

# Lecture 27.

## Maximum Flow / P or NP

Introduction to Algorithms  
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# Max Flow Problem

- $\mathbf{G} = G(V, E)$
- $\mathbf{x}_{ij}$  = flow on arc  $(i, j)$
- $\mathbf{u}_{ij}$  = capacity of flow in arc  $(i, j)$
- $\mathbf{s}$  = source node
- $\mathbf{t}$  = sink node
- **Maximize  $v$**

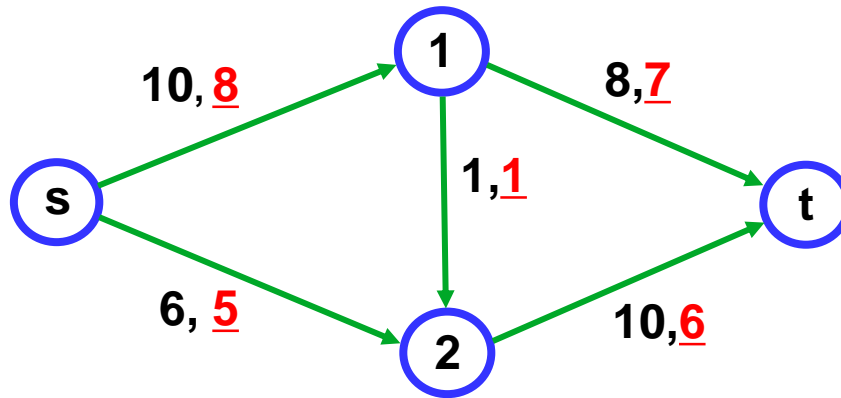
**Subject to:**  $\sum_j x_{ij} - \sum_k x_{ki} = 0$  for each  $i \neq s, t$

$$\sum_j x_{sj} = v$$

$$0 \leq x_{ij} \leq u_{ij} \quad \text{for all } (i, j) \in E$$

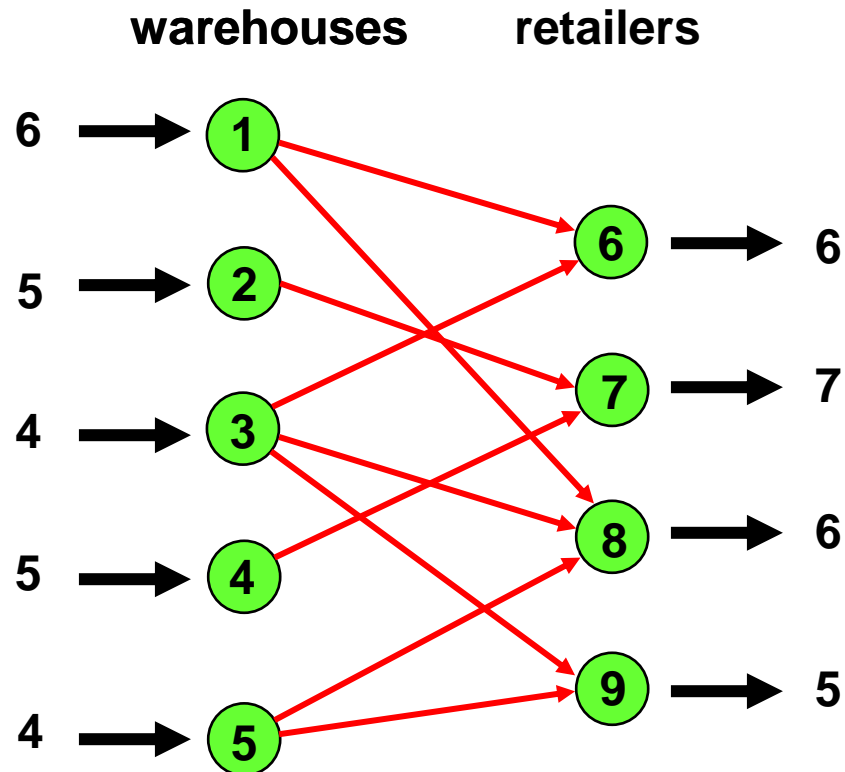
# Maximum Flows

- We refer to a flow  $x$  as *maximum* if it is feasible and maximizes  $v$
- Our objective in the max flow problem is to find a maximum flow



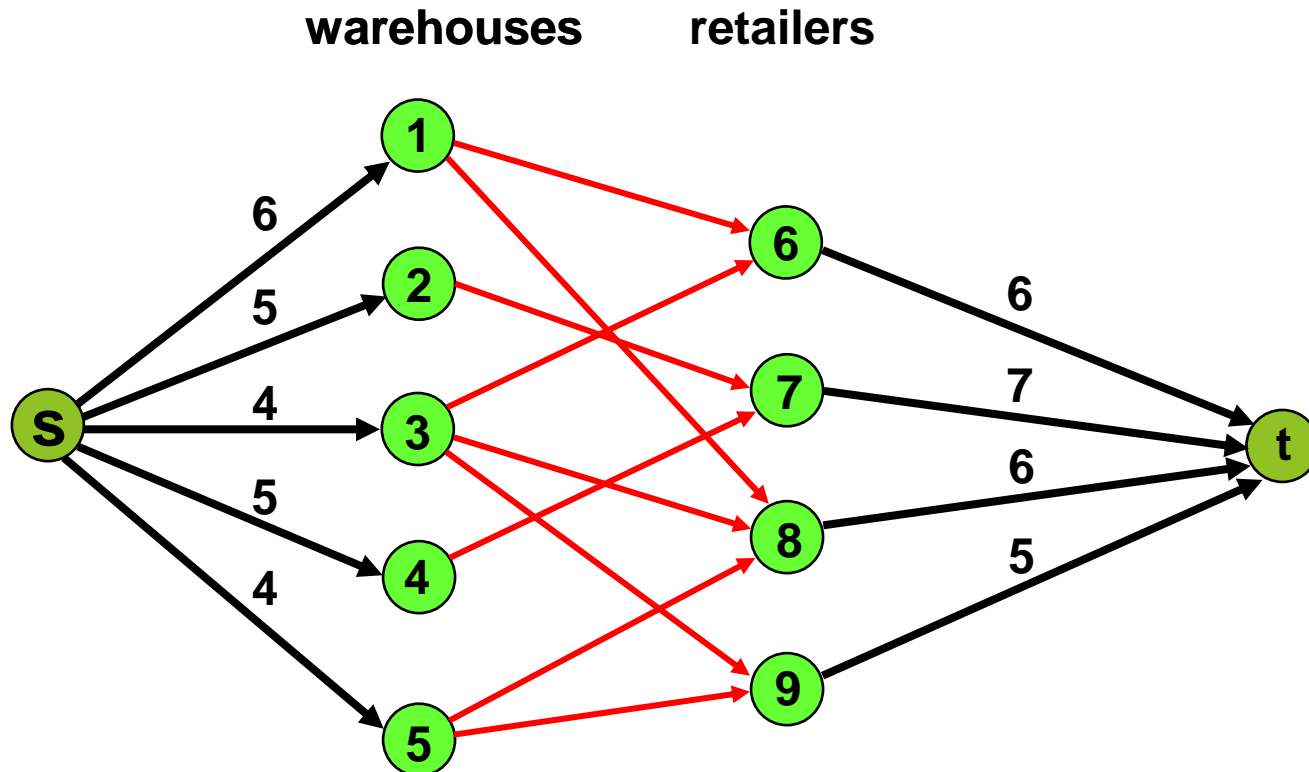
A max flow problem  
Capacities and a non-optimum flow

# Feasibility Problem: Find a Feasible Flow



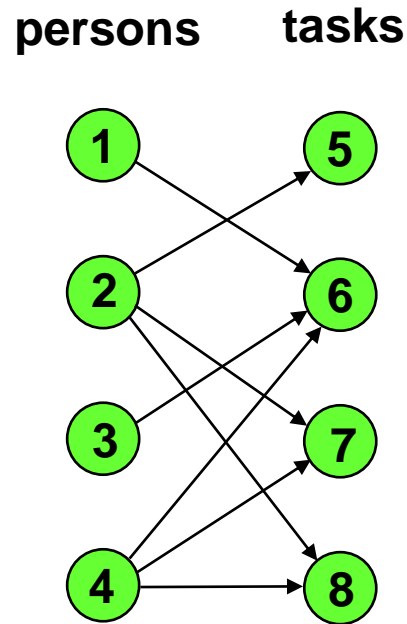
**Is there a way of shipping from the warehouses to the retailers to satisfy demand?**

# Transformation to a Max Flow Problem



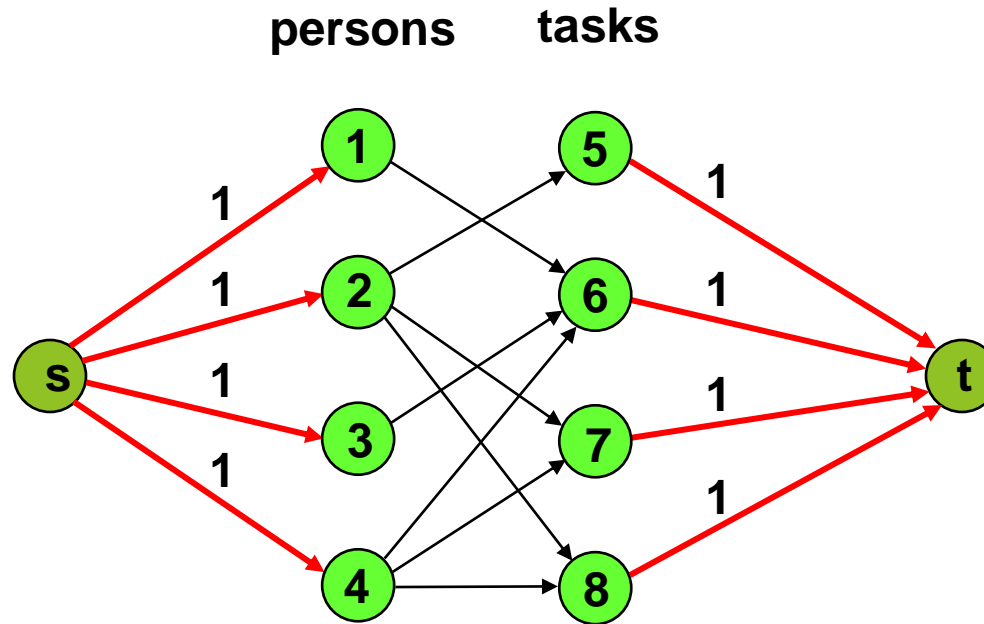
**There is a 1-1 correspondence with flows from  $s$  to  $t$  with 24 units (why 24?) and feasible flows for the transportation problem**

# Feasibility Problem: Find a Matching



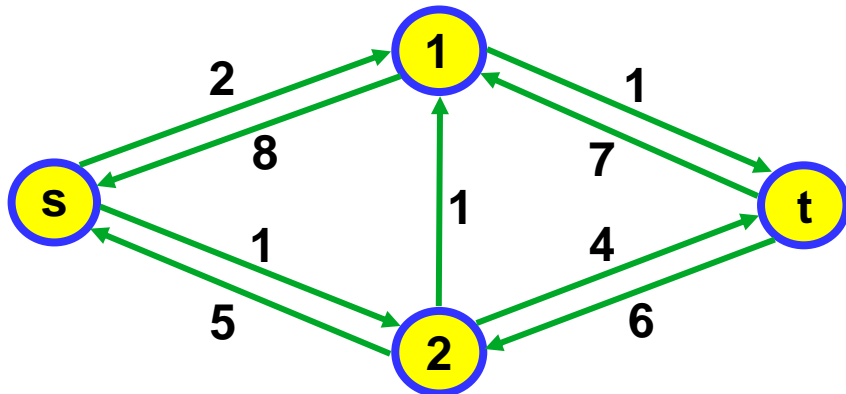
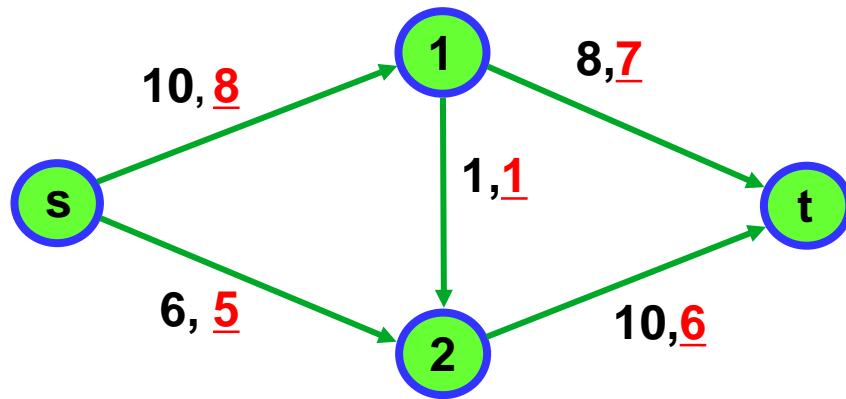
**Is there a way of assigning persons to tasks so that each person is assigned a task, and each task has a person assigned to it?**

# Transformation to a Max Flow Problem

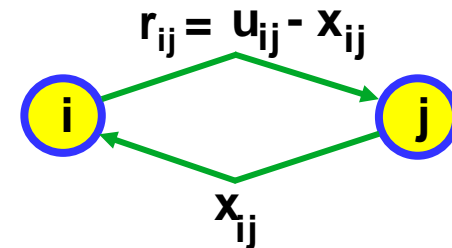


**Does the maximum flow from s to t have 4 units?**

# Residual Networks



The **Residual Network**  $G(x)$

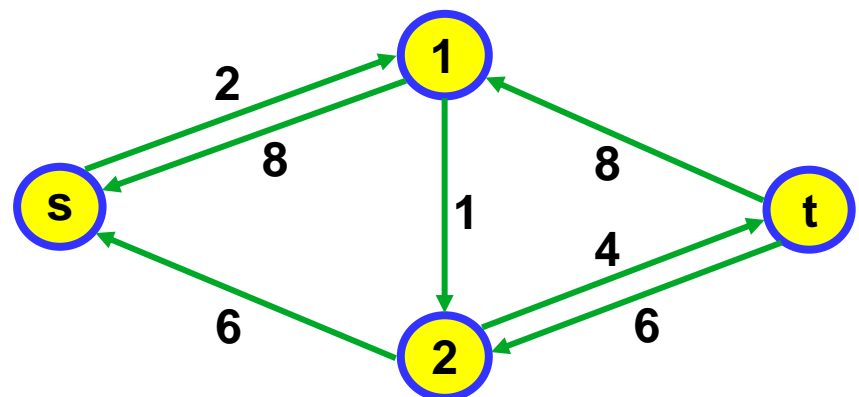
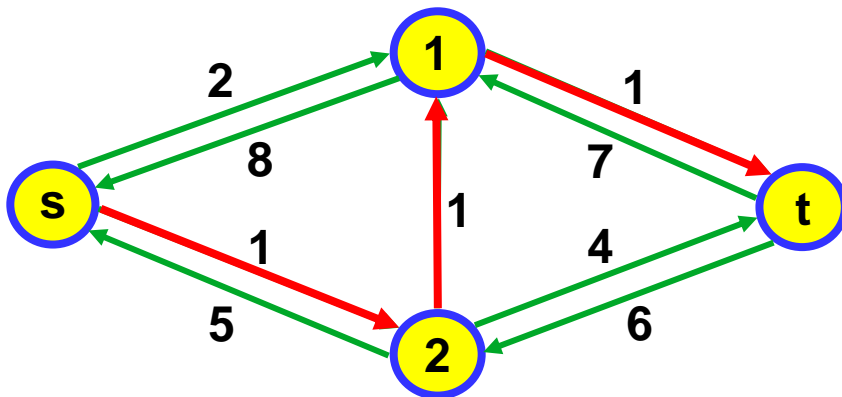


Let  $r_{ij}$  denote the **residual capacity** of arc  $(i,j)$



# Augmenting Paths

- An *augmenting path* is a path from  $s$  to  $t$  in the residual network
- The *residual capacity* of the augmenting path  $P$ 
  - ▶  $\delta(P) = \min\{r_{ij} : (i,j) \in P\}$
- To *augment along  $P$* , send  $\delta(P)$  units of flow along each arc of the path, then, modify  $x$  and the residual capacities appropriately
- $r_{ij} := r_{ij} - \delta(P)$  and  $r_{ji} := r_{ji} + \delta(P)$  for  $(i,j) \in P$



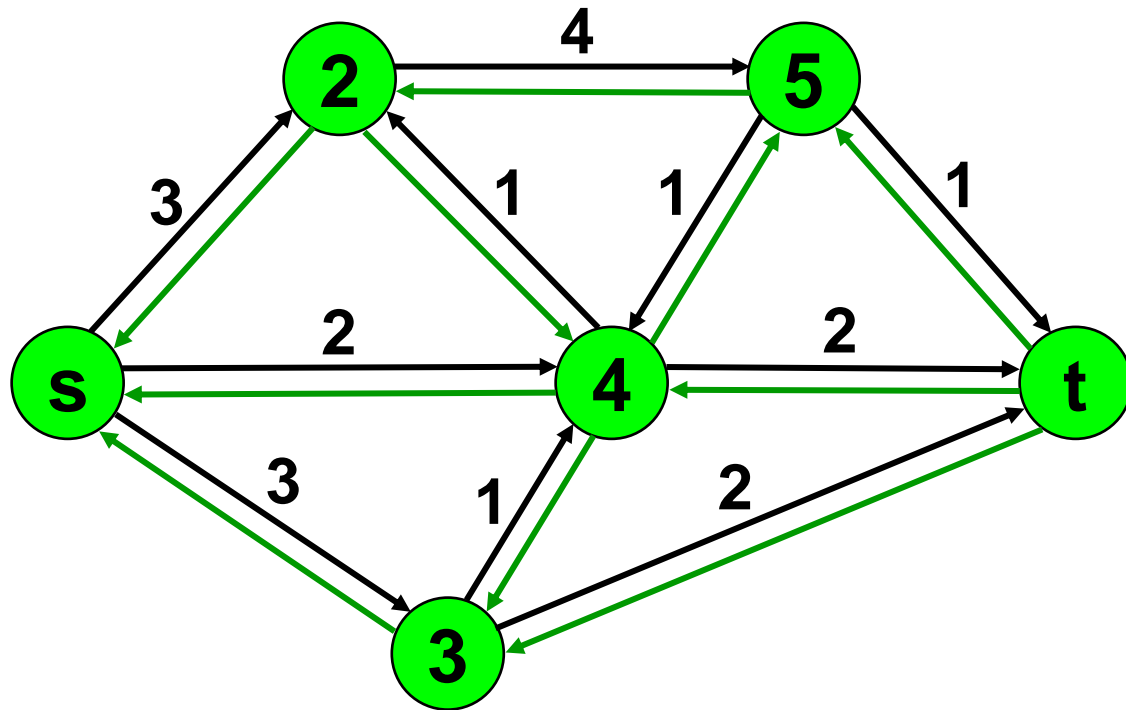
# Ford-Fulkerson Max-Flow (1 / 16)

## ■ Begin

- ▶  $x := 0$
- ▶ create the residual network  $G(x)$
- ▶ while there is some directed path from  $s$  to  $t$  in  $G(x)$  do
- ▶ begin
  - ★ let  $P$  be a path from  $s$  to  $t$  in  $G(x)$
  - ★  $\Delta := \delta(P)$
  - ★ send  $\Delta$  units of flow along  $P$
  - ★ update the  $r$ 's
- ▶ end

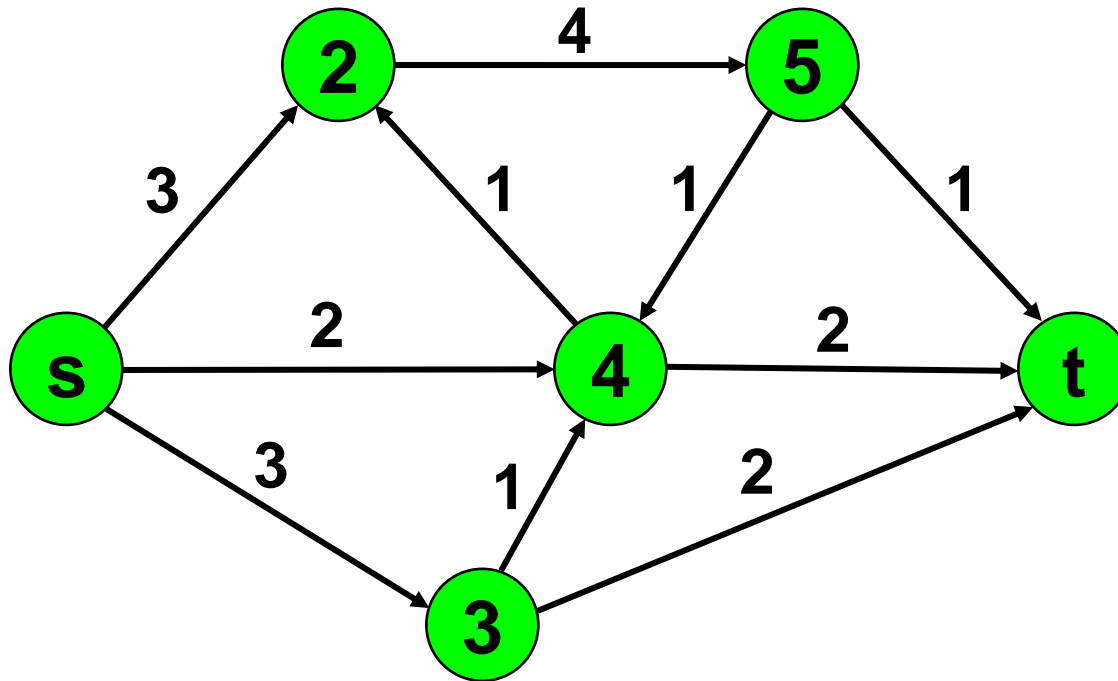
## ■ End {the flow $x$ is now maximum}

# Ford-Fulkerson Max-Flow (2/16)



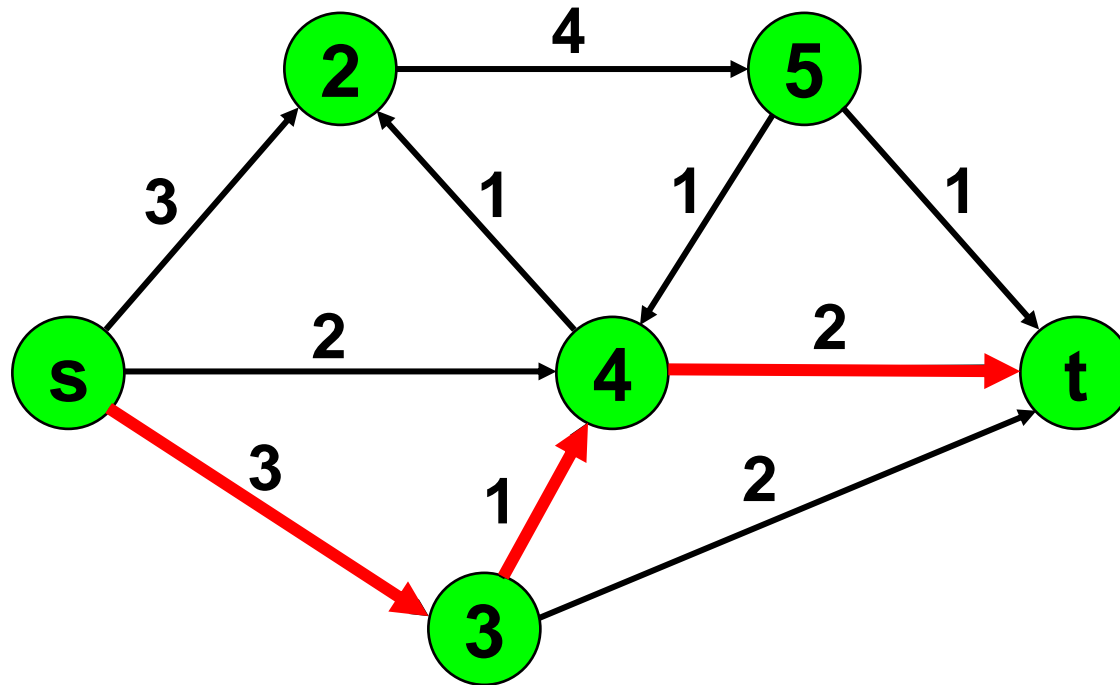
**This is the original network, plus reversals of the arcs**

# Ford-Fulkerson Max-Flow (3/16)



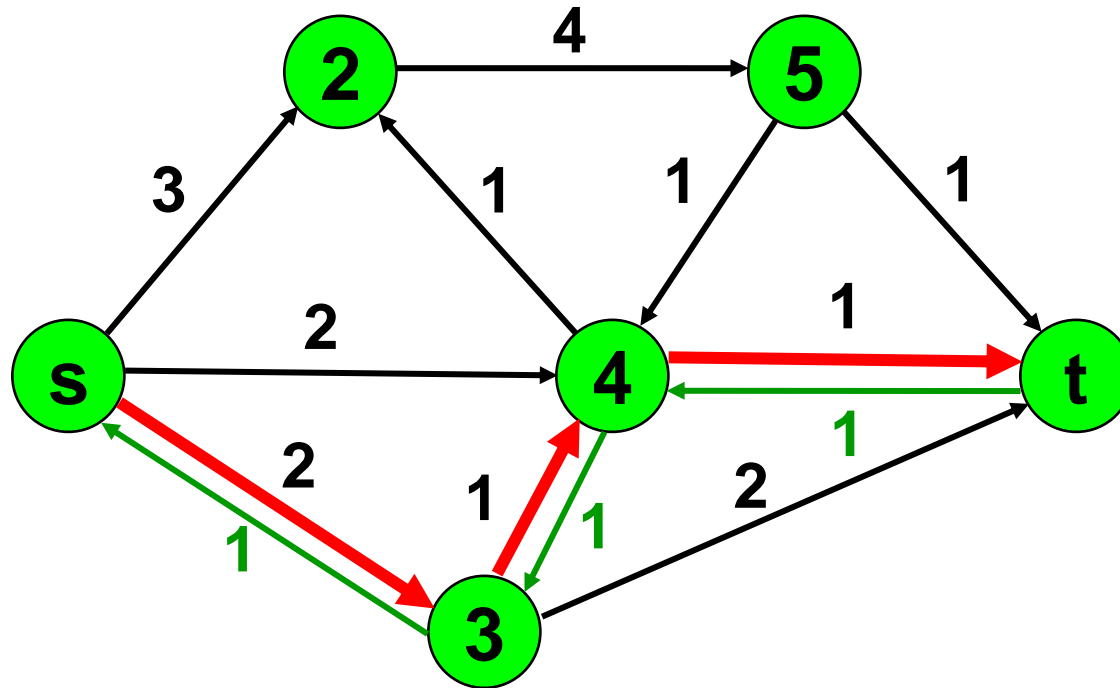
**This is the original network, and  
the original residual network**

# Ford-Fulkerson Max-Flow (4/16)



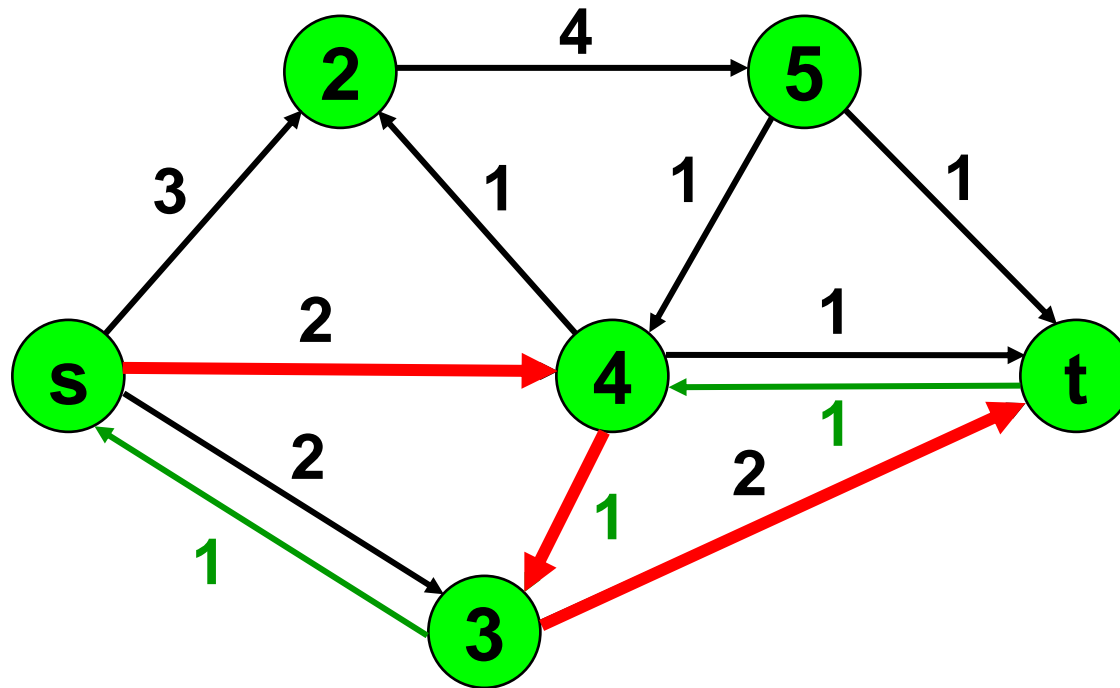
**Find any s-t path in  $G(x)$**

# Ford-Fulkerson Max-Flow (5/16)



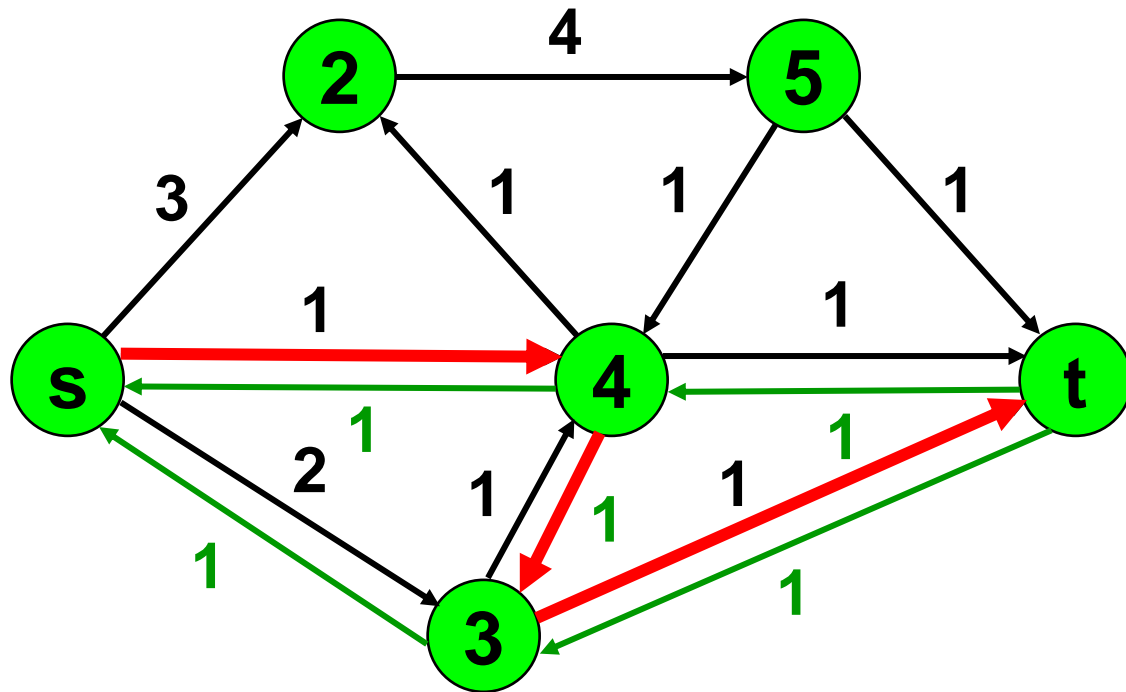
**Determine residual capacity  $\Delta$  of the path**  
**Send  $\Delta$  units of flow in the path**  
**Update residual capacities**

# Ford-Fulkerson Max-Flow (6/16)



**Find any s-t path**

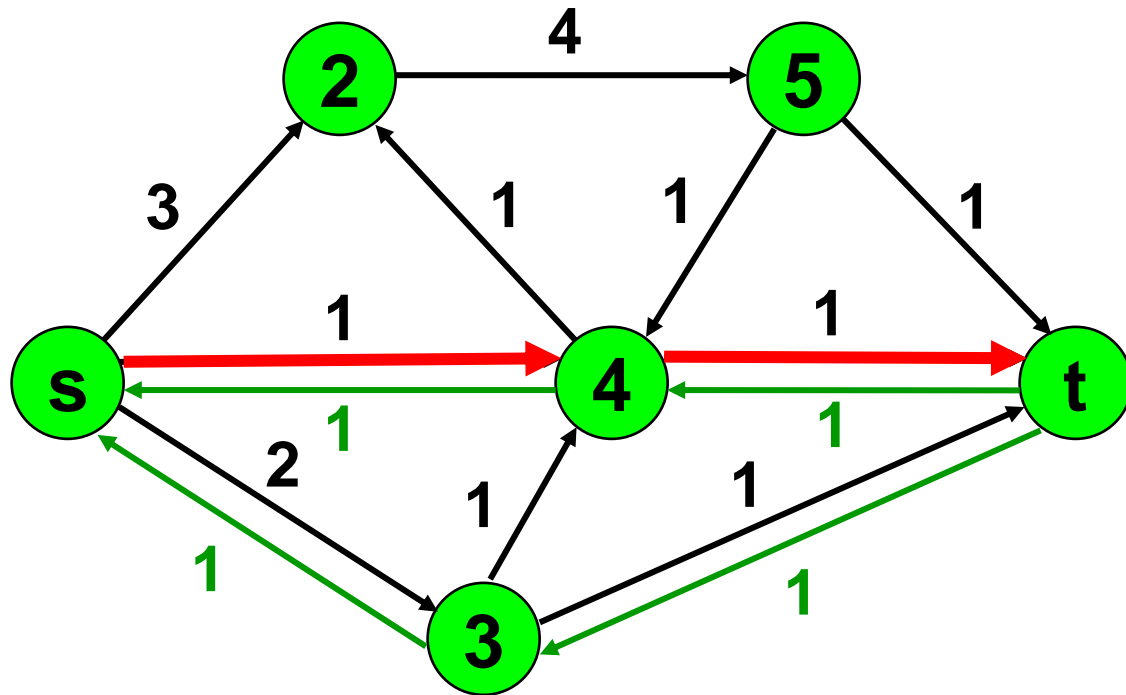
# Ford-Fulkerson Max-Flow (7/16)



**Determine the residual capacity  $\Delta$  of the path**  
**Send  $\Delta$  units of flow in the path**  
**Update residual capacities**

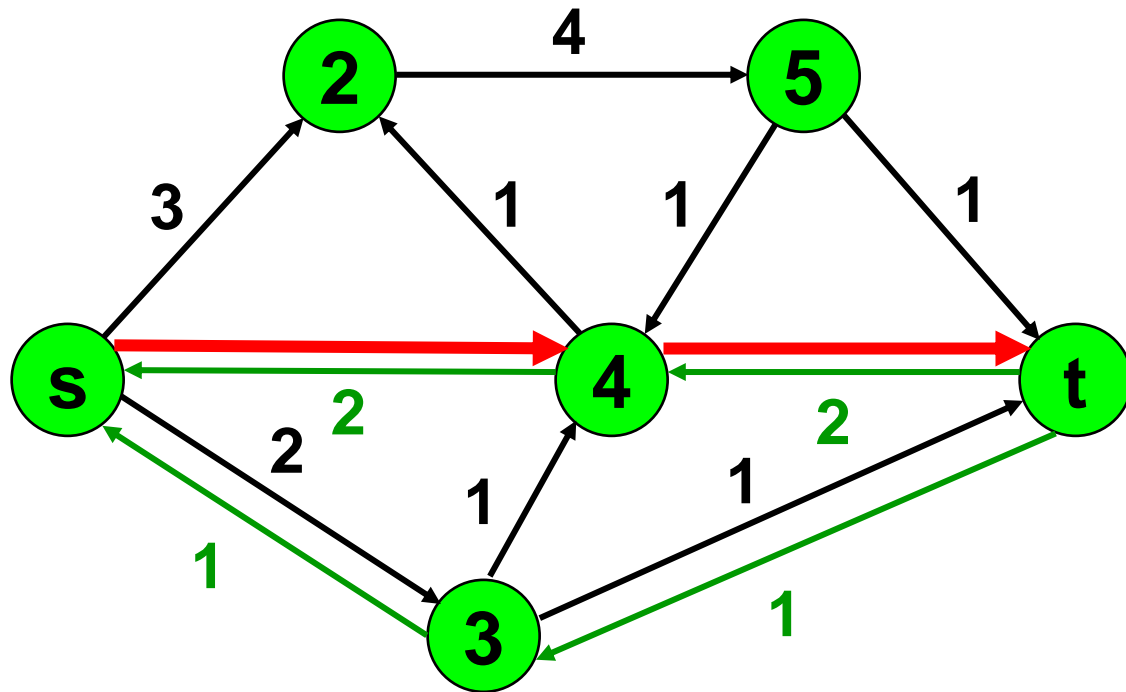


# Ford-Fulkerson Max-Flow (8/16)



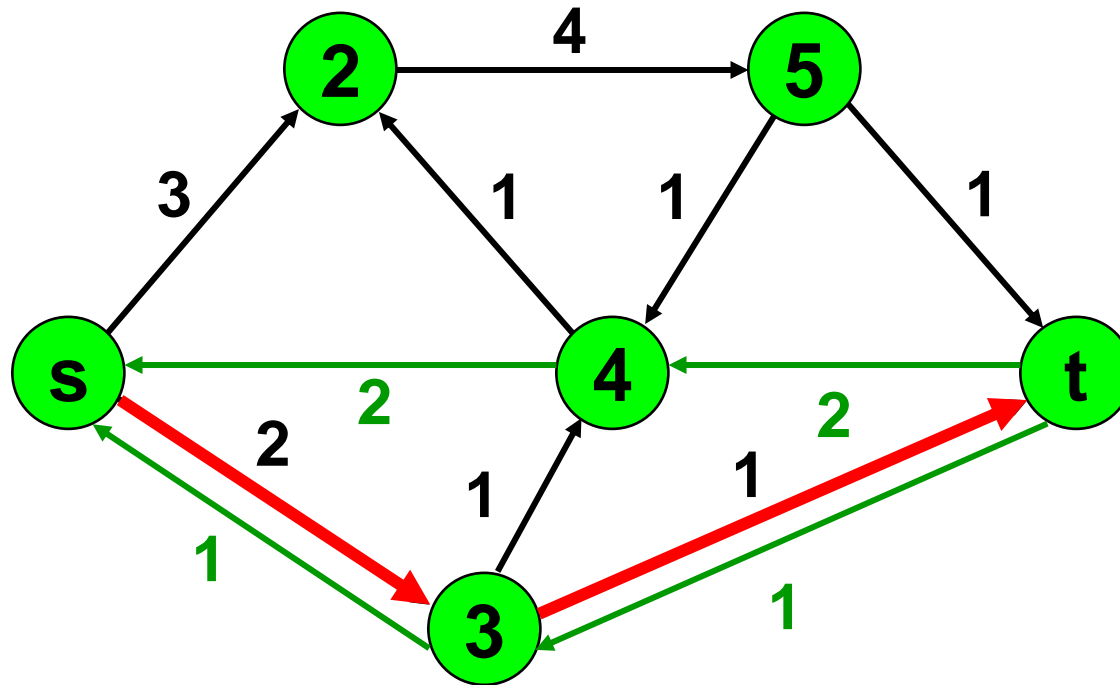
**Find any s-t path**

# Ford-Fulkerson Max-Flow (9/16)



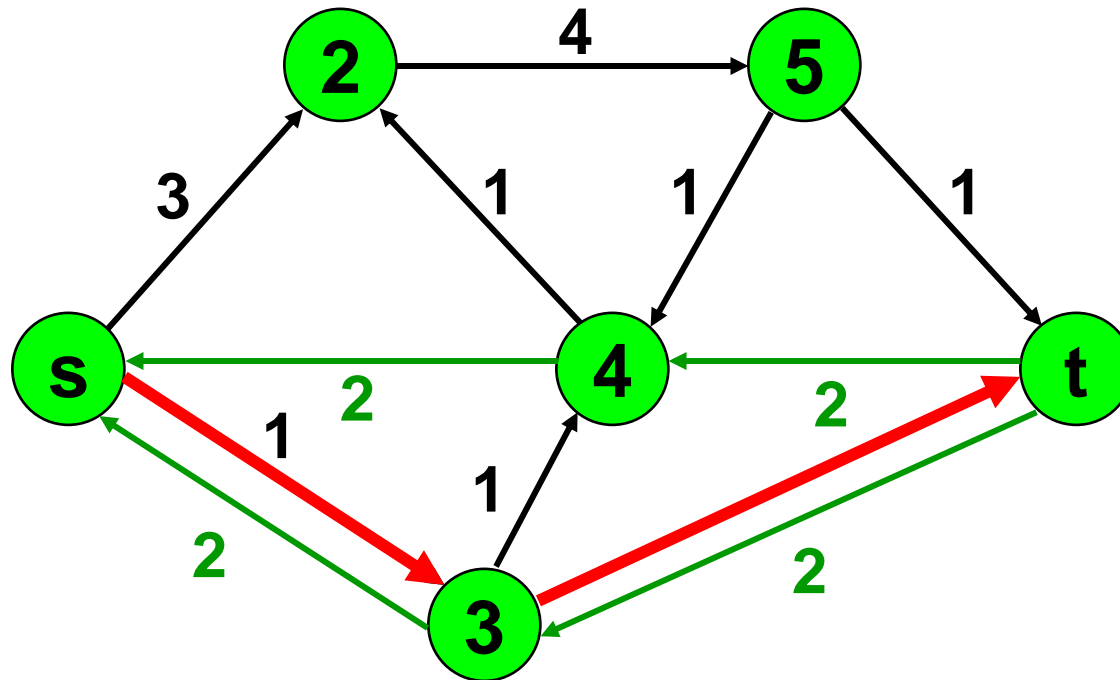
**Determine the residual capacity  $\Delta$  of the path**  
**Send  $\Delta$  units of flow in the path**  
**Update residual capacities**

# Ford-Fulkerson Max-Flow (10/16)



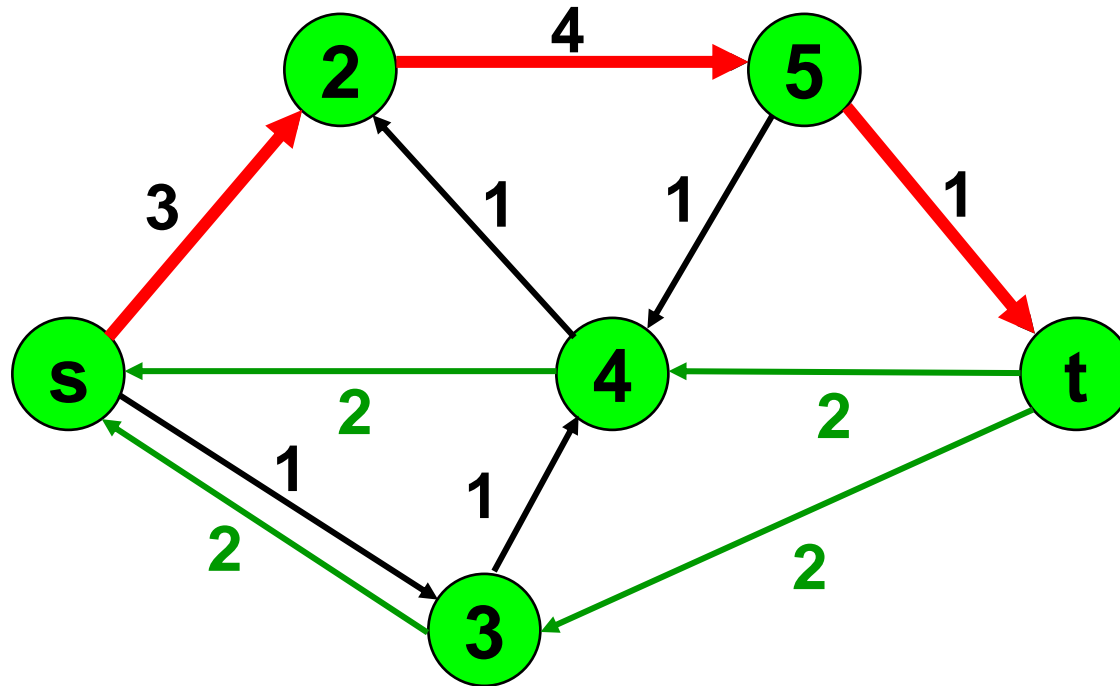
**Find any s-t path**

# Ford-Fulkerson Max-Flow (11/16)



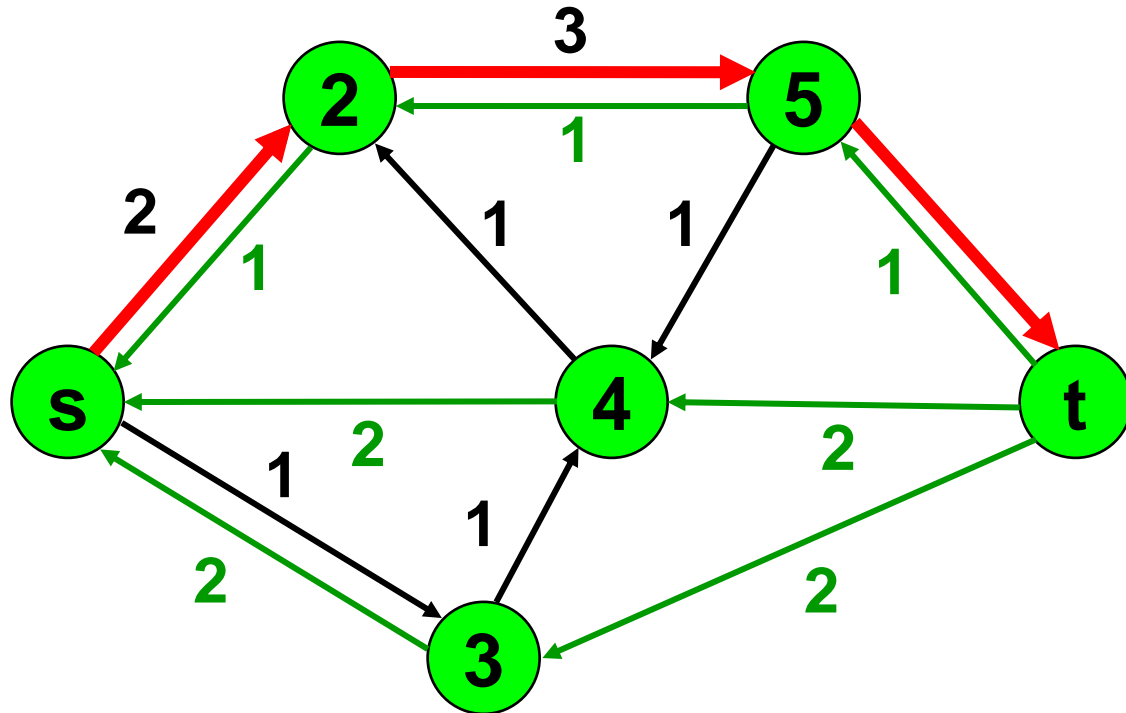
**Determine the residual capacity  $\Delta$  of the path**  
**Send  $\Delta$  units of flow in the path**  
**Update residual capacities**

# Ford-Fulkerson Max-Flow (12/16)



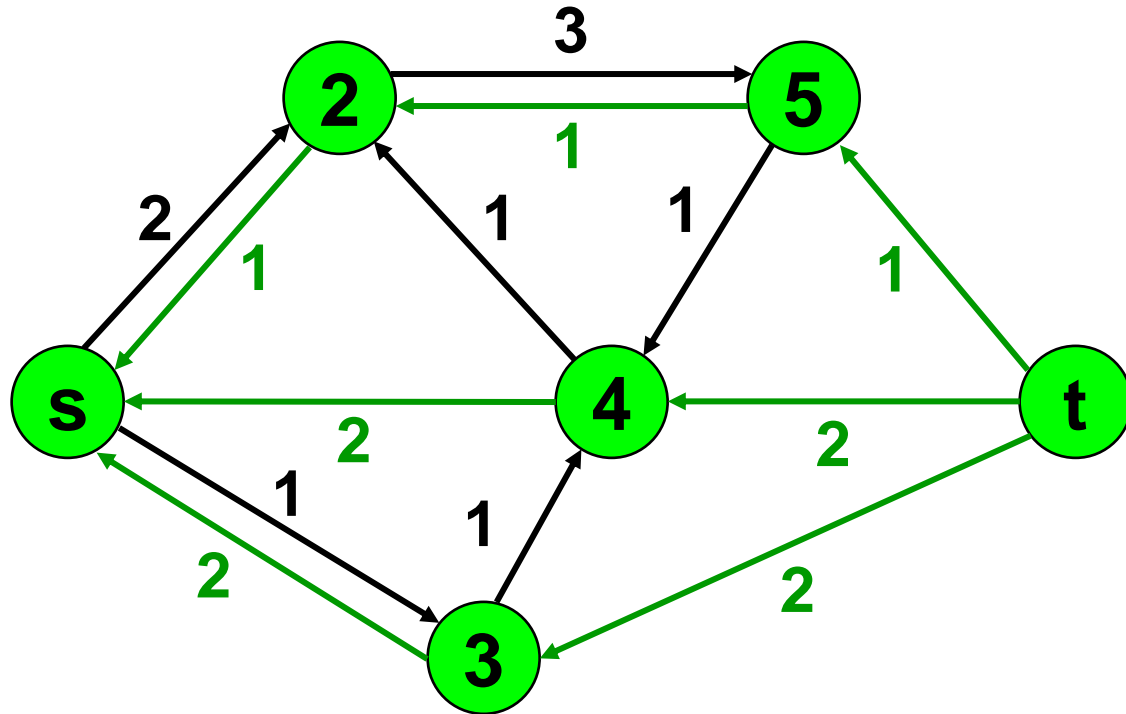
**Find any s-t path**

# Ford-Fulkerson Max-Flow (13/16)



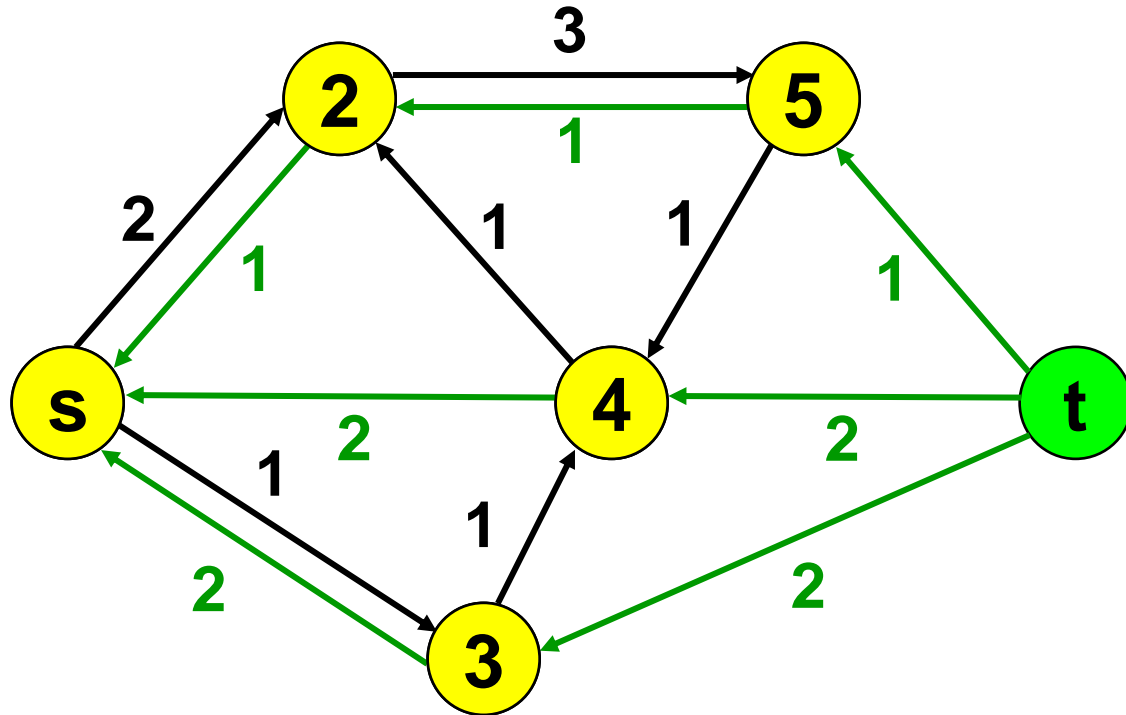
**Determine the residual capacity  $\Delta$  of the path**  
**Send  $\Delta$  units of flow in the path**  
**Update residual capacities**

# Ford-Fulkerson Max-Flow (14/16)



**There is no s-t path in the residual network  
This flow is optimal**

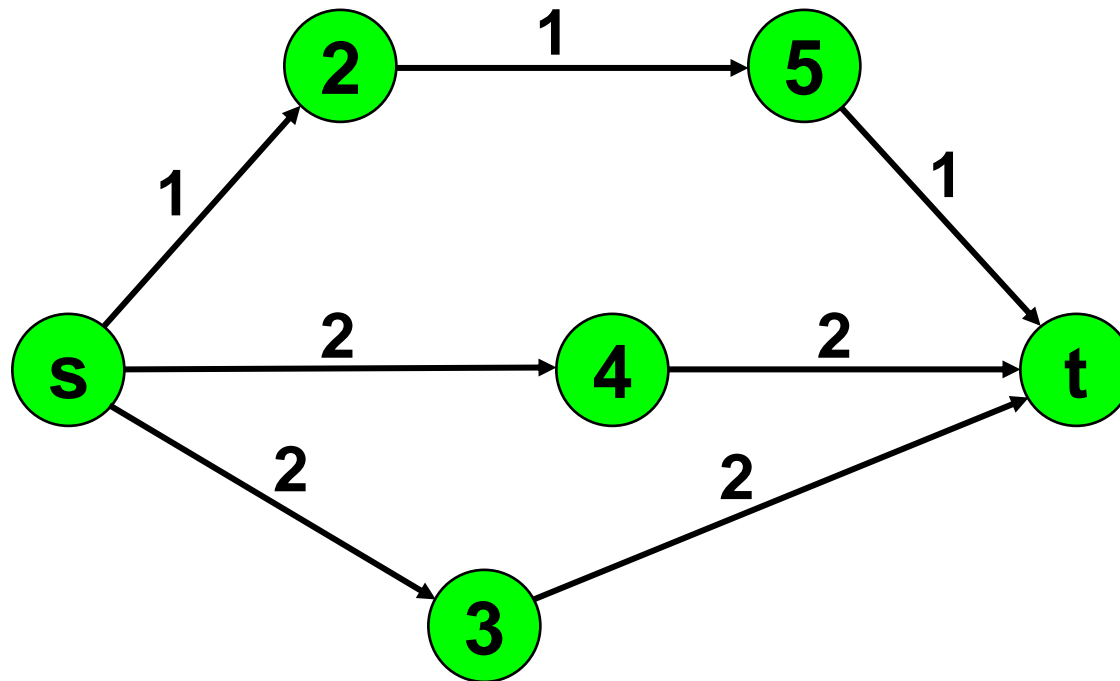
# Ford-Fulkerson Max-Flow (15/16)



**These are the nodes that are reachable from node s**

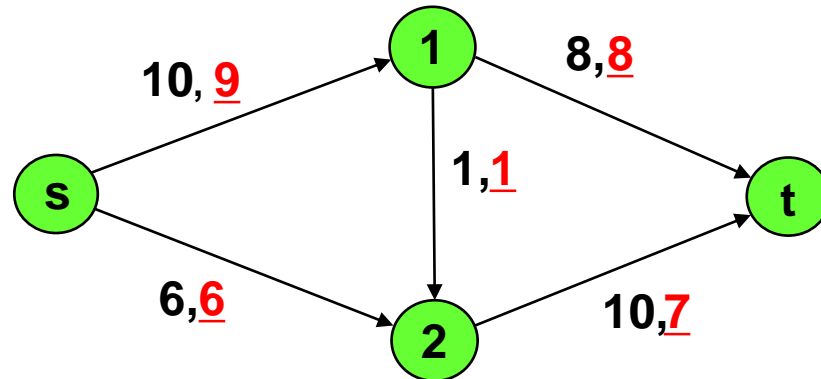


# Ford-Fulkerson Max-Flow (16/16)



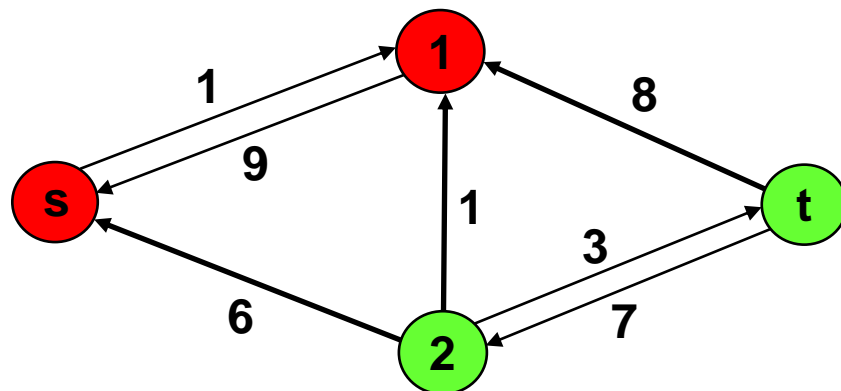
**Here is the optimal flow**

# How Do We Know When a Flow Is Optimal?



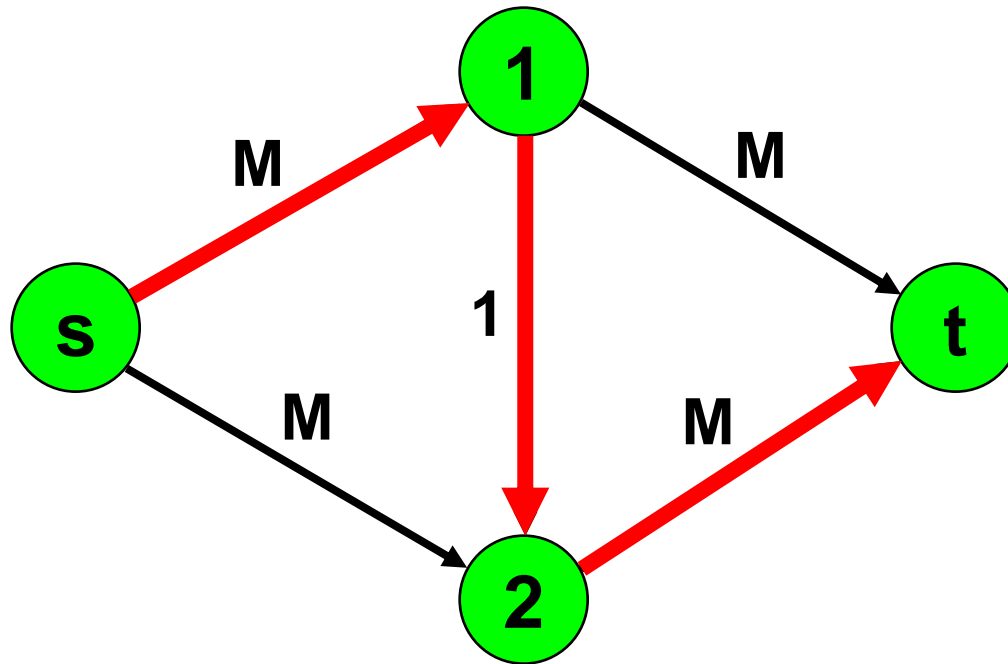
## ■ METHOD

- There is no augmenting path in the residual network

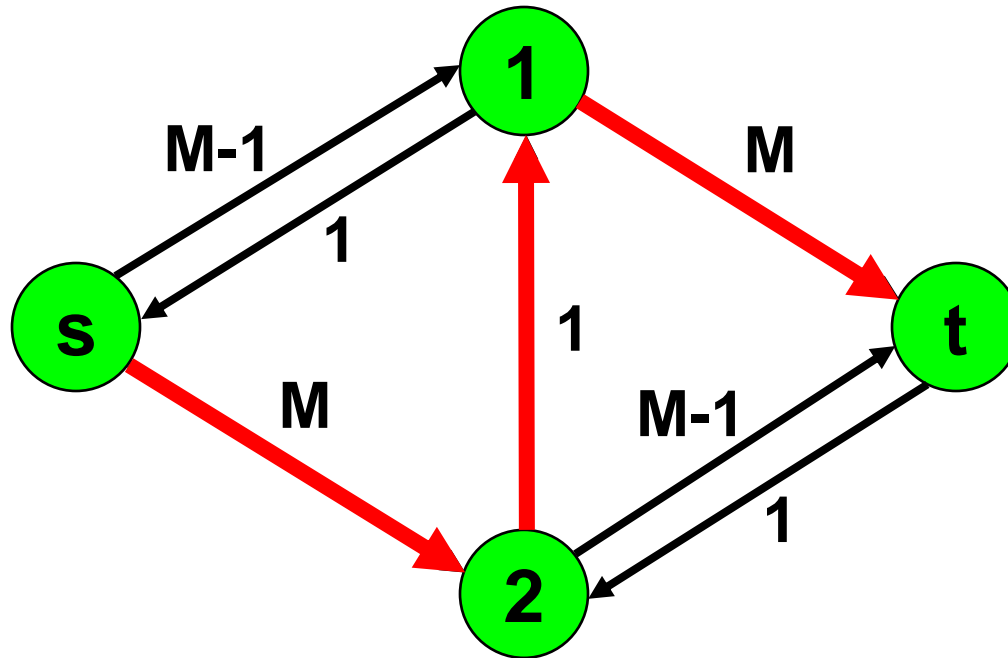


- reachable from  $s$  in  $G(x)$
- not reachable from  $s$  in  $G(x)$

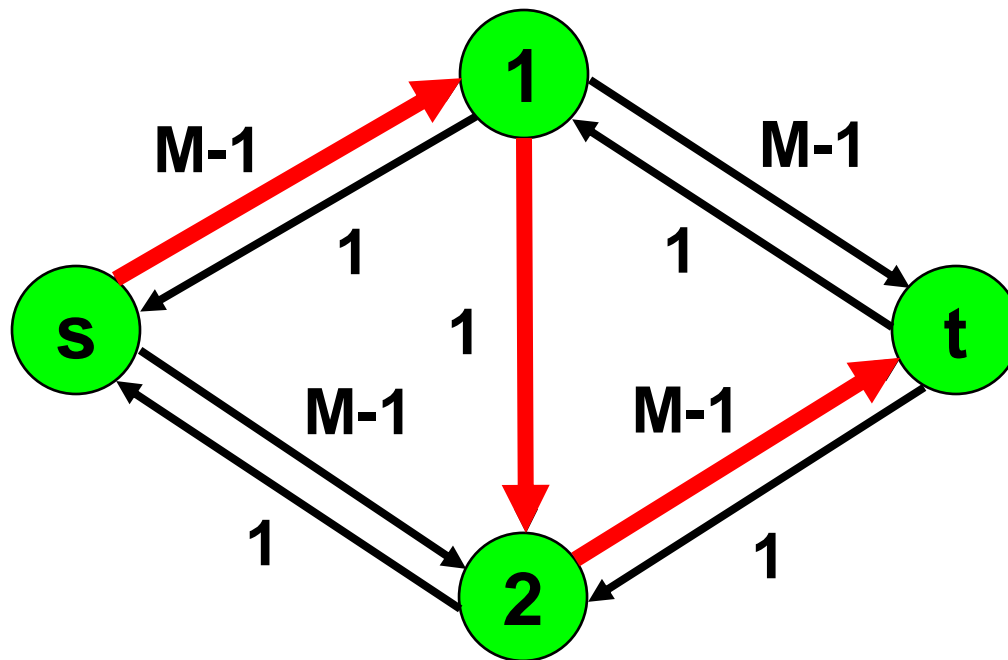
# A Simple and Very Bad Example



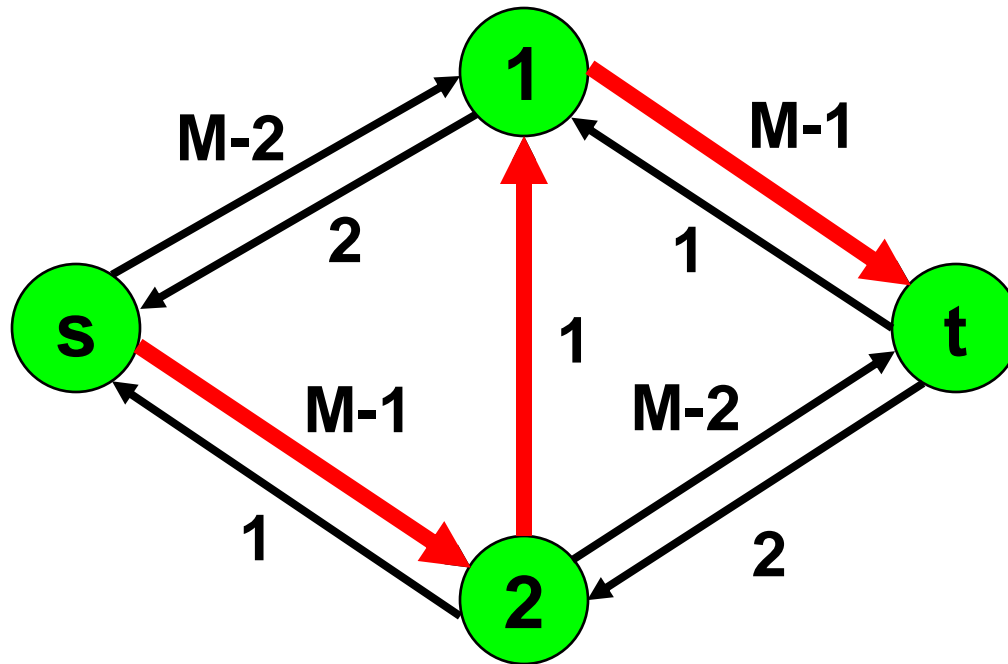
# After 1 Augmentation



# After Two Augmentations



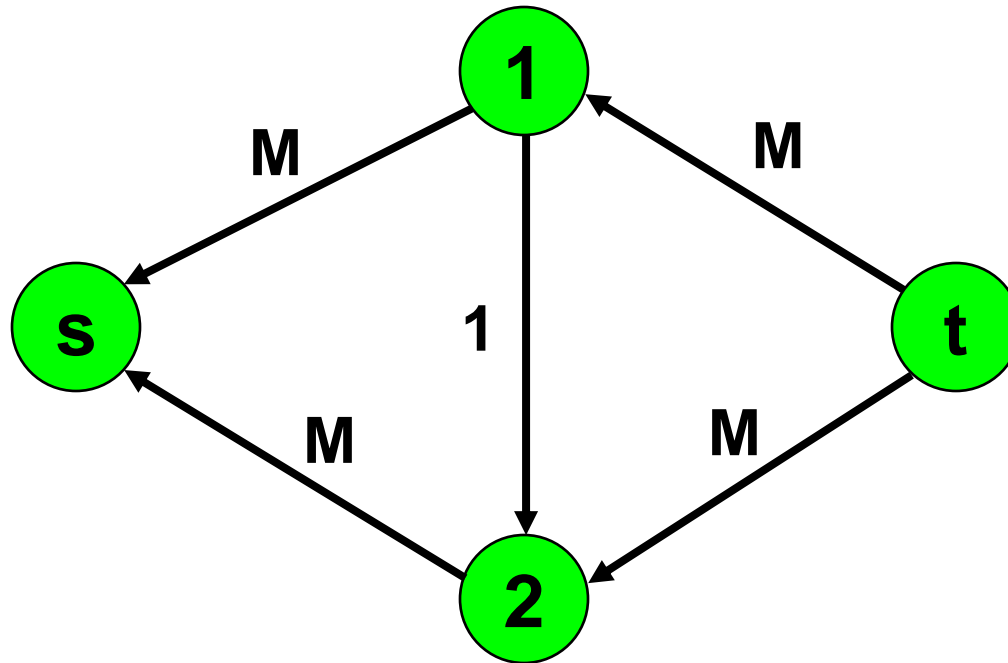
# After Three Augmentations



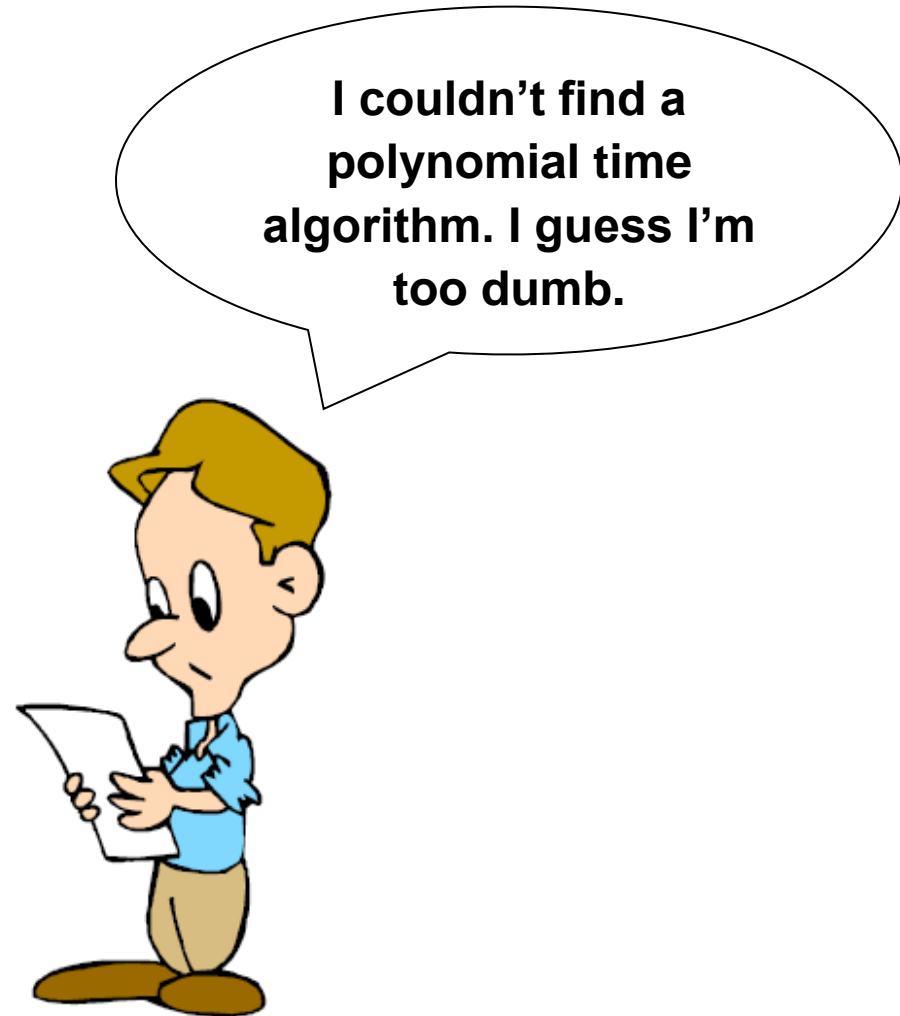
***And so on***



# After 2M Augmentations

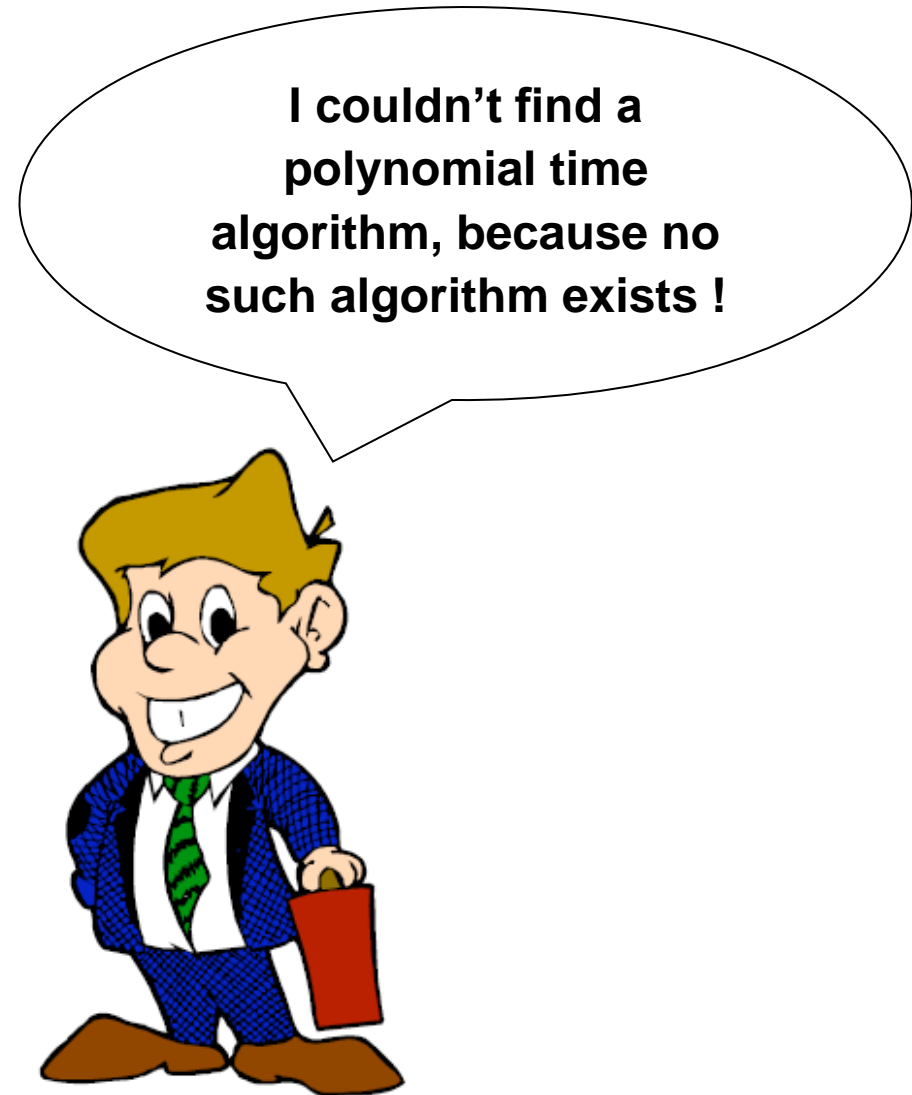


# P or NP



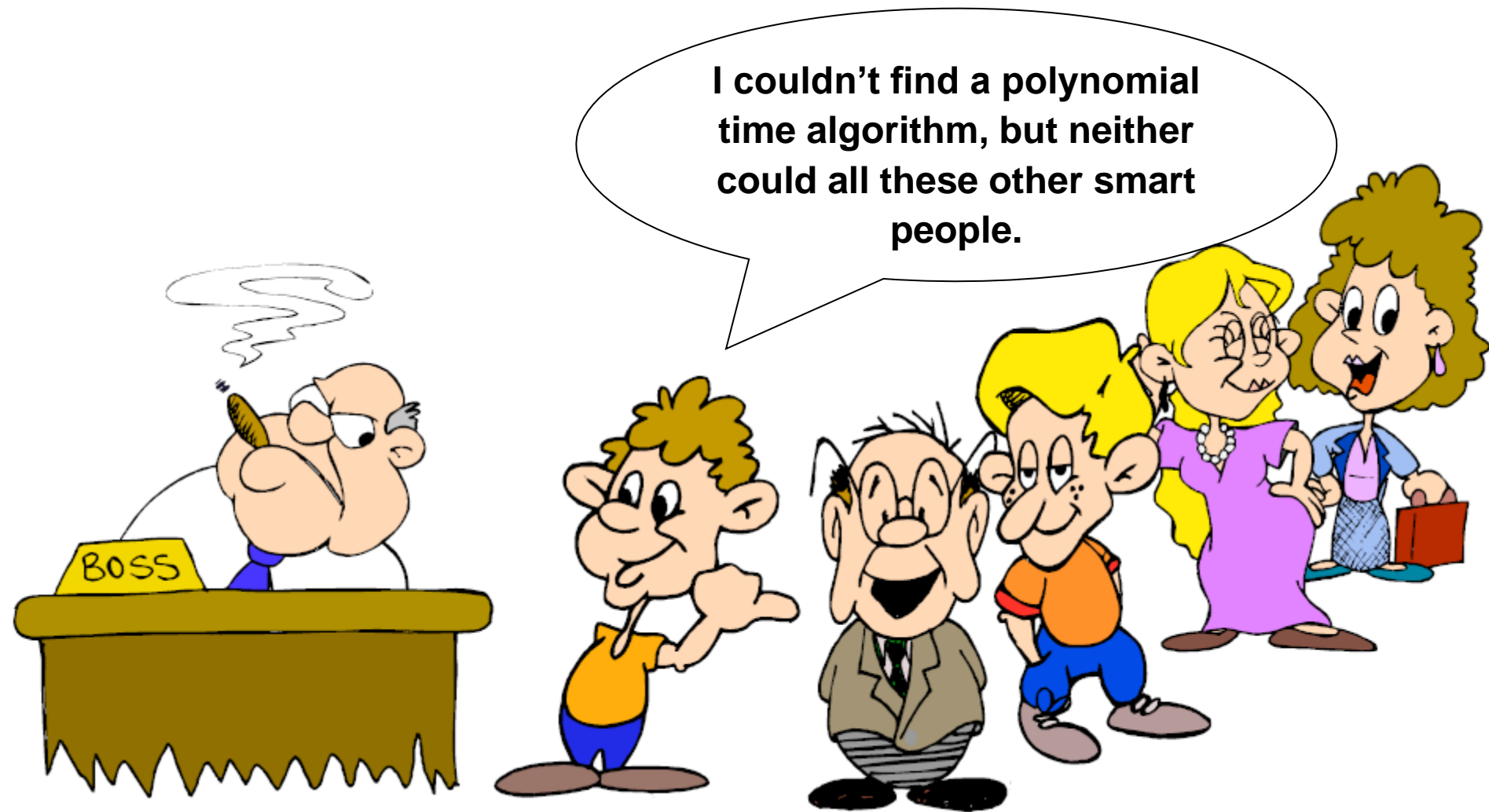


# P or NP



# P or NP

**I couldn't find a polynomial time algorithm, but neither could all these other smart people.**



# P or NP



# NP-Completeness

- Some problems are *intractable*

- ▶ They grow large, we are unable to solve them in reasonable time

- What constitutes reasonable time?

Standard working definition: *polynomial time*

- ▶ For an input of size  $n$ , the worst-case running time is  $O(n^k)$  for some constant  $k$
- ▶ Polynomial time:  $O(1)$ ,  $O(n \lg n)$ ,  $O(n^2)$ ,  $O(n^3)$
- ▶ Not in polynomial time:  $O(2^n)$ ,  $O(n^n)$ ,  $O(n!)$

# Polynomial-Time Algorithms

- Are some problems solvable in polynomial time?
  - ▶ Every algorithm we've studied provides polynomial-time solution to some problems
  - ▶ We define  $\mathbf{P}$  to be the class of problems solvable in polynomial time
- Are all problems solvable in polynomial time?
  - ▶ No: Turing's "Halting Problem" is not solvable by any computer, no matter how much time is given
  - ▶ Such problems are clearly intractable, not in  $\mathbf{P}$

# NP-Complete Problems

## ■ Definition

- ▶ The class P (or NP) denotes the family of all problems that can be solved by deterministic (nondeterministic) polynomial time algorithms

All decision problems only answer YES or NO

## ■ Nondeterministic polynomial time algorithm exist?

# NP-Complete Problems

- The *NP-Complete* problems are an interesting class of problems whose status is unknown
  - ▶ No polynomial-time algorithm has been discovered for an NP-Complete problem
- We call this the  $P = NP?$ 
  - ▶ The biggest open problem in CS
- Examples of NP-Complete problems:
  - ▶ Vertex cover problem
  - ▶ Traveling salesman problem
  - ▶ Job scheduling problem
  - ▶ ...

# Thanks to contributors

Mr. Pham Van Nguyen (2022)

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