

Chapter 05: CPU Scheduling

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Outline

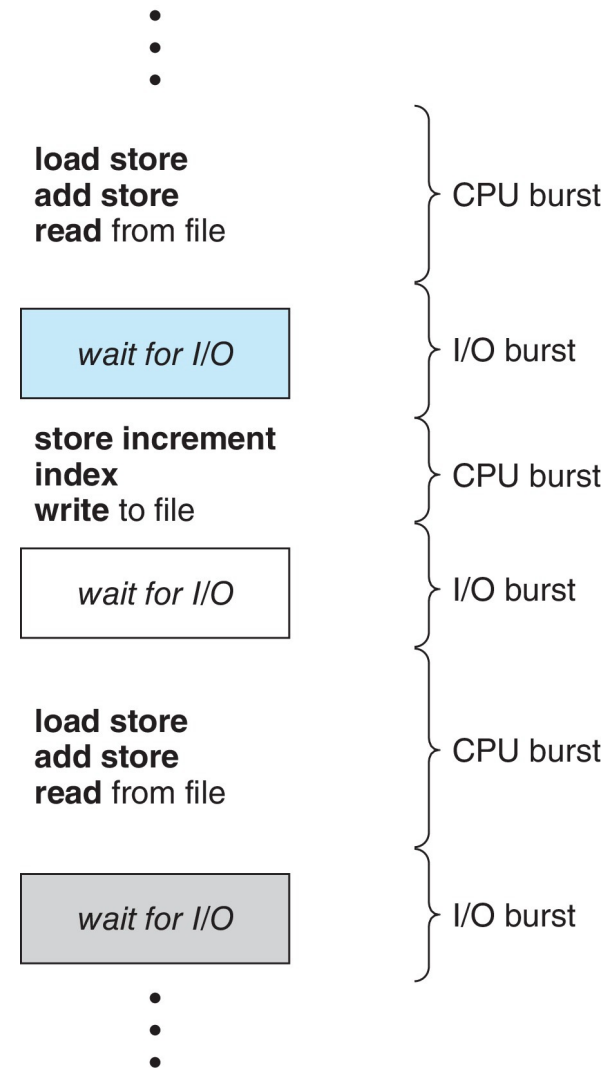
- Basic Concepts
- Scheduling Criteria
- Scheduling Algorithms
- Thread Scheduling
- Multi-Processor Scheduling
- Real-Time CPU Scheduling
- Operating Systems Examples
- Algorithm Evaluation

Objectives

- Describe various CPU scheduling algorithms
- Assess CPU scheduling algorithms based on scheduling criteria
- Explain the issues related to multiprocessor and multicore scheduling
- Describe various real-time scheduling algorithms

Basic Concepts

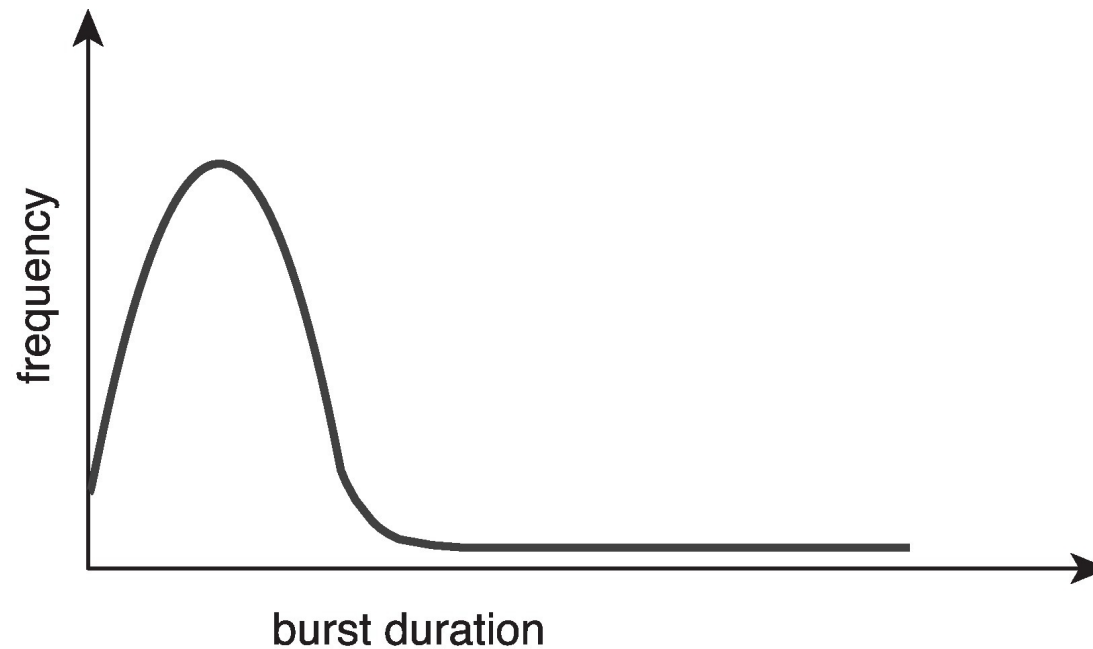
- Maximum CPU utilization obtained with multiprogramming
- CPU–I/O Burst Cycle – Process execution consists of a **cycle** of CPU execution and I/O wait
- **CPU burst** followed by **I/O burst** and it repeats
- CPU burst distribution is of main concern



Histogram of CPU-burst Times

Large number of short bursts

Small number of longer bursts





CPU Scheduler

- The **CPU scheduler** selects from among the processes in ready queue, and allocates a CPU core to one of them
 - Queue may be ordered in various ways
- CPU scheduling decisions may take place when a process:
 1. Switches from running to waiting state (for example, as the result of an I/O request)
 2. Switches from running to ready state (for example, when an interrupt occurs)
 3. Switches from waiting to ready (for example, at completion of I/O)
 4. Terminates
- For situations 1 and 4, there is no choice in terms of scheduling. A new process (if one exists in the ready queue) must be selected for execution.
- For situations 2 and 3, however, there is a choice.



Preemptive and Nonpreemptive Scheduling

- When scheduling takes place only under circumstances 1 and 4, the scheduling scheme is **nonpreemptive or cooperative**.
- Otherwise, it is **preemptive**.
- Under Nonpreemptive scheduling, once the CPU has been allocated to a process, the process keeps the CPU until it releases it either by terminating or by switching to the waiting state.
- Virtually all modern operating systems including Windows, MacOS, Linux, and UNIX use preemptive scheduling algorithms.

Preemptive Scheduling and Race Conditions

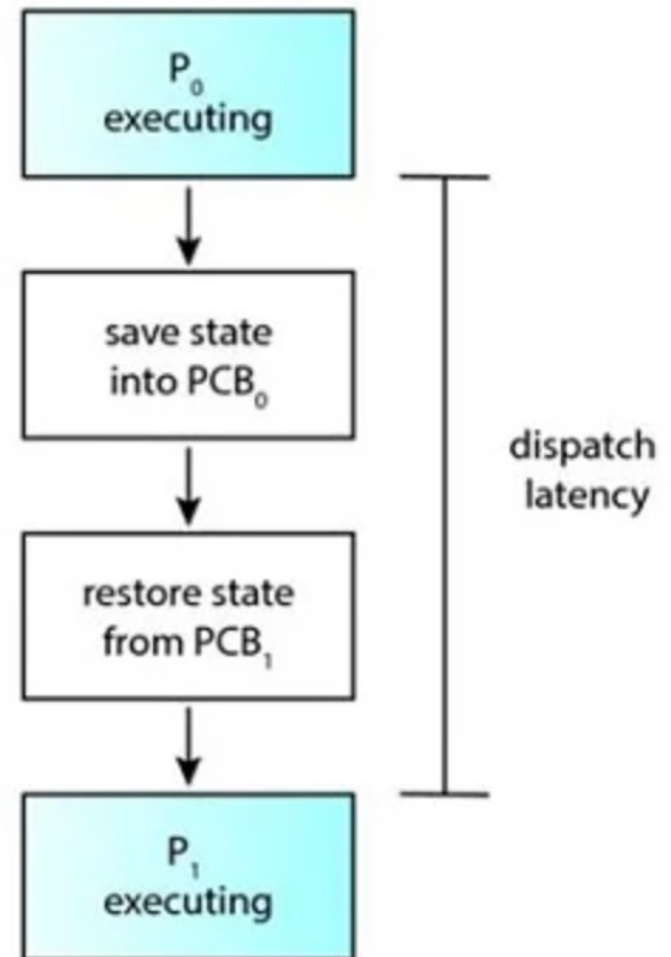
- Preemptive scheduling can result in race conditions when data are shared among several processes.
- Consider the case of two processes that share data. While one process is updating the data, it is preempted so that the second process can run. The second process then tries to read the data, which are in an inconsistent state.
- This issue will be explored in detail in Chapter 6.

Questions

1. Which of the following is true of cooperative scheduling?
- A) It requires a timer.
 - B) A process keeps the CPU until it releases the CPU either by terminating or by switching to the waiting state. ✓
 - C) It incurs a cost associated with access to shared data.
 - D) A process switches from the running state to the ready state when an interrupt occurs.

Dispatcher

- Dispatcher module gives control of the CPU to the process selected by the CPU scheduler; this involves:
 - Switching context
 - Switching to user mode
 - Jumping to the proper location in the user program to restart that program
- **Dispatch latency** – time it takes for the dispatcher to stop one process and start another running



Scheduling Criteria

- **CPU utilization** – keep the CPU as busy as possible (top command on Linux, macOS, and UNIX)
- **Throughput** – # of processes that complete their execution per time unit
- **Turnaround time** – amount of time to execute a particular process
- **Waiting time** – amount of time a process has been waiting in the ready queue
- **Response time** – amount of time it takes from when a request was submitted until the first response is produced.



Scheduling Algorithm Optimization Criteria

- Max CPU utilization
- Max throughput
- Min turnaround time
- Min waiting time
- Min response time

Q. _____ is the number of processes that are completed per time unit.

- A) CPU utilization
- B) Response time
- C) Turnaround time
- D) Throughput

✓

First- Come, First-Served (FCFS) Scheduling

<u>Process</u>	<u>Burst Time</u>
P_1	24
P_2	3
P_3	3

- Suppose that the processes arrive in the order: P_1 , P_2 , P_3
The Gantt Chart for the schedule is:



- Waiting time for $P_1 = 0$; $P_2 = 24$; $P_3 = 27$
- Average waiting time: $(0 + 24 + 27)/3 = 17$

FCFS Scheduling (Cont.)

Suppose that the processes arrive in the order:

$$P_2, P_3, P_1$$

- The Gantt chart for the schedule is:



- Waiting time for $P_1 = 6$; $P_2 = 0$; $P_3 = 3$
- Average waiting time: $(6 + 0 + 3)/3 = 3$
- Much better than previous case
- Convoy effect** - short process behind long process
 - Consider one CPU-bound and many I/O-bound processes



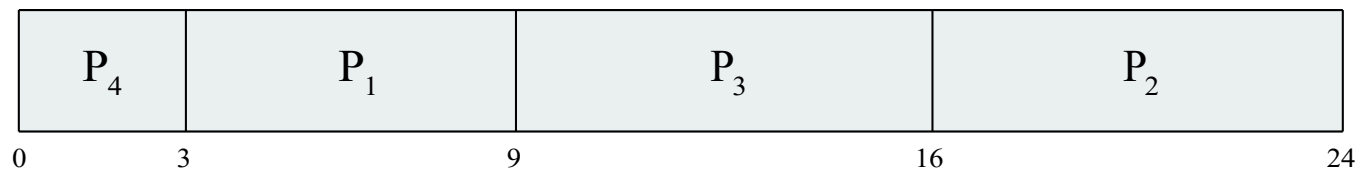
Shortest-Job-First (SJF) Scheduling

- Associate with each process the length of its next CPU burst
 - Use these lengths to schedule the process with the shortest time
- SJF is optimal – gives minimum average waiting time for a given set of processes
- Preemptive version called **shortest-remaining-time-first**
- How do we determine the length of the next CPU burst?
 - Could ask the user
 - Estimate

Example of SJF

<u>Process</u>	<u>Burst Time</u>
P_1	6
P_2	8
P_3	7
P_4	3

- SJF scheduling chart



- Average waiting time = $(3 + 16 + 9 + 0) / 4 = 7$

Determining Length of Next CPU Burst

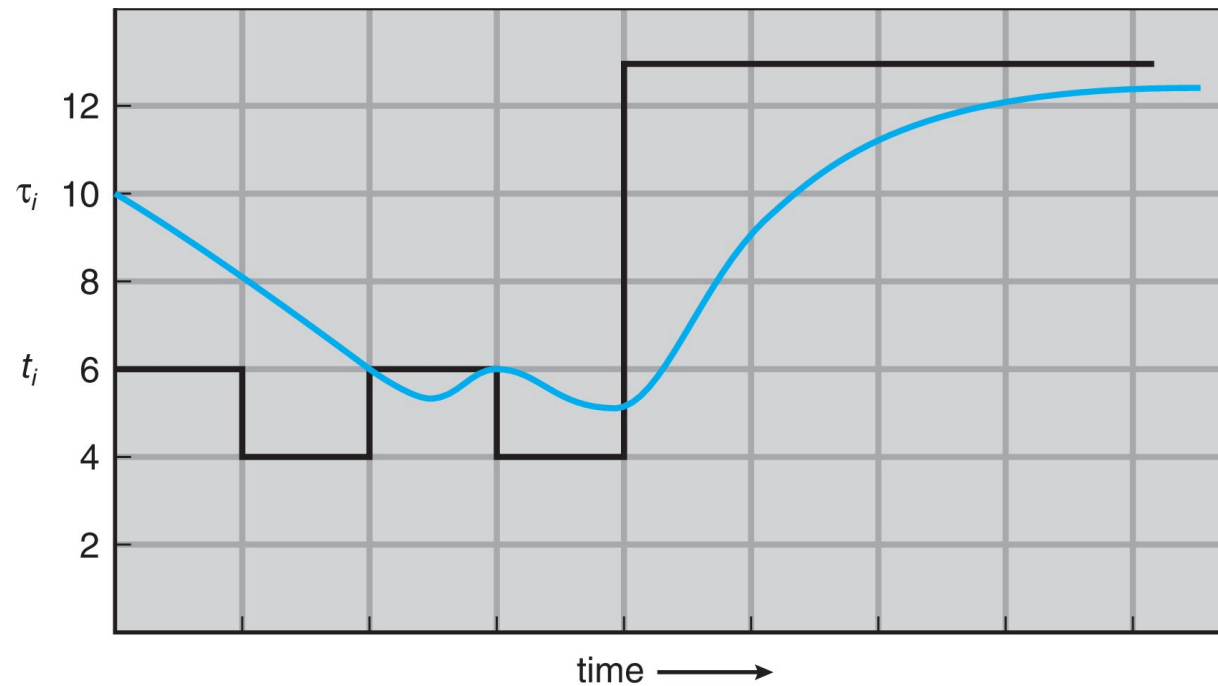
- Can only estimate the length – should be similar to the previous one
 - Then pick process with shortest predicted next CPU burst
- Can be done by using the length of previous CPU bursts, using exponential averaging

1. t_n = actual length of n^{th} CPU burst
2. τ_{n+1} = predicted value for the next CPU burst
3. α , $0 \leq \alpha \leq 1$
4. Define:

$$\tau_{n+1} = \alpha t_n + (1 - \alpha)\tau_n.$$

- Commonly, α set to $\frac{1}{2}$

Prediction of the Length of the Next CPU Burst



CPU burst (t_i)	6	4	6	4	13	13	13	...	
"guess" (τ_i)	10	8	6	6	5	9	11	12	...



Examples of Exponential Averaging

- $\alpha = 0$
 - $\tau_{n+1} = \tau_n$
 - Recent history does not count (only the latest prediction counts)
- $\alpha = 1$
 - $\tau_{n+1} = \alpha t_n$
 - Only the actual last CPU burst counts
- If we expand the formula, we get:
$$\tau_{n+1} = \alpha t_n + (1 - \alpha)\alpha t_{n-1} + \dots$$
$$+ (1 - \alpha)^j \alpha t_{n-j} + \dots$$
$$+ (1 - \alpha)^{n+1} \tau_0$$
- Since both α and $(1 - \alpha)$ are less than or equal to 1, each successor predecessor term has less weight than its predecessor



Shortest Remaining Time First Scheduling

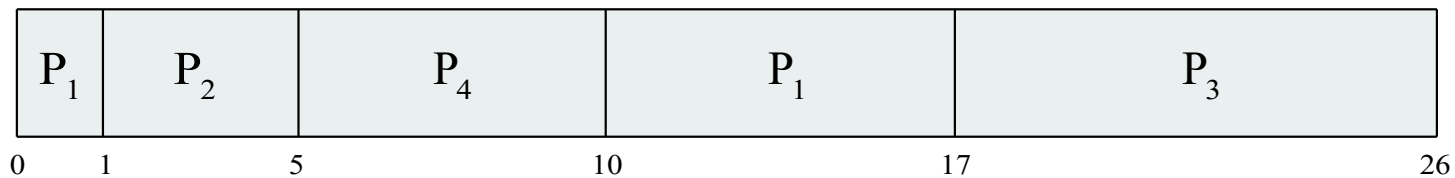
- Preemptive version of SJN (SJF + nonpreemptive)
- Whenever a new process arrives in the ready queue, the decision on which process to schedule next is redone using the SJN algorithm.
- Is SRT more “optimal” than SJN in terms of the minimum average waiting time for a given set of processes?

Example of Shortest-remaining-time-first

- Now we add the concepts of varying arrival times and preemption to the analysis

<u>Process</u>	<u>Arrival Time</u>	<u>Burst Time</u>
P_1	0	8
P_2	1	4
P_3	2	9
P_4	3	5

- Preemptive* SJF Gantt Chart



- Average waiting time = $[(10-1)+(1-1)+(17-2)+(5-3)]/4 = 26/4 = 6.5$

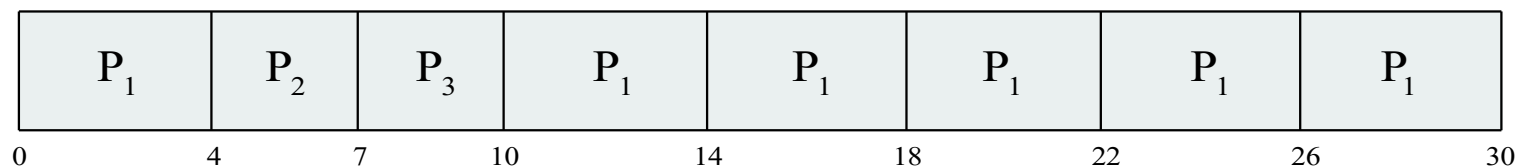
Round Robin (RR)

- Each process gets a small unit of CPU time (**time quantum** q), usually 10-100 milliseconds. After this time has elapsed, the process is preempted and added to the end of the ready queue.
- If there are n processes in the ready queue and the time quantum is q , then each process gets $1/n$ of the CPU time in chunks of at most q time units at once. No process waits more than $(n-1)q$ time units.
- Timer interrupts every quantum to schedule next process
- Performance
 - q large \Rightarrow FIFO (FCFS)
 - q small \Rightarrow RR (a large number of context switches.)
- Note that q must be large with respect to context switch, otherwise overhead is too high (as there are many context switches)

Example of RR with Time Quantum = 4

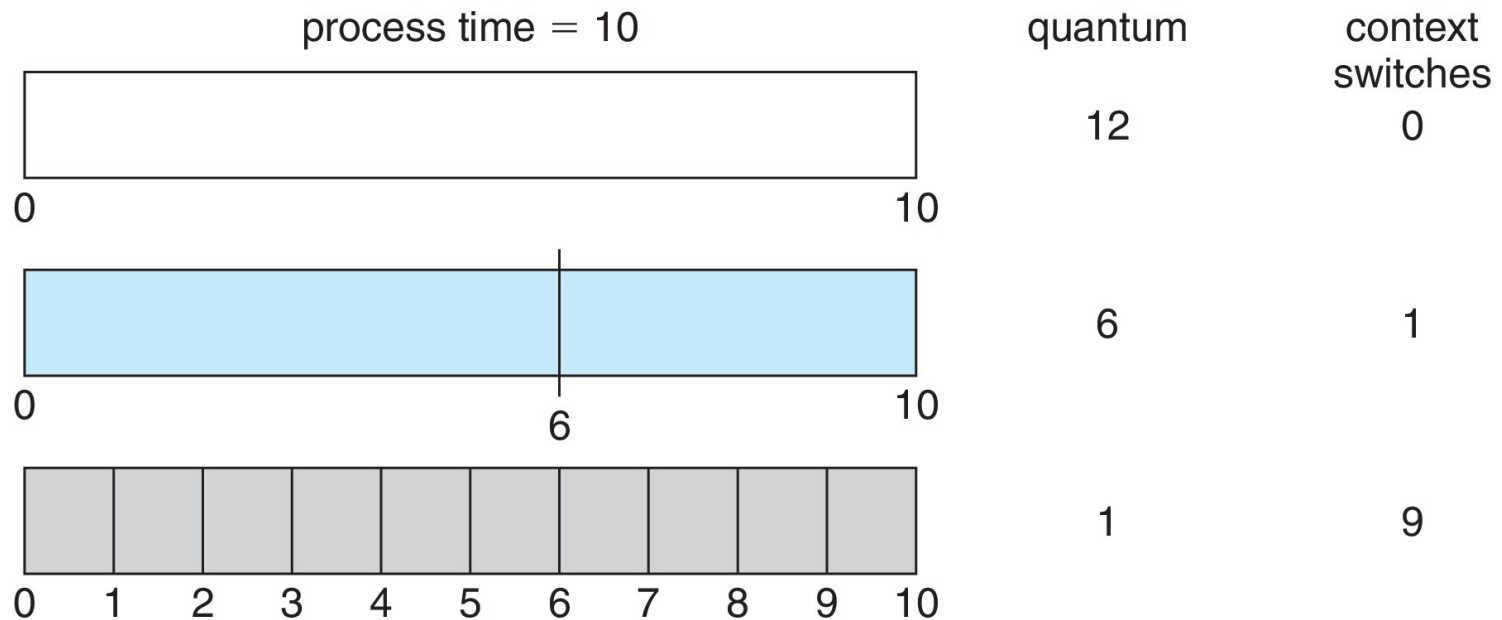
<u>Process</u>	<u>Burst Time</u>
P_1	24
P_2	3
P_3	3

- The Gantt chart is:



- Typically, higher average turnaround than SJF, but better **response**
- q should be large compared to context switch time
 - q usually 10 milliseconds to 100 milliseconds,
 - Context switch < 10 microseconds

Time Quantum and Context Switch Time



a smaller time quantum increases context switches.