

# CSC 4320/6320: Operating Systems

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## Chapter 07: Synchronization Examples- contd.

Spring 2025

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# POSIX Unnamed Semaphores

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- Creating and initializing the semaphore:

```
#include <semaphore.h>
sem_t sem;

/* Create the semaphore and initialize it to 1 */
sem_init(&sem, 0, 1); /* the semaphore is shared between
                      threads in the same process */
```

- Acquiring and releasing the semaphore:

```
/* acquire the semaphore */
sem_wait(&sem);

/* critical section */

/* release the semaphore */
sem_post(&sem);
```

# POSIX Condition Variables

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- Since POSIX is typically used in C/C++ and these languages do not provide a monitor (another locking mechanism to ensure data integrity), POSIX condition variables are associated with a POSIX mutex lock to provide mutual exclusion: Creating and initializing the condition variable:

```
pthread_mutex_t mutex;  
pthread_cond_t cond_var;  
  
pthread_mutex_init(&mutex, NULL);  
pthread_cond_init(&cond_var, NULL);
```

# POSIX Condition Variables

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- Thread waiting for the condition `a == b` to become true:

```
pthread_mutex_lock(&mutex);  
while (a != b)  
    pthread_cond_wait(&cond_var, &mutex);  
  
pthread_mutex_unlock(&mutex);
```

/\* releases lock, puts the thread **to sleep** instead of busy waiting \*/

- Thread signaling another thread waiting on the condition variable:

```
pthread_mutex_lock(&mutex);  
a = b;  
pthread_cond_signal(&cond_var);  
pthread_mutex_unlock(&mutex);
```

/\* the signaled thread becomes the owner of the mutex lock and returns control from the call to pthread\_cond\_wait(). \*/

# Questions

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1. Pthreads can be implemented

- A) only inside the operating system kernel
- B) only at the user level
- C) at the user level or inside the operating system kernel ✓
- D) only Windows OS

2. When the owner of a mutex lock invokes pthread mutex unlock(), all threads blocked on that mutex's lock are unblocked.

True

False ✓

3. A call to pthread\_cond\_signal()

- A) releases the mutex lock and signals one thread waiting on the condition variable.
- B) releases the mutex lock and signals all threads waiting on the condition variable.
- C) signals one thread waiting on the condition variable, but does not release the mutex lock. ✓
- D) signals all threads waiting on the condition variable, but does not release the mutex lock.

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## Chapter 08: Deadlocks

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# Outline

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- System Model
- Deadlock Characterization
- Methods for Handling Deadlocks
- Deadlock Prevention
- Deadlock Avoidance
- Deadlock Detection
- Recovery from Deadlock



# Chapter Objectives

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- Illustrate how deadlock can occur when mutex locks are used
- Define the four necessary conditions that characterize deadlock
- Identify a deadlock situation in a resource allocation graph
- Evaluate the four different approaches for preventing deadlocks
- Apply the banker's algorithm for deadlock avoidance
- Apply the deadlock detection algorithm
- Evaluate approaches for recovering from deadlock

# System Model

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- System consists of resources
- Resource types  $R_1, R_2, \dots, R_m$ 
  - *CPU cycles, memory space, I/O devices*
- Each resource type  $R_i$  has  $W_i$  instances.
- Each process utilizes a resource as follows:
  - **request**
  - **use**
  - **release**

# Deadlock and livelock

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**Deadlock** occurs when every thread in a set is blocked waiting for an event that can be caused only by another thread in the set

**Livelock** occurs when a thread continuously attempts an action that fails.

# Deadlock in multithreaded application

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```
/* thread_one runs in this function */
void *do_work_one(void *param)
{
    pthread_mutex_lock(&first_mutex);
    pthread_mutex_lock(&second_mutex);
    /**
     * Do some work
     */
    pthread_mutex_unlock(&second_mutex);
    pthread_mutex_unlock(&first_mutex);

    pthread_exit(0);
}
```

```
/* thread_two runs in this function */
void *do_work_two(void *param)
{
    pthread_mutex_lock(&second_mutex);
    pthread_mutex_lock(&first_mutex);
    /**
     * Do some work
     */
    pthread_mutex_unlock(&first_mutex);
    pthread_mutex_unlock(&second_mutex);

    pthread_exit(0);
}
```

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# Deadlock with Semaphores

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- Data:
  - A semaphore  $s_1$  initialized to 1
  - A semaphore  $s_2$  initialized to 1
- Two threads  $T_1$  and  $T_2$
- $T_1$ :
  - `wait(s1)`
  - `wait(s2)`
- $T_2$ :
  - `wait(s2)`
  - `wait(s1)`

# Livelock Example

```
/* thread_one runs in this function */
void *do_work_one(void *param)
{
    int done = 0;

    while (!done) {
        pthread_mutex_lock(&first_mutex);
        if (pthread_mutex_trylock(&second_mutex)) {
            /**
             * Do some work
             */
            pthread_mutex_unlock(&second_mutex);
            pthread_mutex_unlock(&first_mutex);
            done = 1;
        }
        else
            pthread_mutex_unlock(&first_mutex);
    }
    pthread_exit(0);
}
```

```
/* thread_two runs in this function */
void *do_work_two(void *param)
{
    int done = 0;

    while (!done) {
        pthread_mutex_lock(&second_mutex);
        if (pthread_mutex_trylock(&first_mutex)) {
            /**
             * Do some work
             */
            pthread_mutex_unlock(&first_mutex);
            pthread_mutex_unlock(&second_mutex);
            done = 1;
        }
        else
            pthread_mutex_unlock(&second_mutex);
    }

    pthread_exit(0);
}
```

What if thread one acquires **first\_mutex**, followed by thread two acquiring **second\_mutex**. Each thread then invokes **pthread\_mutex\_trylock()**, which fails, releases their respective locks, and repeats the same actions indefinitely.

# Questions

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1. A deadlocked state occurs whenever \_\_\_\_.

- A) a process is waiting for I/O to a device that does not exist
- B) the system has no available free resources
- C) every process in a set is waiting for an event that can only be caused by another process in the set ✓
- D) a process is unable to release its request for a resource after use

2. Deadlock occurs when every thread in a set is blocked waiting for an event that can be caused only by another thread in the set, while livelock occurs when a thread continuously attempts an action that fails.

True ✓

False

# Deadlock Characterization

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Deadlock can arise if four conditions hold simultaneously.

- **Mutual exclusion:** only one thread at a time can use a resource
- **Hold and wait:** a thread holding at least one resource is waiting to acquire additional resources held by other threads
- **No preemption:** a resource can be released only voluntarily by the thread holding it, after that thread has completed its task
- **Circular wait:** there exists a set  $\{T_0, T_1, \dots, T_n\}$  of waiting threads such that  $T_0$  is waiting for a resource that is held by  $T_1$ ,  $T_1$  is waiting for a resource that is held by  $T_2$ , ...,  $T_{n-1}$  is waiting for a resource that is held by  $T_n$ , and  $T_n$  is waiting for a resource that is held by  $T_0$ .



# Resource-Allocation Graph

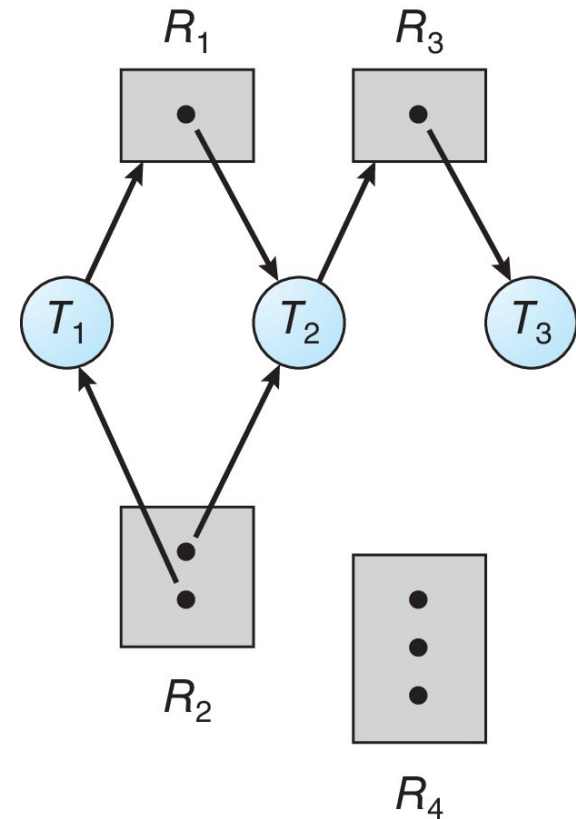
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A set of vertices  $V$  and a set of edges  $E$ .

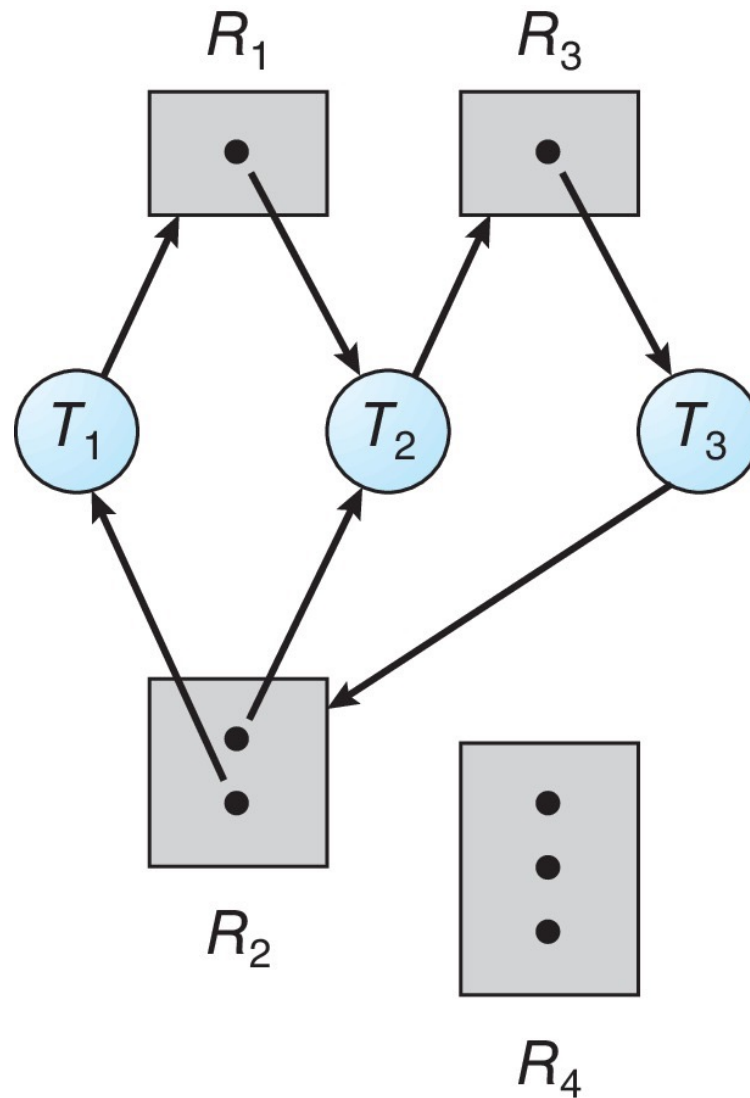
- $V$  is partitioned into two types:
  - $T = \{T_1, T_2, \dots, T_n\}$ , the set consisting of all the threads in the system.
  - $R = \{R_1, R_2, \dots, R_m\}$ , the set consisting of all resource types in the system
- **request edge** – directed edge  $T_i \rightarrow R_j$
- **assignment edge** – directed edge  $R_j \rightarrow T_i$

# Resource Allocation Graph Example

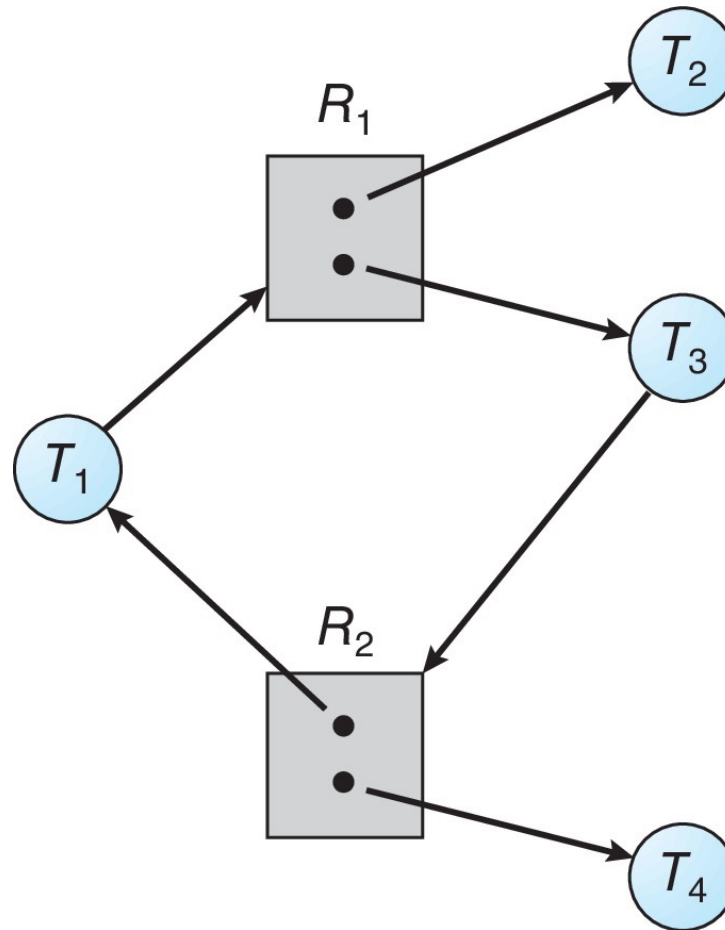
- One instance of  $R_1$
- Two instances of  $R_2$
- One instance of  $R_3$
- Three instance of  $R_4$
- $T_1$  holds one instance of  $R_2$  and is waiting for an instance of  $R_1$
- $T_2$  holds one instance of  $R_1$ , one instance of  $R_2$ , and is waiting for an instance of  $R_3$
- $T_3$  holds one instance of  $R_3$



# Resource Allocation Graph with a Deadlock



# Graph with a Cycle But no Deadlock



Observe that thread  $T_4$  may release its instance of resource type  $R_2$ . That resource can then be allocated to  $T_3$ , breaking the cycle.

# Basic Facts

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- If graph contains no cycles  $\Rightarrow$  no deadlock
- If graph contains a cycle  $\Rightarrow$ 
  - if only one instance per resource type, then deadlock
  - if several instances per resource type, possibility of deadlock

# Questions

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1. A cycle in a resource-allocation graph is \_\_\_\_\_.
  - A) a necessary and sufficient condition for deadlock in the case that each resource has more than one instance
  - B) a necessary and sufficient condition for a deadlock in the case that each resource has exactly one instance ✓
  - C) a sufficient condition for a deadlock in the case that each resource has more than once instance
  - D) is neither necessary nor sufficient for indicating deadlock in the case that each resource has exactly one instance
  
2. If a resource-allocation graph has a cycle, the system must be in a deadlocked state.
  - True
  - False ✓