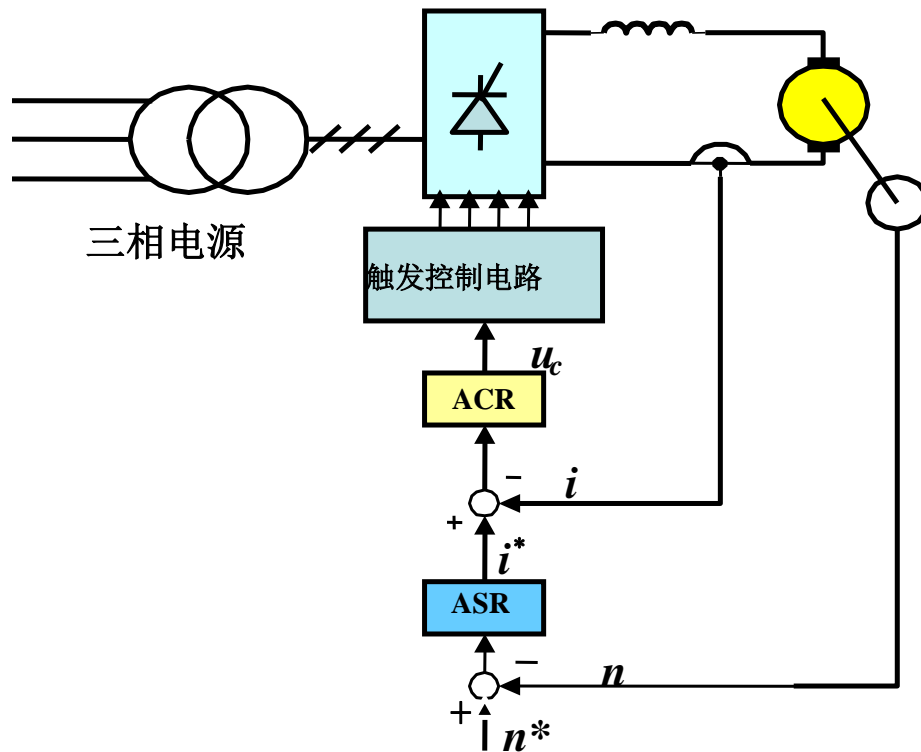


Simulation on Dual-loop DC Motor Drives

Design and simulate a dual-loop DC motor drive system as shown below by using MATLAB/SIMULINK.



- 1) Power source: 3-phase 380V 50Hz;
- 2) Power electronics converter: Diode rectifier + Switching mode full bridge converter
- 3) DC Motor model: DC machines
Preset model: 01 5HP 240V 1750rpm Field:300V
Mechanical output: Speed
- 4) PWM method: optional

1. Design ASR and ACR and determine their parameters. The output limit for ASR is 30, and the output limit for ACR is 300;
2. Simulate the system operating with step change from 1500rpm to 1200rpm without load, operating at 1200rpm with 3 seconds and step up to 1500rpm;
3. Simulate the system operating at 1500rpm without load at the initial, and then with a load change of 10Nm at $t=3\text{sec}$;
3. Give the input and output of each section in steady-state;
5. Discuss the effects and influences of K_p , K_i and output limit.

Notes:

- (1) The basic principle is to speed up the acceleration process with minimum overshoot;
- (2) Design the regulator parameters by control theory first and then adjust them manually;
- (3) Determine the parameters of ACR (inner loop) first and then adjust the parameters of ASR (outer loop).

注：除之前作业中曾用过的元件外，本次仿真可能用到的元件：

1. Control & Measurements->Pulse & Signal Generators->Stair Generator:产生阶跃信号。

2. Fundamental Blocks->Machines->DC Machine:直流电机。

3. Simulink->Continuous->PID Controller:控制PI参数。

4. Simulink->Continuous->Transfer fcn:设置传递函数