

第五章

5.10. 已知半径 R , 圆洞中心距离原薄板 $\frac{R}{2}$, 材料密度为 m .

求: J .

$$J_1 = \frac{1}{2} m_1 \left(\frac{R}{2}\right)^2 + m_1 \left(\frac{R}{2}\right)^2$$

$$= \frac{3}{2} m_1 \left(\frac{R}{2}\right)^2$$

$$= \frac{3}{2} \pi \left(\frac{R}{2}\right)^2 \rho \left(\frac{R}{2}\right)^2$$

$$= \frac{3}{32} \pi \rho R^4$$

$$J_2 = \frac{1}{2} m_2 R^2$$

$$= \frac{1}{2} \pi \rho R^4$$

$$J = J_2 - J_1 = \frac{1}{2} \pi \rho R^4 - \frac{3}{32} \pi \rho R^4$$

$$= \frac{13}{32} \pi \rho R^4$$

$$m_2 = \pi R^2 \rho$$

$$m = \pi \left(\frac{R}{2}\right)^2 \rho \text{ 厚度}$$

$$\text{因为 } m = [\pi R^2 - \pi \left(\frac{R}{2}\right)^2] \rho$$

$$m = \pi R^2 \rho - \frac{\pi R^2}{4} \rho$$

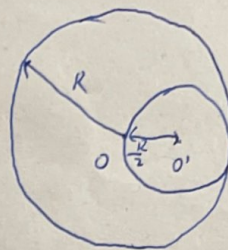
$$m = \frac{3\pi R^2 \rho}{4}$$

$$\pi R^2 \rho = \frac{4m}{3}$$

$$\text{代入 } J = \frac{13}{32} \pi \rho R^4$$

$$= \frac{13}{32} \cdot \frac{4m}{3} R^2$$

$$= \frac{13}{24} m R^2$$



5.11. 已知: 质量为 m_1, m_2, m , 半径为 r . m_2 与桌面间摩擦系数为 μ_k , 求:

求: a, T_1, T_2

解: 对 m 受力分析:

$$mg - T_1 = m_1 a$$

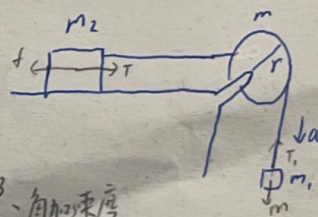
对 m_2 受力分析:

$$T_2 - \mu_k m_2 g = m_2 a$$

对滑轮:

根据转动定理:

$$(T_1 - T_2) r = \frac{1}{2} m r^2 \beta$$



因为 $a = r\beta$

联立上式:

$$\begin{cases} T_1 = m_1 g - m_1 a \\ T_2 = m_2 a + \mu_k m_2 g \\ (T_1 - T_2) r = \frac{1}{2} m r^2 \beta \\ \beta = \frac{a}{r} \end{cases} \Rightarrow$$

$$mg - m_1 a - m_2 a - \mu_k m_2 g = \frac{1}{2} m r \frac{a}{r}$$

$$-m_1 a - m_2 a - \frac{1}{2} m a = \mu_k m_2 g - m_1 g$$

$$a = \frac{m_1 - \mu_k m_2}{m_1 + m_2 + \frac{m}{2}} g$$

$$T_1 = m_1 g - m_1 a$$

$$T_2 = m_2 a + \mu_k m_2 g$$

$$T_1 = m_1 \left(g - \frac{m_1 - \mu_k m_2}{m_1 + m_2 + \frac{m}{2}} g \right)$$

$$= m_2 \left(\frac{m_1 - \mu_k m_2}{m_1 + m_2 + \frac{m}{2}} g + \mu_k g \right)$$

$$T_1 = m_1 g \frac{(1 + \mu_k) m_1 + \frac{m}{2}}{m_1 + m_2 + \frac{m}{2}}$$

$$= m_2 g \frac{(1 + \mu_k) m_1 + \frac{m}{2}}{m_1 + m_2 + \frac{m}{2}}$$

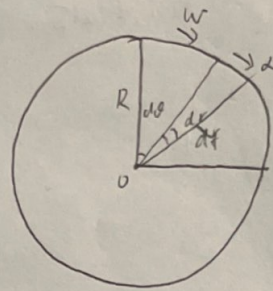
5.14. 已知半径为 R , 质量为 m , 滑动摩擦系数为 μ_k , 角速度为 ω .

求: M, t, A, E_k

解. 设元面积为 $ds = r d\theta dr$.

$$\text{质量为 } dm = \frac{m r d\theta dr}{\pi R^2}$$

$$dM = r df = r \mu_k dm g = \frac{m g \mu_k r^2 d\theta dr}{\pi R^2}$$



$$\textcircled{1} M = \int dM = \frac{\mu_k m g}{\pi R^2} \int_0^{2\pi} d\theta \int_0^R r^2 dr = \frac{\mu_k m g}{\pi R^2} \cdot 2\pi \cdot \frac{1}{3} R^3 = \frac{2}{3} \mu_k m g R$$

$$\textcircled{2} t = \frac{\omega}{\alpha} = \frac{\omega}{\frac{M}{\frac{1}{2} m R^2}} = \frac{\omega}{\frac{\frac{2}{3} \mu_k m g R}{\frac{1}{2} m R^2}} = \frac{3 R \omega}{4 \mu_k g}$$

$M = J \alpha$ $\frac{1}{2} m R^2$ 转动惯量

$$\textcircled{3} A = M \cdot \Delta\theta = M \cdot \omega t = \frac{2}{3} \mu_k m g R \cdot \omega \cdot \frac{3 R \omega}{4 \mu_k g} = \frac{1}{2} m R^2 \omega^2$$

$$\textcircled{4} E_k = \frac{1}{2} J \omega^2 = \frac{1}{2} \left(\frac{1}{2} m R^2 \right) \omega^2 = \frac{1}{4} m R^2 \omega^2$$

5.16. 已知 $L = 0.4 \text{ m}$, $M = 1 \text{ kg}$, $m = 8 \text{ g}$, $v_0 = 200 \text{ m/s}$, $d = \frac{3L}{4}$

求: ω, θ

解. 根据角动量守恒. $L = r \times p$, $L = J \omega$.

$$m v_0 \times \frac{3}{4} L = \left[\frac{1}{3} M L^2 + \left(\frac{3L}{4} \right)^2 \right] \omega$$

$$\omega = \frac{3 m v_0 L}{4 \left(\frac{1}{3} M L^2 + \frac{9}{16} L^2 \right)}$$

$$\omega = \frac{3 \times 0.008 \times 200 \times 0.4}{4 \times \left(\frac{1}{3} \times 1 \times 0.4^2 + \frac{9}{16} \times 0.008 \times 0.4^2 \right)}$$

$$\omega = 8.88 \text{ (rad/s)}$$

根据机械能守恒:

$$\frac{1}{2} \left(\frac{1}{3} M L^2 + \frac{9}{16} m L^2 \right) \omega^2 = \left(M g \frac{L}{2} + m g \frac{3}{4} L \right) (1 - \cos \theta)$$

$$\theta = \arccos \left(1 - \frac{\frac{1}{2} \left(\frac{1}{3} M L^2 + \frac{9}{16} m L^2 \right) \omega^2}{M g \frac{L}{2} + m g \frac{3}{4} L} \right)$$

$$\theta = 94.18^\circ$$

5.19. 已知: $R = 2.5\text{m}$, $J = 3 \times 10^5 \text{kg} \cdot \text{m}^2$, $m = 70\text{kg}$, $\theta = 30^\circ$.

求: v , ω , n .

解:

$$mg = \frac{mv^2}{r}$$

$$v = \sqrt{gr}$$

$$v = \sqrt{9.8 \times 2.5}$$

$$v = 4.95(\text{m/s})$$

根据角动量守恒

$$3mvR = J\omega$$

$$\omega = \frac{3mvR}{J}$$

$$\omega = \frac{3 \times 70 \times 4.95 \times 2.5}{3 \times 10^5}$$

$$\omega = 8.66 \times 10^{-3}(\text{rad/s})$$

$$\text{时间 } t = \frac{\pi}{6\omega}, \text{角速度} = \omega + \frac{v}{R}$$

$$n = \frac{(\omega + \frac{v}{R}) \cdot t}{2\pi}$$

$$n = \frac{(8.66 \times 10^{-3} + \frac{4.95}{2.5}) \cdot \frac{\pi}{6 \times 8.66 \times 10^{-3}}}{2\pi}$$

$$n = 19.14(1\frac{1}{2})$$

5.21 已知: $T = 0.033$, $dT = 1.26 \times 10^{-5} \text{s/a}$

求: α , $\frac{dE}{dt}$, t .

$$\alpha = \frac{d\omega}{dt} = \frac{d}{dt} \frac{2\pi}{T} = -\frac{2\pi}{T^2} \frac{dT}{dt} = -\frac{2\pi}{0.033^2} \times \frac{1.26 \times 10^{-5}}{3.15 \times 10^7} = -2.3 \times 10^{-9}(\text{rad/s}^2)$$

$$\frac{dE}{dt} = \frac{d}{dt} \left(\frac{1}{2} J \omega^2 \right) = \frac{1}{2} J \times 2\omega \frac{d\omega}{dt} = \frac{2}{5} m R^2 \omega \frac{d\omega}{dt}$$

$$= \frac{2}{5} \times 1.5 \times 10^{30} \times (10^4)^2 \times \frac{2\pi}{0.033} \times (-2.3 \times 10^{-9})$$

$$= -2.6 \times 10^{31}(\text{J/s})$$

$$t = \frac{E}{|\frac{dE}{dt}|} = \frac{\frac{1}{2} J \omega^2}{|\frac{dE}{dt}|} = \frac{2 \times 1.5 \times 10^{30} \times (10^4)^2 (2\pi)^2}{2 \times 5 \times 0.033^2 \times 2.6 \times 10^{31}}$$

$$= 4.18 \times 10^{10}(\text{s})$$

$$= 1300(\text{a})$$

5.27. 已知: $T = 2660 \text{ a}$, $J = 8.65 \times 10^{37} \text{ kg} \cdot \text{m}^2$, $\theta = 23.5^\circ$

求: M , $|\frac{dL}{dt}|$

解: $|\frac{dL}{dt}| = L \sin \theta \frac{d\theta}{dt} = J \omega \sin \theta \frac{d\theta}{dt}$

$$= 8.65 \times 10^{37} \times \frac{2\pi}{86400} \times \sin 23.5^\circ \times \frac{2\pi}{26600 \times 3.15 \times 10^7}$$

$$= 1.79 \times 10^{22} (\text{kg} \cdot \text{m/s}^2)$$

$$M = |\frac{dL}{dt}| = 1.79 \times 10^{22} (\text{N} \cdot \text{m})$$