CSC 4320/6320: Operating Systems



Chapter 04: Threads and Concurrency-Part 2

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Outline



- Overview
- Multicore Programming
- Multithreading Models
- Thread Libraries
- Implicit Threading
- Threading Issues

Objectives



- Identify the basic components of a thread, and contrast threads and processes
- Describe the benefits and challenges of designing multithreaded applications
- Illustrate different approaches to implicit threading including thread pools, fork-join, and Grand Central Dispatch
- Describe how the Windows and Linux operating systems represent threads
- Designing multithreaded applications using the Pthreads, Java, and Windows threading APIs

Thread Libraries



- Thread library provides programmer with API for creating and managing threads
- Two primary ways of implementing
 - Library entirely in user space
 - Kernel-level library supported by the OS

It is possible to create a thread library without any kernel-level support.

True √ False

User-level Threads



- Thread Creation: The thread library allocates memory for the thread's stack and registers, and it creates the thread control block (TCB) to store its state.
- Context Switching: Kernel is unaware of the threads; the thread library must handle switching between threads by saving and restoring the register state.
- Scheduling: The thread library must implement its own scheduler to decide when to switch between threads.
- **Synchronization**: Since the threads are not managed by the kernel, the thread library must provide synchronization to coordinate access to shared resources.

Pthreads



- May be provided either as user-level (usually not now) or kernel-level
- A POSIX standard (IEEE 1003.1c) API for thread creation and synchronization
- Specification, not implementation (Operatingsystem designers may implement the specification)
- API specifies behavior of the thread library, implementation is up to development of the library
- Common in UNIX operating systems (Linux & Mac OS X)
- Most modern operating systems, such as Linux and macOS, use kernel-level threads for Pthreads.

Pthreads Example



Task: construct a multithreaded program that calculates the summation up to a non-negative integer in a separate thread.

$$sum = \sum_{i=1}^{N} i$$

```
#include <pthread.h>
#include <stdio.h>
#include <stdlib.h>
int sum; /* this data is shared by the thread(s) */
void *runner(void *param); /* threads call this function */
int main(int argc, char *argv[])
  pthread t tid; /* the thread identifier */
  pthread attr t attr; /* set of thread attributes */
  /* set the default attributes of the thread */
    pthread attr init(&attr);
  /* create the thread */
  pthread create(&tid, &attr, runner, argv[1]);
  /* wait for the thread to exit */
  pthread join(tid,NULL);
  printf("sum = %d\n",sum);
```

Pthreads Example (Cont.)



- Note: You are free to use any valid C thread function.
- The thread function must return a void*.
- The thread function must take a single argument of type void*.

```
/* The thread will execute in this function */
function name for the void *runner(void *param)
                    int i, upper = atoi(param);
                    sum = 0;
                    for (i = 1; i <= upper; i++)
                      sum += i;
                    pthread exit(0);
```

void* is a generic pointer, the thread function can return any data type by casting it to void*. A concrete example of how to use this generic pointer (void *) to return an integer is shown in the next slide.





```
#include <pthread.h>
                                                            /* The thread will execute in this function */
#include <stdio.h>
                                                           void *runner(void *param){
#include <stdlib.h>
                                                              int i, upper = atoi(param);
                                                              sum = 0;
int sum; /* this data is shared by the thread(s) */
                                                              for (i = 1; i <= upper; i++)</pre>
void *runner(void *param); /* threads call this function */
                                                                  sum += i;
int main(int argc, char *argv[]) {
                                                              /* do the following to return a local variable */
  pthread t tid; /* the thread identifier */
                                                              int* result = malloc(sizeof(int));/*heap will be alive*/
 pthread attr t attr; /* set of thread attributes */
                                                              *result = 42; /* e.g., store an integer value
                                                             /* We can use both ways to return values */
  /* set the default attributes of the thread */
 pthread_attr_init(&attr);
                                                             // return (void*)result; /*one way to return */
                                                              pthread exit((void *)result); /*another way to return */
  /* create the thread */
 pthread create(&tid, &attr, runner, argv[1]);
  /* handle return value */
 void *return value;
 /* wait for the thread to exit */
 pthread join(tid, &return value); /*use NULL (if not interested)*/
  int *result = (int *)return value;
 printf("The returned value:%d\n", *result); /*a dummy ret value*/
 printf("sum = %d\n",sum);
 free(result);
  return 0;
```

Pthreads Code for Joining 10 Threads Georgia State



A simple method for waiting on several threads using the pthread join() function is to enclose the operation within a simple for loop

#define NUM THREADS 10

```
/* an array of threads to be joined upon */
pthread_t workers[NUM_THREADS];
for (int i = 0; i < NUM THREADS; i++)</pre>
  pthread_join(workers[i], NULL);
```

Windows Multithreaded C Program



```
#include <windows.h>
#include <stdio.h>
DWORD Sum; /* data is shared by the thread(s) */

/* The thread will execute in this function */
DWORD WINAPI Summation(LPVOID Param)

{
    DWORD Upper = *(DWORD*)Param;
    for (DWORD i = 1; i <= Upper; i++)
        Sum += i;
    return 0;
}</pre>
```

DWORD: 32-bit unsigned integer.(double word) **LPVOID** is equivalent to **void*** in standard C/C++. (Long Pointer to Void)

(DWORD*) Param: This part casts the generic param pointer to a pointer of type **DWORD***.

Windows Multithreaded C Program (Cont.) orga State

```
int main(int argc, char *argv[])
  DWORD ThreadId;
  HANDLE ThreadHandle;
  int Param;
  Param = atoi(argv[1]);
  /* create the thread */
  ThreadHandle = CreateThread(
     NULL, /* default security attributes */
     0, /* default stack size */
     Summation, /* thread function */
     &Param, /* parameter to thread function */
     0, /* default creation flags */
     &ThreadId); /* returns the thread identifier */
   /* now wait for the thread to finish */
  WaitForSingleObject(ThreadHandle, INFINITE);
  /* close the thread handle */
  CloseHandle(ThreadHandle);
  printf("sum = %d\n",Sum);
```

Java Threads



- Java threads are managed by the JVM
- Typically implemented using the threads model provided by underlying OS
- Java threads may be created by:
 - Extending Thread class
 - Implementing the Runnable interface

```
public interface Runnable
{
    public abstract void run();
}
```

Standard practice is to implement Runnable interface

Java Threads



Implementing Runnable interface:

```
class Task implements Runnable
{
   public void run() {
      System.out.println("I am a thread.");
   }
}
```

Creating a thread:

```
Thread worker = new Thread(new Task());
worker.start();
```

Waiting on a thread:

```
try {
   worker.join();
}
catch (InterruptedException ie) { }
```

Creating thread and waiting are within the main function in public class

Questions



- A _____ provides an API for creating and managing threads.
- A) set of system calls
- B) multicore system
- C) thread library
- D) multithreading model

Pthreads refers to _____.

- A) the POSIX standard.
- B) an implementation for thread behavior.
- C) a specification for thread behavior.
- D) an API for process creation and synchronization.

Implicit Threading



- Growing in popularity as numbers of threads increase, program correctness more difficult with explicit threads
- In implicit threading, creation and management of threads done by compilers and run-time libraries rather than programmers
- Five methods explored
 - Thread Pools
 - Fork-Join
 - OpenMP
 - Grand Central Dispatch
 - Intel Threading Building Blocks

Thread Pools



- Create a number of threads in a pool where they await work
- Advantages:
 - Usually slightly faster to service a request with an existing thread than create a new thread
 - Allows the number of threads in the application(s) to be bound to the size of the pool
 - Separating task to be performed from mechanics of creating task allows different strategies for running task
 - i.e, Tasks could be scheduled to run after a time delay or to run periodically
- Windows API supports thread pools:

```
DWORD WINAPI PoolFunction(PVOID Param) {
    /* this function runs as a separate thread. */
}
```

How does Thread Pool work?

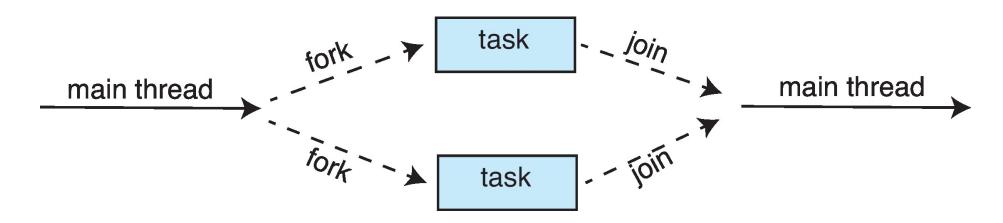


- When a server receives a request, rather than creating a thread, it instead submits the request to the thread pool and resumes waiting for additional requests.
- If there is an available thread in the pool, it is awakened, and the request is serviced immediately.
- If the pool contains no available thread, the task is queued until one becomes free.
- Once a thread completes its service, it returns to the pool and awaits more work.

Fork-Join Parallelism



Multiple threads (tasks) are forked, and then joined.



Fork-Join Parallelism



General algorithm for fork-join strategy:

```
Task(problem)
  if problem is small enough
    solve the problem directly
  else
    subtask1 = fork(new Task(subset of problem)
    subtask2 = fork(new Task(subset of problem)

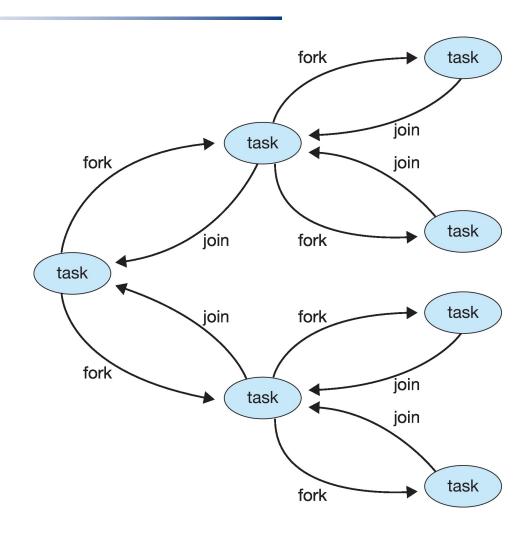
    result1 = join(subtask1)
    result2 = join(subtask2)

return combined results
```

Java introduced a fork-join library in Version 1.7 of the API that is designed to be used with recursive divide-and-conquer algorithms such as Quicksort and Mergesort.



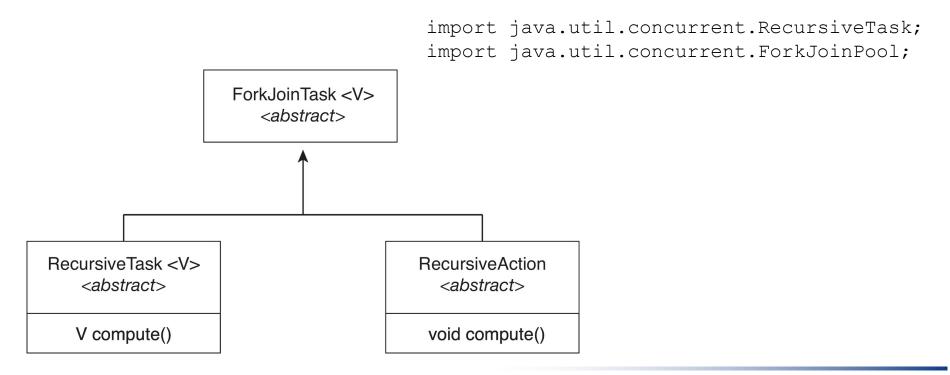




Fork-Join Parallelism in Java



- The ForkJoinTask is an abstract base class
- RecursiveTask and RecursiveAction classes extend ForkJoinTask
- RecursiveTask returns a result (via the return value from the compute() method)
- RecursiveAction used for task that does not return a result



OpenMP



- OpenMP is a set of compiler directives and an API for C, C++, FORTRAN
- Provides support for parallel programming in shared-memory environments
- Identifies parallel regions blocks of code that can run in parallel

#pragma omp parallel
Create as many threads as
there are cores

```
#include <omp.h>
#include <stdio.h>
int main(int argc, char *argv[])
  /* sequential code */
  #pragma omp parallel
    printf("I am a parallel region.");
  /* sequential code */
  return 0;
```

How to execute:

```
gcc -fopenmp openmp_ex.c -o openmp
./openmp
```

OpenMP (contd.)



Run the for loop in parallel

```
#pragma omp parallel for
for (i = 0; i < N; i++) {
   c[i] = a[i] + b[i];
}</pre>
```

 OpenMP divides the work contained in the for loop among the threads it has created in response to the directive

```
#pragma omp parallel for
```

 Available on several open-source and commercial compilers for Linux, Windows, and macOS systems.





```
#include <stdio.h>
#include <omp.h>
int main() {
    #pragma omp parallel
        printf("Hello from thread %d\n", omp_get_thread_num());
    return 0;
Output:
Hello from thread 2
Hello from thread 0
Hello from thread 3
Hello from thread 1
```

Grand Central Dispatch



- Apple technology for macOS and iOS operating systems
- Extensions to C, C++ and Objective-C languages, API, and run-time library
- Allows identification of parallel sections, like OpenMP
- Manages most of the details of threading
- Block is in "^{ }":

```
^{ printf("I am a block"); }
```

- Blocks placed in dispatch queue
 - Assigned to available thread in thread pool when removed from queue (i.e., takes from the queue and assigns a thread)

Intel Threading Building Blocks (TBB) Georgia States and States an

- Georgia State
 University
- Template library for designing parallel C++ programs
- A serial version of a simple for loop

```
for (int i = 0; i < n; i++) {
   apply(v[i]);
}</pre>
```

 The same for loop written using TBB with parallel_for statement:

```
parallel_for (size_t(0), n, [=](size_t i) {apply(v[i]);});
```

- TBB library will divide the loop iterations into separate "chunks" and create a number of tasks that operate on those chunks.
- Supported by major OS: Linux/Windows/Mac OS

Questions



- 1. A _____ uses an existing thread rather than creating a new one to complete a task.
- A) lightweight process
- B) thread pool

C) scheduler activation

D) asynchronous procedure call

When OpenMP encounters the #pragma omp parallel directive, it

- A) constructs a parallel region
- B) creates a new thread
- C) creates as many threads as there are processing cores

D) parallelizes for loops

C\

B√

Threading Issues



- Semantics of fork () and exec () system calls
- Signal handling
 - Synchronous and asynchronous
- Thread cancellation of target thread
 - Asynchronous or deferred
- Thread-local storage
- Scheduler Activations

Semantics of fork() and exec()



- Does fork () duplicate only the calling thread or all threads?
 - Some UNIXes have two versions of fork: fork() and vfork()
- exec() usually works as normal replace the running process including all threads
 - if a thread invokes the exec() system call, the program specified in the parameter to exec() will replace the entire process including all threads.

Which version of fork () to use?



- Depends on the application.
- If exec() is called immediately after forking, then duplicating all threads is unnecessary
 - the program specified in the parameters to exec() will replace the process.
 - duplicating only the calling thread is appropriate.
- If the separate process does not call exec() after forking, the separate process should duplicate all threads.

```
pid_t pid = vfork(); /* instead of a fork() call */
```

 vfork() is faster than fork(), because memory space of the parent process is not copied.

Signal Handling



- Signals are used in UNIX systems to notify a process that a particular event has occurred.
- A signal handler is used to process signals
 - 1. Signal is generated by particular event
 - 2. Signal is delivered to a process
 - 3. Signal is handled by one of two signal handlers:
 - 1. default
 - 2. user-defined
- Every signal has default handler that kernel runs when handling signal
 - User-defined signal handler can override default
 - For single-threaded, signal delivered to process





```
#include <stdio.h>
#include <signal.h>
#include <unistd.h>
#include <stdlib.h>
/* define user friendly handler */
void handle sigint(int sig) {
    printf("Caught signal %d (SIGINT)!\n", sig);
    printf("\nExiting from the program intentionally");
    exit(0);
int main() {
    /* set which signal we want to handle: SIGINT */
    signal(SIGINT, handle sigint);
    printf("Press Ctrl + C (SIGINT) to test. Process ID: %d\n", getpid());
    while (1) {
        sleep(1); /* Infinite loop */
    return 0;
```

Signal Handling (Cont.)



- Where should a signal be delivered for multithreaded?
 - Deliver the signal to the thread to which the signal applies
 - Deliver the signal to every thread in the process
 - Deliver the signal to certain threads in the process
 - Assign a specific thread to receive all signals for the process
- Synchronous signals need to be delivered to the thread causing the signal and not to other threads in the process.
- Some asynchronous signals—such as a signal that terminates a process (<control><C>, for example)—should be sent to all threads.

Thread Cancellation



- Terminating a thread before it has finished
- Thread to be canceled is target thread
- Two general approaches:
 - Asynchronous cancellation: one thread terminates the target thread immediately
 - Deferred cancellation allows the target thread to periodically check if it should terminate.
- Pthread code to create and cancel a thread:

```
pthread_t tid;

/* create the thread */
pthread_create(&tid, 0, worker, NULL);

. . .

/* cancel the thread */
pthread_cancel(tid);

/* wait for the thread to terminate */
pthread_join(tid,NULL);
```

Note: Invoking thread cancellation requests cancellation, but actual cancellation depends on thread state

Thread-Local Storage



- Thread-local storage (TLS) allows each thread to have its own copy of data
- Useful when you do not have control over the thread creation process (i.e., when using a thread pool)
- Different from local variables
 - Local variables visible only during single function invocation
 - TLS visible across function invocations
- Similar to static data
 - TLS is unique to each thread
- The gcc compiler provides the storage class keyword thread for declaring TLS data. For example:

```
- static __thread int threadID;
```

Scheduler Activations



- Both M:M and Two-level models require communication to maintain the appropriate number of kernel threads allocated to the application
- Typically use an intermediate data structure between user and kernel threads lightweight process (LWP)
 - Appears to be a virtual processor on which process can schedule user thread to run
 - Each LWP attached to kernel thread
 - How many LWPs to create? (varies; good to start with creating one LWP per available core)
- Scheduler activations provide upcalls a communication mechanism from the kernel to the upcall handler in the thread library
- This communication allows an application to maintain the correct number kernel threads

