

Lecture 28.

Approximation Algorithms

Introduction to Algorithms
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Lecture Contents

■ Approximation Algorithms

- ▶ Vertex Cover Problem
- ▶ Traveling Salesman Problem
- ▶ Job Scheduling Problem

Approximation Algorithms

- Possible ways to deal with NP-completeness
 - ▶ If the input is small, an algorithm with exponential running time may be satisfactory
 - ▶ Isolate special cases that can be solved in polynomial time
 - ▶ Find near-optimal solutions in polynomial time
- An approximation algorithm is an algorithm which can provide a **near-optimal** solution for a **NP-complete problem** in **polynomial time**

Approximation Ratio

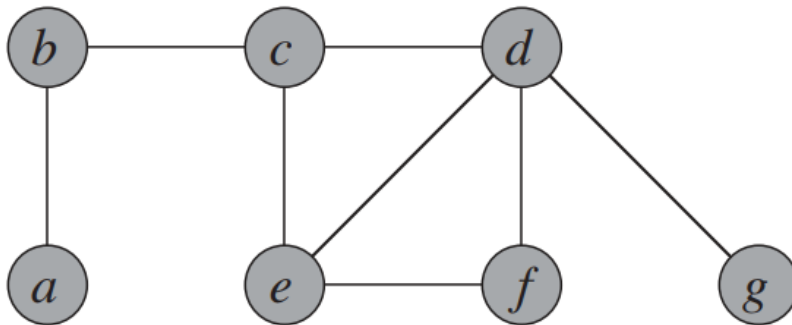
- An approximation algorithm for a problem has an **approximation ratio** of $\rho(n)$ if for any input of size n :

$$\max \left(\frac{C}{C^*}, \frac{C^*}{C} \right) \leq \rho(n)$$

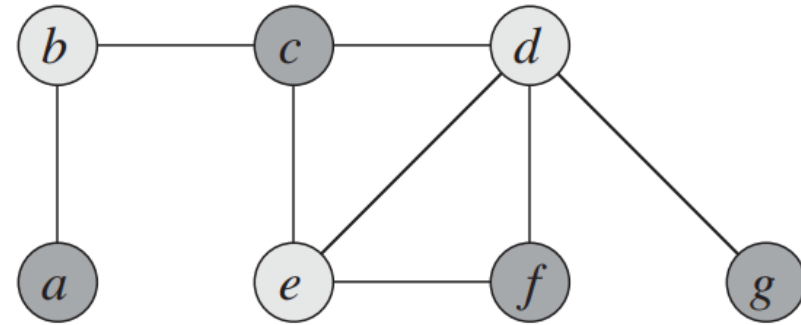
- ▶ C is the cost of the approximation algorithm
- ▶ C^* is the optimal cost of an optimal solution
- ▶ $\rho(n) \geq 1$ ($\frac{C^*}{C} \geq 1$ for maximization problems, $\frac{C}{C^*} \geq 1$ for minimization problems)
- ▶ The algorithm is called an $\rho(n)$ -*approximation algorithm*
- ▶ An optimal algorithm has $\rho(n) = 1$

Vertex Cover Problem

- A **vertex cover** of an undirected graph $G = (V, E)$ is a subset $V' \subseteq V$ such that if (u, v) is an edge of G , then either $u \in V'$ or $v \in V'$ (or both); the **size of a vertex cover** is the number of vertices in it
- The **vertex cover problem** is to find a vertex cover of **minimum size** in a given undirected graph



Input graph



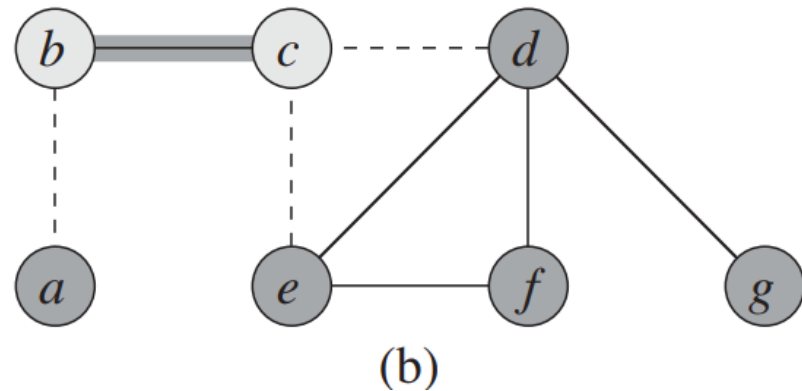
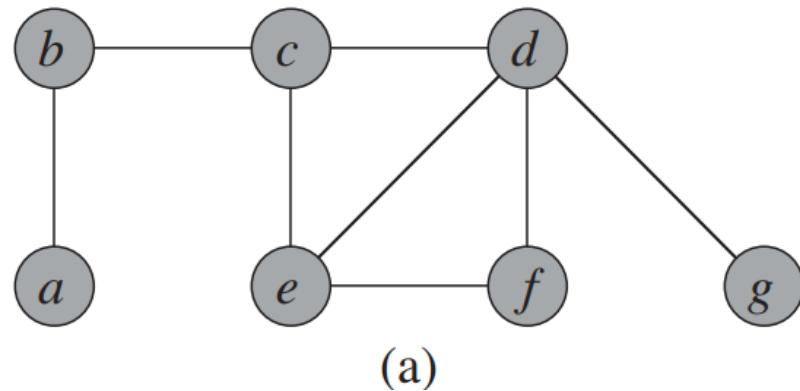
Optimal vertex cover
includes vertices b, d, e

Vertex Cover Problem: Algorithm

APPROX-VERTEX-COVER(G)

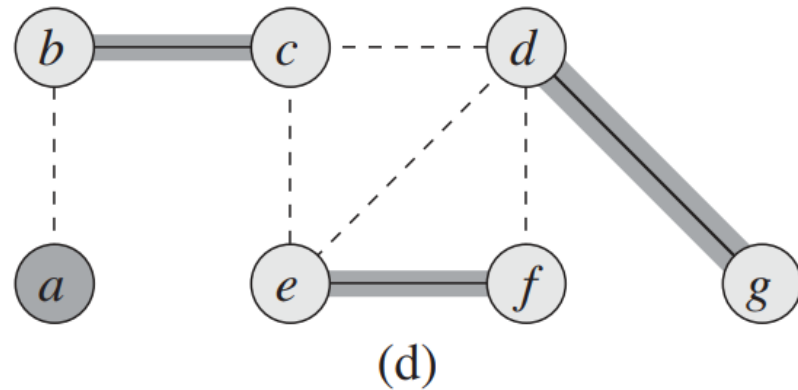
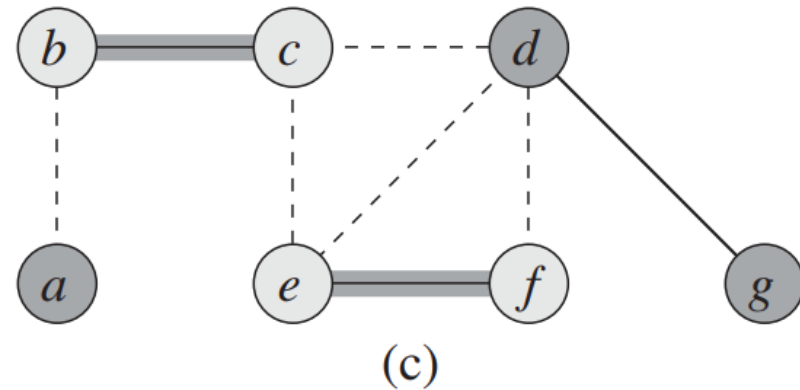
```
1   $C = \emptyset$ 
2   $E' = G.E$ 
3  while  $E' \neq \emptyset$ 
4      let  $(u, v)$  be an arbitrary edge of  $E'$ 
5       $C = C \cup \{u, v\}$ 
6      remove from  $E'$  every edge incident on either  $u$  or  $v$ 
7  return  $C$ 
```

Vertex Cover Problem: Example (1 / 3)



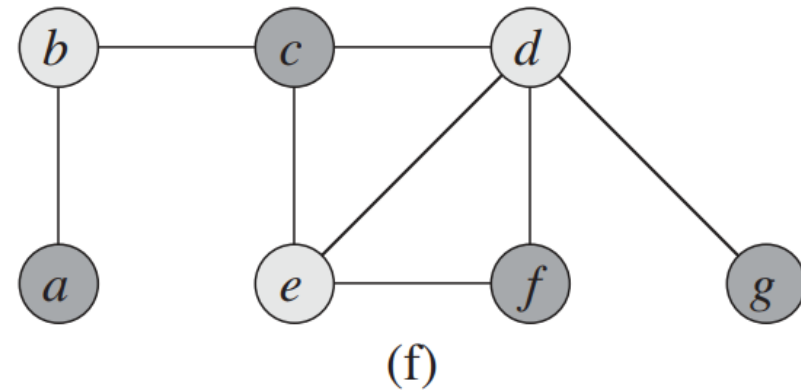
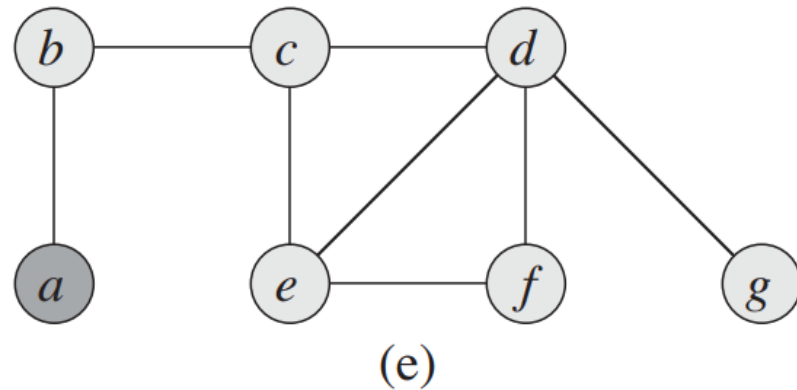
(a) Input graph G . **(b)** The edge (b, c) , shown heavy, is the first edge chosen by APPROX-VERTEX-COVER. Vertices b and c , shown lightly shaded, are added to the set C containing the vertex cover being created. Edges (a, b) , (c, e) , and (c, d) , shown dashed, are removed since they are now covered by some vertex in C .

Vertex Cover Problem: Example (2/3)



(c) Edge (e, f) is chosen; vertices e and f are added to C ; edges (d, e) and (d, f) are removed. **(d)** Edge (d, g) is chosen; vertices d and g are added to C

Vertex Cover Problem: Example (3/3)



(e) The set C which is the vertex cover produced by APPROX-VERTEX-COVER, contains six vertices: b, c, d, e, f, g . **(f)** The optimal vertex cover for this problem contains only three vertices: $b, d,$ and e .

Cover Vertex Problem: Analysis

■ APPROX-VERTEX-COVER is a 2-approximation algorithm

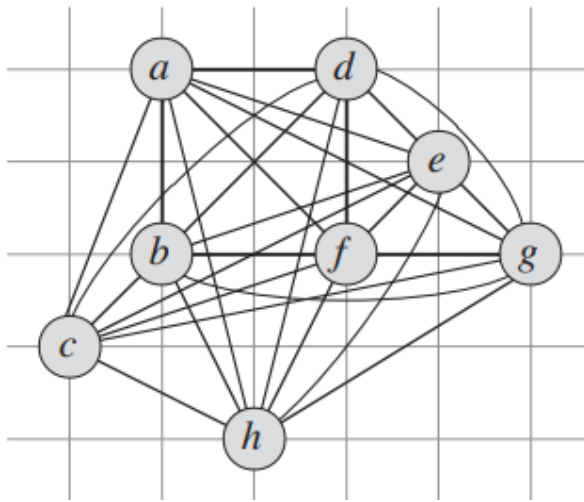
Proof:

- Let A denote the set of edges that line 4 of APPROX-VERTEX-COVER picked
- An optimal solution must include at least one vertex of each edge in A , so $|C^*| \geq |A|$
- In line 5 of APPROX-VERTEX-COVER, for each edge of A , two vertices are added to C , so, number of vertices in C is $|C| = 2|A| \leq 2|C^*|$ that means

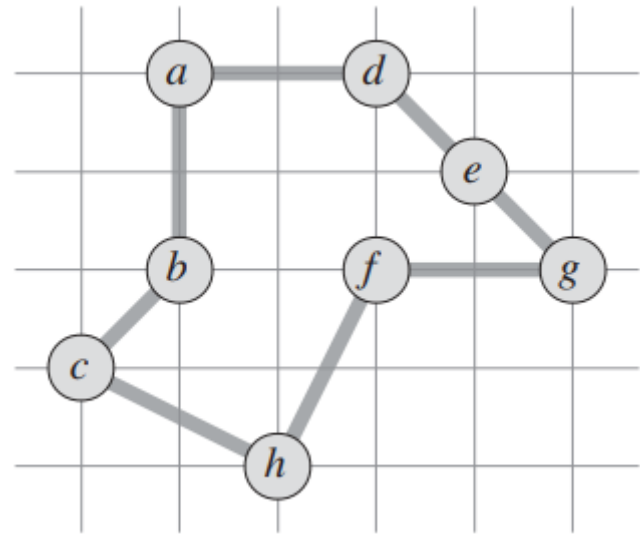
$$\frac{|C|}{|C^*|} \leq 2$$

Traveling Salesman Problem

- In traveling salesman problem, we are given a complete undirected graph $G = (V, E)$ that has a non-negative integer cost $c(u, v)$ associated with each edge $(u, v) \in E$, and we must find a Hamiltonian cycle of G with minimum cost



Input graph



A Hamiltonian cycle with minimum cost

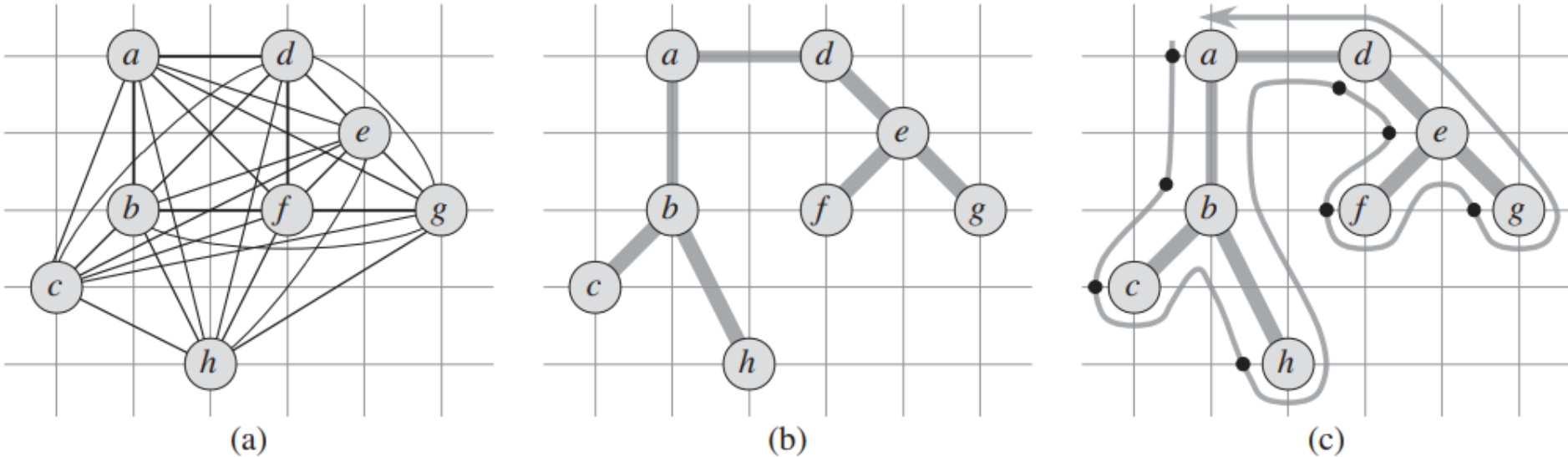
Traveling Salesman Problem: Algorithm

- The following algorithm uses minimum spanning tree to create a tour whose cost is no more than twice that of the minimum spanning tree's weight. MST-PRIM algorithm is used to compute the minimum spanning tree

APPROX-TSP-TOUR(G, c)

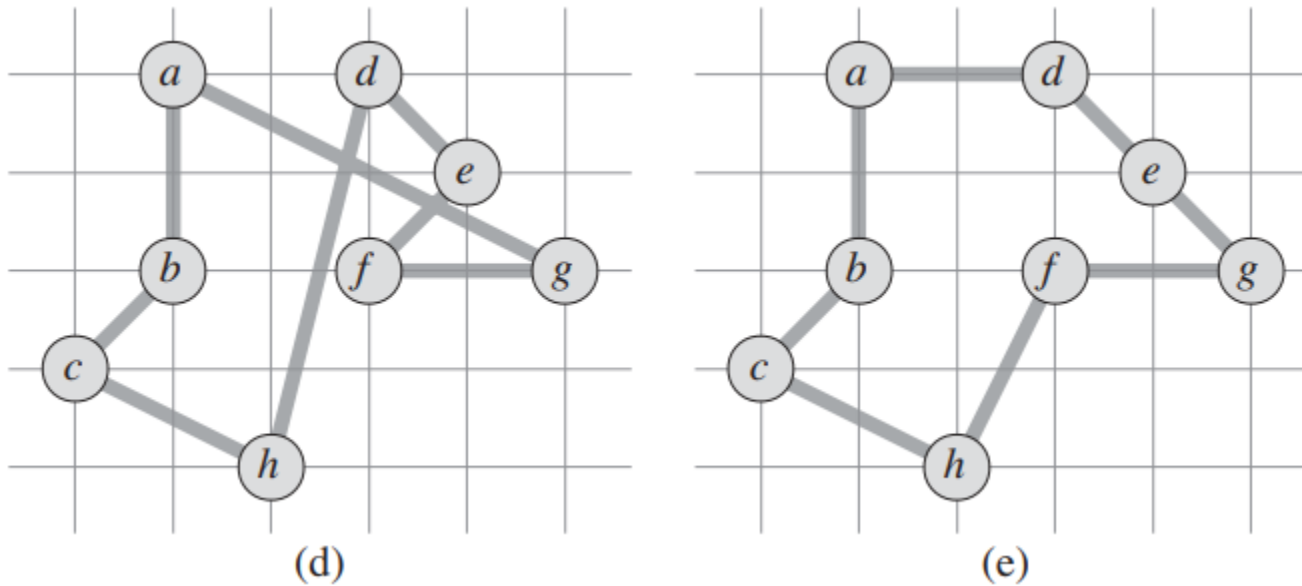
- 1 select a vertex $r \in G.V$ to be a “root” vertex
- 2 compute a minimum spanning tree T for G from root r
using MST-PRIM(G, c, r)
- 3 let H be a list of vertices, ordered according to when they are first visited
in a preorder tree walk of T
- 4 **return** the hamiltonian cycle H

Traveling Salesman Problem: Example



(a) A complete undirected graph. **(b)** A minimum spanning tree T of the graph computed by MST-PRIM, a is the root vertex. **(c)** A walk of T , starting at a . A **full walk** of the tree visits the vertices in the order $a; b; c; b; h; b; a; d; e; f; e; g; e; d; a$. A **preorder walk** of T lists a vertex just when it is first encountered, as indicated by the dot next to each vertex, yielding the ordering $a; b; c; h; d; e; f; g$.

Traveling Salesman Problem: Example



(d) A tour obtained by visiting the vertices in the order given by the preorder walk, which is the tour H returned by APPROX-TSP-TOUR. **(e)** An optimal tour H^* for the original complete graph

Traveling Salesman Problem: Analysis

■ APPROX-TSP-TOUR is a 2-approximation algorithm

Proof:

- Let H^* denote an optimal tour. A spanning tree is obtained if one edge is removed from the tour. Therefore, the weight of the minimum spanning tree in line 2 of the algorithm is a lower bound for the cost of H^*

$$c(T) \leq c(H^*)$$

- Let W denote a full walk of the minimum spanning tree T . Since the full walk traverses every edge of T exactly twice

$$c(W) = 2c(T) \leq 2c(H^*)$$

Traveling Salesman Problem: Analysis

■ APPROX-TSP-TOUR is a 2-approximation algorithm

Proof (continue):

- The tour H is obtained by removing vertices from the full walk W , so

$$c(H) \leq c(W) \leq 2c(H^*)$$
$$\frac{c(H)}{c(H^*)} \leq 2$$

Job Scheduling Problem

- Suppose we have n jobs, each of which take time t_i to process, and m identical machines on which we schedule the jobs. Jobs cannot be split between machines. For a given scheduling, let A_j be the set of jobs assigned to machine j . Let $T_j = \sum_{i \in A_j} t_i$ be the load of machine j . The job scheduling problem asks for an assignment of jobs to machines that minimizes the makespan, where the makespan is defined as the maximum load over all machines.
- Example: 5 jobs with processing time $\{3, 3, 2, 2, 2\}$, and 2 machines
 - ▶ The optimal schedule: $\{3, 3\}$ and $\{2, 2, 2\}$, makespan = 6

Job Scheduling Problem: Algorithm

- Consider the following greedy algorithm which iteratively allocates the next job to the machine with the least load.

GREEDY-JOB-SCHEDULING (A, T, t, m, n)

```
1  for  $j = 1$  to  $m$ 
2     $A_j = \emptyset$ 
3     $T_j = 0$ 
4  for  $i = 1$  to  $n$ 
5     $j = \underset{k}{\operatorname{argmin}} T_k$ 
6     $A_j = A_j \cup \{i\}$ 
7     $T_j = T_j + t_i$ 
8  return  $A$ 
```

A : sets of jobs assigned to machines
 T : loads of machines
 t : processing times of jobs
 m : number of machines
 n : number of jobs

Job Scheduling Problem: Example

- We are given 5 jobs with processing time $\{3, 3, 2, 2, 2\}$, and 2 machines
 - ▶ The optimal schedule: $\{3, 3\}$ and $\{2, 2, 2\}$, makespan = 6
 - ▶ The schedule given by GREEDY-JOB-SCHEDULING: $\{3, 2, 2\}$ and $\{3, 2\}$, makespan = 7

Job Scheduling Problem: Analysis

- GREEDY-JOB-SCHEDULING is a 2-approximation algorithm

Proof:

- Let T^* denote the optimal makespan, then:

$$T^* \geq \max_i t_i$$
$$T^* \geq \frac{1}{m} \sum_i^n t_i$$

Job Scheduling Problem: Analysis

- GREEDY-JOB-SCHEDULING is a 2-approximation algorithm

Proof (continue):

- Consider machine j with maximum load T_j . Let i be the last job scheduled on machine j . Before i was scheduled, j had the smallest load, so j must have had load smaller than the average load. Then,

$$T_j = (T_j - t_i) + t_i \leq \frac{1}{m} \sum_i^n t_i + \max_i t_i \leq T^* + T^* = 2T^*$$

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