

**NANYANG
TECHNOLOGICAL
UNIVERSITY**

SINGAPORE

CZ2003 Computer Graphics and Visualisation

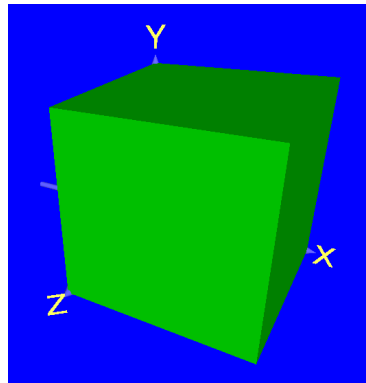
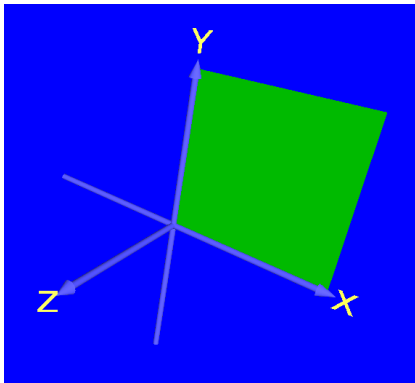
Experiment 3: Parametric Surfaces and Solids

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Matriculation Number: XXXXXXXXXX

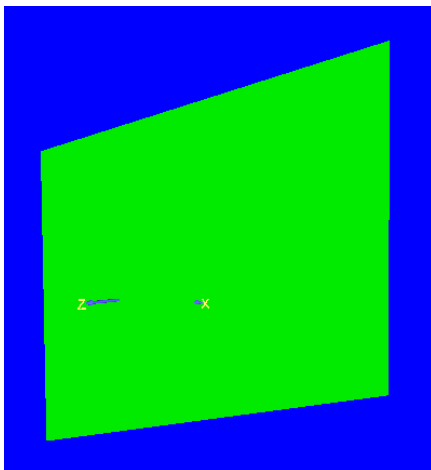
Lab Group: XXX

Exercise 1

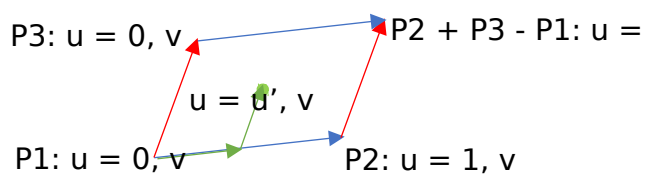


Exercise 2 (may have to pan and zoom to see the shapes)

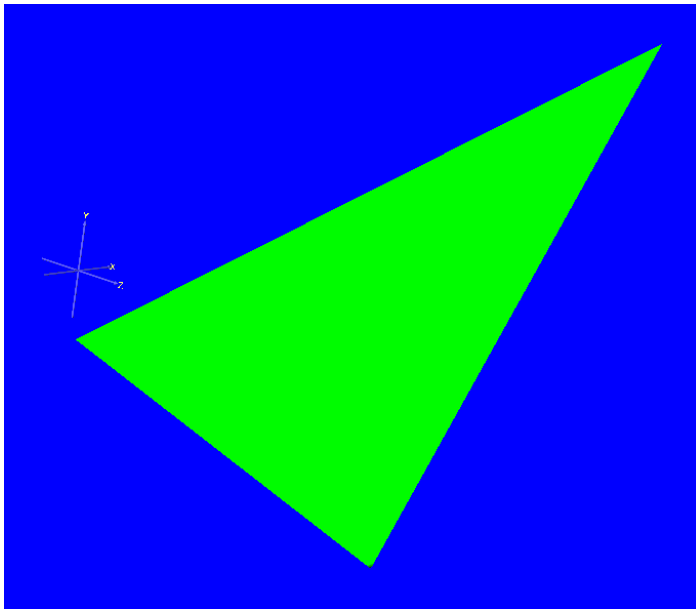
1. 3D Plane



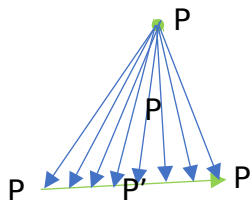
- defines a parallelogram in 3D space
- any point on the parallelogram can be obtained by adding 2 offsets to a base point
- a base point with known, fixed coordinates:
 - o $P1$
- offset in first direction:
 - o $u(P2 - P1)$
- offset in second direction:
 - o $v(P3 - P1)$
- any point on the parallelogram:
 - o $P1 + u(P2 - P1) + v(P3 - P1)$
 - o $u \in [0,1], v \in [0,1]$



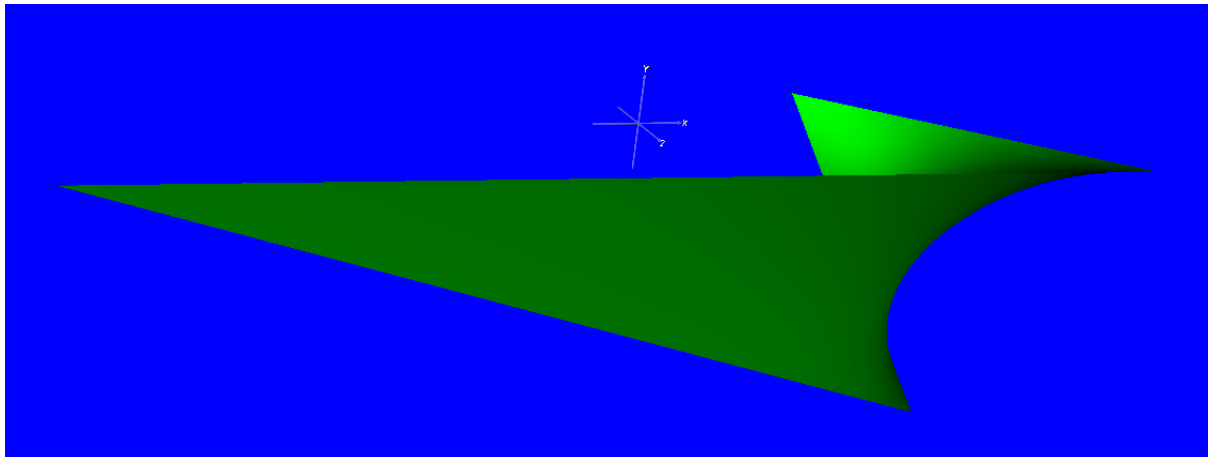
2. 3D Triangle



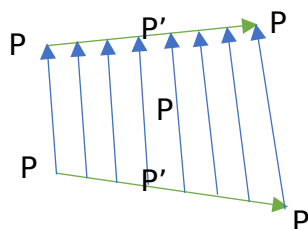
- defines a triangle in 3D space
- can be thought of as a set of point obtained via interpolation from a point to a set of points on a line segment (or vice versa)
- any point on line segment, P' :
 - $P1 + u(P2 - P1)$
- point:
 - $P3$
- any point on the triangle, P :
 - $P3 + v(P' - P3)$
 - $= P3 + v(P1 + u(P2 - P1) - P3)$
 - $= P3 + v(P1 - P3) + uv(P2 - P1)$



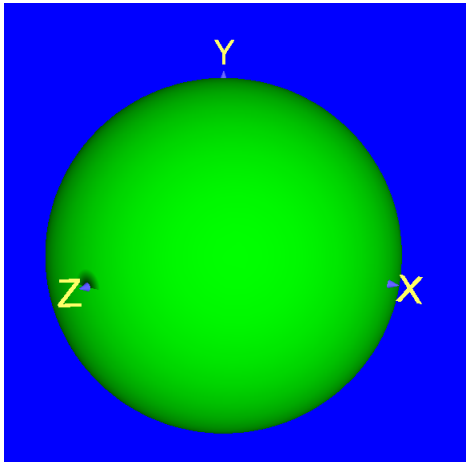
3. Bilinear Surface



- defines a bilinear surface
- can be thought of as a set of points bounded by 2 line segments
 - each line segment is a set of points, which can be obtained via interpolation from a starting point to an ending point
 - each point on the surface can be obtained via interpolation from a point (of a relative offset determined by parameter u) on the first line segment to a point (of a relative offset, also determined by parameter u) on the second line segment
- any point on first line segment, P' :
 - $P_1 + u(P_2 - P_1)$
- any point on second line segment, P'' :
 - $P_3 + u(P_4 - P_3)$
- any point on the surface, P :
 - $P' + v(P'' - P')$
 - $= P_1 + u(P_2 - P_1) + v(P_3 + u(P_4 - P_3) - P_1 + u(P_2 - P_1))$
 - $= P_1 + u(P_2 - P_1) + v(P_3 - P_1 + u(P_4 - P_3 + P_2 - P_1))$
 - $= P_1 + u(P_2 - P_1) + v(P_3 - P_1) + uv(P_4 - P_3 + P_2 - P_1)$

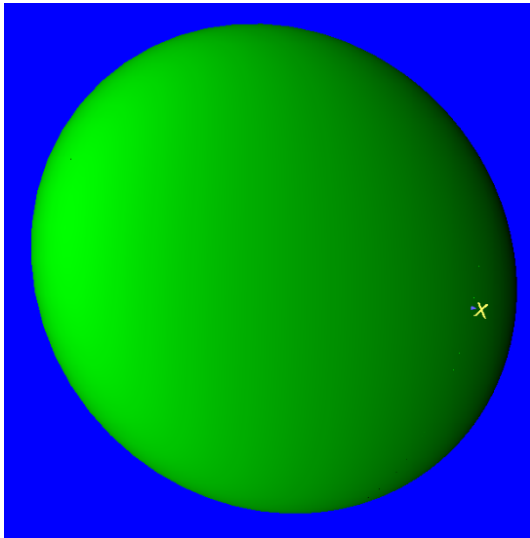


4. Sphere



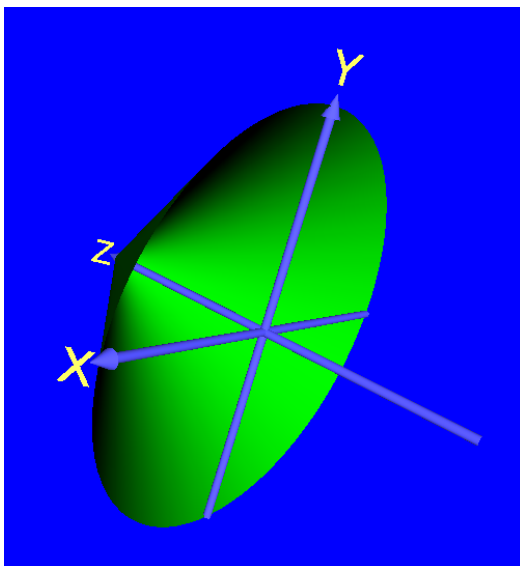
- defines a spherical surface (hollow inside)
- can be thought of as a ring that does rotational sweeping about an axis
- start with a circle on the y-z plane:
 - o $z = r * \cos(2\pi*u)$
 - o $y = r * \sin(2\pi*u)$
 - o $u \in [0,1]$
- rotate the circle about z-axis by half a revolution:
 - o rotation appears to draw a circle on the x-y plane:
 - $x = r' * \cos(\pi*v)$
 - $y = r' * \sin(\pi*v)$
 - $v \in [0,1]$
 - o during the drawing (rendering) of the sphere, the x and y coordinates change, but z coordinates stay constant
 - $x = (r * \sin(2\pi*u)) * \cos(\pi*v)$
 - $y = (r * \sin(2\pi*u)) * \sin(\pi*v)$
 - $z = r * \cos(2\pi*u)$
 - $u \in [0,1], v \in [0,1]$

5. Ellipsoid



- defines an ellipsoidal surface (hollow inside)
- can be thought of as a deformed ring that is spun about an axis
 - essentially a deformed sphere
 - deformation done using 3 parameters: a, b, and c
- apply semi-axes to sphere:
 - $x = (r/a * \sin(2\pi*u)) * \cos(\pi*v)$
 - $y = (r/b * \sin(2\pi*u)) * \sin(\pi*v)$
 - $z = r/c * \cos(2\pi*u)$
 - $u \in [0,1]$, $v \in [0,1]$

6. Cone

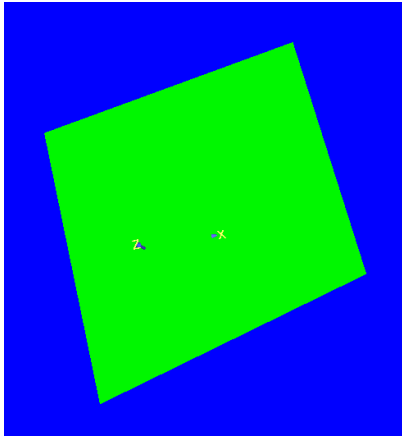


- defines a conical surface (hollow inside)
- can be thought of as smaller and smaller rings stacked on top of a base ring

Exercise 3

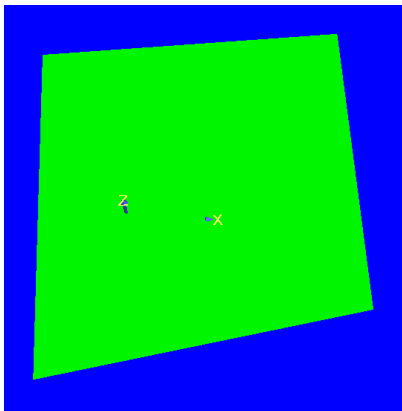
1. 3D Plane

a. resolution 1 1:



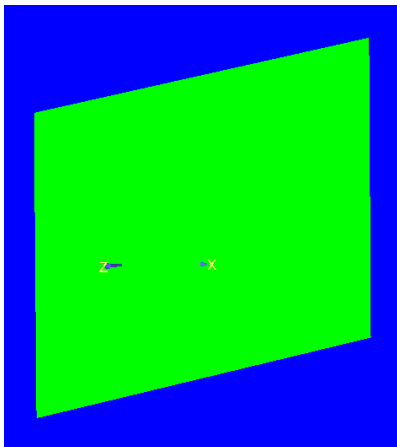
- no noticeable change from the original

b. resolution 1000 1000:



- takes a few seconds to render, unlike the original which renders almost instantaneously
- panning and zooming feels more laggy

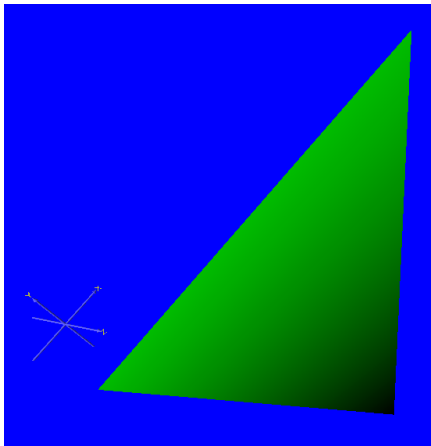
c. resolution 100 20:



- no noticeable change from the original

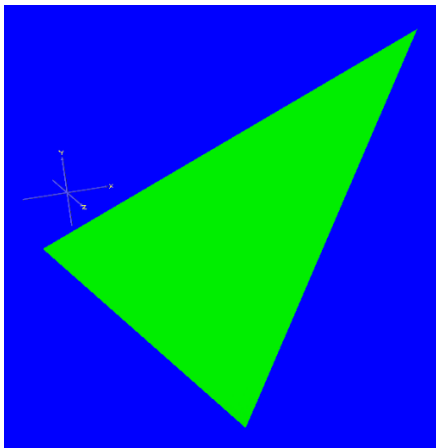
2. 3D Triangle

a. resolution 1 1:



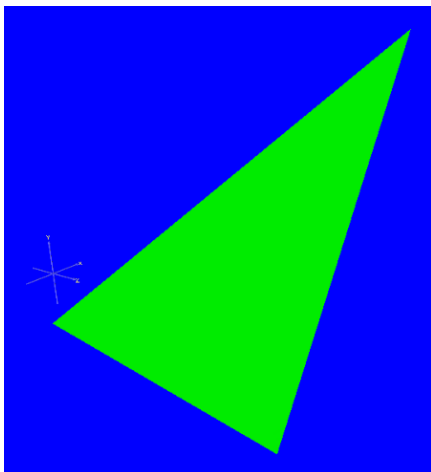
- no noticeable change from the original

b. resolution 1000 1000:



- takes a few seconds to render, unlike the original which renders almost instantaneously
- panning and zooming feels more laggy

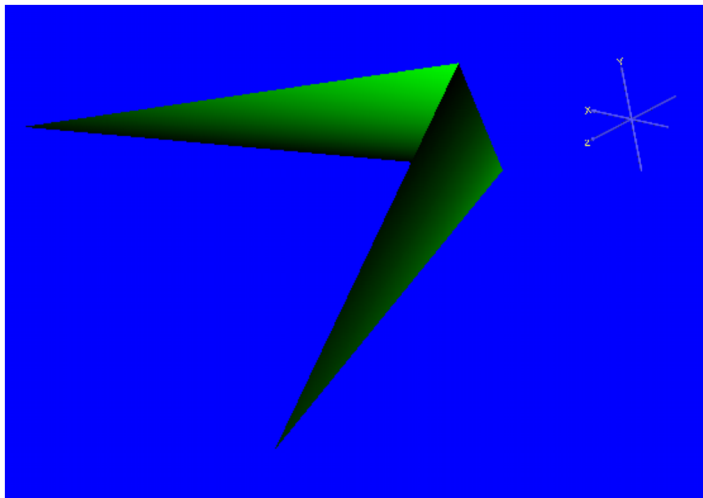
c. resolution 1 500:



- no noticeable change from the original

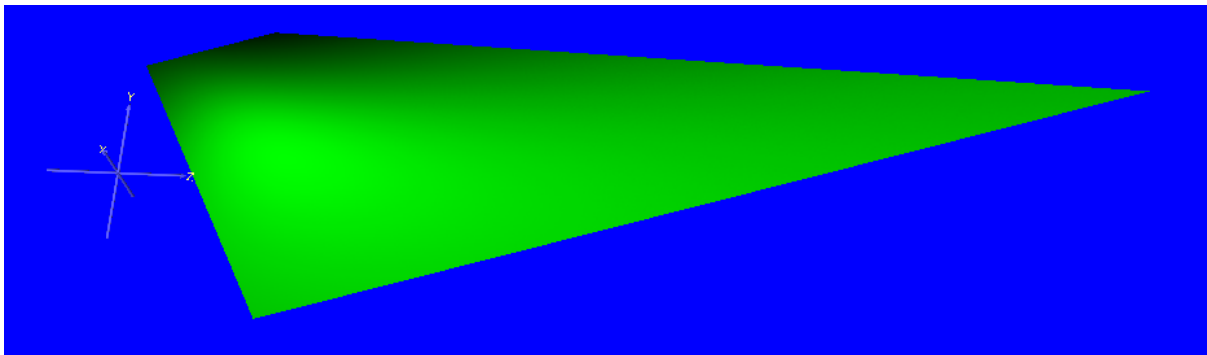
3. Bilinear Surface

a. resolution 1 1:



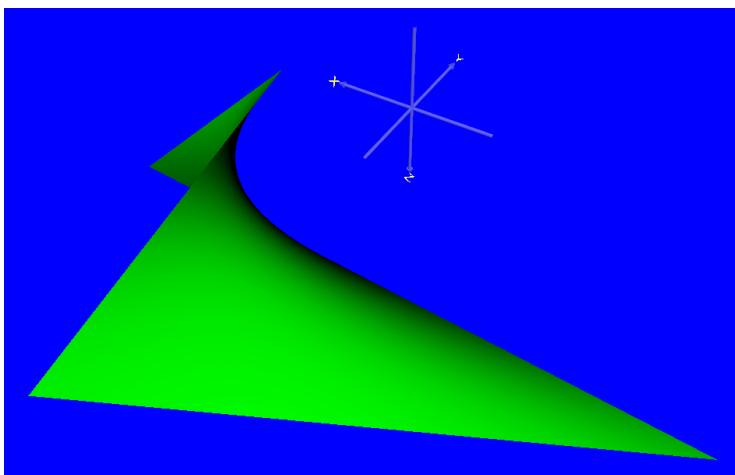
- becomes flattened
 - o looks like 2 planes joined together

b. resolution 1000 1000:



- takes a few seconds to render, unlike the original which renders almost instantaneously
- panning and zooming feels more laggy

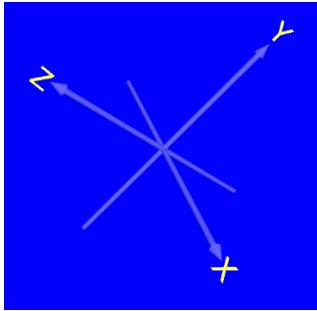
c. resolution 69 420:



- no noticeable change from the original

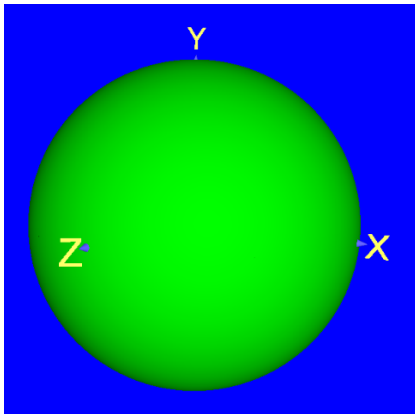
4. Sphere

a. resolution 1 1:



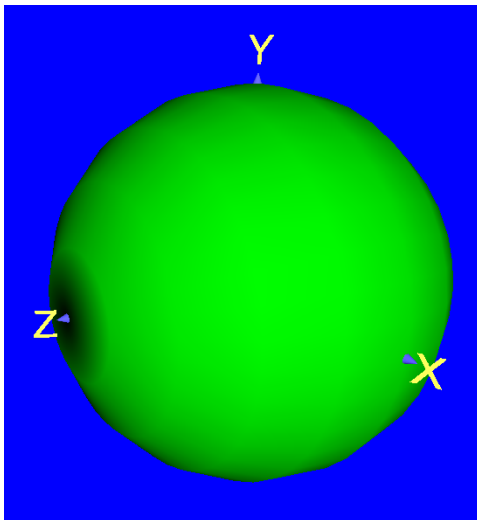
- appears that no shape was rendered

b. resolution 1000 1000:



- takes a few seconds to render, unlike the original which renders almost instantaneously
- panning and zooming feels more laggy
- no 'shadow' near the z-axis label

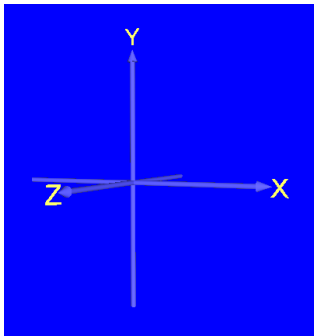
c. resolution 20 20:



- surface is not smooth, unlike the original

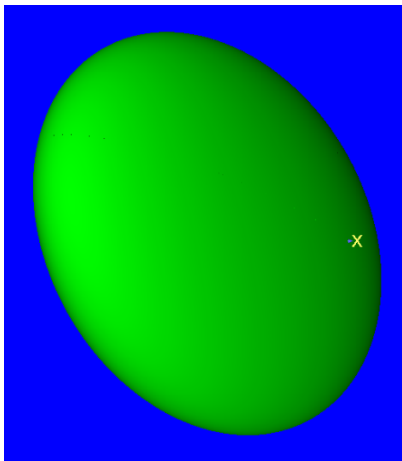
5. Ellipsoid

a. resolution 1 1:



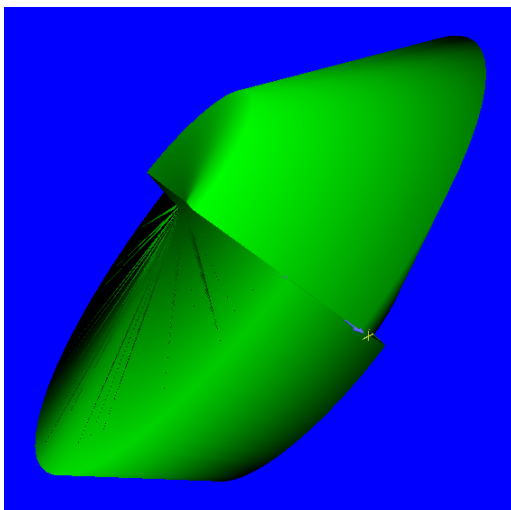
- appears that no shape was rendered

b. resolution 1000 1000:



- takes a few seconds to render, unlike the original which renders almost instantaneously
- panning and zooming feels more laggy
- looks very smooth

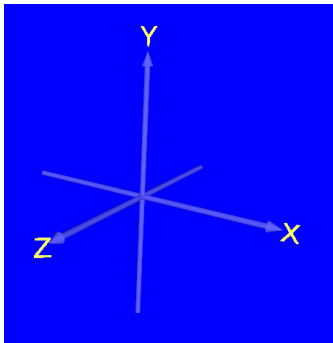
c. resolution 5 30:



- weird shape

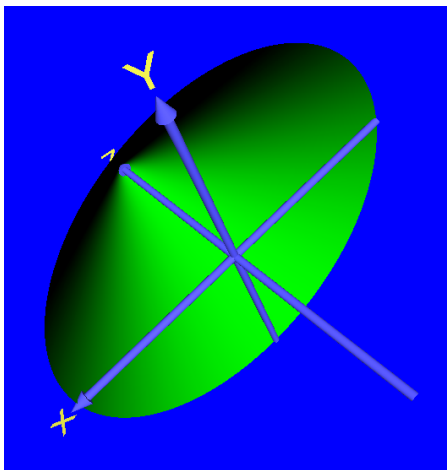
6. Cone

a. resolution 1 1:



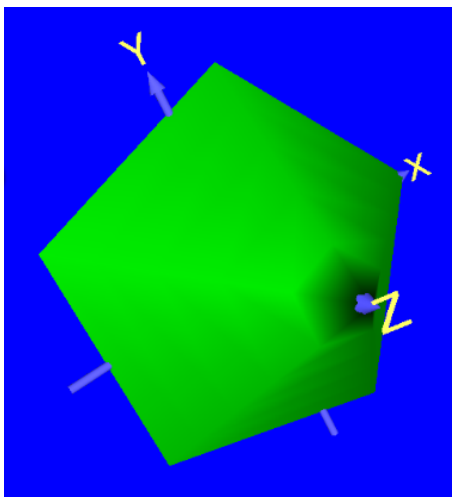
- appears that no shape was rendered

b. resolution 1000 1000:



- takes a few seconds to render, unlike the original which renders almost instantaneously
- panning and zooming feels more laggy

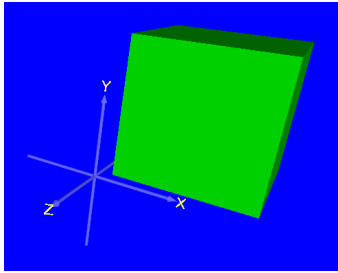
c. resolution 5 5:



- a 3D pentagon
 - o a penta-cone

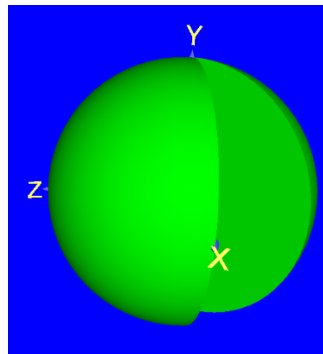
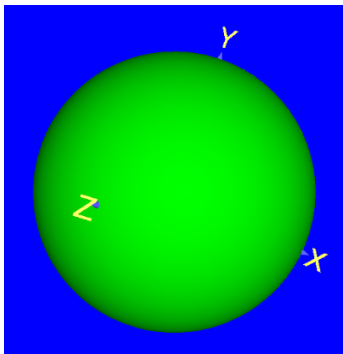
Exercise 4

1. Solid Box



- defines a solid cuboid

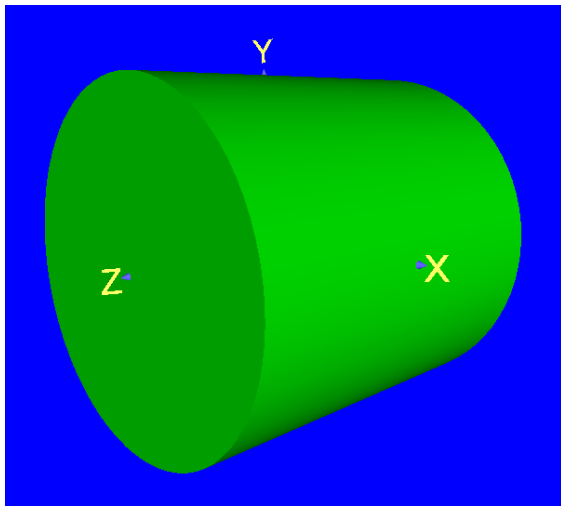
2. Solid Sphere



(cut open)

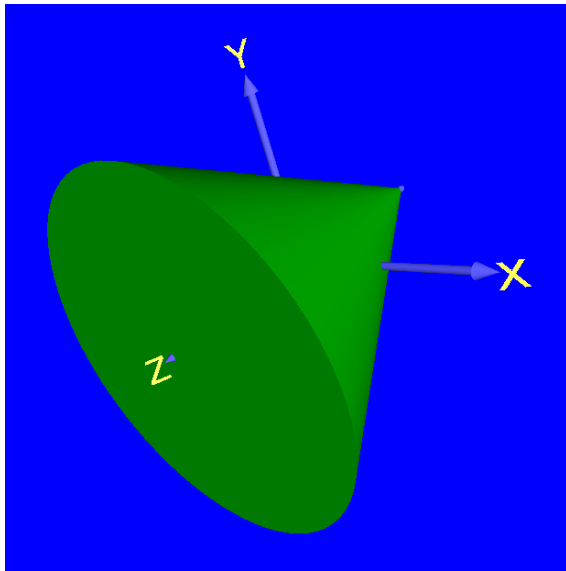
- defines a solid sphere
- can be thought of as a disk that is spun about an axis
- start with a circle on the x-y plane:
 - o $x = r * \cos(2\pi*u)$
 - o $y = r * \sin(2\pi*u)$
 - o $u \in [0,1]$
- fill the circle with infinitely many concentric circles to form a disk:
 - o $x = (v * r) * \cos(2\pi*u)$
 - o $y = (v * r) * \sin(2\pi*u)$
 - o $u \in [0,1], v \in [0,1]$
- rotate the disk about x-axis by half a revolution:
 - o rotation appears to draw a circle on the y-z plane:
 - $z = r' * \cos(\pi*w)$
 - $y = r' * \sin(\pi*w)$
 - $w \in [0,1]$
 - o during the drawing (rendering) of the sphere, the y and z coordinates change, but x coordinates stay constant
 - $x = (v * r) * \cos(2\pi*u)$
 - $y = ((v * r) * \sin(2\pi*u)) * \sin(\pi*w)$
 - $z = ((v * r) * \sin(2\pi*u)) * \cos(\pi*w)$
 - $u \in [0,1], v \in [0,1], w \in [0,1]$

3. Solid Cylinder



- defines a solid cylinder
- can be thought of as a set of disks of the same radius that are stacked on top (or in front) of each other
- start with a circle on the x-y plane:
 - o $x = r * \cos(2\pi*u)$
 - o $y = r * \sin(2\pi*u)$
 - o $u \in [0,1]$
- fill the circle with infinitely many concentric circles to form a disk:
 - o $x = (v * r) * \cos(2\pi*u)$
 - o $y = (v * r) * \sin(2\pi*u)$
 - o $u \in [0,1], v \in [0,1]$
- extend the disk in the z-direction (translational sweeping), from -1 to 1:
 - o $x = (v * r) * \cos(2\pi*u)$
 - o $y = (v * r) * \sin(2\pi*u)$
 - o $z = -1 + 2*w$
 - o $u \in [0,1], v \in [0,1], w \in [0,1]$

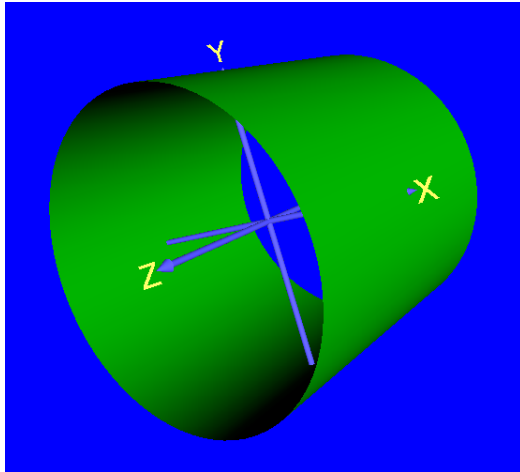
4. Solid Cone



- defines a solid cone
- can be thought of as a set of disks, each smaller in radius than the last, that are stacked on top of each other
- same idea as that of a cylinder, but the radius varies with respect to the growth/extension of the disk stack (cylinder)
- start with a cylinder:
 - o $x = (v * r) * \cos(2\pi * u)$
 - o $y = (v * r) * \sin(2\pi * u)$
 - o $z = -1 + 2 * w$
 - o $u \in [0,1]$, $v \in [0,1]$, $w \in [0,1]$
- let r , the radius of the disks, varies with respect to w , the parameter that is responsible for controlling the growth of the disk stack
 - o $x = (w * v * r) * \cos(2\pi * u)$
 - o $y = (w * v * r) * \sin(2\pi * u)$
 - o $z = -1 + 2 * w$
 - o $u \in [0,1]$, $v \in [0,1]$, $w \in [0,1]$

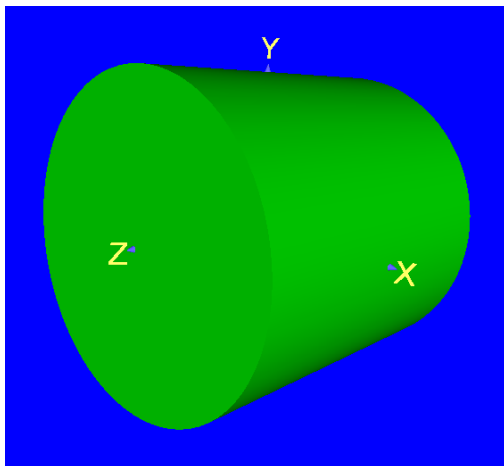
Exercise 5

cylindrical surface:



- 2 parameters: $u \in [0, 1]$, $v \in [0, 1]$
- $x = \cos(2\pi u)$
- $y = \sin(2\pi u)$
- $z = 2v - 1$

solid cylinder:



- additional parameter: $w \in [0, 1]$
 - o controls growth in radius of circle
- $x = w * \cos(2\pi u)$
- $y = w * \sin(2\pi u)$
- $z = 2v - 1$

Exercise 6

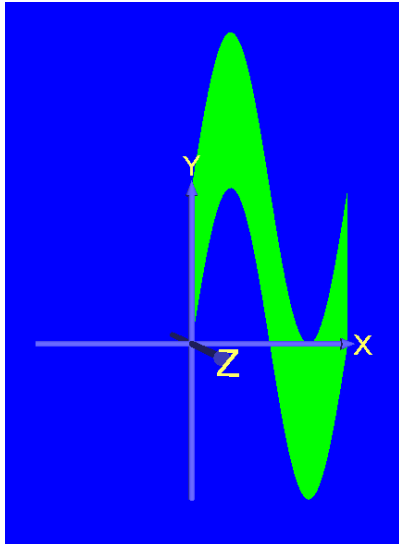
- translational sweeping – refer to cones and cylinders
- rotational sweeping – refer to spheres and ellipsoid

Exercise 7

start with a sine curve:

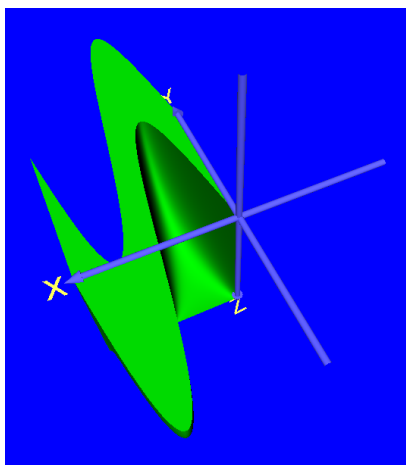
- unable to get it to render
 - not sure of the reason (tried changing resolution and domain of u)
- $x = u$
- $y = \sin(2\pi u)$
- $z = 0$

translational sweeping in y-directional by v units to get a surface:



- $x = u$
- $y = \sin(2\pi u) + v$
- $z = 0$

rotational sweeping about x-axis to get solid:



- rotate by $\pi/2$ instead of π to see cross-section
- $x = u$
- $y = (\sin(2\pi u) + v) * \cos(\pi/2 * w)$
- $z = \sin(\pi/2 * w)$

Exercise 8

- refer to the folder "Created_Shapes"

Exercise 9

- refer to this report