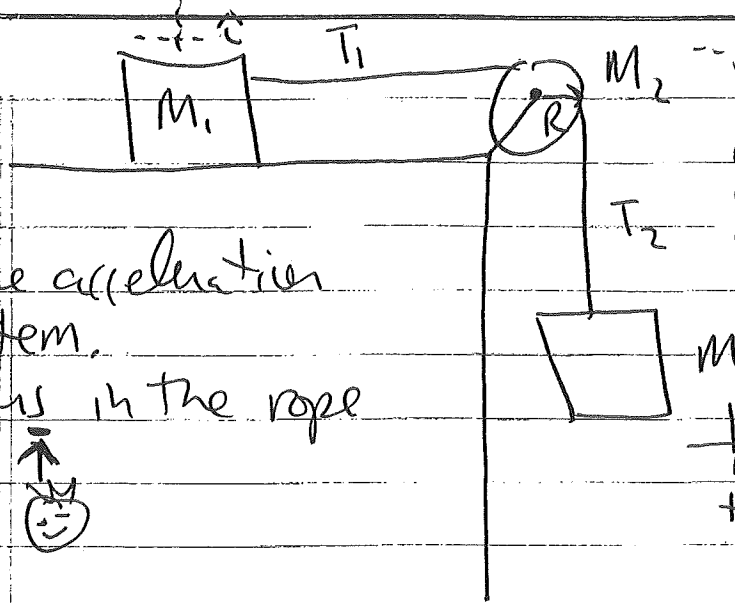


These are NOT notes. They are a visual aid (20%) for a verbal explanation (80%).

①

EX.



Find the acceleration of system.
Tension in the rope

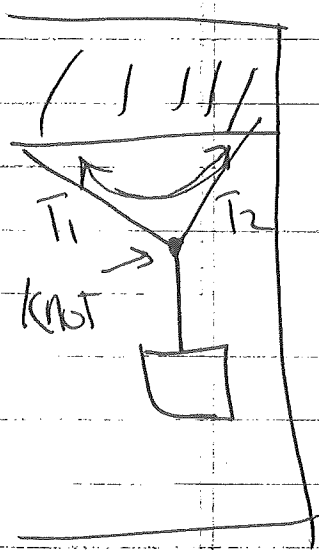
Pulley: $M_2 = 2 \text{ kg}$
 $R = 0.05 \text{ meters}$

$M_1 = 5 \text{ kg}$
 $M_3 = 20 \text{ kg}$

"Start from rest"

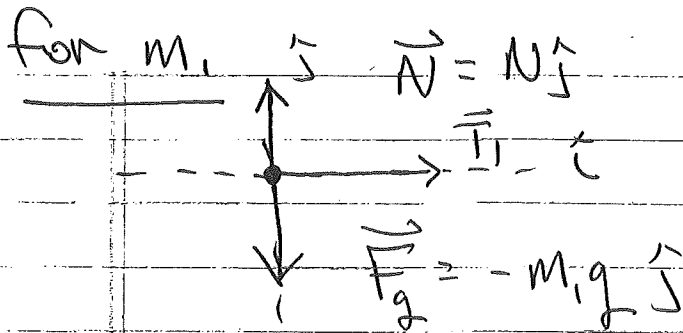
No friction on table.
Massless rope.

Recall Process



- Choose a mass to which you wish to apply 2nd
 - Show mass at a pt. Choose a coord. system.
 - Identify forces & write as vectors
 - Apply 2nd Law $\sum \vec{F} = m\vec{a}$
 - Algebra
- Repeat as needed

These are NOT notes. They are a visual aid(20%) for a verbal explanation(80%). (2)



$$\vec{T}_1 = T_1 \hat{i}$$

1st $\sum \vec{F} = m_1 \vec{a}$

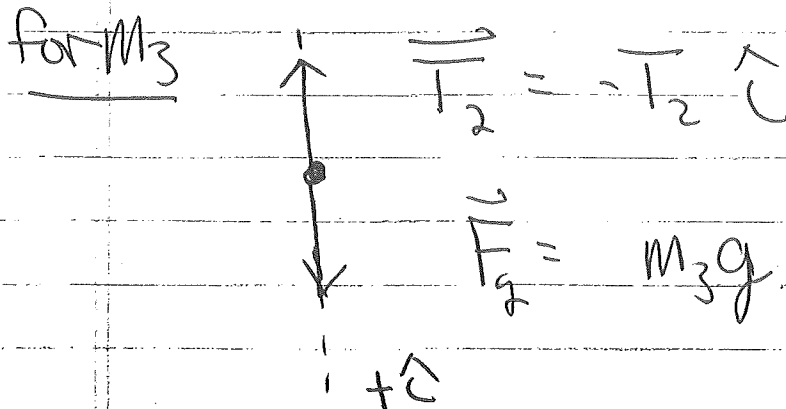
\hat{j} $\sum F_y = m_1 a_y$

$$N - m_1 g = 0$$

$$\underline{\underline{N = m_1 g}}$$

\hat{i} $\sum F_x = m_1 a_x$

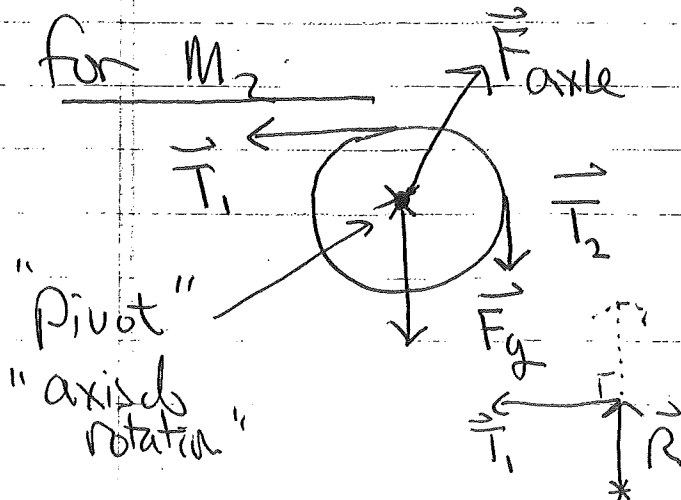
1 $\boxed{T_1 = m_1 a_x}$



2nd

\hat{i} $\sum F_x = m_3 a_x$

2 $\boxed{-T_2 + m_3 g = m_3 a_x}$



Write a Torque for every force.

$$\vec{\tau}_{\vec{F}_g} = \vec{r} \times \vec{F}_g = |\vec{r}| |\vec{F}_g| \sin \theta$$

$$\vec{\tau}_{\vec{F}_g} = 0$$

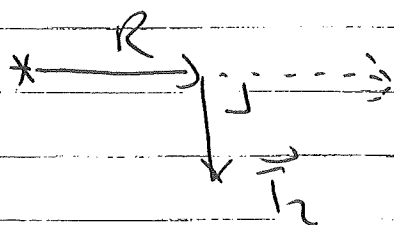
$$\vec{\tau}_{\vec{T}_1} = \vec{r} \times \vec{T}_1 = R T_1 \sin(90)$$

\rightarrow **OUT**
 Counter Clockwise
 (CCW)

These are NOT notes. They are a visual aid(20%) for a verbal explanation(80%).

③

$$\vec{\tau}_{T_2} = \vec{R} \times \vec{T}_2 = RT_2 \sin(\alpha_0)$$



(In) ↙
[Clockwise]
(cw)

" + " ||
≡ ≡ ≡

2nd law $\sum \vec{\tau} = I \alpha$

$$\boxed{3} \quad +RT_2 - RT_1 = I \alpha$$

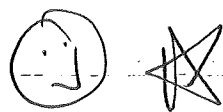
$$\boxed{2} \quad -T_2 + m_3 g = m_3 a_x$$

$$\boxed{1} \quad T_1 = m_1 a_x$$

TABLE 9.2 $I = \frac{m_2 R^2}{2}$ || "cross talk"
 $a_x = R \alpha$
 $\therefore \alpha = \frac{a_x}{R}$

$$\therefore \boxed{3} \Rightarrow RT_2 - RT_1 = \frac{m_2 R^2}{2} \frac{a_x}{R}$$

$$RT_2 - RT_1 = \frac{m_2 R a_x}{2}$$



$$T_2 - T_1 = m_2 a_x / 2$$

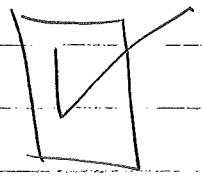
These are NOT notes. They are a visual aid(20%) for a verbal explanation(80%). (4)

Use [2] and [1] in ~~the~~ to get:

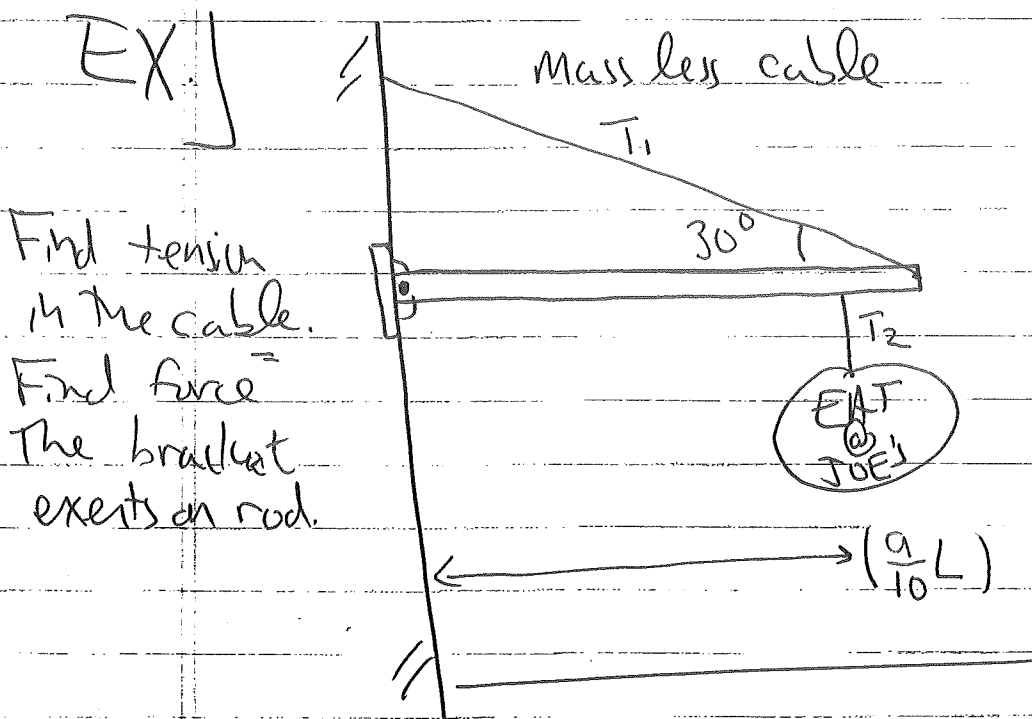
$$m_3 g - m_3 a_x - m_1 a_x = \frac{m_2 a_x}{2}$$

$$m_3 g = a_x \left(\frac{m_2}{2} + m_3 + m_1 \right)$$

$$7.54 \text{ m/s}^2 = \frac{m_3 g}{\left(\frac{m_2}{2} + m_3 + m_1 \right)} = a_x$$



STATIC EQUIL.



length 'L'
uniform
mass 'M'
Let 'M' be
mass of sign.

for sign

$$\begin{aligned} \vec{T}_2 &= T_2 \hat{j} \\ \vec{F}_g &= -Mg \hat{j} \end{aligned}$$

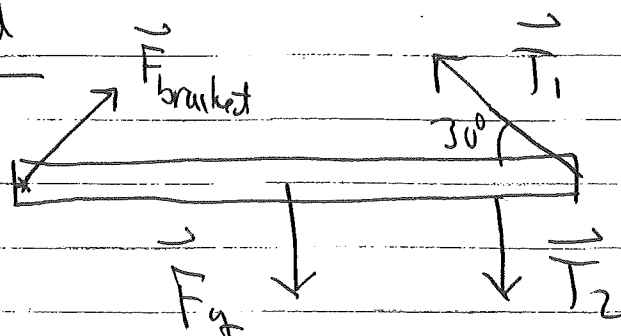
2nd

$$\begin{aligned} \hat{j} \sum F_y &= 0 \\ \therefore T_2 &= Mg \end{aligned}$$

These are NOT notes. They are a visual aid(20%) for a verbal explanation(80%).

5

for rod



$$\begin{cases} \vec{T}_2 = -Mg \hat{j} \\ \vec{F}_g = -mg \hat{j} \\ \vec{F}_{\text{bracket}} = F_x \hat{i} + F_y \hat{j} \\ \vec{T}_1 = -T_1 \cos(30) \hat{i} + T_1 \sin(30) \hat{j} \end{cases}$$

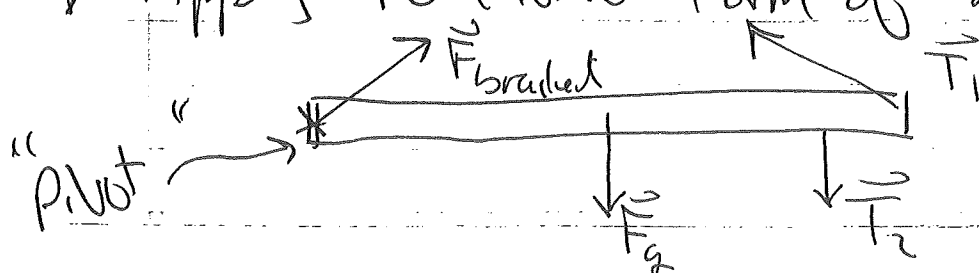
2nd $\sum \vec{F} = m\vec{a} \rightarrow 0$

$(\hat{i}) \quad \sum F_x = 0$
 $F_x - T_1 \cos(30) = 0 \quad [1]$

$(\hat{j}) \quad \sum F_y = 0$
 $-Mg - mg + F_y + T_1 \sin(30) = 0 \quad [2]$

Hmmm... $\sum \vec{\tau} = I\vec{\alpha} \rightarrow 0$

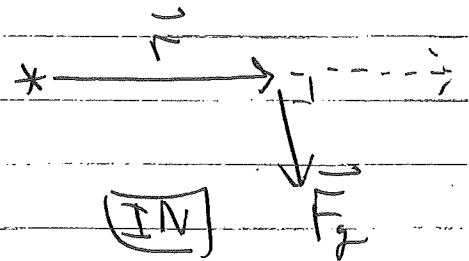
★ Apply rotational form of 2nd Law.



These are NOT notes. They are a visual aid(20%) for a verbal explanation(80%). (6)

$$\vec{\tau}_{F_{\text{bracket}}} = 0 \quad (\odot)$$

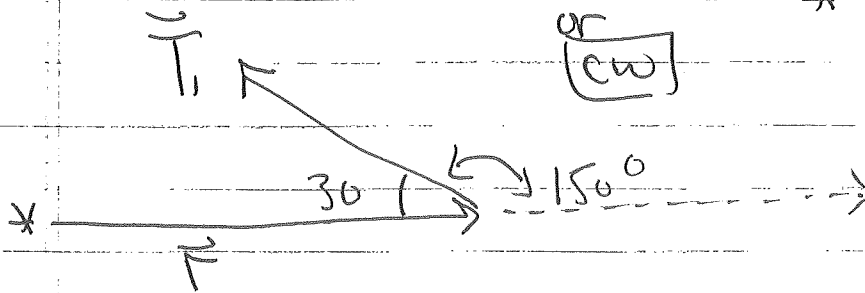
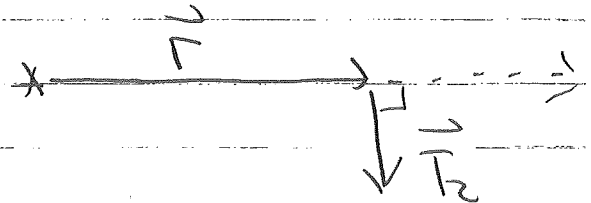
$$\vec{\tau}_{F_g} = \vec{r} \times \vec{F}_g = \left(\frac{L}{2}\right)(mg)\sin(90)$$



(IN)
or
(CW)

$$\vec{\tau}_{T_2} = \vec{r} \times \vec{T}_2 = \left(\frac{9L}{10}\right)(Mg)\sin(90)$$

(IN)
or
(CW)



$$\vec{\tau}_{T_1} = \vec{r} \times \vec{T}_1 = (L)(T_1)\sin(150)$$

(CW)
(CCW)

2nd.

$$\sum \vec{\tau} = \cancel{\frac{1}{2}} \rightarrow 0$$