```
In [48]:
```

```
import cv2
import numpy as np
```

In [52]:

```
# Video input path
video path = "roads.mp4"
video = cv2.VideoCapture(video path)
# Video output path
output path = "output video.mp4"
# Get video properties (width, height, frames per second)
width = int(video.get(3))
height = int(video.get(4))
fps = int(video.get(5))
# Define codec and create VideoWriter object
fourcc = cv2.VideoWriter fourcc(*'XVID')
output video = cv2. Video Writer (output path, fourcc, fps, (width, height))
_, prev_frame = video.read()
while True:
   ret, curr frame = video.read()
   if not ret:
       break
   frame diff = cv2.absdiff(curr frame, prev frame)
    frame diff gray = cv2.cvtColor(frame diff, cv2.COLOR BGR2GRAY)
    # Erosion followed by dilation để lọc gợn ảnh
    \# kernel = np.ones((2,2),np.uint8)
    # opening = cv2.morphologyEx(frame diff gray, cv2.MORPH OPEN, kernel)
    # Blur frames
    opening = cv2.blur(frame_diff_gray, (10,10))
    , threshold = cv2.threshold(opening, 15, 255, cv2.THRESH BINARY)
    number contours, hierarchy = cv2.findContours(threshold.copy(), cv2.RETR CCOMP,
                                                       cv2.CHAIN APPROX SIMPLE)
    test = curr frame.copy()
    for i in range(len(number_contours)):
        if hierachy[0][i][3] == -1:
            x1,y1,w,h= cv2.boundingRect(number contours[i])
            a = cv2.rectangle(test, (x1,y1), (x1+w, y1+h), color = [0,255,0], thickness=
1)
    # Your processing code here
    # Write the processed frame to the output video
    output video.write(a) # You can change this to write the processed frame
   prev frame = curr frame
    cv2.imshow("frame", a)
    if cv2.waitKey(1) \& 0xFF == ord('q'):
# Release the VideoCapture and VideoWriter objects
video.release()
output video.release()
cv2.destroyAllWindows()
```