Applying Hidden Markov Models (HMMs) in AFRICRIX for Crisis Signal Analysis

1. Observations in AFRICRIX

In AFRICRIX, the observations for an HMM would be **measurable crisis-related signals** captured over time from various data streams. These include:

- Real-time social media signals (e.g., tweet counts, trending crisis keywords, Telegram messages)
- News article event counts (e.g., "flood" mentions per hour)
- Satellite-based indices (e.g., NDVI, water extent)
- Citizen report counts and sensor readings (e.g., number of uploads, geolocated sensor pings)
- Temporal features: rolling averages, 24h signal deltas, 7-day slopes, and anomaly scores
 - Each observation at time t is a vector summarizing the system's detected signal strength and type across sources and locations.

2. Type of HMM Problem

I do not know the true underlying "crisis state" (e.g., "calm", "building risk", "escalating crisis") at each timestep in real life—these are hidden. We only observe noisy, multi-source signals. Thus, this is an unsupervised HMM (learning hidden states), commonly formulated as an HMM learning problem:

• **Objective**: Infer the sequence of hidden "crisis states" and learn their temporal dynamics purely from the observations.

3. Training Algorithm

a. Known Values at the Start

• The sequence of observed vectors over time $(0 = o_1, o_2, \ldots, o)$, e.g., hourly features from signals.

- (Optionally) Initial guesses for the number of hidden states (e.g., K = 3: calm, rising risk, crisis).
- (Optionally) Initial parameter estimates (can be random or from clustering, e.g., K-means).

b. Unknown Values to Learn

- State transition probabilities (A): How likely is it to move from one hidden crisis state to another (e.g., calm → rising risk)?
- Emission probabilities (B): How likely is each observable signal pattern given a particular hidden state (often modeled as multivariate Gaussian for continuous features)?
- *Initial state probabilities* (π) : Probability of starting in each hidden crisis state.

The **Baum-Welch (EM) algorithm** is used to learn these parameters by maximizing the likelihood of the observed signal sequences.

4. Parameter Updates in Training

During training, the HMM iteratively updates:

- The **transition matrix (A)**: Probabilities of moving between hidden states, e.g., from "building risk" to "active crisis".
- The **emission parameters (B)**: For each hidden state, the parameters of the probability distribution generating the observed features (means/covariances for Gaussian HMM).
- The *initial state distribution* (π): Probability of the system starting in each hidden state.

ΑII	these	are	updated	via	expectation-maximization:	computing	posteriors	over	state
sequences (E-step) and then updating parameters to maximize data likelihood (M-step).									

AFRICRIX uses an unsupervised HMM to model and infer the hidden crisis states underlying streams of real-time signals. The HMM is trained using the Baum-Welch algorithm, which learns the transition, emission, and initial state probabilities. The model continually updates these parameters based on incoming data, allowing the

In summary:

system to detect subtle transitions from "safe" to "at-risk" to "crisis"—enabling proactive alerting before human operators can detect the pattern.