Unlike the gravitational force, which has the precise and unambiguous magnitude $\mathbf{F}_G = mg$, the size of the static friction force depends on how hard you push. The barder the person in Figure 6.11 pushes, the harder the floor pushes back. Reduce the pushing force, and the static friction force will automatically be reduced to match. Static friction acts in *response* to an applied force. FIGURE 6.12 illustrates this idea.

But there's clearly a limit to how big f_s can get. If you push hard enough, the object slips and starts to move. In other words, the static friction force has a *maximum* possible size $f_{s \text{ max}}$.

- An object remains at rest as long as $f_s < f_{s,max}$.
- The object slips when $f_s = f_{s \text{ max}}$.
- A static friction force $f_s > f_{s \text{ max}}$ is not physically possible.

Experiments with friction (first done by Leonardo da Vinci) show that $f_{s \text{ max}}$ is proportional to the magnitude of the normal force. That is,

$$f_{\rm s \, max} = \mu_{\rm s} \dot{n} \tag{6.12}$$

where the proportionality constant μ_s is called the **coefficient of static friction.** The coefficient is a dimensionless number that depends on the materials of which the object and the surface are made. Table 6.1 shows some typical coefficients of friction. It is to be emphasized that these are only approximate. The exact value of the coefficient depends on the roughness, cleanliness, and dryness of the surfaces.

NOTE Equation 6.12 does *not* say $f_s = \mu_s n$. The value of f_s depends on the force or forces that static friction has to balance to keep the object from moving. It can have any value from 0 up to, but not exceeding, $\mu_s n$.

Kinetic Friction

Once the box starts to slide, in **FIGURE 6.13**, the static friction force is replaced by a limetic friction force \vec{f}_k . Experiments show that kinetic friction, unlike static friction, has a nearly *constant* magnitude. Furthermore, the size of the kinetic friction force is than the maximum static friction, $f_k < f_{s \text{ max}}$, which explains why it is easier to the box moving than it was to start it moving. The direction of \vec{f}_k is always opposite to the direction in which an object slides across the surface.

The kinetic friction force is also proportional to the magnitude of the normal force:

$$f_{\mathbf{k}} = \mu_{\mathbf{k}} n \tag{6.13}$$

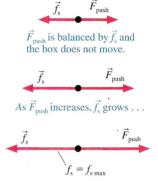
where μ_k is called the **coefficient of kinetic friction.** Table 6.1 includes typical values μ_k . You can see that $\mu_k < \mu_s$, causing the kinetic friction to be less than the maximum static friction.

Rolling Friction

slam on the brakes hard enough, your car tires slide against the road surface and save skid marks. This is kinetic friction. A wheel *rolling* on a surface also experiences inction, but not kinetic friction. The portion of the wheel that contacts the surface is sufficiently with respect to the surface, not sliding. To see this, roll a wheel slowly and such how it touches the ground.

Textbooks draw wheels as circles, but no wheel is perfectly round. The weight of wheel, and of any object supported by the wheel, causes the bottom of the wheel to where it touches the surface, as FIGURE 6.14 on the next page shows. The contact between a car tire and the road is fairly large. The contact area between a steel between a steel and a steel rail is much less, but it's not zero.

Molecular bonds are quickly established where the wheel presses against the sur-These bonds have to be broken as the wheel rolls forward, and the effort needed them causes **rolling friction.** (Think how it is to walk with a wad of chewing **FIGURE 6.12** Static friction acts in *response* to an applied force.

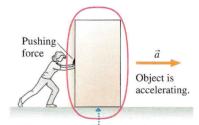


... until f_s reaches $f_{s \text{ max}}$. Now, if \vec{F}_{push} gets any bigger, the object will start to move.

TABLE 6.1 Coefficients of friction

Materials	Static $\mu_{\rm s}$	Kinetic μ_k	Rolling $\mu_{ m r}$
Rubber on concrete	1.00	0.80	0.02
Steel on steel (dry)	0.80	0.60	0.002
Steel on steel (lubricated)	0.10	0.05	
Wood on wood	0.50	0.20	
Wood on snow	0.12	0.06	
Ice on ice	0.10	0.03	

FIGURE 6.13 The kinetic friction force is opposite the direction of motion.



Kinetic friction is opposite the motion.

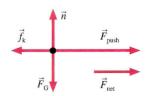


FIGURE 6.14 Rolling friction is due to the contact area between a wheel and the surface.



The wheel flattens where it touches the surface, giving a contact area rather than a point of contact. gum stuck to the sole of your shoe!) The force of rolling friction can be calculated in terms of a **coefficient of rolling friction** μ_r :

$$f_{\rm r} = \mu_{\rm r} n \tag{6.14}$$

Rolling friction acts very much like kinetic friction, but values of μ_r (see Table 6.1) are much lower than values of μ_k . This is why it is easier to roll an object on wheels than to slide it.

A Model of Friction

These ideas can be summarized in a *model* of friction:

Static:
$$\vec{f}_s \leq (\mu_s n, \text{ direction as necessary to prevent motion})$$

Kinetic: $\vec{f}_k = (\mu_k n, \text{ direction opposite the motion})$ (6.15)
Rolling: $\vec{f}_r = (\mu_r n, \text{ direction opposite the motion})$

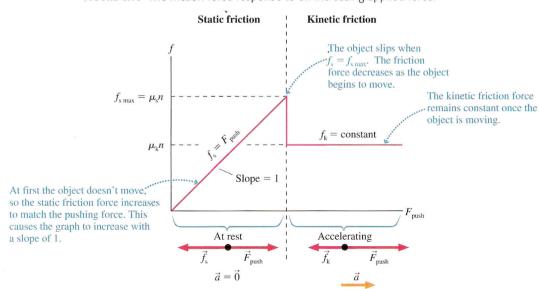
2.5, 2.6 Act v

Here "motion" means "motion relative to the surface." The maximum value of static friction $f_{s,max} = \mu_s n$ occurs at the point where the object slips and begins to move.

NOTE ► Equations 6.15 are a "model" of friction, not a "law" of friction. These equations provide a reasonably accurate, but not perfect, description of how friction forces act. For example, we've ignored the surface area of the object because surface area has little effect. Likewise, our model assumes that the kinetic friction force is independent of the object's speed. This is a fairly good, but not perfect, approximation. Equations 6.15 are a simplification of reality that works reasonably well, which is what we mean by a "model." They are not a "law of nature" on a level with Newton's laws.

FIGURE 6.15 summarizes these ideas graphically by showing how the friction force changes as the magnitude of an applied force \vec{F}_{push} increases.

FIGURE 6.15 The friction force response to an increasing applied force.



The angle at which slipping begins is called the *angle of repose*. **FIGURE 6.18** shows that knowing the angle of repose can be very important because it is the angle at which loose materials (gravel, sand, snow, etc.) begin to slide on a mountainside, leading to landslides and avalanches.

Causes of Friction

It is worth a brief pause to look at the *causes* of friction. All surfaces, even those quite smooth to the touch, are very rough on a microscopic scale. When two objects are placed in contact, they do not make a smooth fit. Instead, as **FIGURE 6.19** shows, the high points on one surface become jammed against the high points on the other surface, while the low points are not in contact at all. Only a very small fraction (typically 10^{-4}) of the surface area is in actual contact. The amount of contact depends on how hard the surfaces are pushed together, which is why friction forces are proportional to n.

At the points of actual contact, the atoms in the two materials are pressed closely together and molecular bonds are established between them. These bonds are the "cause" of the static friction force. For an object to slip, you must push it hard enough to break these molecular bonds between the surfaces. Once they are broken, and the two surfaces are sliding against each other, there are still attractive forces between the atoms on the opposing surfaces as the high points of the materials push past each other. However, the atoms move past each other so quickly that they do not have time to establish the tight bonds of static friction. That is why the kinetic friction force is smaller.

Occasionally, in the course of sliding, two high points will be forced together so closely that they do form a tight bond. As the motion continues, it is not this surface bond that breaks but weaker bonds at the *base* of one of the high points. When this happens, a small piece of the object is left behind "embedded" in the surface. This is what we call *abrasion*. Abrasion causes materials to wear out as a result of friction, be they the piston rings in your car or the seat of your pants. In machines, abrasion is minimized with lubrication, a very thin film of liquid between the surfaces that allows them to "float" past each other with many fewer points in actual contact.

Friction, at the atomic level, is a very complex phenomenon. A detailed understanding of friction is at the forefront of engineering research today, where it is especially important for designing highly miniaturized machines and nanostructures.

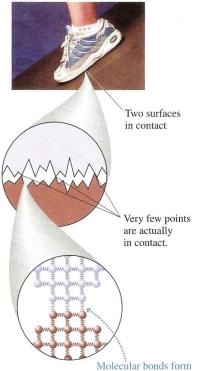
6.5 Drag

The air exerts a drag force on objects as they move through the air. You experience drag forces every day as you jog, bicycle, ski, or drive your car. The drag force is especially important for the skydiver at the beginning of the chapter.

FIGURE 6.18 The angle of repose is the angle at which loose materials, such as gravel or snow, begin to slide.



FIGURE 6.19 An atomic-level view of friction.



between the two materials.
These bonds have to be broken as the object slides.