# **NEWTON**

## Multiphysics coupling master code User's manual

FEDERICO CACCIA

July 28, 2017

## Contents

| 1 | nput cards          | 3 |
|---|---------------------|---|
|   | .1 General cards    | 3 |
|   | 1.1.1 card METHOD   | 3 |
|   | 1.1.2 card PHASES   | 4 |
|   | 1.1.3 card ABS_TOL  | 4 |
|   | 1.1.4 card MAX_ITER | 4 |

iv CONTENTS

### **Preface**

Newton is a master code that solves explicit and implicit coupling in nonlinear calculations. It was designed with a general purpose. For example, it can be used in multiscale coupled problems, in CFD-temalhydraulic problems, in neutronic-termalhydraulic problems, and others. These are the main features of the code:

- Capable of coupling all kind of codes.
- Easy to use.
- Respect the GNU project philosophy.

This is the user's manual. Here you find everything necessary to prepare the input and solve a coupling problem.

2 CONTENTS

### 1

### Input cards

Newton input parser is only case sensitive to cards names and bin command arguments. However, it is a good practise to use upercase letters for cards and lowercase letters for names, strings and other values.

#### 1.1 Comments

To comment a line of Newton input use one of these characters:

```
'#', '@', '%', '_', '-'
```

or just use "NEWTON" as first word of the line.

#### 1.2 General cards

#### 1.2.1 card METHOD

Sets the nonlinear method used to solve the residual of the equations. Available values are:

```
METHOD picard
```

This method is the common dirichlet-to-newmann explicit method. Codes run by phases inside each iteration. Initial guesses are sended to clients in phase run. Newton waits for their solutions and after that, updates unknowns and send necessary values to client codes in phase 2, and so on.

```
METHOD combinated_picard
```

This method is similar to the *picard*, but in this case, guesses are sended to all client codes at the same time. Once all client has ended their calculations, Newton updates the unknown solution with these values and send them again to the clients codes as new guesses.

4 1. INPUT CARDS

```
METHOD newton
```

Newton method. It builds the Jacobian matrix in each iteration, so it requires at least N+1 function evaluations in each iteration (with N amount off coupled client codes).

```
METHOD secant
```

This method builds the Jacobian matrix only at the beggining of the iterations. It is possible to update the matrix until a determined amount of iterations or steps in evolution problems using ITER JAC CALC and STEPS JAC CALC cards.

```
METHOD broyden
```

Broyden method is a quasi-newton method with superlinear convergence order. It is possible to initialize the Jacobian matrix with a guess by J\_INI card or with calculation of the Jacobian matrix by finite difference (Otherwise Newton starts using the identity matrix). Also, it is possible to recalculate the matrix until a determined amount of iterations or steps in evolution problems using ITER\_JAC\_CALC and STEPS\_JAC\_CALC cards.

#### 1.2.2 card PHASES

This card is only necessary using explicit\_serial method. Client code names should be provided in the same order that it is desirable to run. Phases are separated using "&". To end the enumeration, use "&" too. For example, in a problem in wich client1 and client2 should run in phase 1, client3, client4 and client5 should run in phase 2 and client6 should run in phase 3:

```
PHASES client1 client2 & client3 client4 client5 & client6 &
```

It is also posile to use inner iterations in each phase. To habilitite this option, use PHASES\_MAX\_ITER card.

#### 1.2.3 card PHASES MAX ITER

This option can be only used in EXPLICIT\_SERIAL method. It allows to use inner iterations in each phase. To use it set amount of maximum iterations for each phase. For example, if we desire to use up to 10 iterations in phase 1, and just 1 in phase 2, set:

```
PHASES_MAX_ITER 10 1
```

or just

```
PHASES_MAX_ITER 10
```

to leave phase 2 with defafult optiones(just 1 inner iteration).

1.2. GENERAL CARDS 5

#### 1.2.4 card ABS TOL

Absolute nonlinear tolerance in nonlinear iteations to reach the convergence of the solution. Newton step ends with WARNING when norm 2 of the residual falls below ABS\_TOL.

```
ABS_TOL 1e-14
```

#### 1.2.5 card MAX ITER

Maximum amount of nonlinear iteations allowed to reach the convergence of the solution. Newton step ends with WARNING when nonlinear iterations grows above MAX\_ITER.

```
MAX_ITER 100
```

#### 1.2.6 card X\_EXT\_ORDER

Order of extrapolation to set guess at new evolution step. Now it is only available order 1. Use:

```
X_EXT_ORDER 1
```

#### 1.2.7 card J EXT ORDER

Order of extrapolation to set jacobian at new evolution step. It can be used with any implicit method. Now it is only availale order 1. Use:

```
J_EXT_ORDER J
```

#### 1.2.8 card X INI

Initial condition in unknowns. It can be used as general card or inside CLIENT card. After this card set unknown name and unknown value. For example, to set  $x_0 = 0.1$  and  $y_0 = 0.2$  values, use:

```
X_INI x 0.1 y 0.2
```

#### 1.2.9 card STEPS JAC CALC

It can be used with any method that builds system's jacobian, but not for newton (newton computes jacobian in each step and iteration). It sets difference between steps in wich jacobian is computed by finite difference. Its default value is 0. To change it to 100 for example, use:

```
STEPS_JAC_CALC 100
```

6 1. INPUT CARDS

#### 1.2.10 card ITER\_JAC\_CALC

It can be used with any method that builds system's jacobian, but not for newton (newton computes jacobian in each step and iteration). It sets difference between iterations in wich jacobian is computed by finite difference. Its default value is 0. To change it to 100 for example, use:

```
ITER_JAC_CALC 100
```

#### 1.2.11 card DX\_JAC\_CALC

It can be used with any method that builds system's jacobian. It sets delta in unknown to compute residual derivate by finite difference. Its default value is 0.1. To change it to 0.01 for example, use:

```
DX_JAC_CALC 0.01
```

#### 1.2.12 card N STEPS

Number of evolution coupling steps. For example, in a transitory problem with 10 coupling time steps use:

```
N_STEPS 10
```

#### 1.2.13 card DELTA STEP

Difference in evolution parameter between two steps. Its units depend on the problem. For example, in a neutronic neutronic-termalhydraulic coupling problem solving quasi-static steps in a burnup evolution, if we update cross sections every 50 dayys, use:

```
DELTA_STEP 50.0
```

#### 1.2.14 card CLIENT

This is a block card. After setting this card, all CLIENT options can be set, until a new general card or end of file is found. The first option that has to be set is client name. To set *client*1 client options use:

```
CLIENT client1 ...
```

Use any of the CLIENT cards after that.

1.3. CLIENT CARDS

#### 1.2.15 card MAPPER

This is a block card. After setting this card, all MAPPER options can be set, until a new general card or end of file is found. The first option that has to be set is mapper name. To set map1 mapper options use:

```
MAPPER map1
...
```

Use any of the MAPPER cards after that.

#### 1.2.16 card DEBUG\_TIME

It can be used to export time calculation values in time.log. To use it just set:

```
DEBUG_TIME
```

#### 1.3 Client cards

Inside CLIENT block (see general card CLIENT), it can be used any of these cards:

#### 1.3.1 card CONNECTION

This is an obligatory card. Select one of the connection mode options:

```
CONNECTION io_spawn
```

This option is used to communicate master with client by input / output option spawning N processes of the client by  $MPI_{C}omm_{S}pawn$ .  $MPI_{C}omm_{S}pawn$  doesn't wait that the slave ends running and so it is needed an MPI\_Barrier after the spawn. Client should have implemented this barrier too, once the output has been printed.  $newton_{s}pawn$  needs also theese cards: N\_PROCS, INPUT\_NAME, INPUT\_EXT, OUTPUT\_NAME, OUTPUT\_EXT, BIN\_COMMAND, ARGS and IO\_TYPE.

```
CONNECTION io_system
```

This option is used to communicate master with client by input / output option spawning 1 process of the client by system function of the standard library of c++. system waits that the slave ends running and so it isn't needed any barrier as in newton\_spawn. NEWTON\_SPAWN needs also theese cards: N\_PROCS, INPUT\_NAME, INPUT\_EXT, OUTPUT\_NAME, OUTPUT\_EXT, BIN\_COMMAND, ARGS and IO\_TYPE.

```
CONNECTION mpi_port
```

8 1. INPUT CARDS

This option is used to communicate master with client by mpi functions. Master publishes a port to connect with client and then connection has to be stablished using some functions in client. Also, some functions related to send and receive variable values have to be implemented in client. See ?? section to understand how to implement this communication mode in client.

```
CONNECTION mpi-comm
```

This option is used to communicate master with client by mpi functions. Newton and client codes should be run from beggining using mpirun. Also, some functions related to split communicator, to send and to receive variable values have to be implemented in client. See ?? section to understand how to implement this communication mode in client.

#### 1.3.2 card IO\_TYPE

This card is obligatory using io CONNECTION option. If input and output client files are simple (just variable values writen inside), it can be used:

```
IO_TYPE test
```

If input and output client files are complex (not just variable values writen inside), it needs some programmed lines in *userClient.cpp* to help Newton to read and write these files. Use:

```
IO_TYPE USER_CODE
```

Other options pre-programmed are:

```
IO_TYPE RELAP_POW2TH
```

This mode is used running RELAP client with power fraction distribution as input. From the output there are extracted fuel temperatures, refrigerent temperatures and densities in the core.

```
IO_TYPE FERMI_XS2POW
```

This mode is used running FERMI client with cross sections as input. From the output there are extracted power spatial distribution values.

```
IO_TYPE NEUTRONIC_CR2KP
```

This mode is used running FERMI client with control rod positions as input. From the output there are extracted power spatial distribution values and k effective of the core.

```
IO_TYPE NEUTRONIC_KP2CR
```

This mode is used running CR client with power spatial distribution values and k effective of the core as input. From the output there are extracted control rod position values.