

Output analysis:

| Test case | Number of processes created | Analysis |
|-----------|------------------------------|---|
| 1 | 2 (parent + child) | Single fork() creates one child |
| 2 | 3 (1 parent + 2 children) | Contains two separate fork() calls |
| 3 | 2 (parent + child) | Only one fork() occurs |
| 4 | 3 (one parent, two children) | A second fork occurs after program 1 runs |
| 5 | 1 | Fork was not called |

Analysis: the child always runs before the parent resumes, as outlined in the assignment that the child must have higher priority

Memory allocation and loading programs:

| Test case | Loaded programs | Memory partitions in use | Analysis |
|-----------|----------------------------------|------------------------------|--|
| 1 | Program1: 10MB Program2: 15MB | Partition 4 then partition 3 | Larger program causes longer load time |
| 2 | Program1: 10MB | Partition 4, then 3, then 2 | Test case demonstrated process replacement |
| 3 | Program2 twice:15MB | Partition 4 | I/O interrupts occur after execution begins |
| 4 | Program1: 10MB | Partition 4 then 3 | Multiple syscalls and CPU bursts extend runtime |
| 5 | No program loaded | none | Only system calls and CPU bursts occur, no memory reallocation |

Across the 5 test cases the simulation consistently reproduced expected IS process management behaviour. Fork() cloned PCB state and immediately scheduled the child. Exec() replaced the running process's memory image and updated PCB and partition entries. Program loading time depended on program size, and system calls followed the required kernel-mode transition steps. Test case 5 provides a contrast since it is a test case that doesn't create any processes or reassigns memory. The tests show the simulator behaves according to the assignment rules and expectations as proven by the outputs.

Github links:

https://github.com/Nhfaris627/SYSC4001_A2_P3

https://github.com/EnderAres183/SYSC4001_A2_P2