end{bmatrix}$$

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$$\left[\begin{array}{cc|cc} 1 & 0 & 1 & 2 \\ 0 & 1 & 3 & 4 \\ \hline 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{array} \right]^{10}$$

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Matrices and Linear systems

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A system of linear equations

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$$\left\{ \begin{array}{cccccc} a_{11}x_1 & + & a_{12}x_2 & + & \cdots & + & a_{1n}x_n & = & b_1 \\ a_{21}x_1 & + & a_{22}x_2 & + & \cdots & + & a_{2n}x_n & = & b_2 \\ & & & & \cdots & & & & \\ a_{m1}x_1 & + & a_{m2}x_2 & + & \cdots & + & a_{mn}x_n & = & b_m \end{array} \right.$$

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A system of linear equations

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can be written as a matrix equation $AX = B$, where

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ & & \cdots & \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}, \quad X = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}, \quad B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}$$

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Notes.

- A matrix may not have an inverse. For example, the matrix $\begin{bmatrix} 1 & 2 \\ 3 & 6 \end{bmatrix}$ does not have an inverse.
- The inverse matrix of a matrix A , if exists, is unique and is denoted by A^{-1} . In this case we say A is **invertible**.

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Example. Find inverses of the matrices

$$A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & 4 \\ 3 & 6 \end{bmatrix}$$

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Consider a system of linear equations $AX = B$. If the matrix A is invertible, then $X = A^{-1}B$ is the solution.

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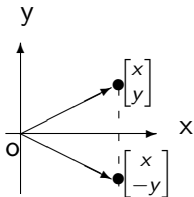
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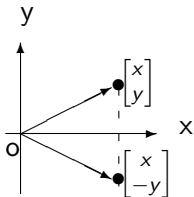
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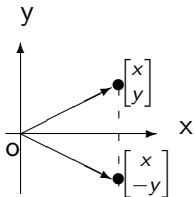
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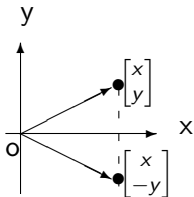
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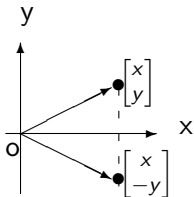


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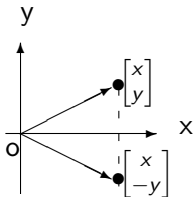


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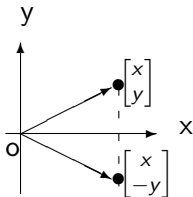
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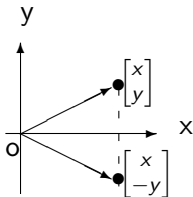
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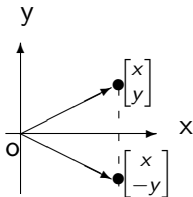
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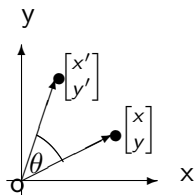
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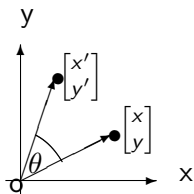
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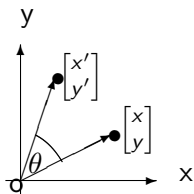




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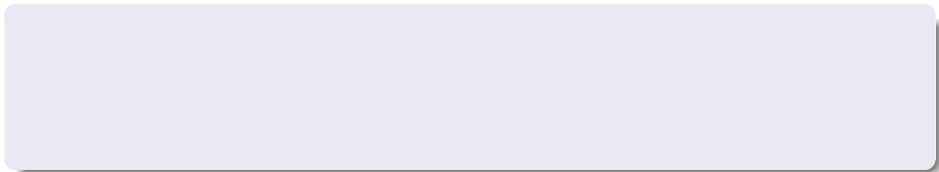
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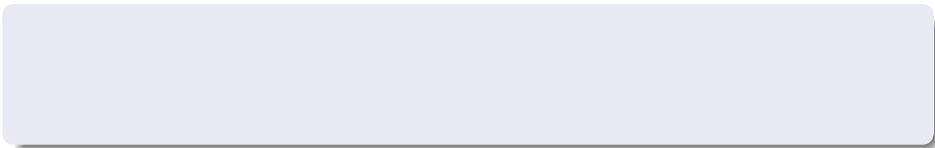
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Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Then

$$T(a_1 \vec{x}_1 + a_2 \vec{x}_2 + \cdots + a_k \vec{x}_k) = a_1 T(\vec{x}_1) + a_2 T(\vec{x}_2) + \cdots + a_k T(\vec{x}_k)$$

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Linear Transformation and Matrix Linear Transformation

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Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear transformation. Then T is a matrix transformation induced by the following $m \times n$ matrix

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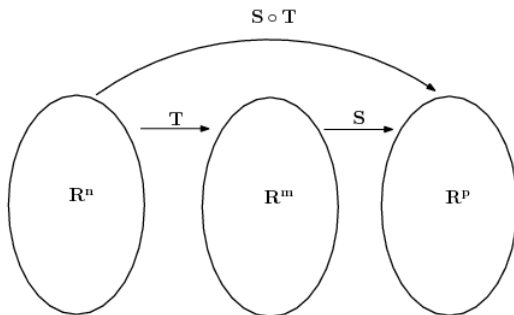
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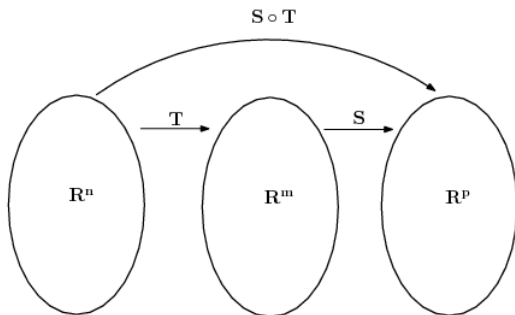
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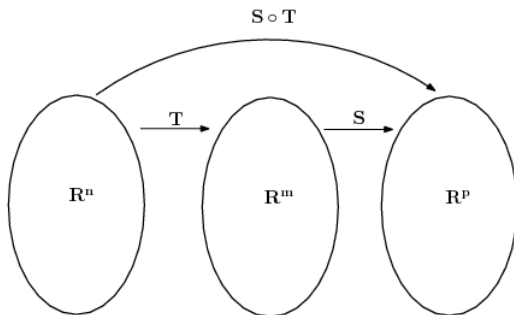


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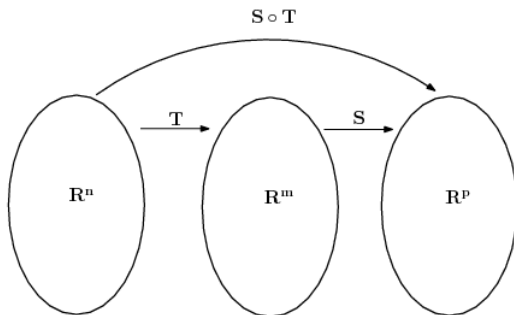
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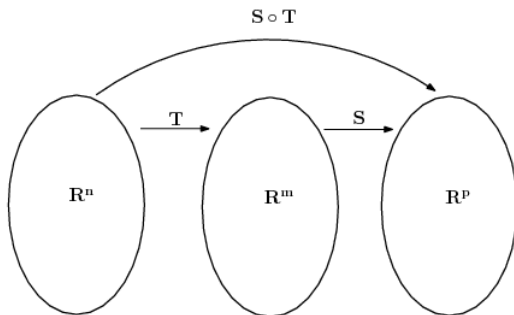


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Solutions P to the equation $(I - E)P = 0$ are called **equilibrium price structures**.